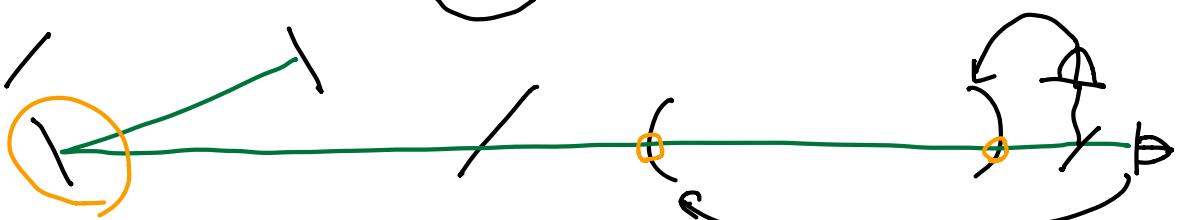


# IFO alignment

## 1. Xarm (Gr)



a. lock Xarm with green

(b-0 Center the beam position on IM, ETM with camera. Take reference of TMS QPDs)

b. engage TMS QPD loop

c. dither PR3 and maximize Gr TRANS

(C-1. move in-vac pico before PR2 if Gr TRANS is too low)

## 2. Xarm (Ik)

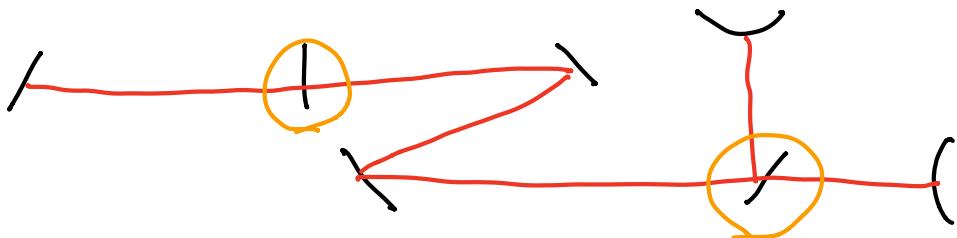


a. Dither PR2, IMM<sub>T2</sub> and maximize Ik TRANS

Notes:

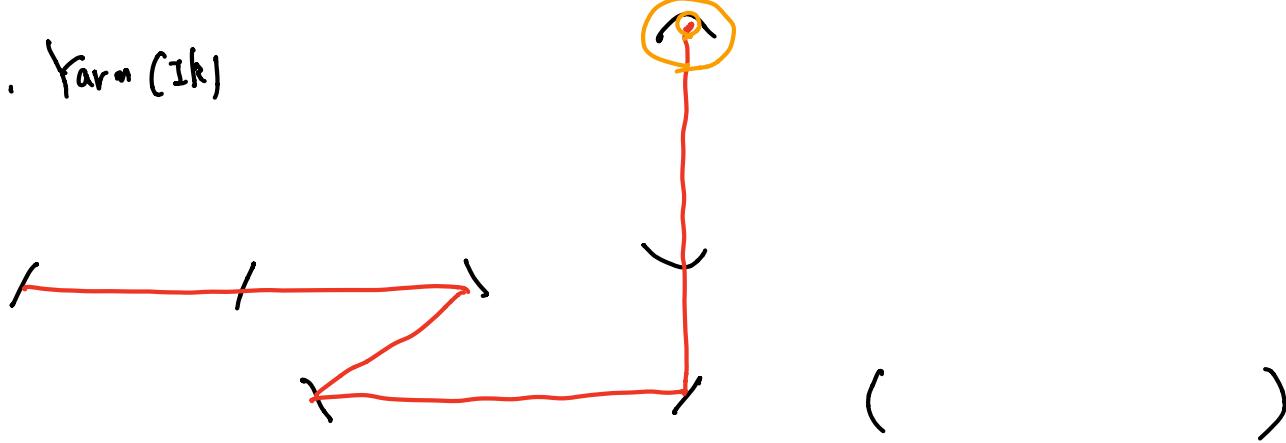
i. IMM<sub>T2</sub> and PR2 are almost degenerated. We often skip the IMM<sub>T2</sub> alignment.

## 3. PRMI



a. Dither PRM, BS and maximize PGP90

#### 4. Yarn (Ik)



a. Dither ETMY and maximize Yarn TRANS

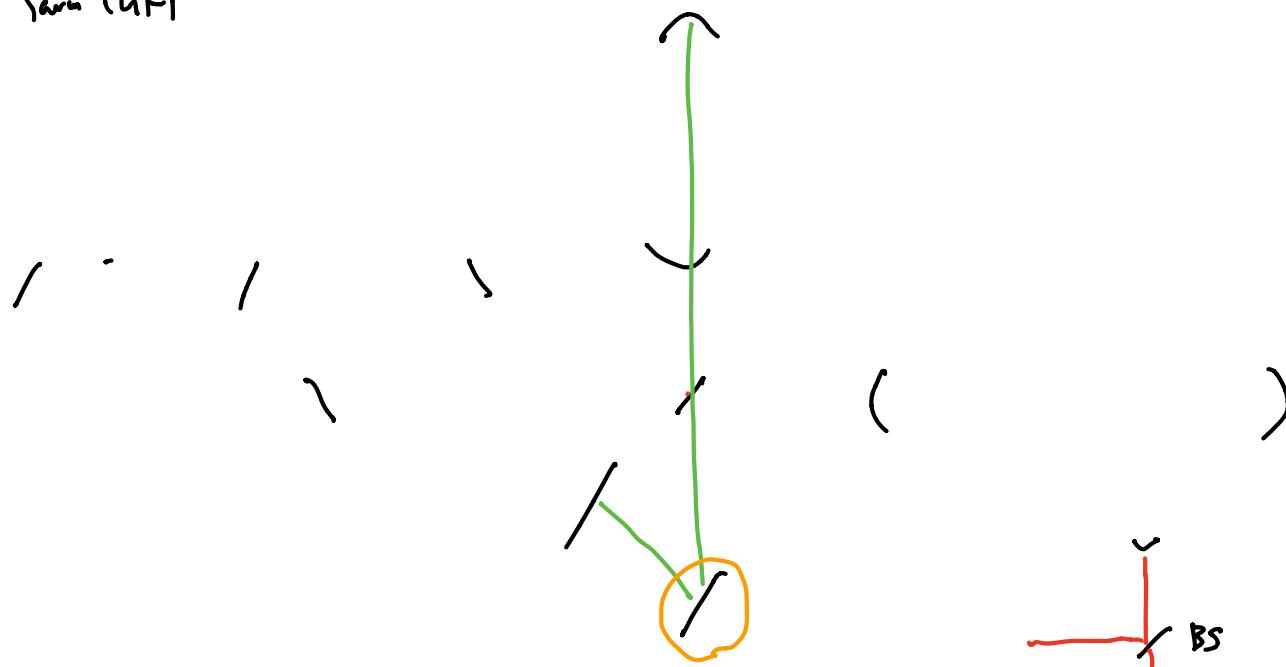
In check beam position on ETMY. If too far from center, move IMY to center it.

c. If IMY was moved, go back PRM2 alignment

Note: Yarn Z<sub>in</sub><sup>ff</sup> in alignment (7場合 (BS, EY 位置?)). PRM2 alignment  
する場合は BS の位置を変更する。

Method: 7種類 (Y1: ピンボル)

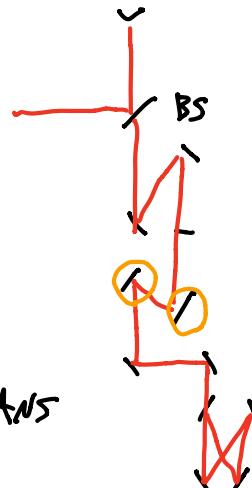
#### 5. Yarn (GR)



a. Dither SR3 and maximize GR TRANS.

(b. If TRANS is too low, move im-race pitch)

6. OMC Dither OMMT 1,2 and maximise OMC TRANS  
with single bounce from IMY.



Notes : 1. We cannot gain the BPC error signal with single arm lock (both of IR and QK). (maybe due to freq. noise)