

LIGO-KAGRA joint CDS meeting

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Contents

Our updates before Phase-1 operation

- Updated ADC firmware for fixing IRIG-B 999996
- Installed trend-writer and SSD for minute-raw data
- Developed a new script for Dolphin network

Remains serious problem toward cryogenic (DR)FPMI

- Too large CPU MAX

IRIG-B problem

[[klog4685](#)]

We updated the ADC firmware. Thanks to Michael!

Rev 1 -> Rev 34

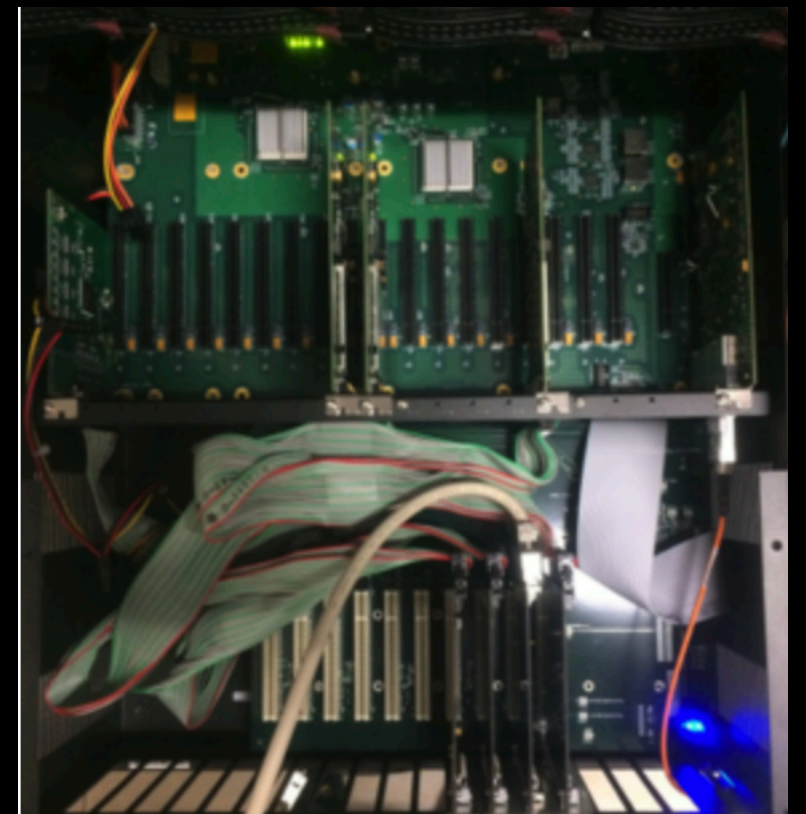
IRIG-B 999996 problem is partially fixed (on 2 of 3 IO chassis)

I noticed that the 1st DAC adapter is installed
in another slot on some(not all) IO chassis.

But we cannot turned ON DAC duotone in this configuration.

Should we turned ON DAC duotone?

What purpose is the DAC duotone?



Installation of trend-writer

Daqd on frame-writers periodically downed before phase-1 operation.

We installed two trend-writers which have local SSD.

- Frame-writers record full/science/minute/second on NFS area
- Trend-writers record minute-raw on local SSD

Periodically hung-up of daqd was stopped after the installation.

Current data rate of KAGRA data

- full: 160MB per 32s
- science: 50MB per 32s
- second: 160MB per 600s
- minute: 100MB per 3600s

Dolphin script

Three RTPC joined dolphin network during Phase-1 (k1ioo, k1imc, k1bs)
- All the models on 3 RTPCs down when we shutdown 1 in 3 RTPCs.

I prepared the new script for disabling the Dolphin communication.

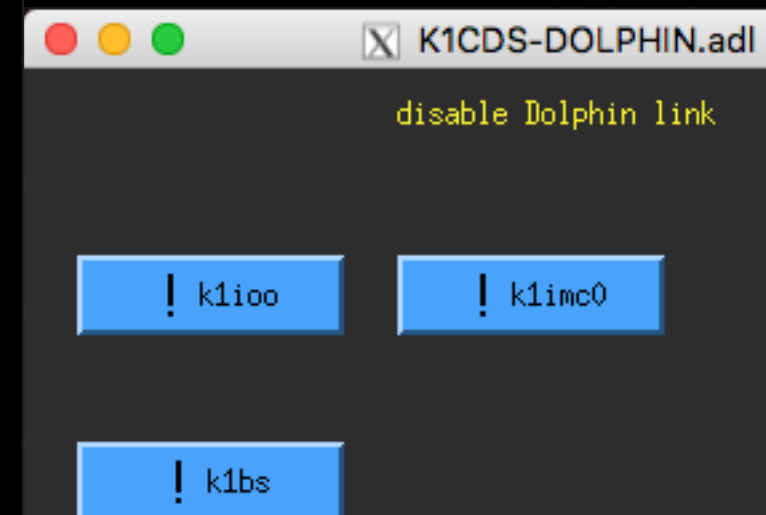
[Ref] Section 9 in [LIGO-T1300518-v6](#)

```
Terminal — screen • ssh — 145x40 — \#\%1
controls@k1ctr0:/opt/rtdcs/userapps/release/cds/common/scripts$ cat dolphin_disable.sh
#!/bin/bash

THIS=/opt/rtdcs/userapps/release/cds/common/scripts/dolphin_disable.sh
BOOTSERVER=k1boot
CONFFILE=/etc/dis/cluster.conf
ADAPTER=0

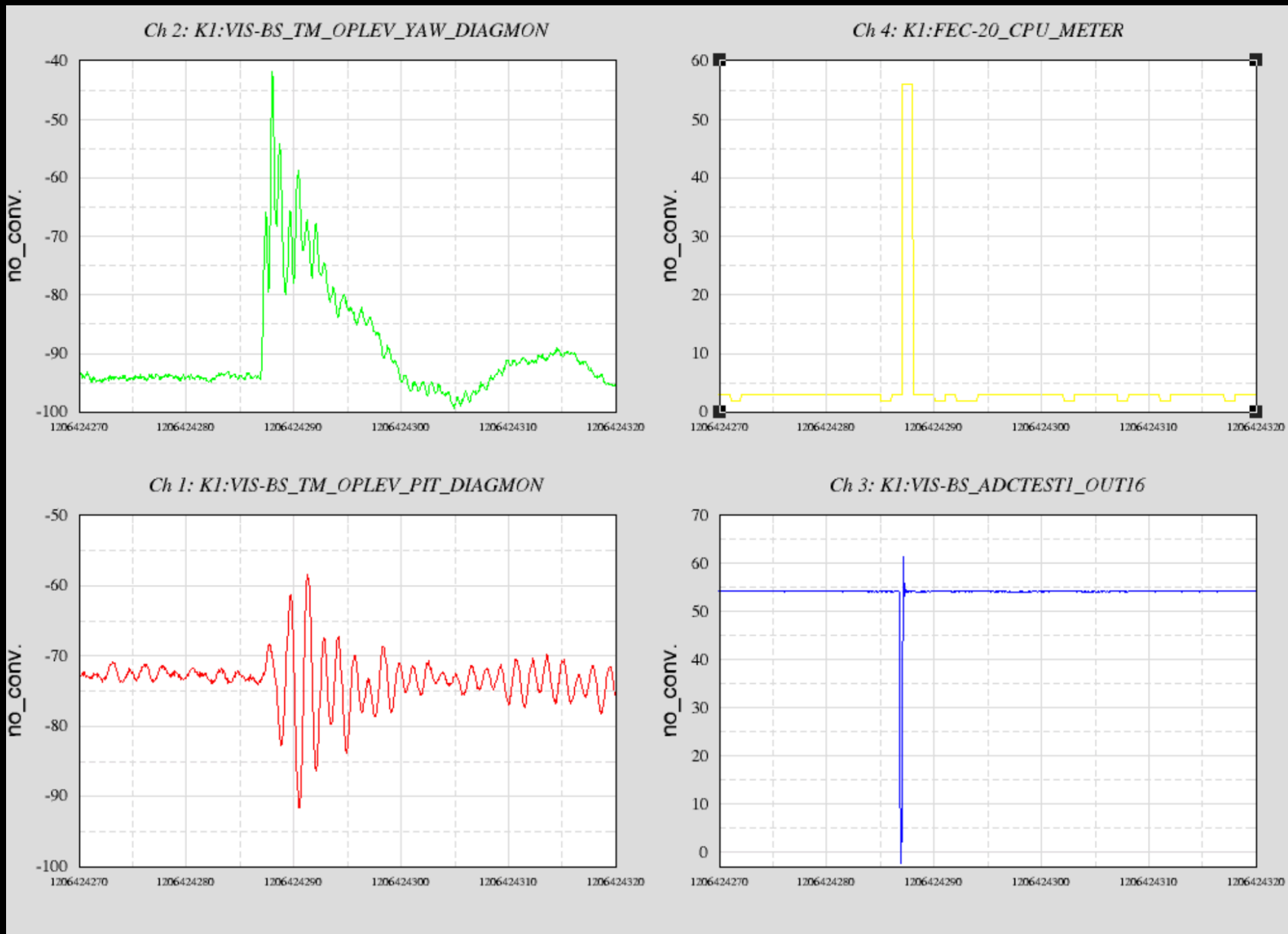
NODENAME=$1
[ "${NODENAME}" = "" ] && echo "usage: $0 hostname" && exit 0

if test `hostname` = "${BOOTSERVER}"
then
  NODEID=`grep '^nodeoption ' ${CONFFILE} | grep " ${NODENAME} " | awk '{print $5}'`
  [ "${NODEID}" = "" ] && echo "[ ERROR ] Can't find $1 in ${CONFFILE}" && exit 0
  printf " Node ID of \033[31;01m${NODENAME}\033[00m = ${NODEID}\n"
  echo ""
  for OTHER in `grep '^nodeoption' ${CONFFILE} | grep -v "${NODENAME}" | awk '{print $2}'`
  do
    if test `ssh ${OTHER} sudo /opt/DIS/sbin/dxdiag | grep "In range" | wc -l` -ne 0
    then
      printf "`hostname`> ssh \033[31;01m${OTHER}\033[00m sudo /opt/DIS/sbin/dxtool disable-remote-link ${ADAPTER} ${NODEID}\n"
      ssh ${OTHER} sudo /opt/DIS/sbin/dxtool disable-remote-link ${ADAPTER} ${NODEID}
    else
      printf " Nothing to be done for \033[31;01m${OTHER}\033[00m\n"
    fi
  done
else
  export SSH_ASKPASS=/usr/lib/seahorse/seahorse-ssh-askpass
  echo ""
  echo "`hostname`> setsid ssh -o NumberOfPasswordPrompts=1 ${BOOTSERVER} ${THIS} ${NODENAME}"
  setsid ssh -o NumberOfPasswordPrompts=1 "${BOOTSERVER}" "${THIS}" "${NODENAME}" 2> /dev/null && zenity --info --text "disable Dolphin for $1"
  2> /dev/null || zenity --error --text "Auth Error" 2> /dev/null
  echo ""
fi
```



CPU MAX problem

CPU meters on almost all models are too large
 Too large CPU meter value causes glitches and lockloss



NAME	GPS [s]	TIM	CPU
☐k1iopioo0	1213539130	🟢🔴	63
☐k1psl	1213539130	🟢🔴	67
☐k1imc	1213539130	🟢🔴	65
☐k1imcasc	1213539130	🟢🔴	74
☐k1iopimc0	1213539130	🟢🔴	62
☐k1vismci	1213539130	🟢🔴	64
☐k1vismce	1213539130	🟢🔴	65
☐k1vismco	1213539130	🟢🔴	65
☐k1vists	1213539130	🟢🟢	62
☐k1visimnt1	1213539130	🟢🔴	66
☐k1visimnt2	1213539130	🟢🔴	65
☐k1lsc			
☐k1calcs			
☐k1iopprm	1213539130	🟢🟢	5
☐k1visprm	1213539130	🟢🟢	25
☐k1ioppr0	1213539130	🟢🔴	62
☐k1vispr3	1213539130	🟢🟢	96
☐k1ioppr2	1213539130	🟢🔴	62
☐k1vispr2	1213539130	🟢🟢	93
☐k1iopbs	1213539130	🟢🔴	61
☐k1visbsp	1213539130	🟢🔴	78
☐k1visbst	1213539130	🟢🟢	71
☐k1iopsrn	1213539129	🟢🔴	61
☐k1vissrn	1213060536	🔴🟢	76
☐k1iopsr2	1213539130	🟢🟢	5
☐k1vissr2	1213539130	🟢🔴	76
☐k1iopsr3	1213539130	🟢🔴	58
☐k1vissr3	1213539130	🟢🔴	84

CPU MAX problem

What we did for phase-1 operation

- changed sampling rate for PRs and ETMs
16kHz → 2kHz
- splitted model for BS
k1visbs (16kHz) → k1visbst (2kHz) for tower
k1visbsp (16kHz) for payload