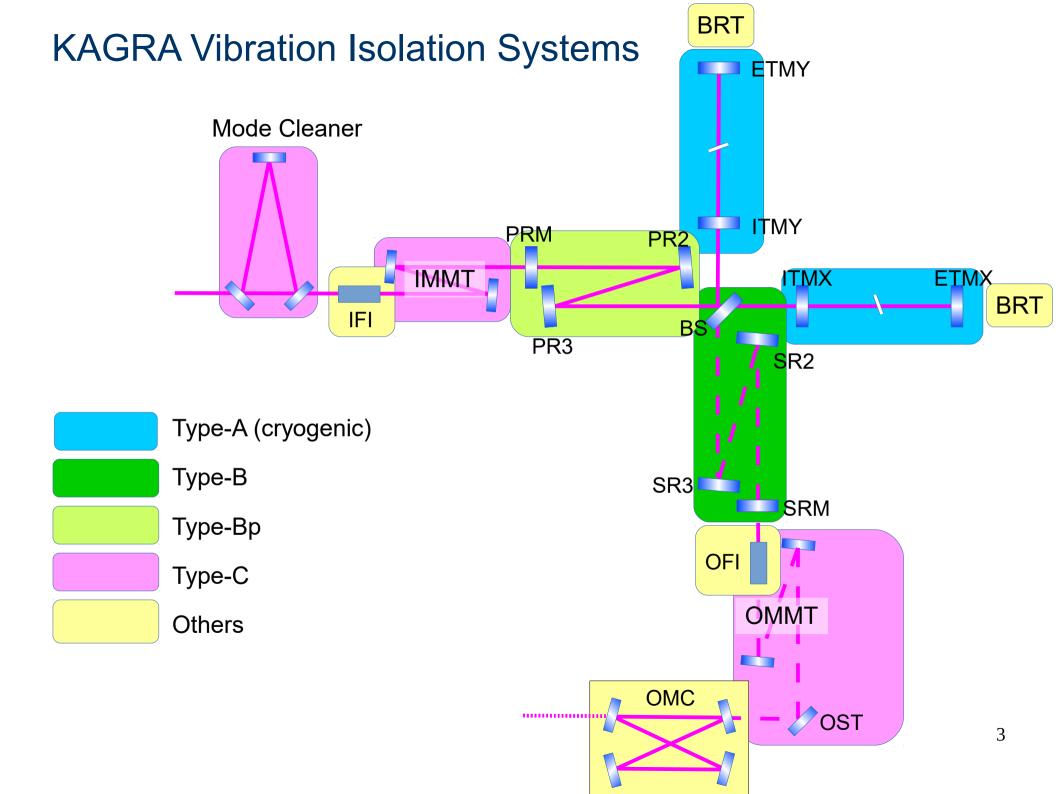
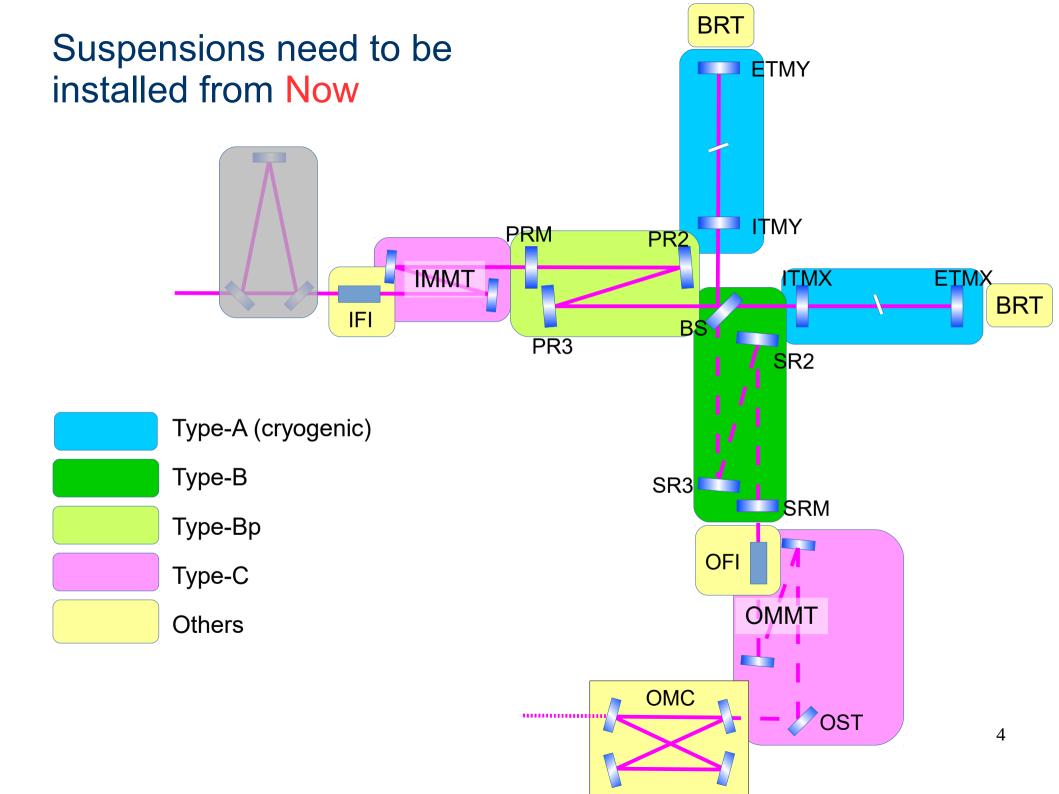
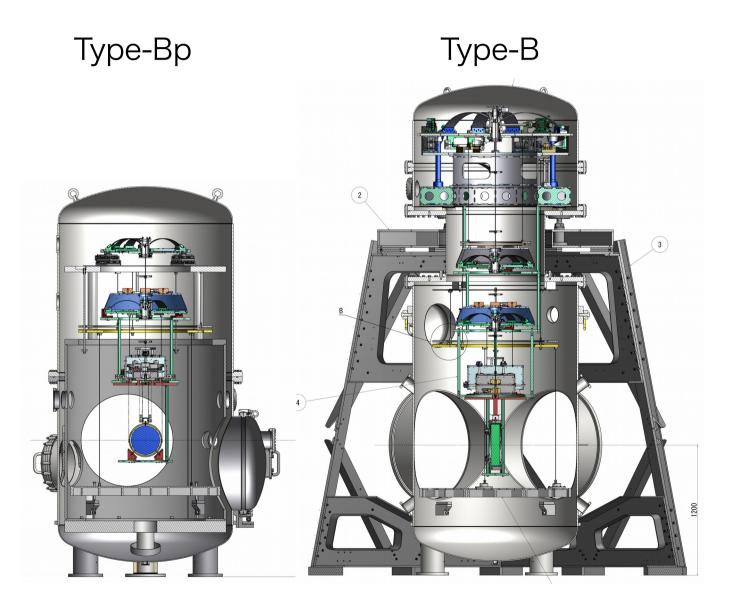
# bKAGRA Vibration Isolation Systems

# **VIS Overview**





# Three types of large suspensions



Type-A

### Other vibration isolation systems

- MC (TAMA suspensions, installed)
- IMMT (TAMA suspensions)
- Output optics
  - OFI (modified TAMA suspension ?)
  - OMMT (newly built TAMA like suspension)
  - OST (newly built TAMA like suspension)
  - OMC (custom made one)
- BRT
  - Custom made one

# Who is responsible for what?

### Large suspension systems + IMMT

(Type-A w/o cryo payload, Type-B, Type-Bp, Type-C)

→ VIS subsystem (NAOJ)

### Cryogenic Payload

→ CRY (KEK)

### Beam Reducing Telescope Suspensions

→ AOS (NAOJ)

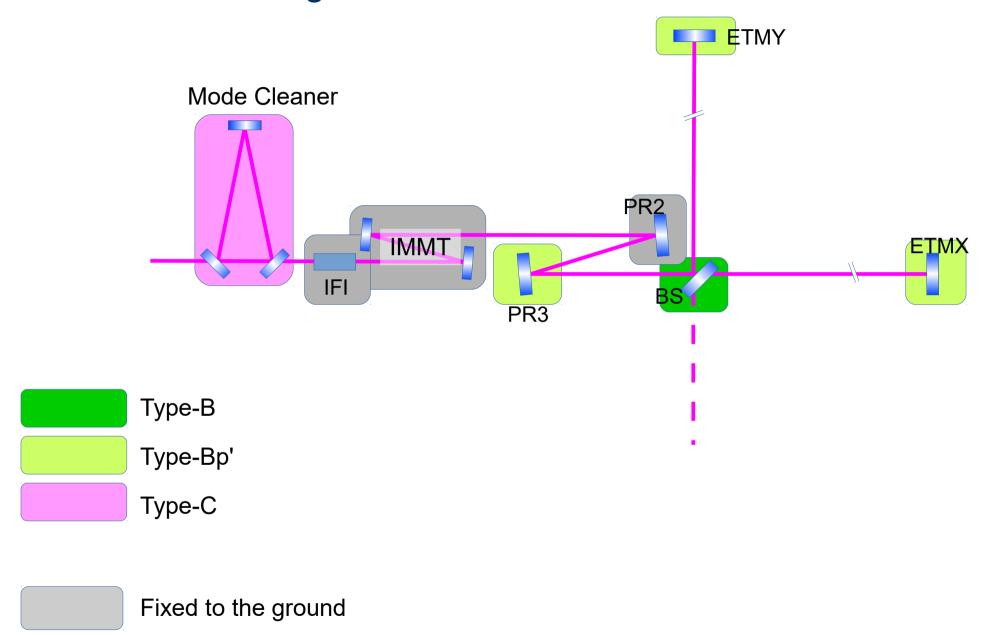
### **Output Optics Suspensions**

(OFI, OMMT, OST, OMC + IFI?)

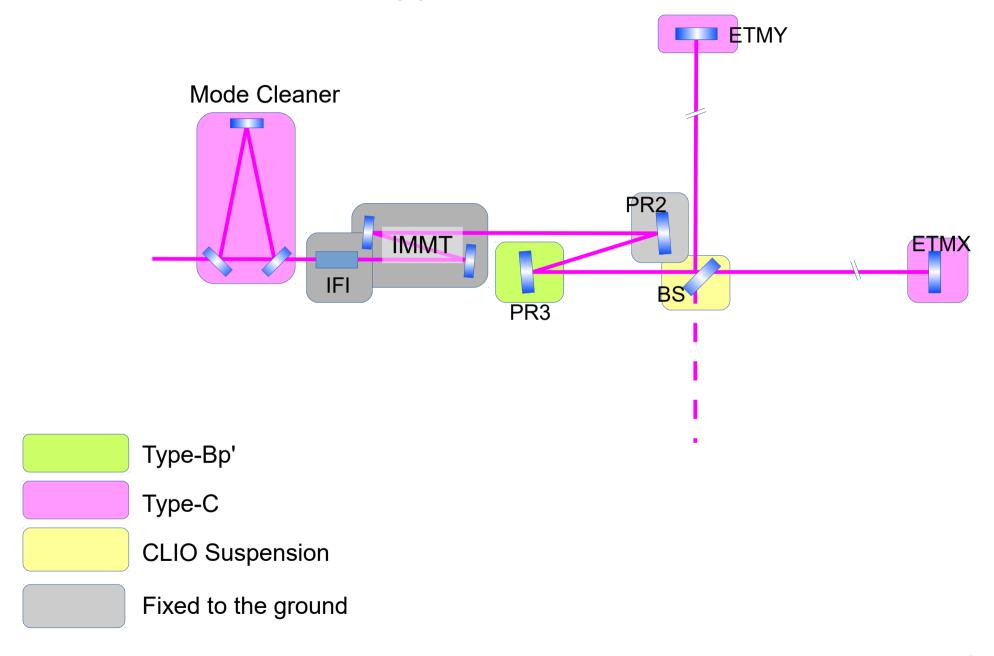
**→ IOO ?** 

# What happened in iKAGRA?

# iKAGRA VIS: Original Plan



### iKAGRA VIS: What happened



### VIS installation took much longer than expected

#### PR3 was the only large suspension installed

- Tunnel environment
- Insufficient preparation
  - Parts missing
  - Not-well-established installation procedure
  - Incorrect drawings
  - Tools missing
- Troubles
  - Cracks in the sapphire prisms
  - Broken OSEM flags
  - Wrong cables
  - Screw galling

Original estimate of installation work duration

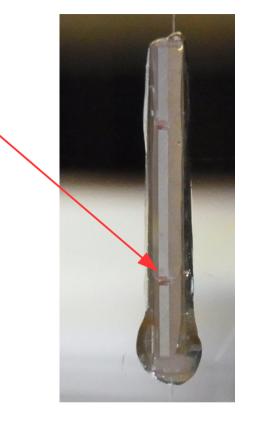
1 month for PR3

### Actually happened

3 months for test installation, 1.5 months for the actual installation.

# PR2 wire breaker developed cracks

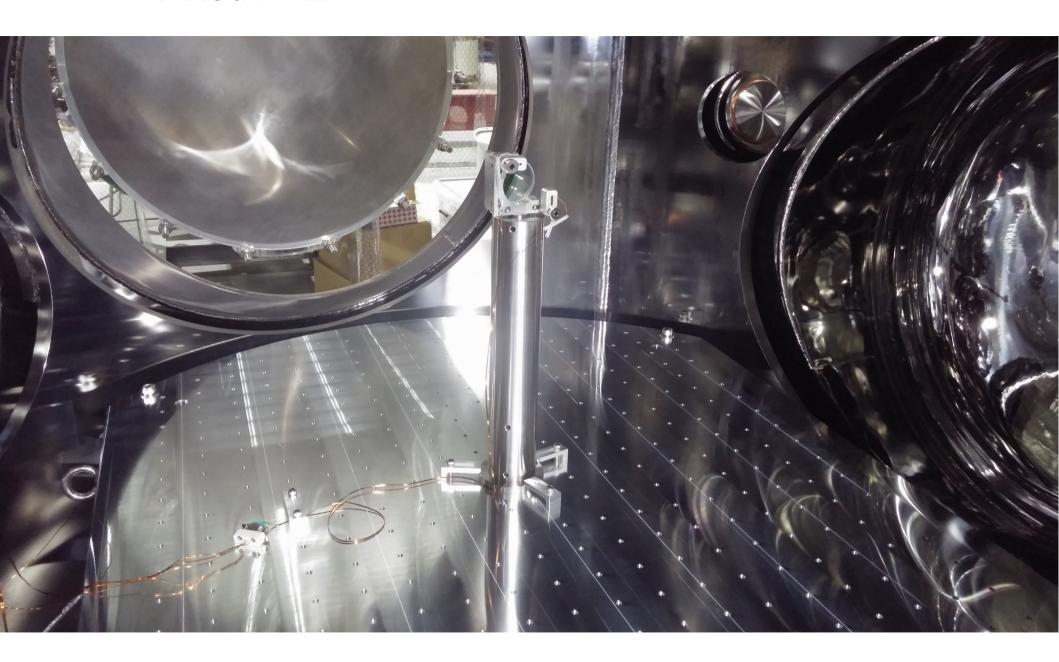
- Small size (2mm height)
- Rough surface finish
- No annealing (!)



Operation of iKAGRA by the end of 2016 March was a strict requirement

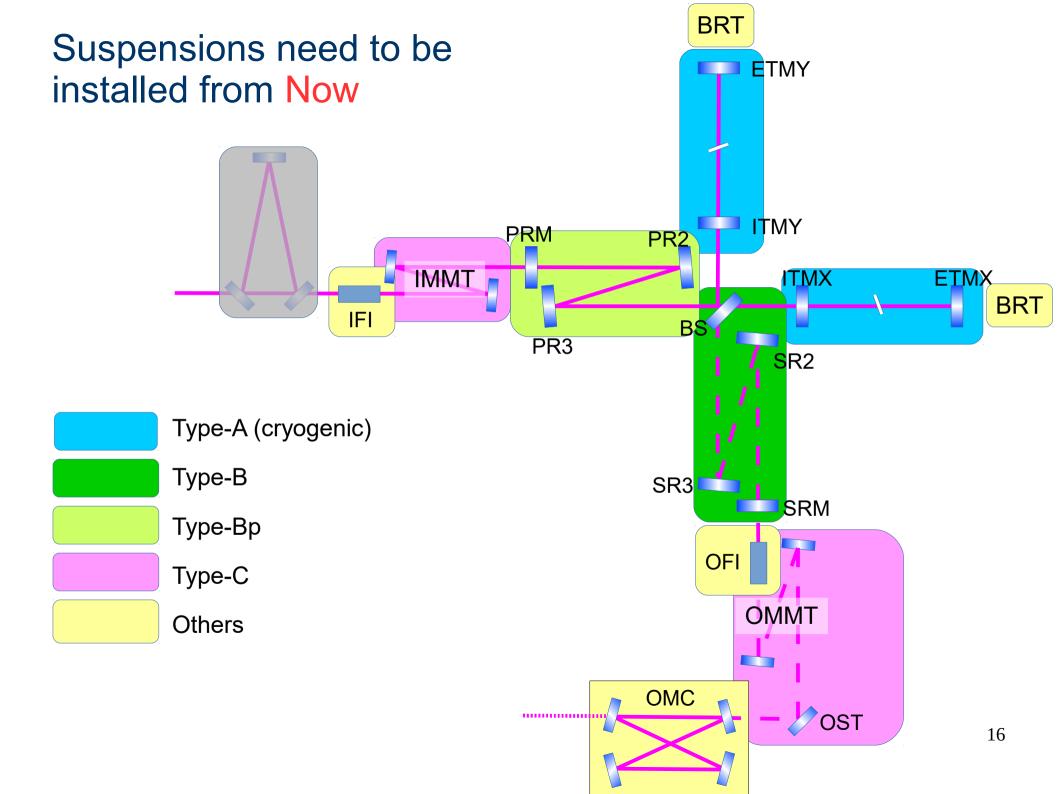
We needed to do something about it

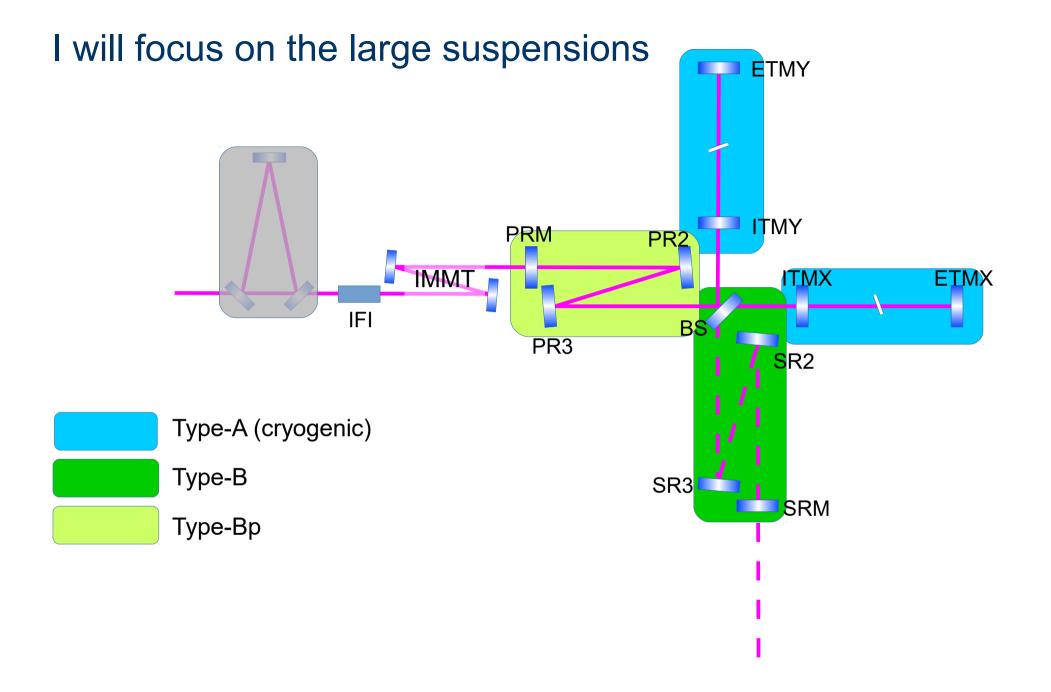
# Fixed PR2



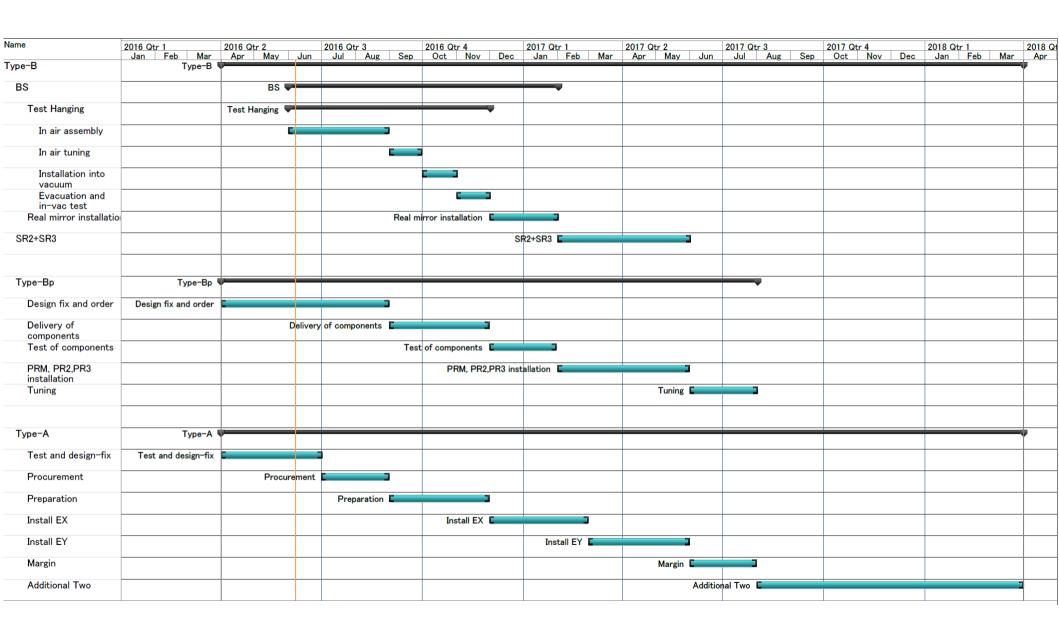


# Plan for bKAGRA





### **Overall Schedule**



### VIS team organization

#### Three teams

Type-A: 1 scientist, 2 engineers, 1 student

Type-B: 2 scientist, 1 engineer

Type-Bp: 1(+1) scientist, 1 student, (1 engineer)

### **Preparation status**

### Type-A

- Suspension components are mostly ready
- Installation procedure is being tested
- Some local sensors needs to be added
- Installation will start from Dec. 2016

#### Type-B

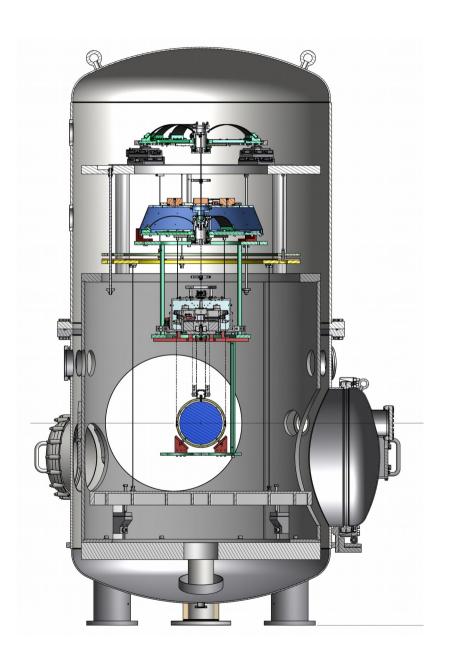
- Most of the components are ready except for two additional payloads
- Installation procedure is being finalized
- Start the test installation from July

### Type-Bp

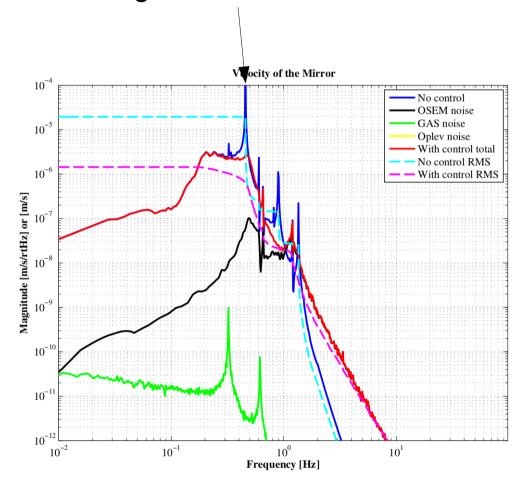
- Additional sensors/actuators need to be retrofitted to damp some resonances
- Except for the modifications above, most of the suspension components are ready
- Installation will start from Feb. 2017

# Technical Issues

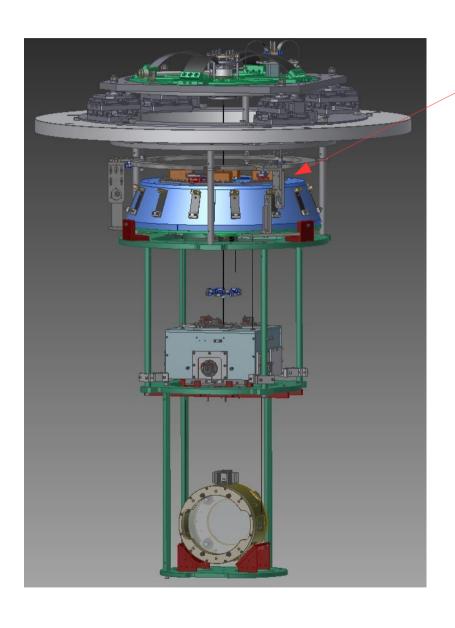
# Type-Bp damping issue



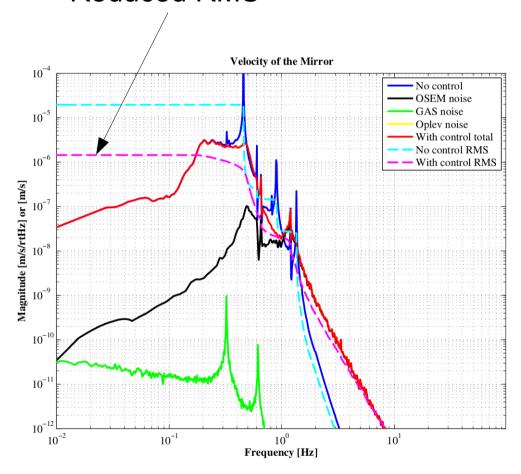
- No inverted pendulum
- A high Q mode survives



### Type-Bp damping issue

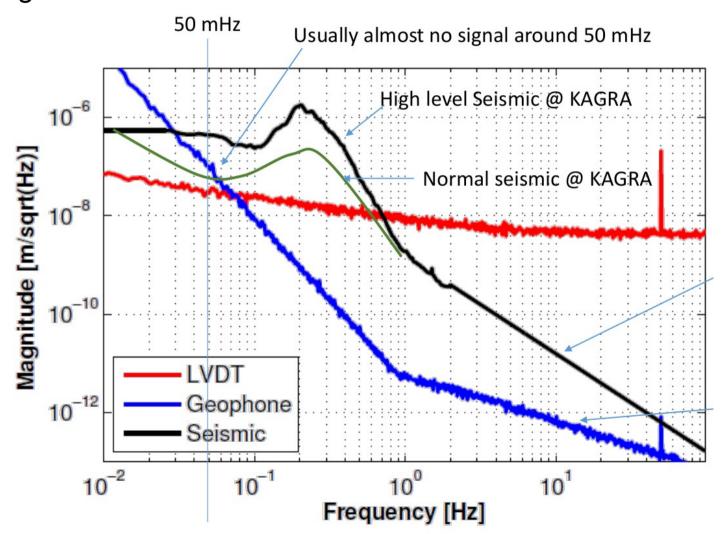


- Additional sensors/actuators
- Active damping on the bottom filter
- Reduced RMS



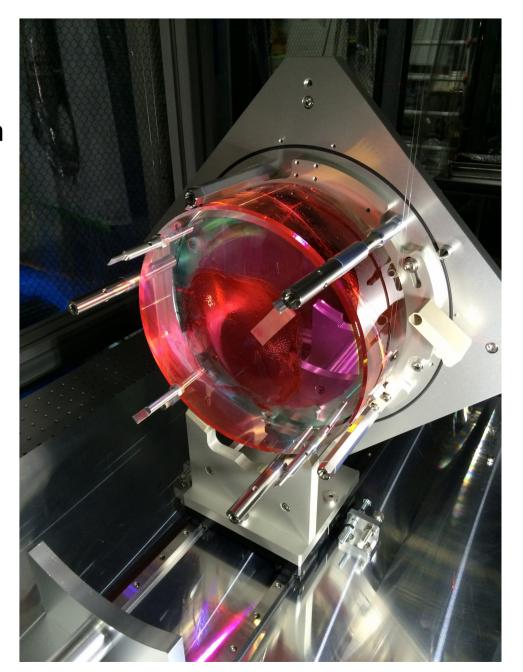
### Better inertial sensors for the pre-isolators? (Type-B and Type-A)

- Original plan: Use Geophones
  - The noise may not be good enough
- Alternative options: Accelerometers by NIKHEF
  - Being tested with BS

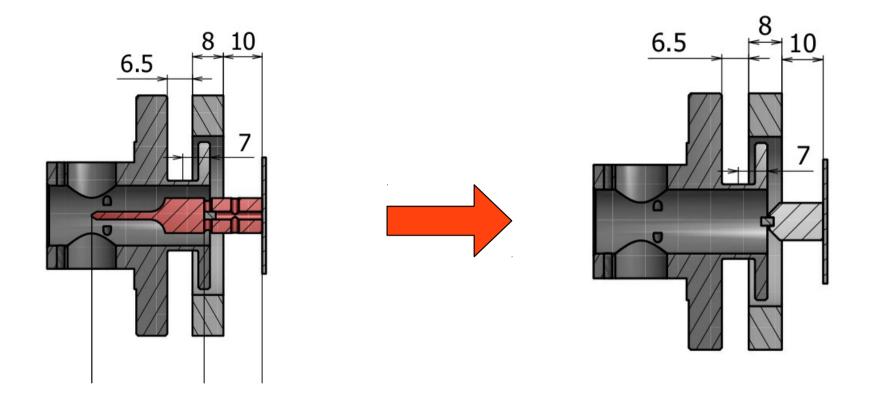


# OSEM flags are huge

- We broke them during the suspension assembly work
- Thermal noise concern
  - -> calculation says barely OK

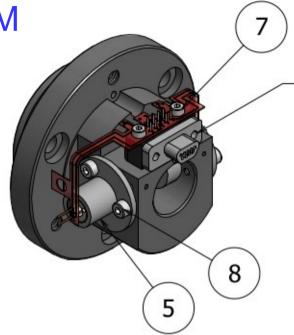


### Decided to remove the flags from the optics



- No sensing. Only actuation.
- Use an optical lever instead
  - Two QPDs at different Gouy phases to sense the longitudinal motion

Wider gap OSEMs for IM



Narrow



