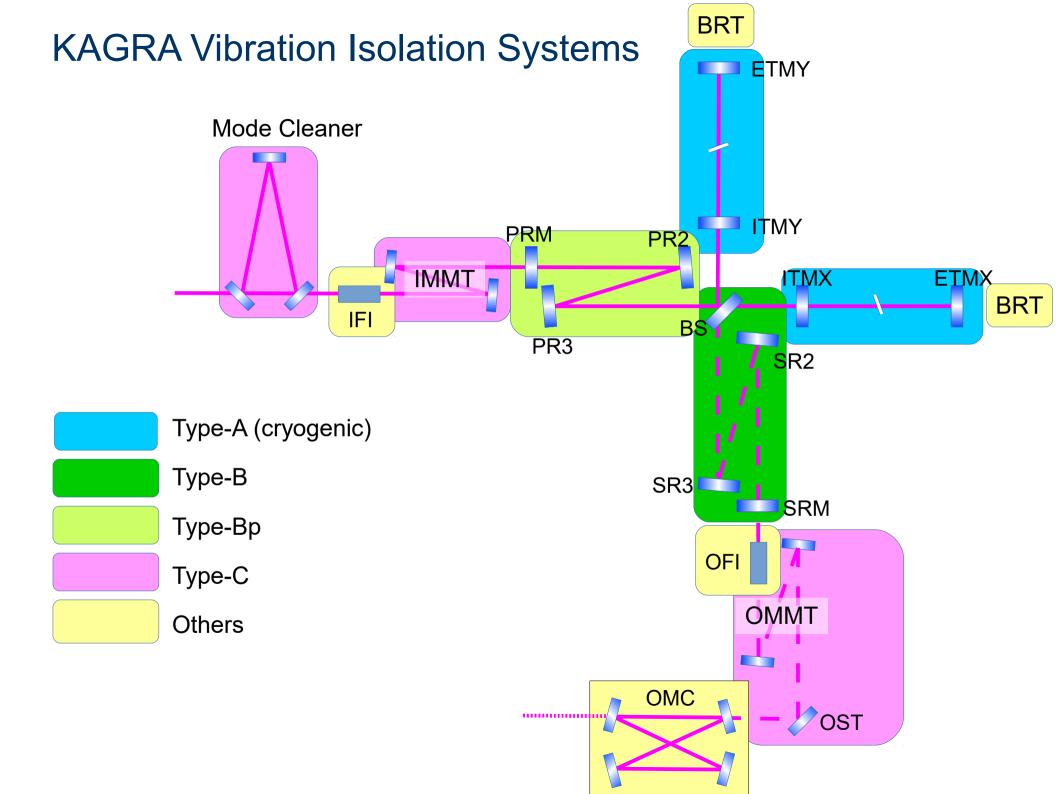
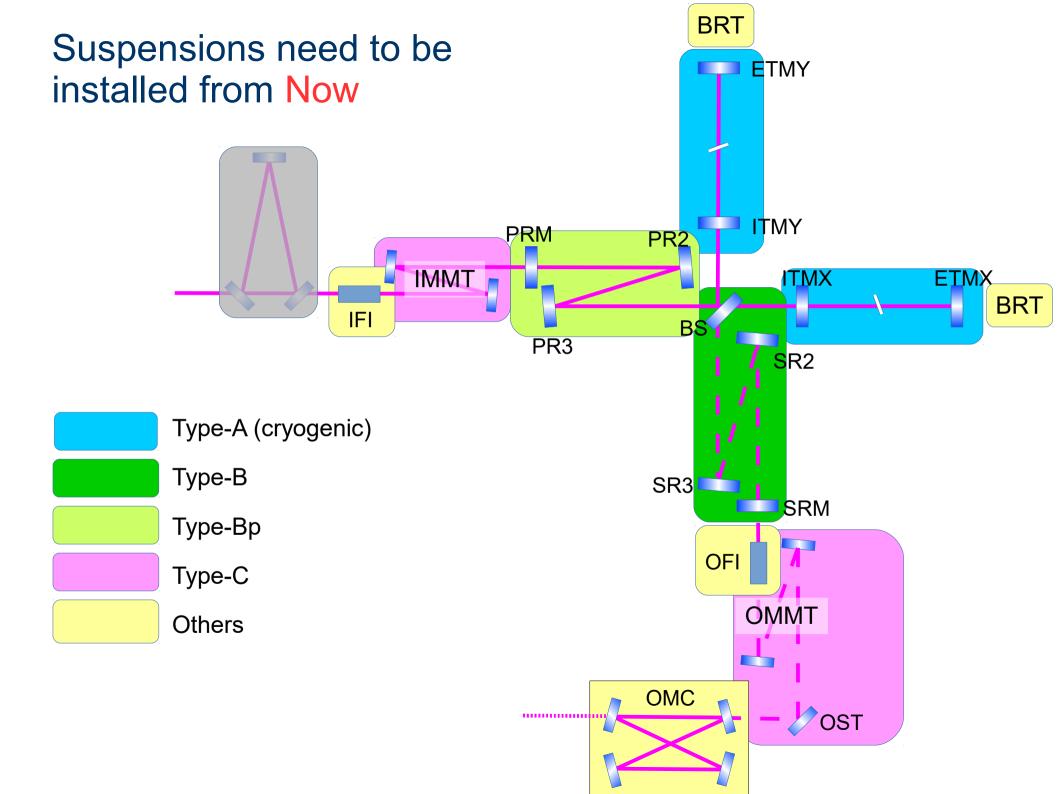
bKAGRA Vibration Isolation Systems

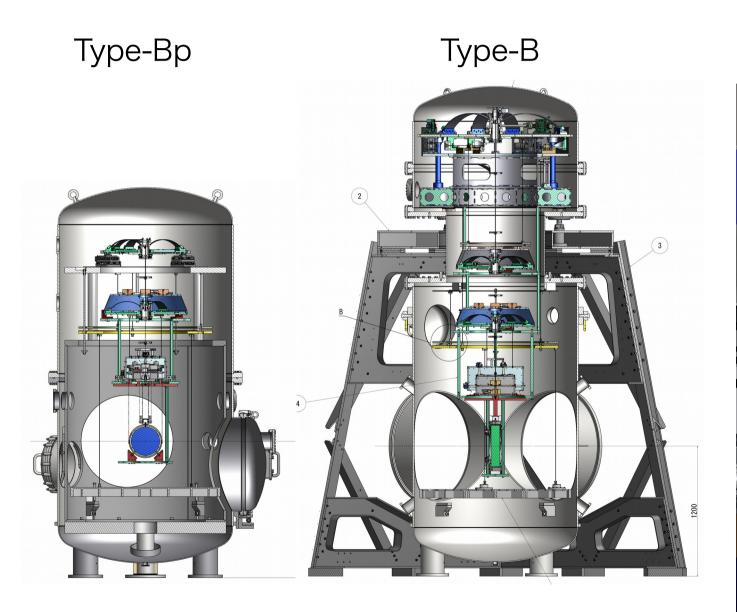
2016/6/21@PAB Y. Aso (NAOJ)

VIS Overview





Three types of large suspensions



Type-A



Other vibration isolation systems

- MC (TAMA suspensions, installed)
- IMMT (TAMA suspensions)
- Output optics
 - OFI (modified TAMA suspension ?)
 - OMMT (newly built TAMA like suspension)
 - OST (newly built TAMA like suspension)
 - OMC (custom made one)
- BRT
 - Custom made one

Who is responsible for what?

Large suspension systems + IMMT

(Type-A w/o cryo payload, Type-B, Type-Bp, Type-C)

→ VIS subsystem (NAOJ)

Cryogenic Payload

→ CRY (KEK)

Beam Reducing Telescope Suspensions

→ AOS (NAOJ)

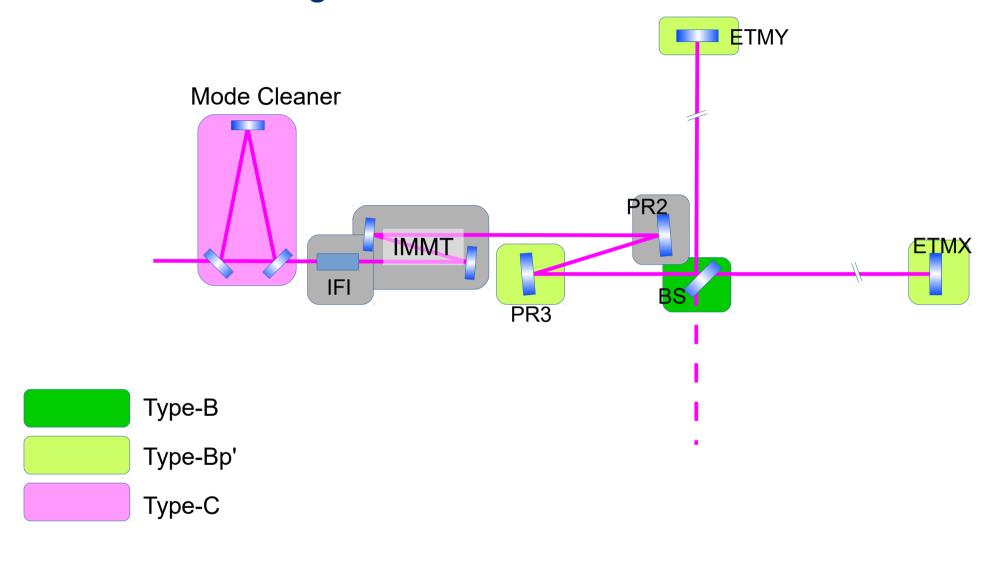
Output Optics Suspensions

(OFI, OMMT, OST, OMC + IFI?)

→ IOO ?

What happened in iKAGRA?

iKAGRA VIS: Original Plan

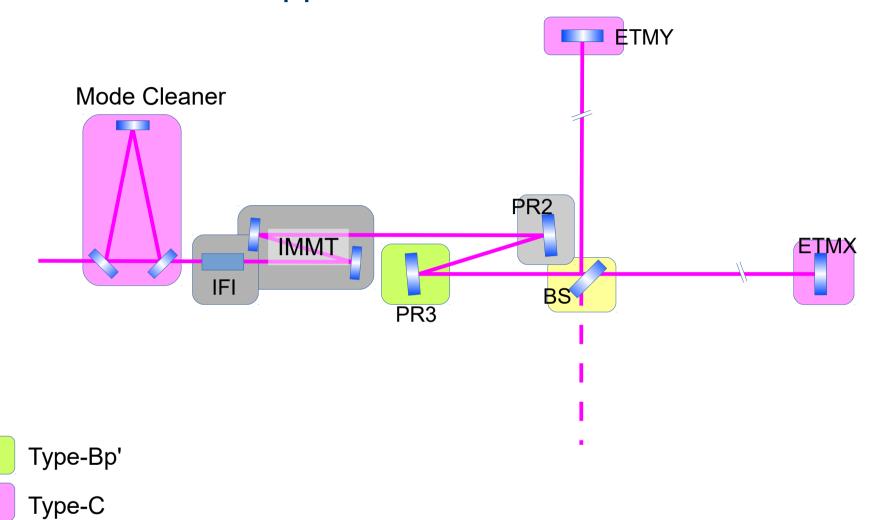


Fixed to the ground

iKAGRA VIS: What happened

CLIO Suspension

Fixed to the ground



VIS installation took much longer than expected

PR3 was the only large suspension installed

- Tunnel environment
- Insufficient preparation
 - Parts missing
 - Not-well-established installation procedure
 - Incorrect drawings
 - Tools missing
- Troubles
 - Cracks in the sapphire prisms
 - Broken OSEM flags
 - Wrong cables
 - Screw galling

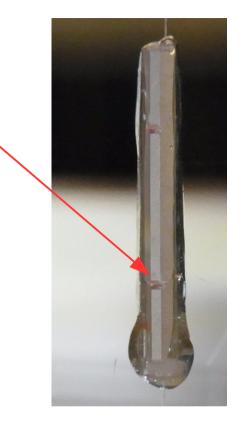
Original estimate of installation work duration 1 month for PR3

Actually happened

3 months for test installation, 1.5 months for the actual installation.

PR2 wire breaker developed cracks

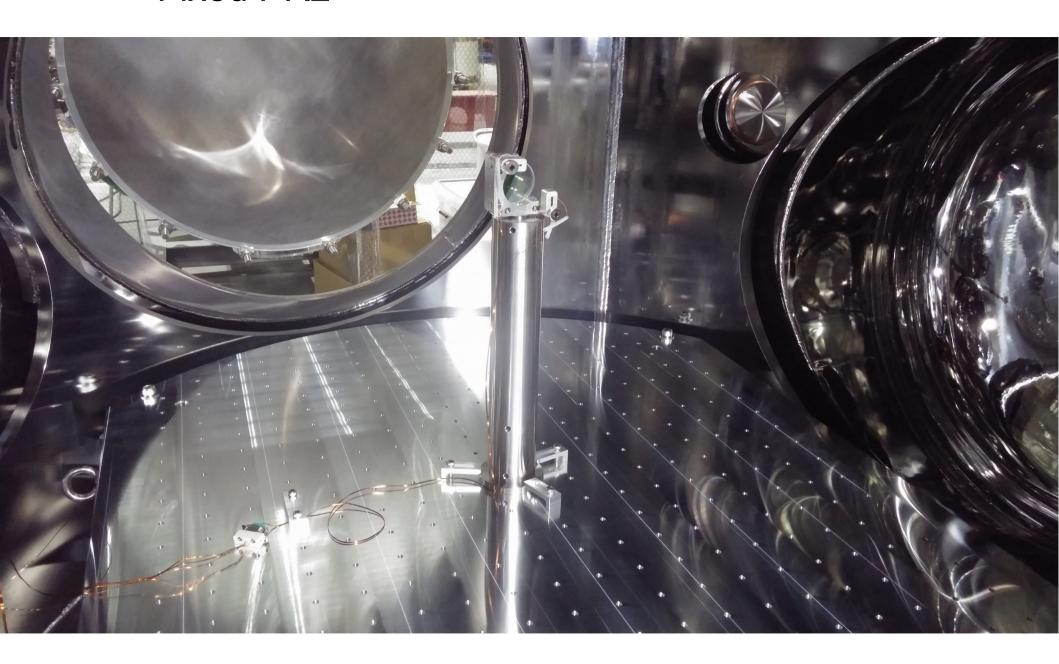
- Small size (2mm height)
- Rough surface finish
- No annealing (!)



Operation of iKAGRA by the end of 2016 March was a strict requirement

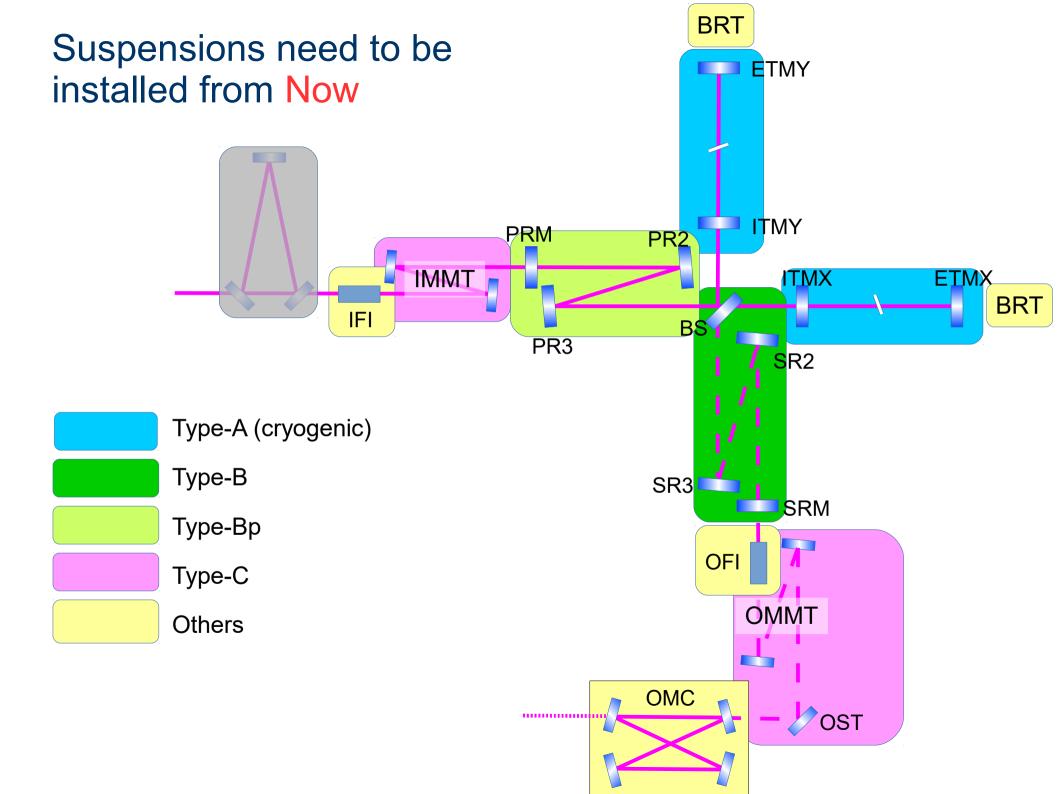
We needed to do something about it

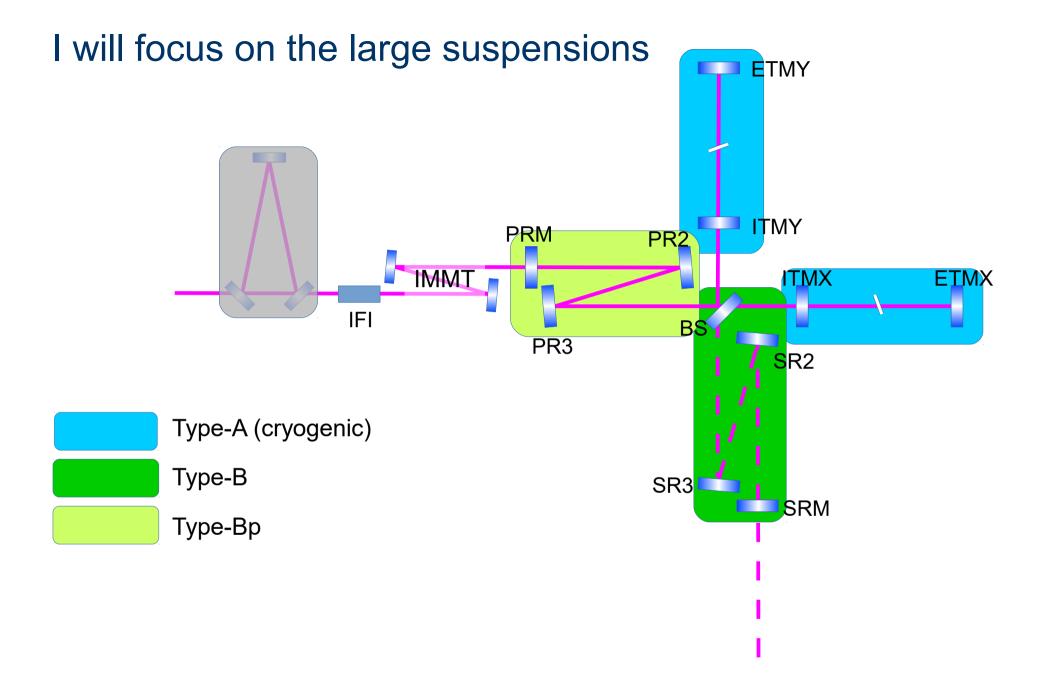
Fixed PR2



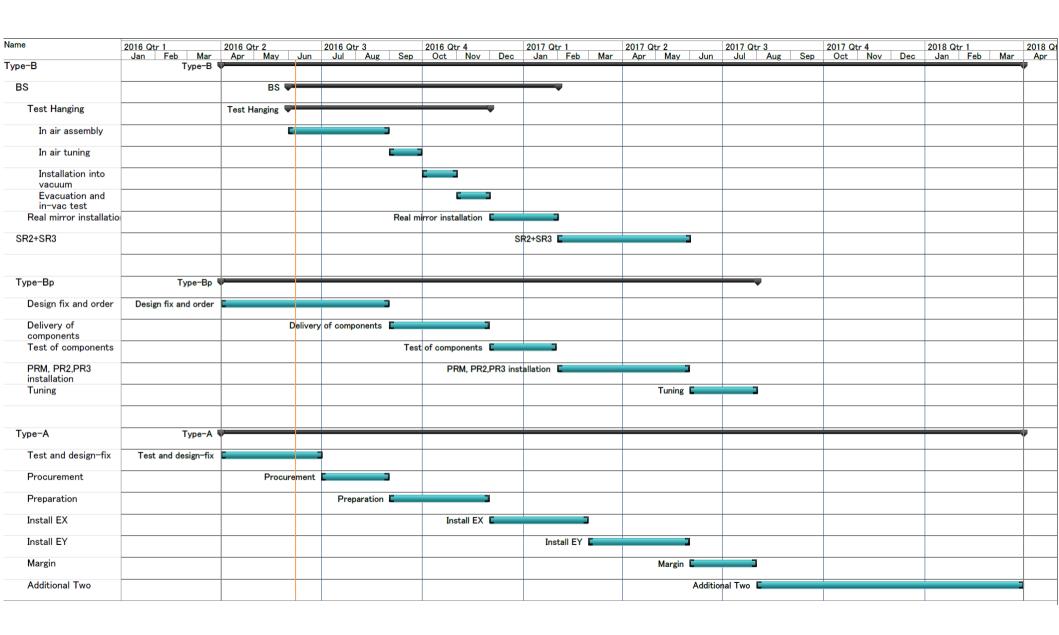


Plan for bKAGRA





Overall Schedule



VIS team organization

Three teams

Type-A: 1 scientist, 2 engineers, 1 student

Type-B: 2 scientist, 1 engineer

Type-Bp: 1(+1) scientist, 1 student, (1 engineer)

Preparation status

Type-A

- Suspension components are mostly ready
- Installation procedure is being tested
- Some local sensors needs to be added
- Installation will start from Dec. 2016

Type-B

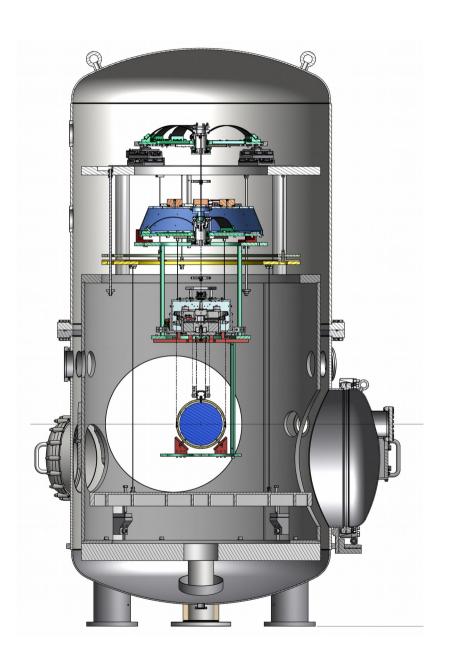
- Most of the components are ready except for two additional payloads
- Installation procedure is being finalized
- Start the test installation from July

Type-Bp

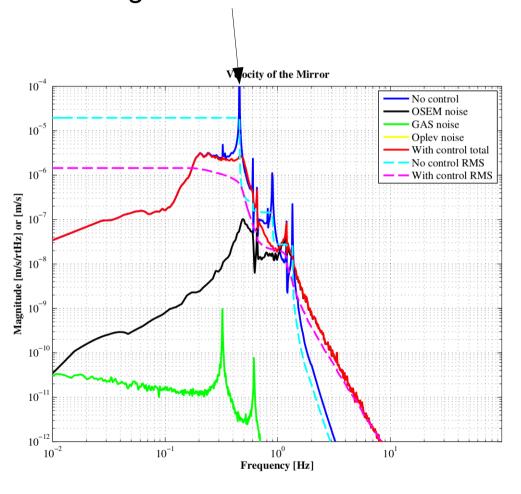
- Additional sensors/actuators need to be retrofitted to damp some resonances
- Except for the modifications above, most of the suspension components are ready
- Installation will start from Feb. 2017

Technical Issues

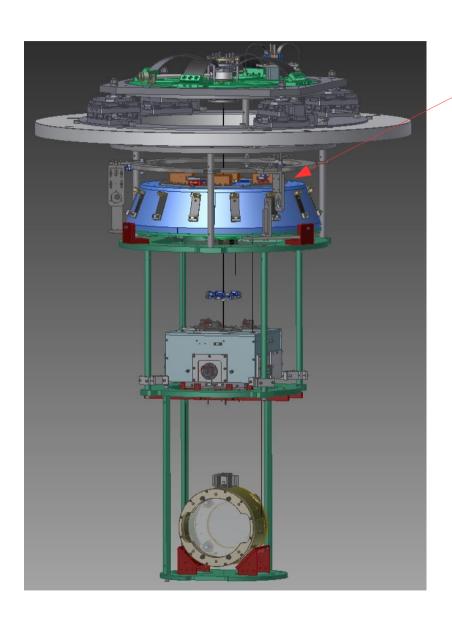
Type-Bp damping issue



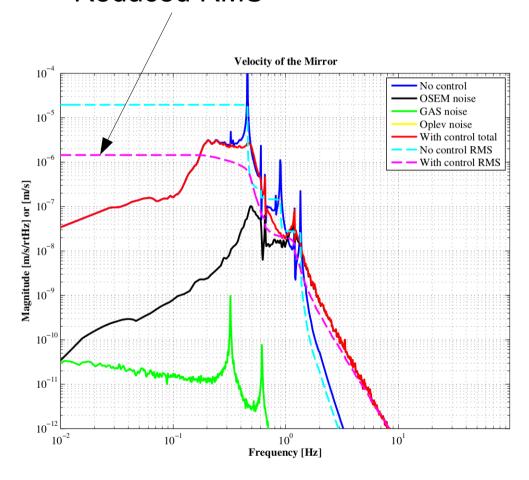
- No inverted pendulum
- A high Q mode survives



Type-Bp damping issue

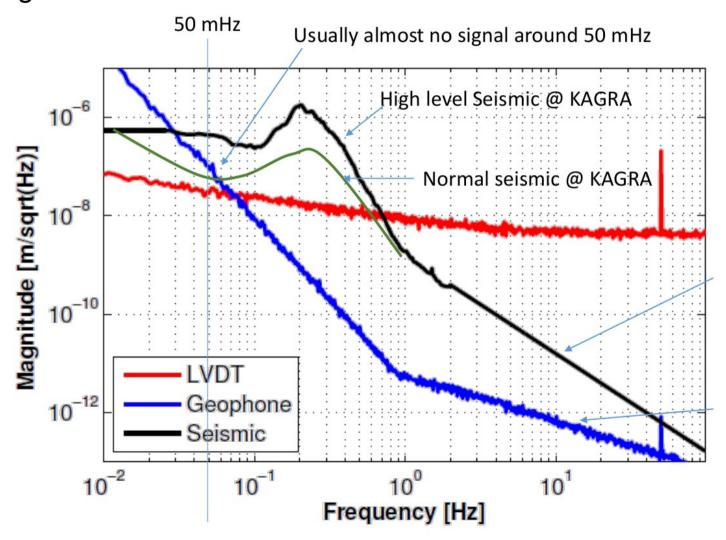


- Additional sensors/actuators
- Active damping on the bottom filter
- Reduced RMS



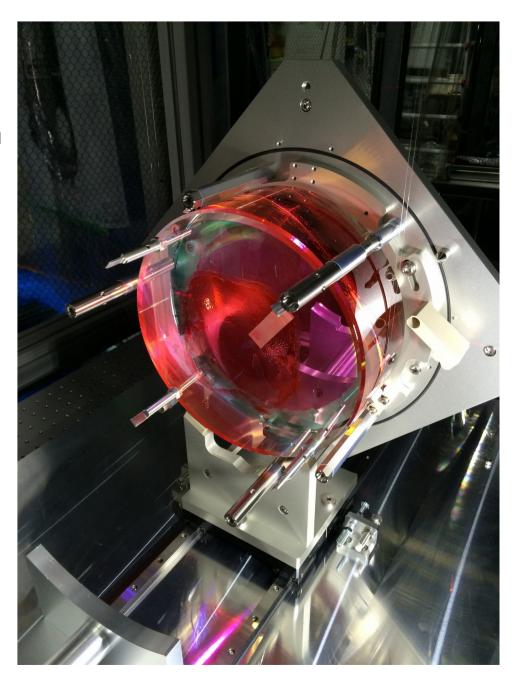
Better inertial sensors for the pre-isolators? (Type-B and Type-A)

- Original plan: Use Geophones
 - The noise may not be good enough
- Alternative options: Accelerometers by NIKHEF
 - Being tested with BS

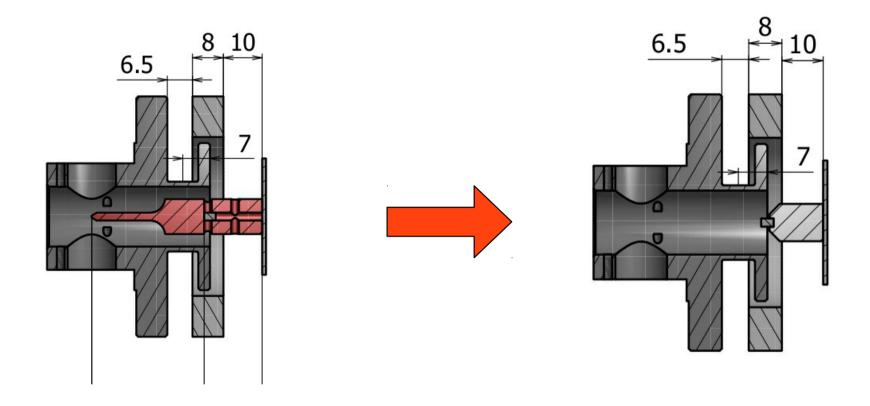


OSEM flags are huge

- We broke them during the suspension assembly work
- Thermal noise concern
 - -> calculation says barely OK

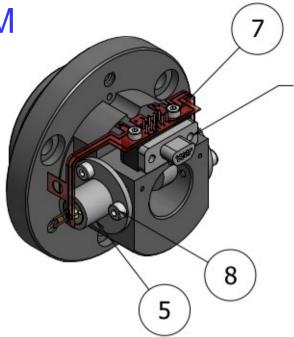


Decided to remove the flags from the optics



- No sensing. Only actuation.
- Use an optical lever instead
 - Two QPDs at different Gouy phases to sense the longitudinal motion

Wider gap OSEMs for IM



Narrow



