

Summary of iKAGRA Test Run Mar 25-31, 2016

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Quick Facts

- 3 km Michelson, mid-fringe lock
- input power to BS ~ 220 mW
- power at detection port (REFL) ~ 8 mW
- duration: Mar 25 9:00 JST - Mar 31 17:00 JST
(from 1142899217 to 1143446417 in GPS time)
- duty cycle (lock): 85.2 % (IMC was 94.4 %)
- total locked time: 129.5 hours
- longest lock: 3.6 hours (but typically ~ 30 minutes)
- strain sensitivity: $\sim 3e-15$ /rtHz @ 100 Hz
(~ 0.77 pc for 1.4Msun-1.4Msun NS-NS inspiral range)

Thanks to inputs from Y. Saito, T. Uchiyama, Y. Aso, O. Miyakawa, K. Kokeyama, K. Hayama, Y. Sasaki, M. Nakano, Y. Enomoto, T. Shimoda, etc

Suspensions and Mirrors

- fused silica, room temperature

MCI, MCo, MCE

Type-C (double pendulum with stacks)
 x config magnets
 95.95 mm dia, 29.5 mm thick
 RoC = 37.33(9) m ([klog #711](#))

PR3

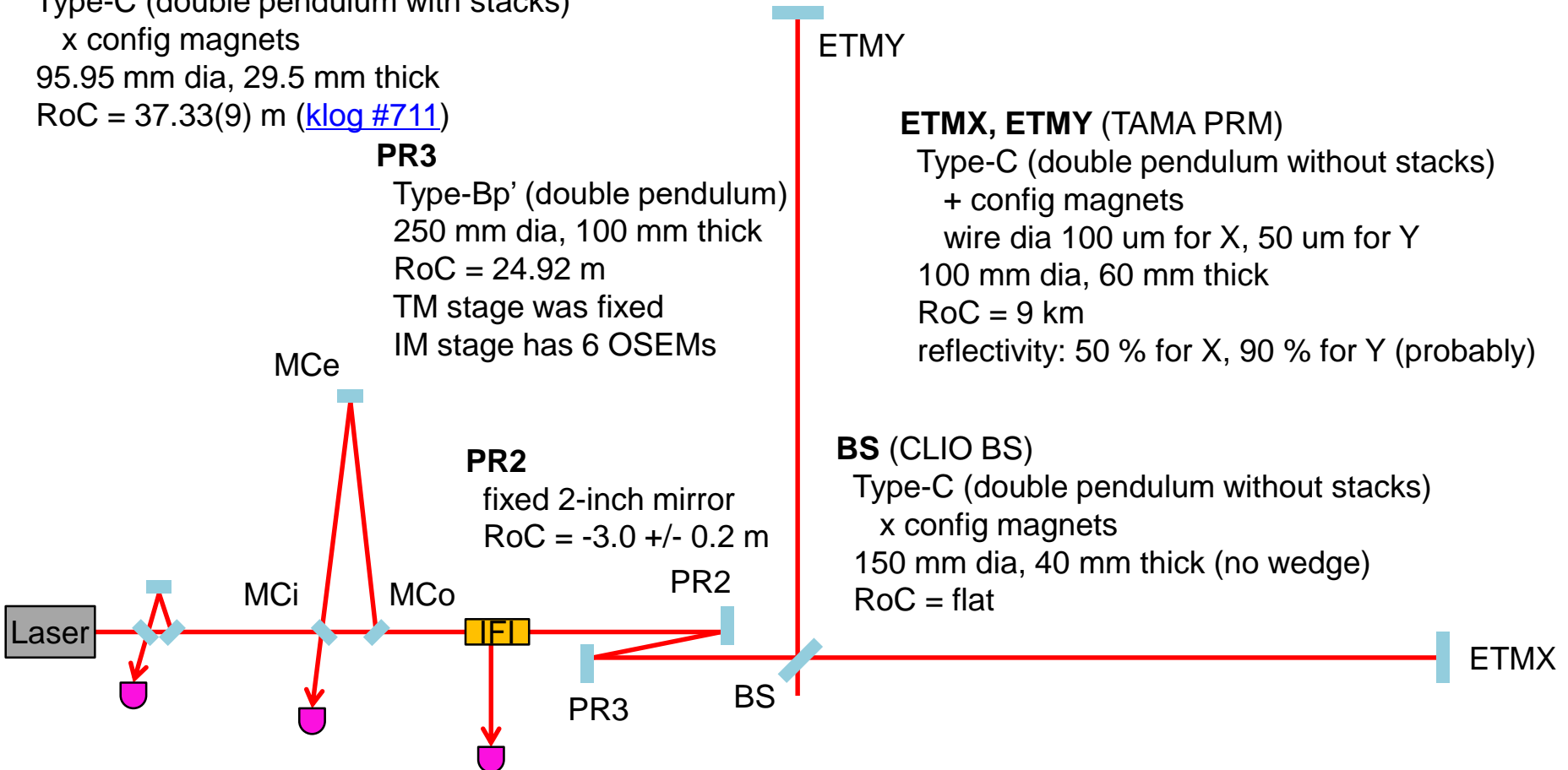
Type-Bp' (double pendulum)
 250 mm dia, 100 mm thick
 RoC = 24.92 m
 TM stage was fixed
 IM stage has 6 OSEMs

ETMX, ETMY (TAMA PRM)

Type-C (double pendulum without stacks)
 + config magnets
 wire dia 100 μ m for X, 50 μ m for Y
 100 mm dia, 60 mm thick
 RoC = 9 km
 reflectivity: 50 % for X, 90 % for Y (probably)

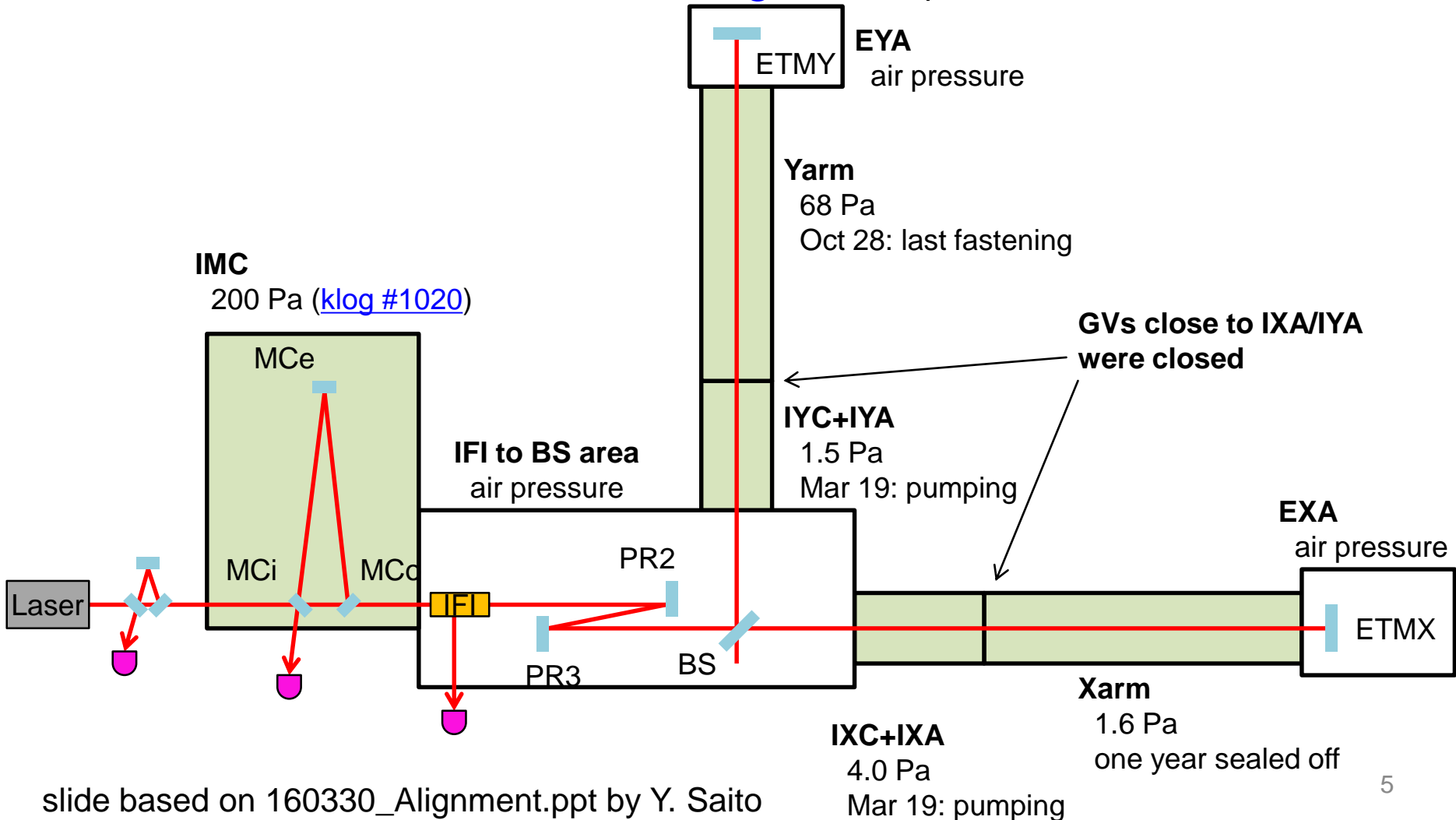
BS (CLIO BS)

Type-C (double pendulum without stacks)
 x config magnets
 150 mm dia, 40 mm thick (no wedge)
 RoC = flat



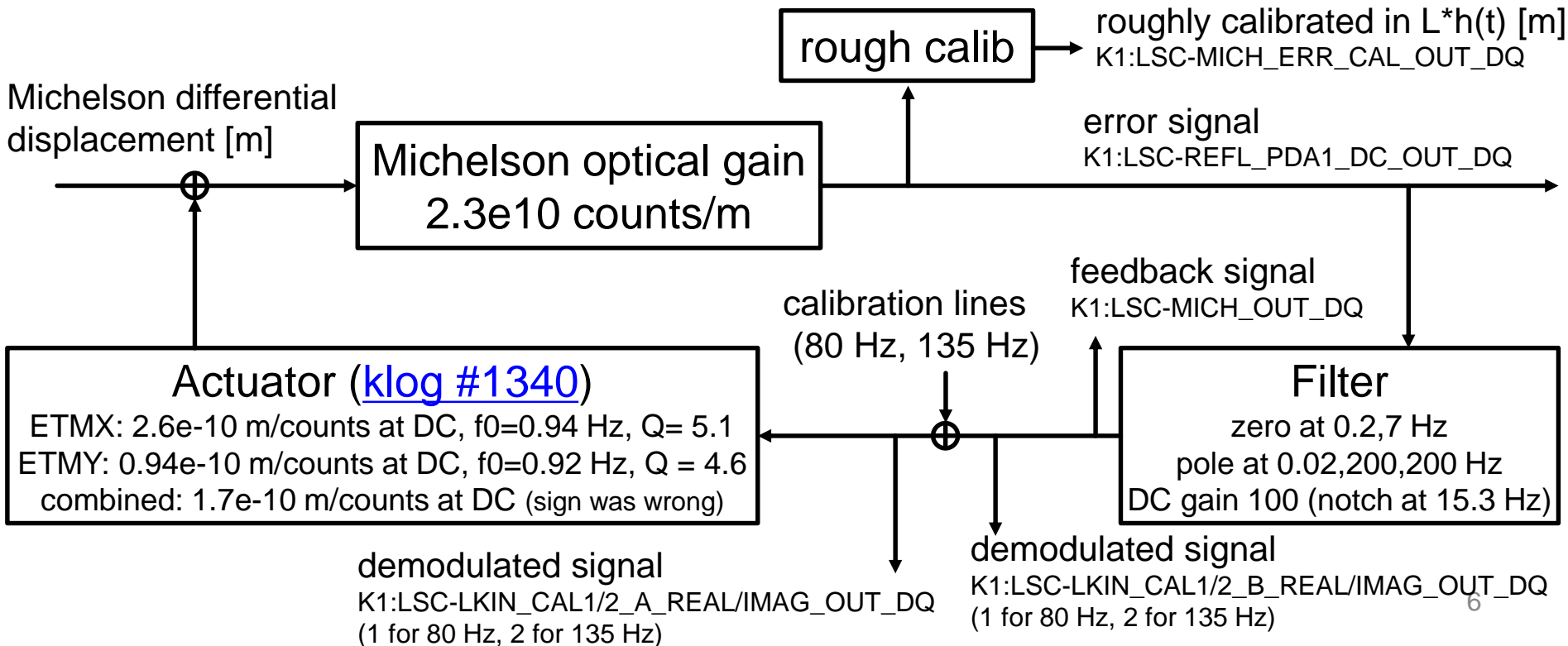
Vacuum

- central part and both ends were at air (PR2-BS was not connected, but covered; [klog #1078](#))



Calibration

- calibration of error signal (optical gain)
2.3e10 counts/m ([klog #1169](#))
- calibration of feedback signal (actuator efficiency)
1.8e-14 m/counts @ 80 Hz ([klog #1169](#))
- calibration lines at 80 Hz and 135 Hz to monitor loop gain

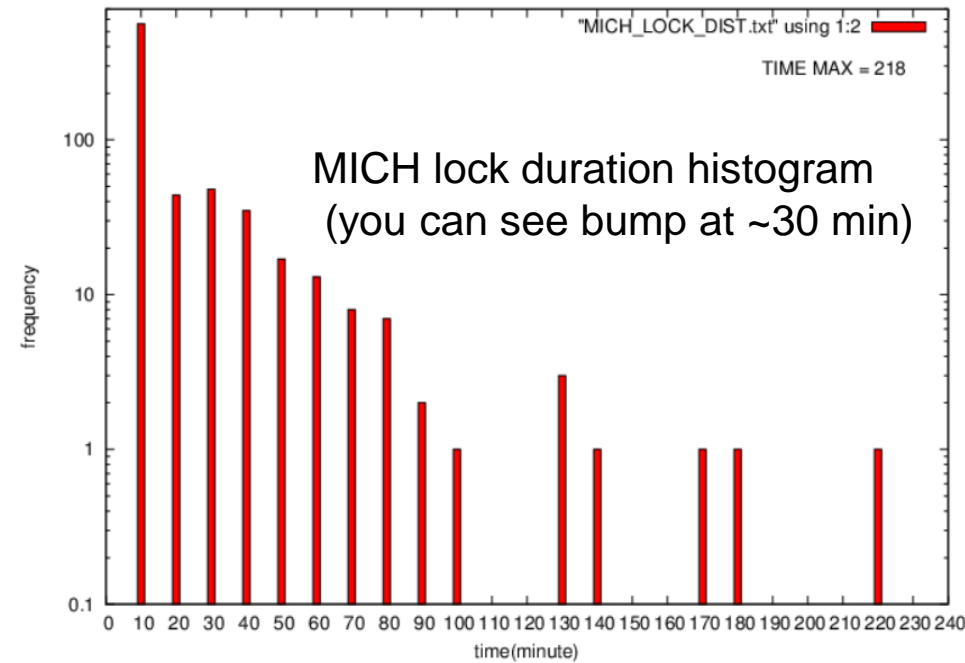
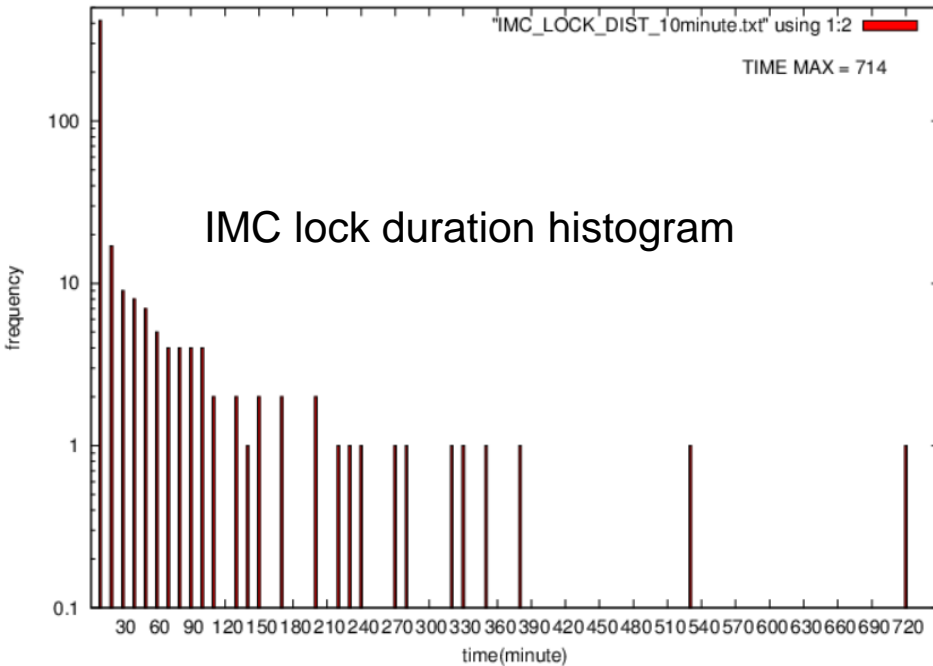
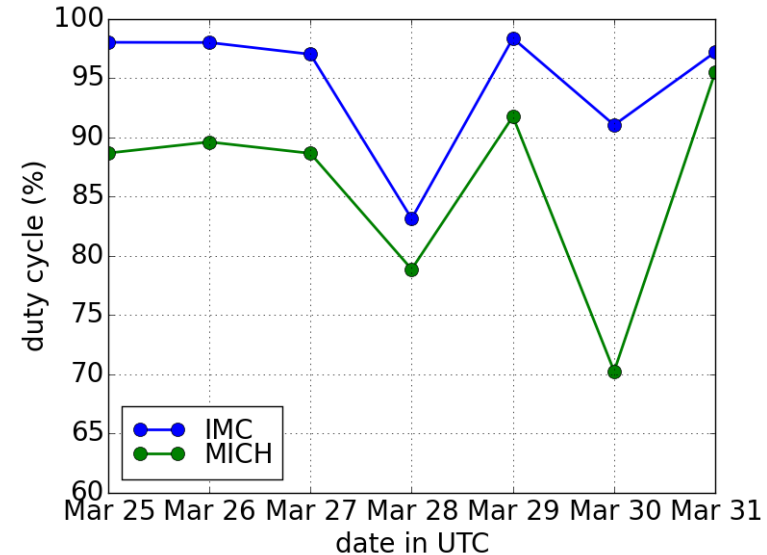


Duty Cycle and Lock Duration

- duty cycle: 85.2 %
(94.4 % for IMC)

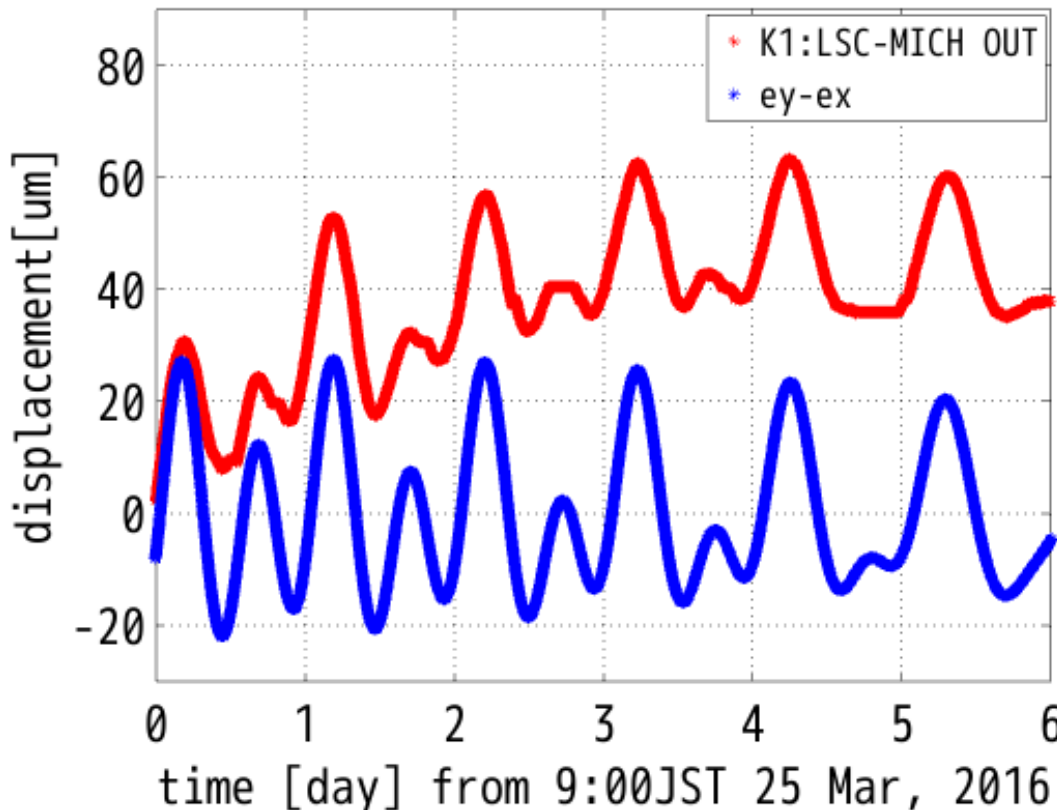
data processing and plot by Y. Sasaki

- longest lock: 3.6 hours
(12 hours for IMC)



Tidal Drift

- X arm length and Y arm length drifts by ~ 60 μm
- this caused lock loss every ~ 30 min because of the saturation of the feedback signal
→ needs more actuation range

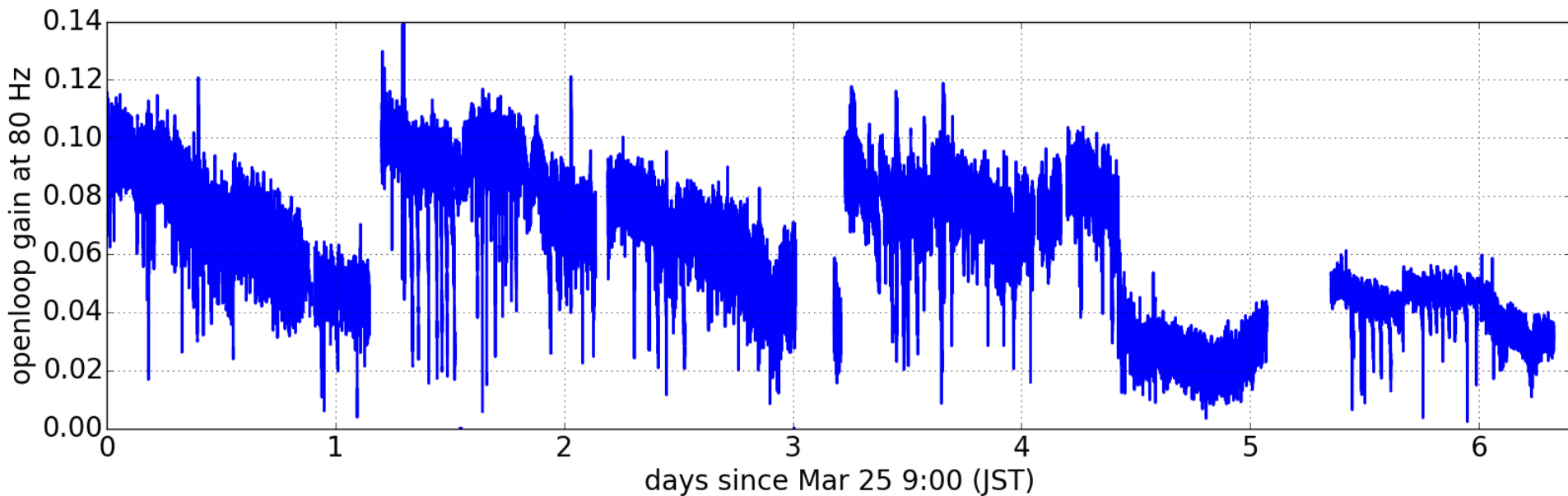


measured with 3-km Michelson

prediction calculated by A. Araya
[JGW-E1605098](#)
used GOTIC2 (tidal effect from
the Moon and the Sun)

Openloop Gain Drift

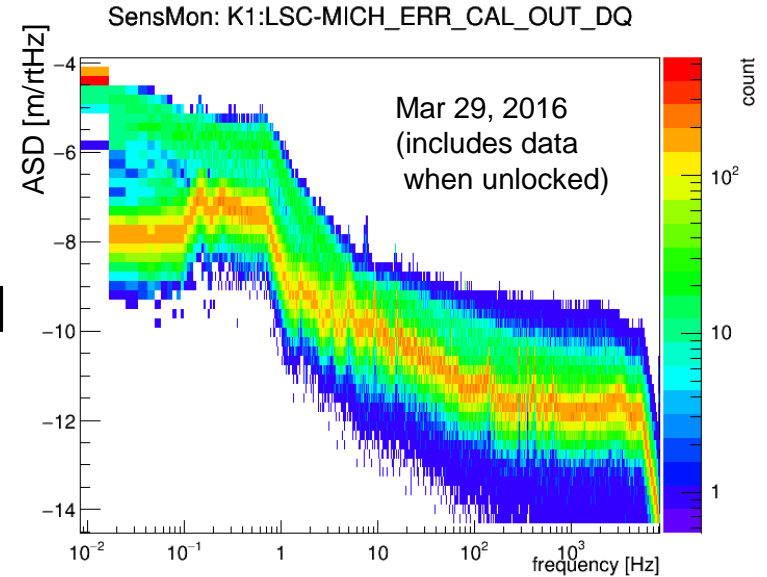
- MICH openloop gain degraded by almost 80 % (likely by alignment drift)
→ needs UGF servo (and online calibration)



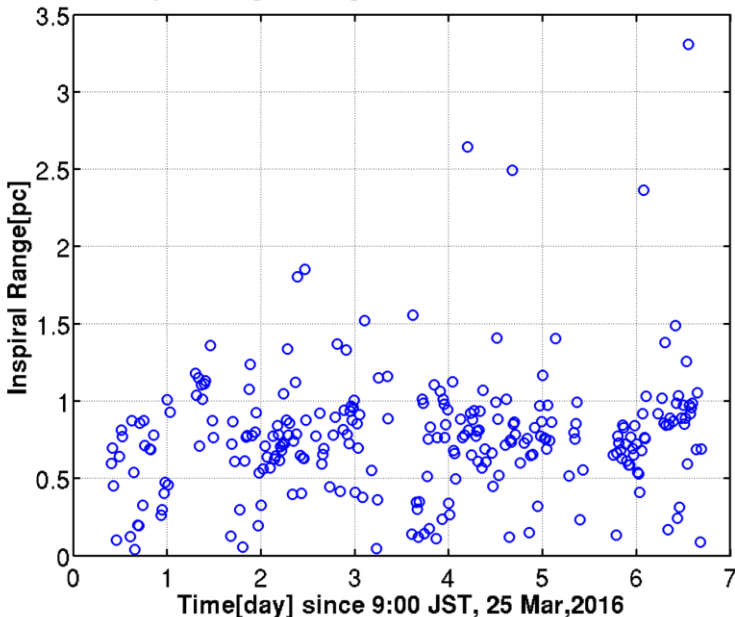
calculation done using K1:LSC-LKIN_CAL1_A/B_REAL/IMAG_OUT_DQ
by Y. Sasaki & Y. Michimura

Inspiral Range

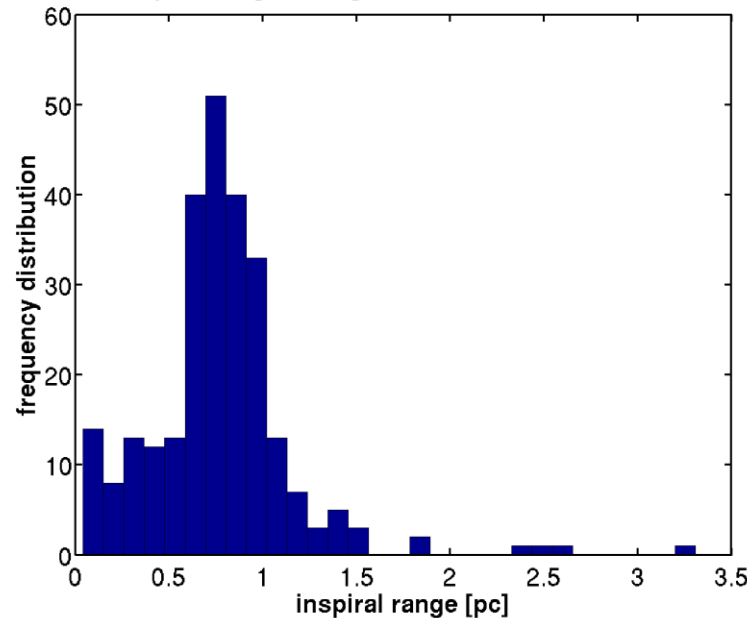
- average: 0.77 pc
standard deviation: 0.39 pc
for 1.4Msun-1.4Msun NS-NS
- rough strain sensitivity fluctuated
by roughly 1 order of magnitude



inspiral range during iKAGRA run in March, 2016



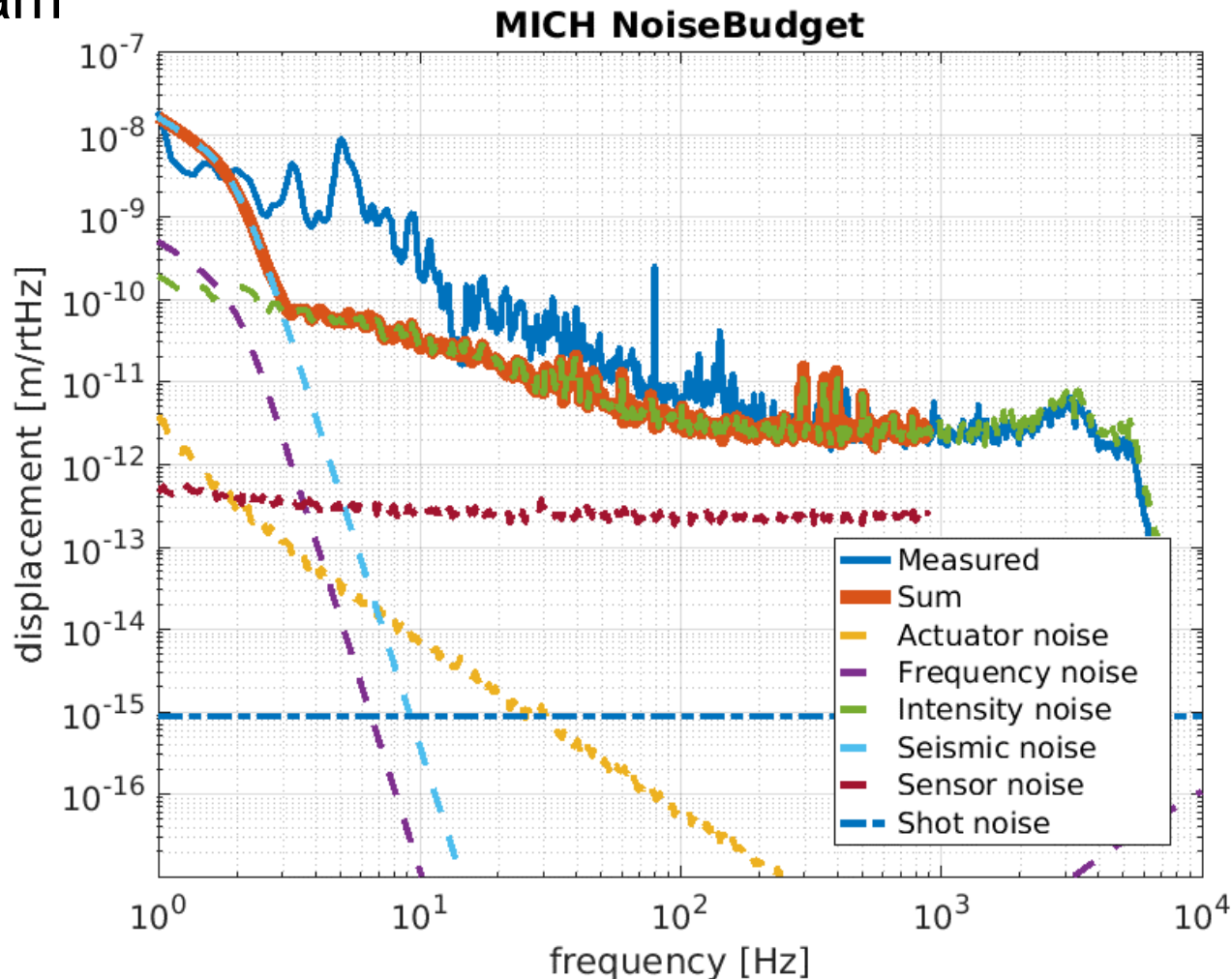
inspiral range during iKAGRA run in March, 2016



plot by K. Hayama

Noise Budget

- likely to be limited by intensity noise of the IMC transmitted beam



Issues in March Test Run

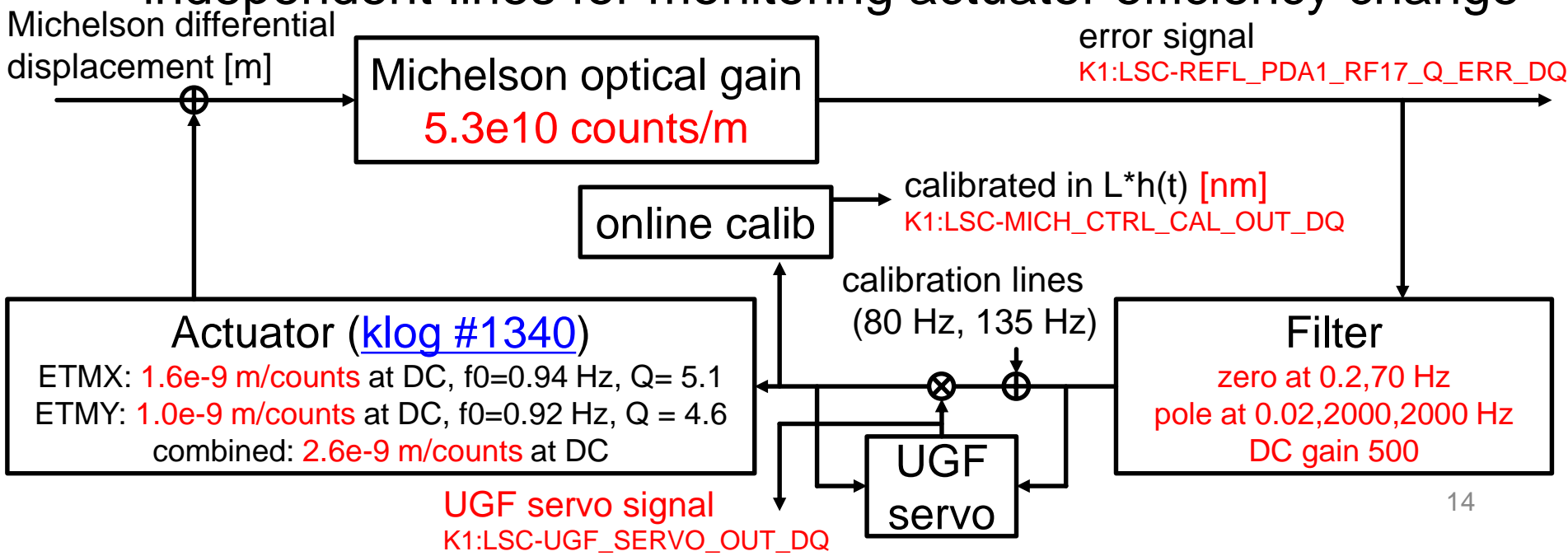
- Michelson lock was lost every ~30 minutes
- Alignment was adjusted manually ~ once per day
- Calibration was done offline
- PMC was re-locked manually
- GVs close to IXA/IYA was closed
- PR2-BS duct was not connected
- Some unsafe issues left unaddressed

What's New in April Test Run

- Michelson lock was lost every ~30 minutes
 - improved to > ~5 hours (limited by IMC; tidal won't be a problem this time [klog #1446](#))
 - new actuation efficiency (ETM differential): $2.6e-9$ m/C at DC([klog #1340](#)), higher UGF ([klog #1344](#)), RF lock instead of DC lock ([klog #1388](#)), x10 sensitivity ([klog #1389](#)), folded oplev for ETMs to reduce L2A ([klog #1355](#))
 - more stable IMC (less feedback to mirrors [klog #1386](#), oplev DC servo turned off [klog #1449](#))
- Alignment was adjusted manually ~ once per day
 - dither alignment installed for IMC (working perfectly; [klog #1484](#), [#1492](#))
- Calibration was done offline
 - UGF servo ([klog #1425](#)) and online calibration ([klog #1456](#))
- PMC ~~was re-locked manually~~ remote control restored ([klog #1351](#))
- GVs close to IXA/IYA was ~~closed~~ opened ([klog #1338](#))
- PR2-BS duct was ~~not connected~~ connected
- Some unsafe issues ~~left unaddressed~~ partially addressed

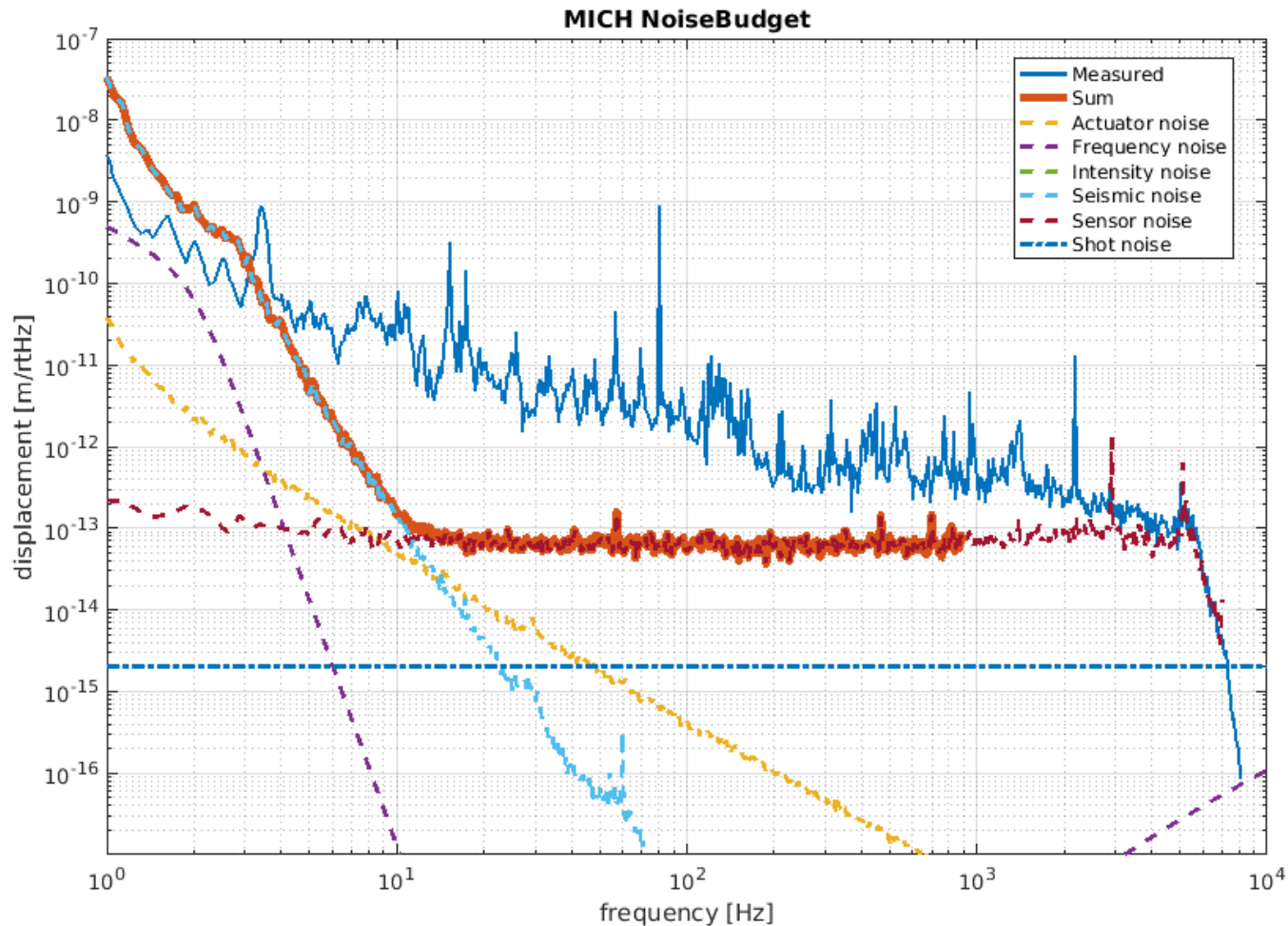
Calibration for April Test Run

- calibration of error signal (optical gain)
 $5.3e10$ counts/m ([klog #1455](#))
- calibration of feedback signal (actuator efficiency)
 $2.6(1)e-9$ m/counts @ DC ([klog #1340](#))
- calibration lines at 80 Hz for UGF servo (UGF controlled at 100 Hz) and at 135 Hz for loop gain monitor, other independent lines for monitoring actuator efficiency change



Updated Noise Budget

- not limited by intensity noise of the IMC transmitted beam
- could be BS angular noise coupling?



What To Do After April Test Run

- evacuate central part and both ends
 - to open all GVs and see optical axis change
 - to investigate alignment change during evacuation
- PR3 height check
- oplev stability, noise measurements with fixed mirror
- investigate scattering noise from vibration of ducts
- investigate why measured ETMX/Y actuator efficiency don't match calculation from coil efficiency
- what else?