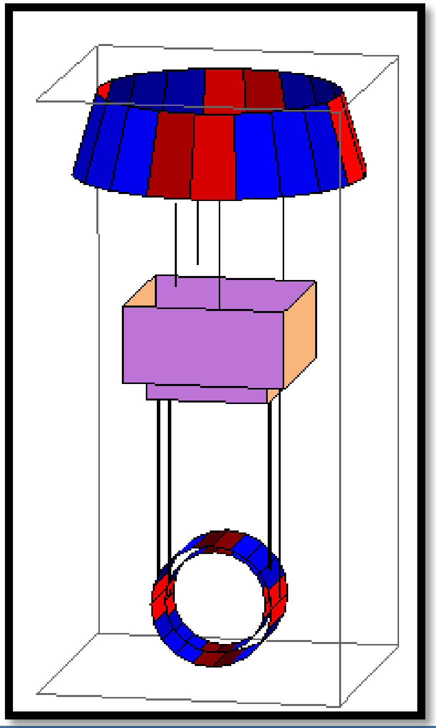
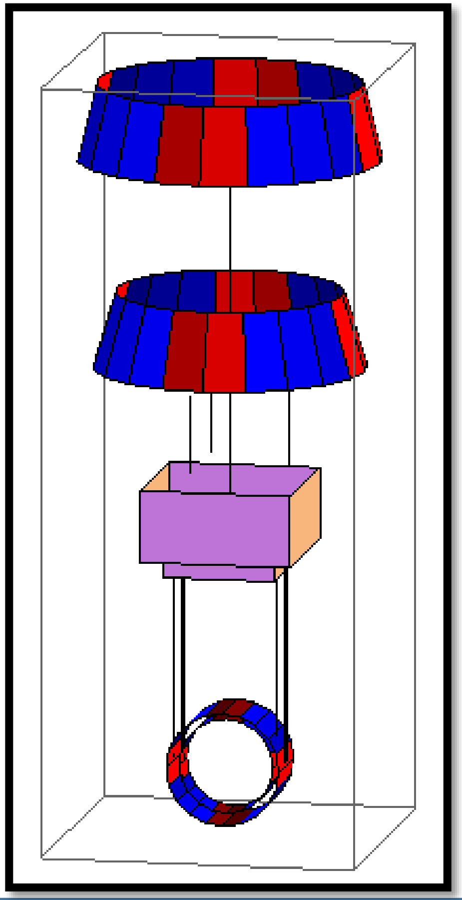
TypeBp SAS Study

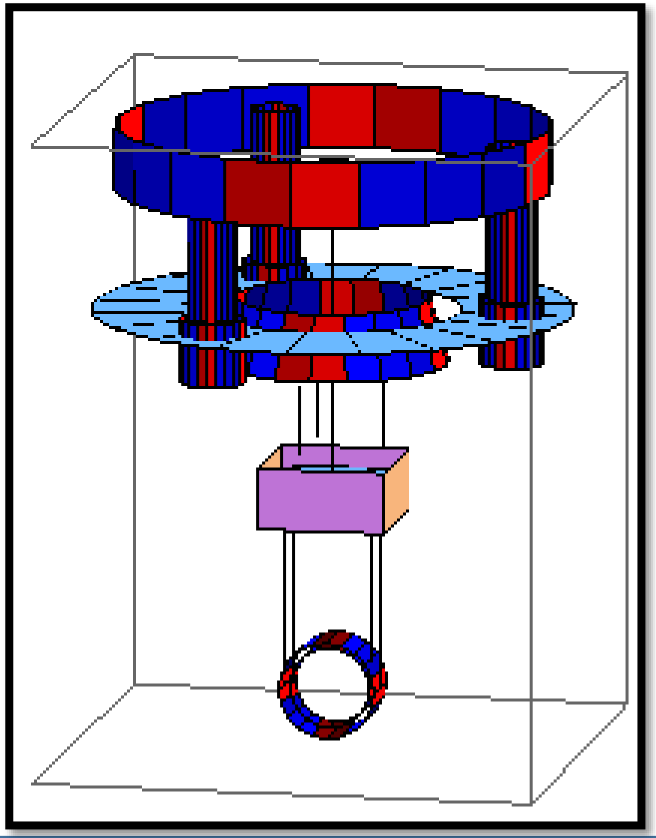
- ❐ Frequency response investigation of typeBpp
- ❐ One modification idea for bKAGRA PR SAS

Yoshinori Fujii

U. of Tokyo / NAOJ







Contents

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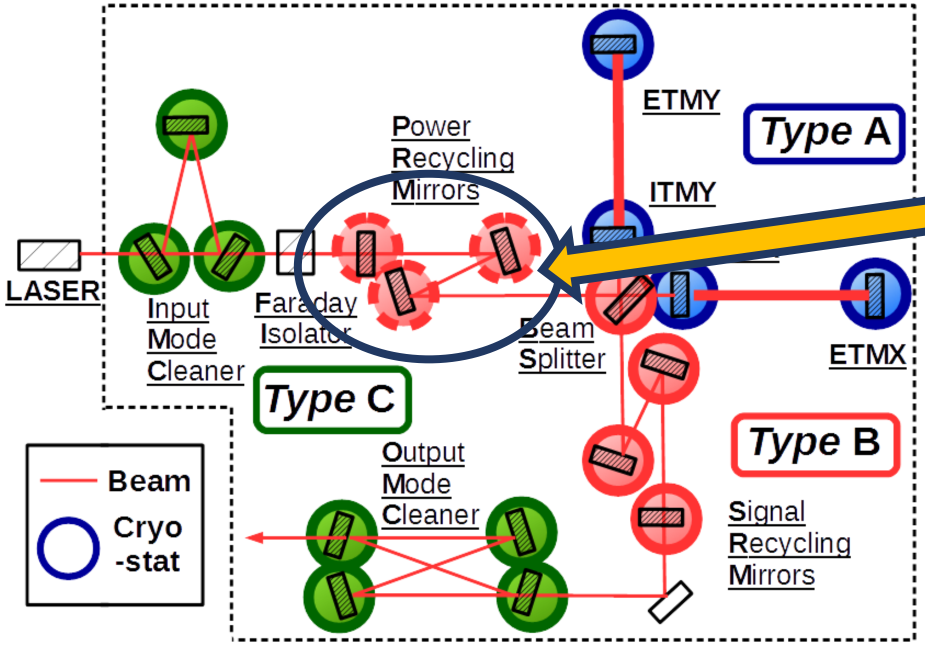
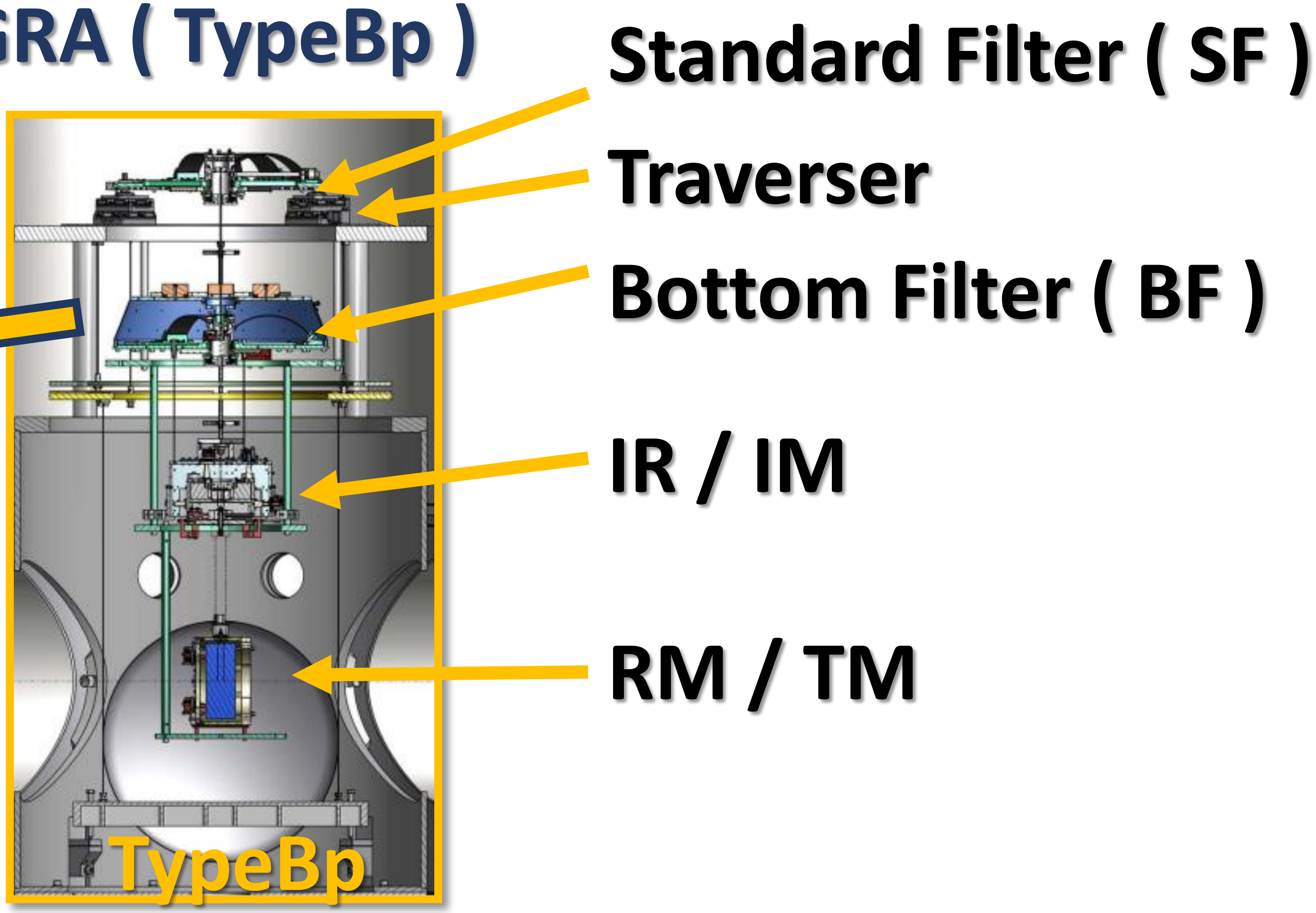
- Investigation of TypeBpp Frequeny response
  - Transfer functions / Spectrums
- One modification idea for bKAGRA
  - Requirement
  - TypeBp with IP

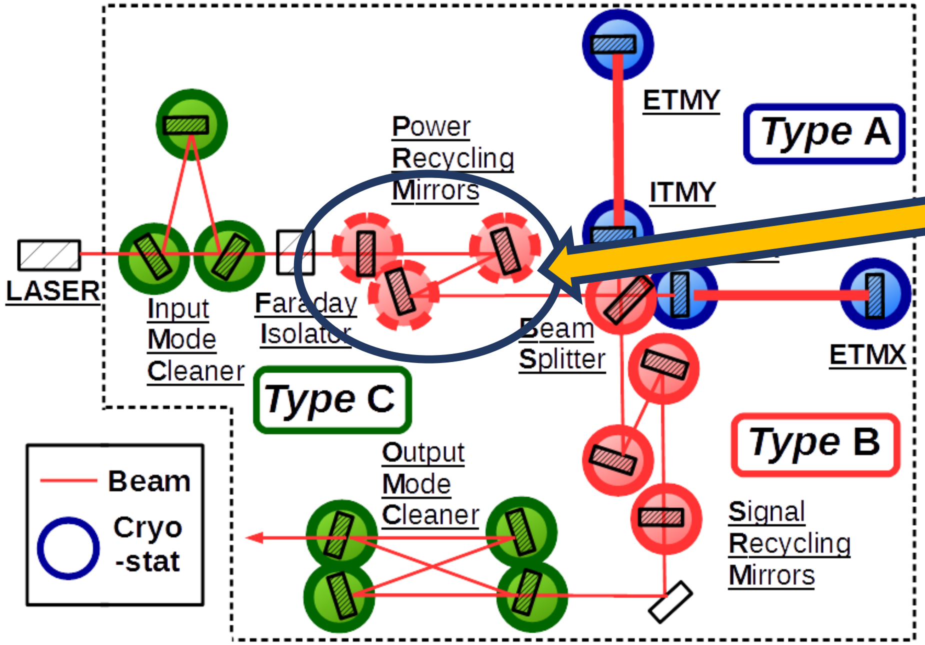
❖ Intro : PR SAS in bKAGRA (TypeBp)

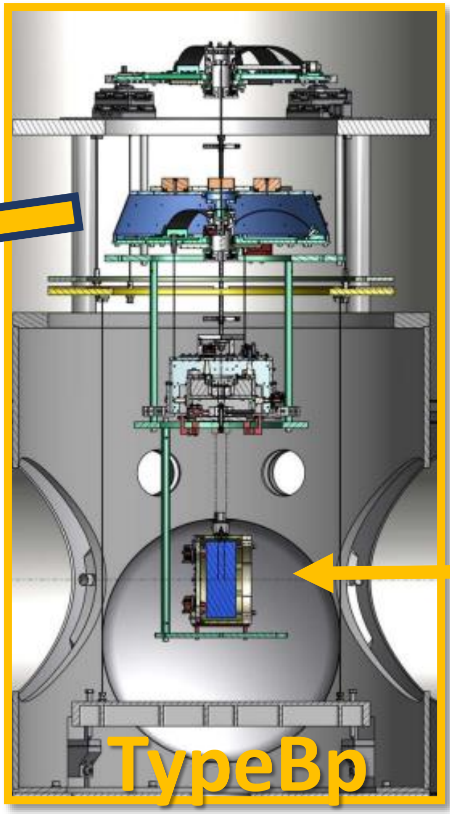




Current bKAGRA PR SAS = TypeBp

❖ Intro : PR SAS in bKAGRA (TypeBp)





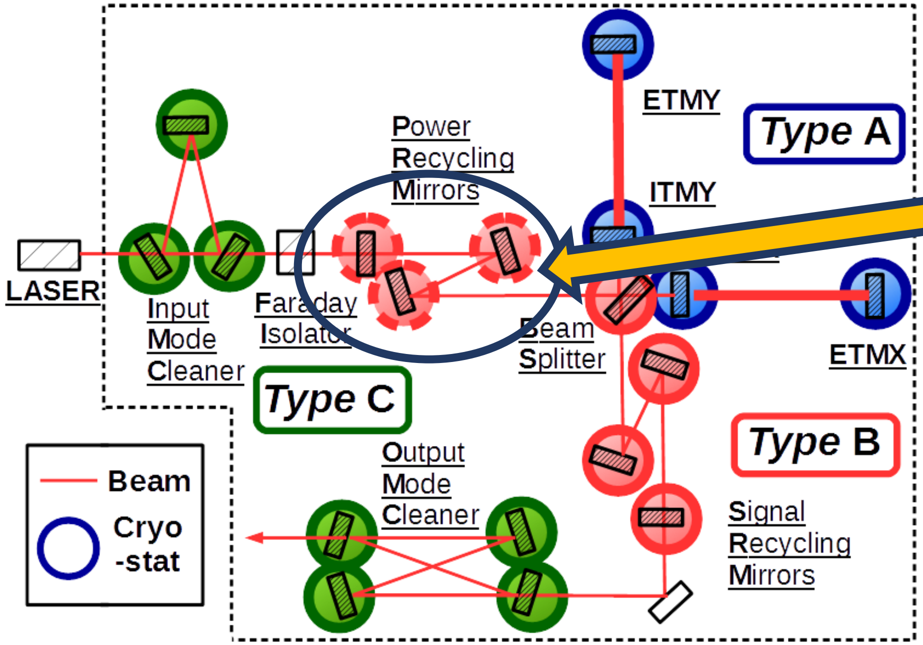
RM / TM

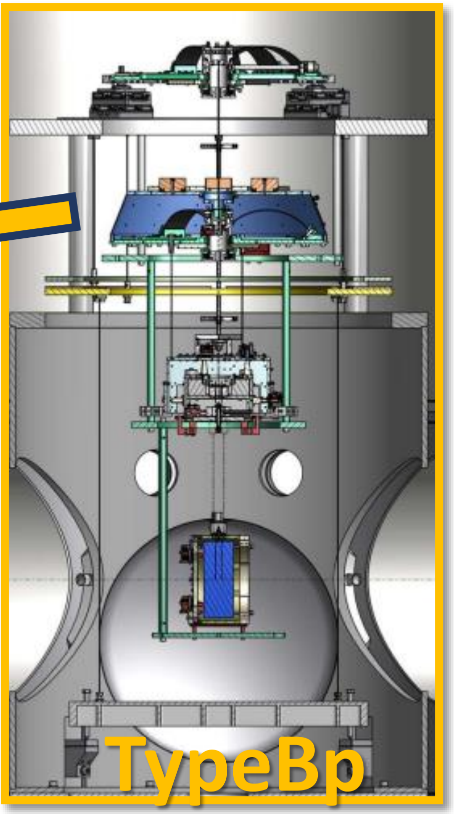
PR TMs are required :

1) disp. < 10^{-15} m/rtHz at 10 Hz
2) RMS velocity < 0.5 um/s
3) RMS angular fluct. < 1 urad

Current bKAGRA PR SAS = TypeBp

❖ Intro : PR SAS in bKAGRA (TypeBp)





PR TMs are required :

1) disp. < 10^{-15} m/rtHz at 10 Hz
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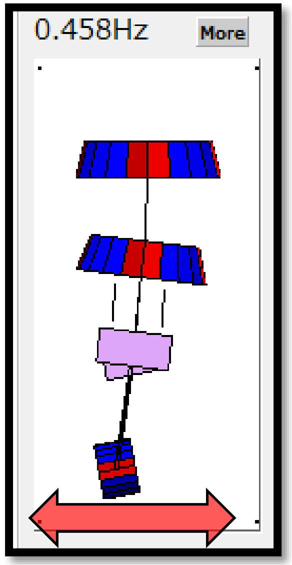
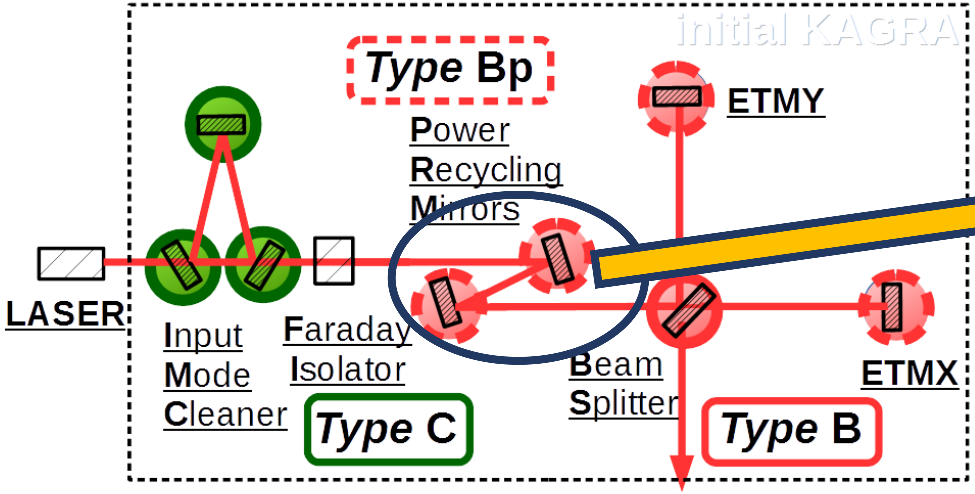


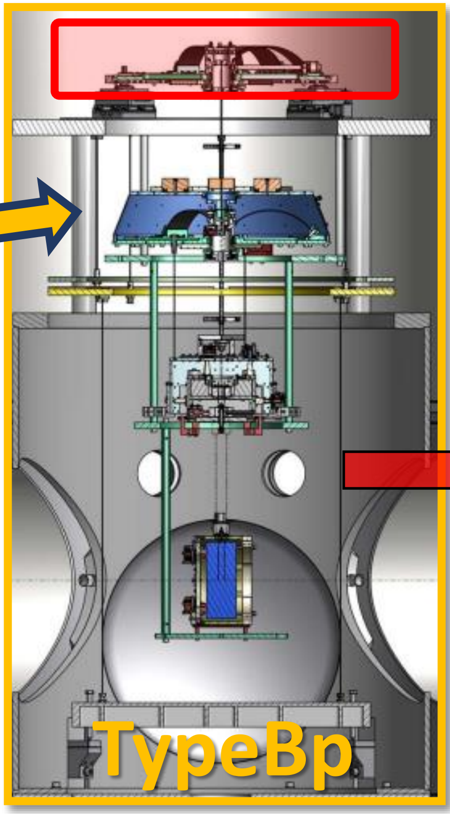
Problems :

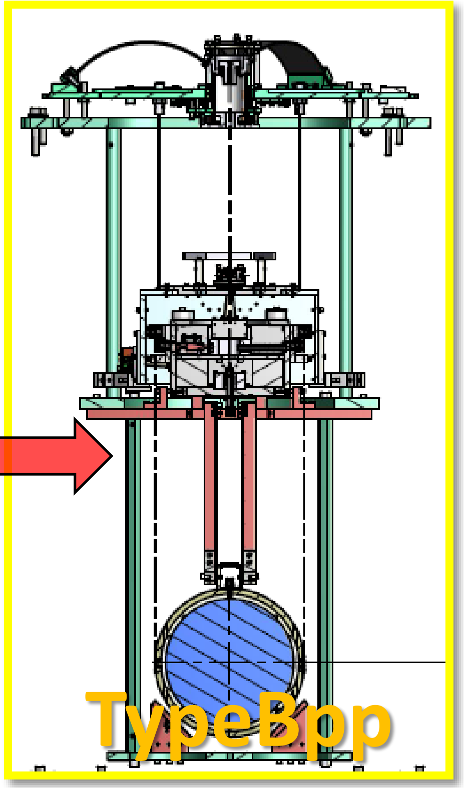
Whole suspension mode cannot be damped enough.

RMS velocity cannot reach lower than 0.7 um/s, because of seismic noise.

❖ Intro : PR SAS in iKAGRA (TypeBpp)





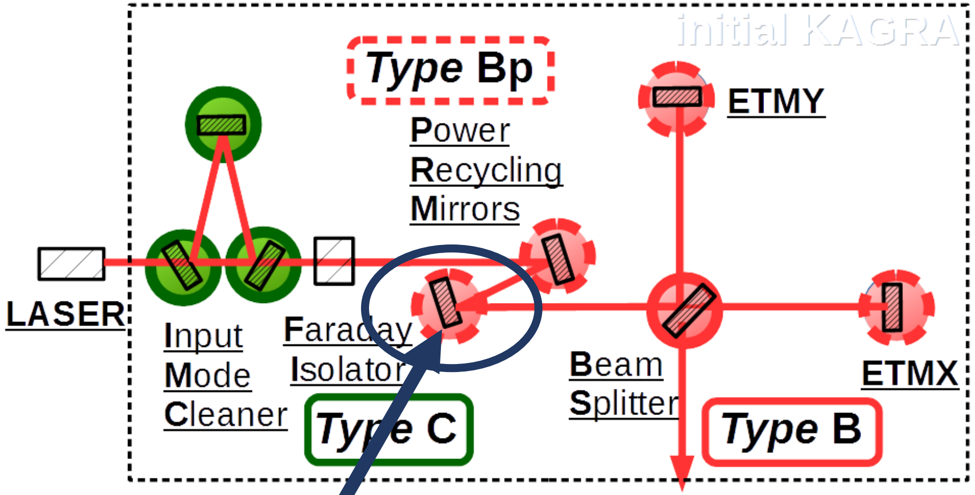


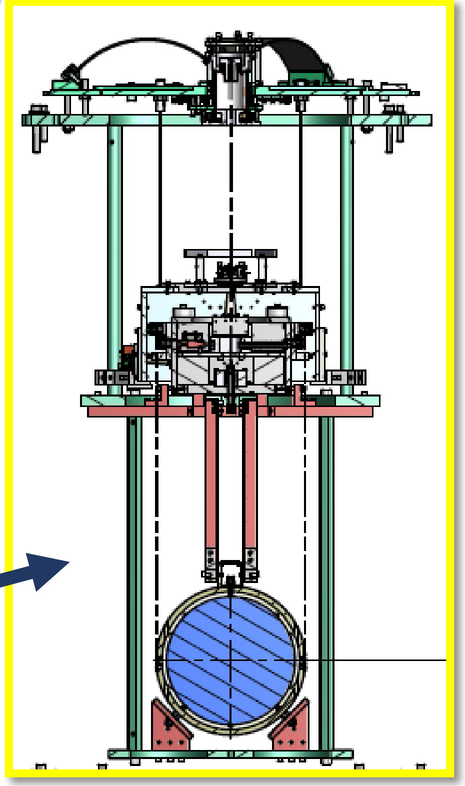
iKAGRA

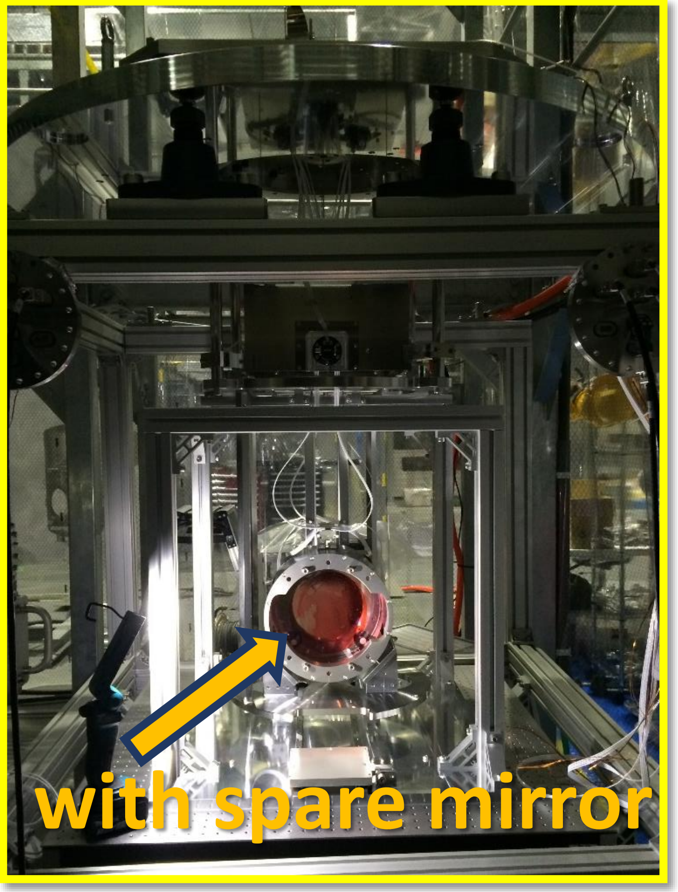
If SF is removed,
though vibration isolation ratio gets worse,
RMS velocity and RMS angular fluctuation get better.

(We have to modify this SAS design to meet the bKAGRA requirements.)

❖ Intro : PR SAS in iKAGRA (TypeBpp)







Now, we are constructing with real mirror.

iKAGRA PR SAS = TypeBpp

(= TypeBp without SF)

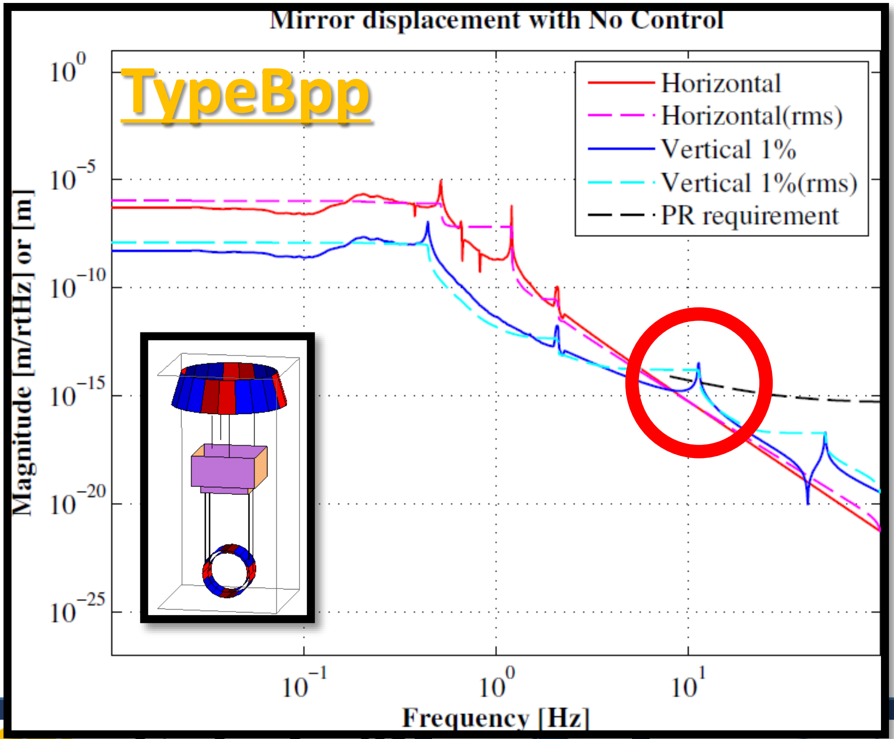
❖ One modification idea for bKAGRA / Requirement

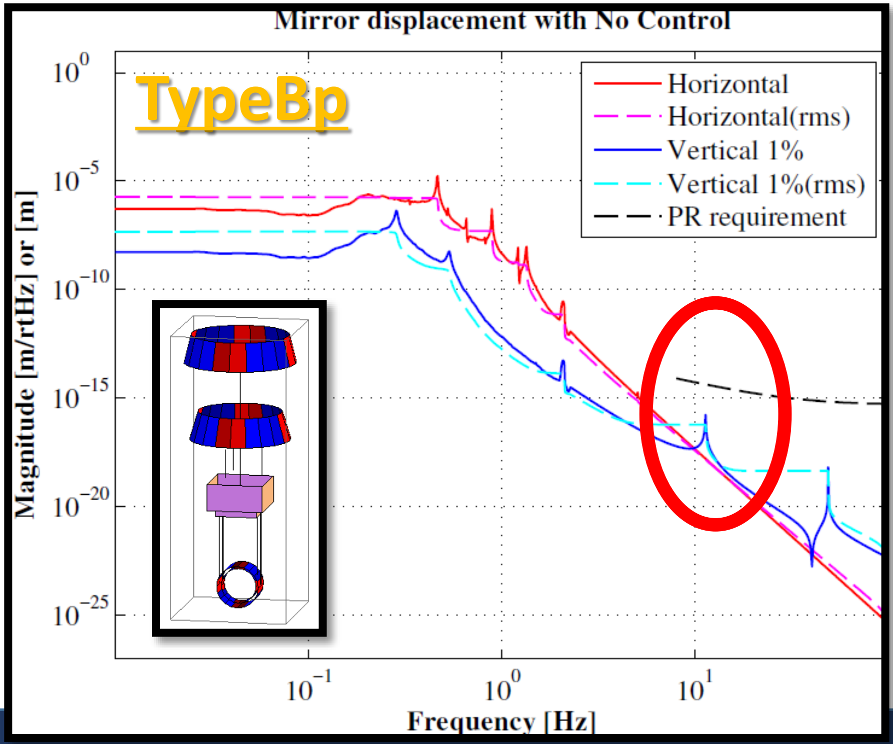
PR TMs are required :

1) disp. < 10^{-15} m/rtHz at 10 Hz
2) RMS velocity < 0.5 um/s
3) RMS angular fluct. < 1 urad

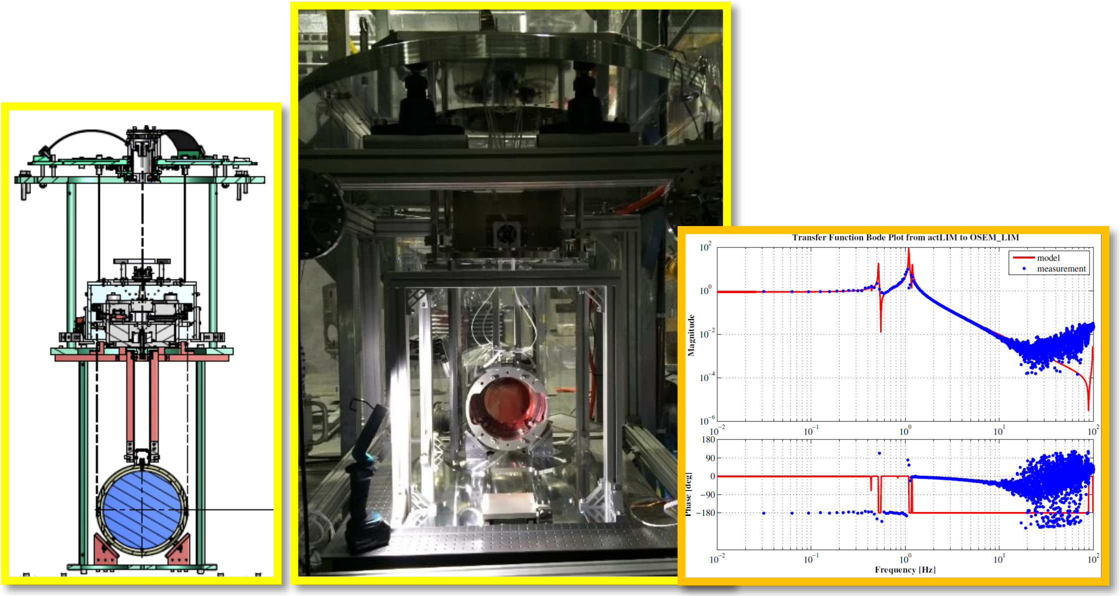
TypeBpp	TypeBp
Not meet	meet
~ 1 um/sec (with ctrl)	~ 5 um/sec (with ctrl)
~ 0.4 urad (with ctrl)	~ 1.4 urad (w ctrl)

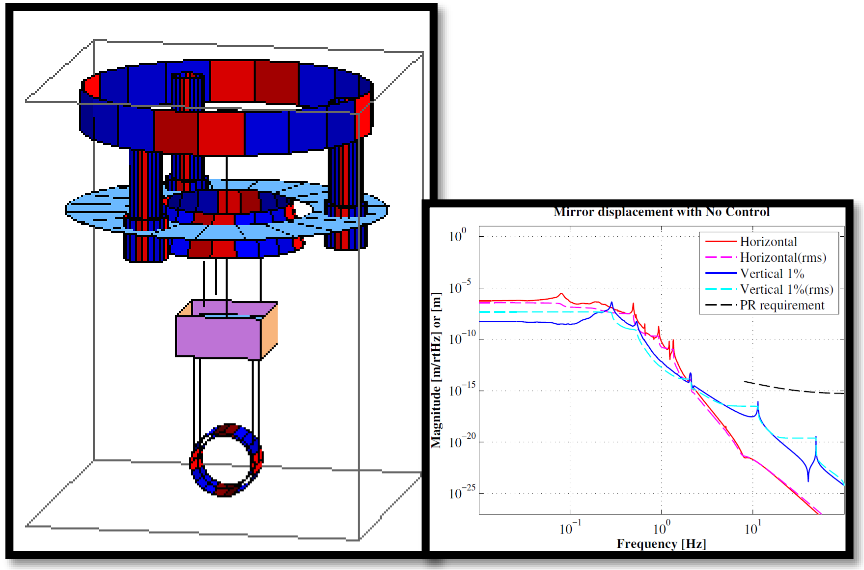
Also, RMS seismic velocity can be ~ 0.7 um/sec





❖ Intro : PR SAS / Main topic of this talk





① Frequency response investigation of the TypeBpp SAS (, which we constructed in the tunnel)

② One modification idea for bKAGRA PR SAS

How do we meet both (VI performance and RMS) requirements?

Contents

- Intro : PR SAS
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- Investigation of TypeBpp Frequency response
    - Transfer functions / Spectrums
- One modification proposal for bKAGRA
    - requirement
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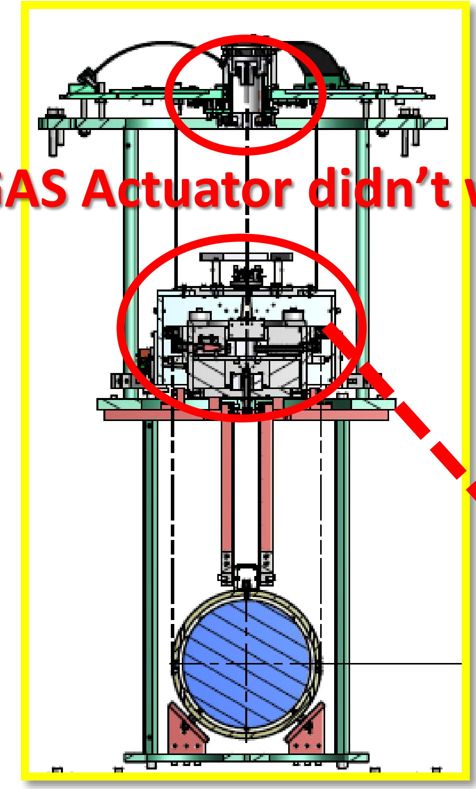
❖ Investigation of TypeBpp Frequency response

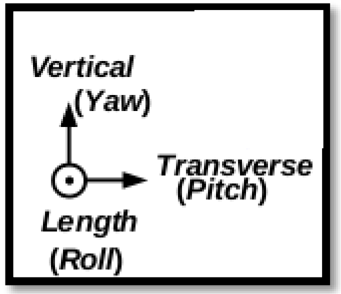


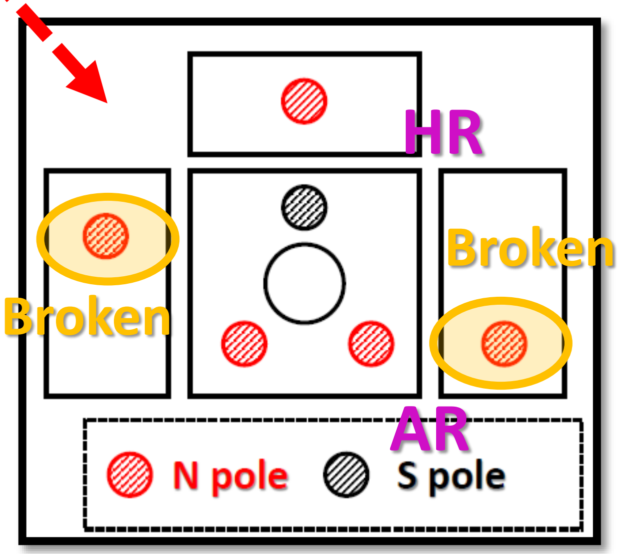
Measured DoF :

Transfer functions → IM (L, P, R), TM (L, P, Y)

Spectrums → BF (V), IM (L, P, R, V), TM (L, P, Y)

○ Measured by Oplev and OSEMs
(The others → measured by OSEMs)





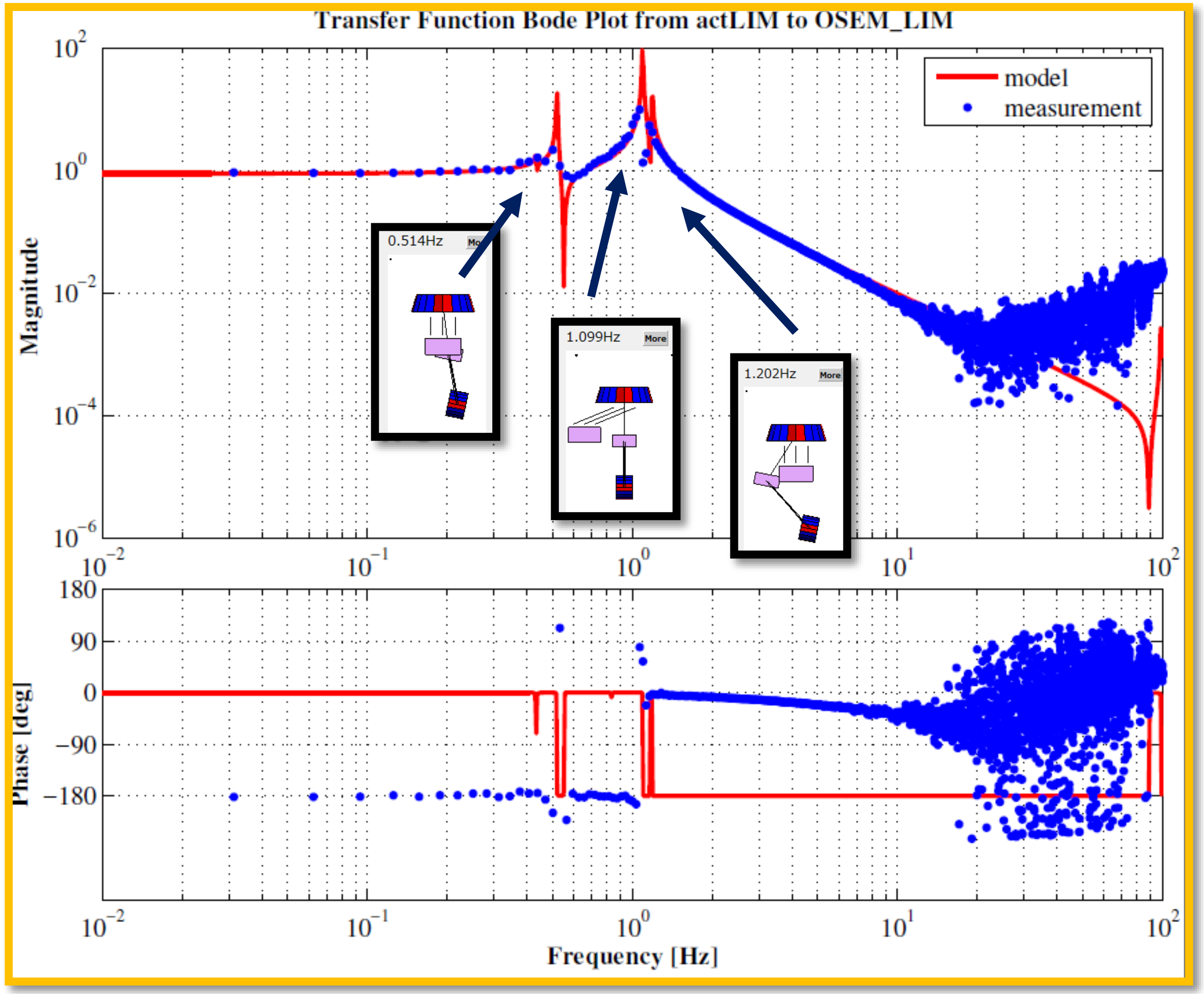
Not Measured DoF :

Transfer functions → BF(V), IM (T, V, Y)

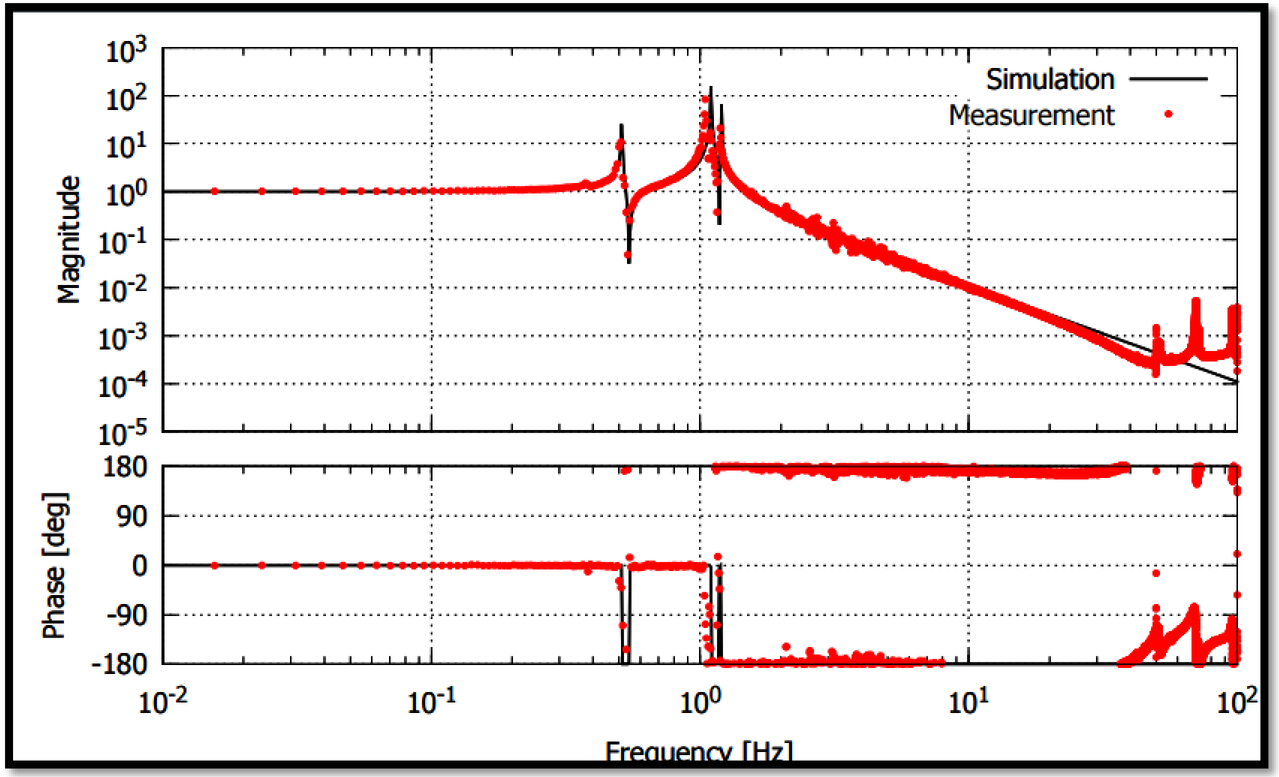
Spectrums → IM (T, Y)

❖ Investigation of TypeBpp Frequency response

LIM (OSEM) TF

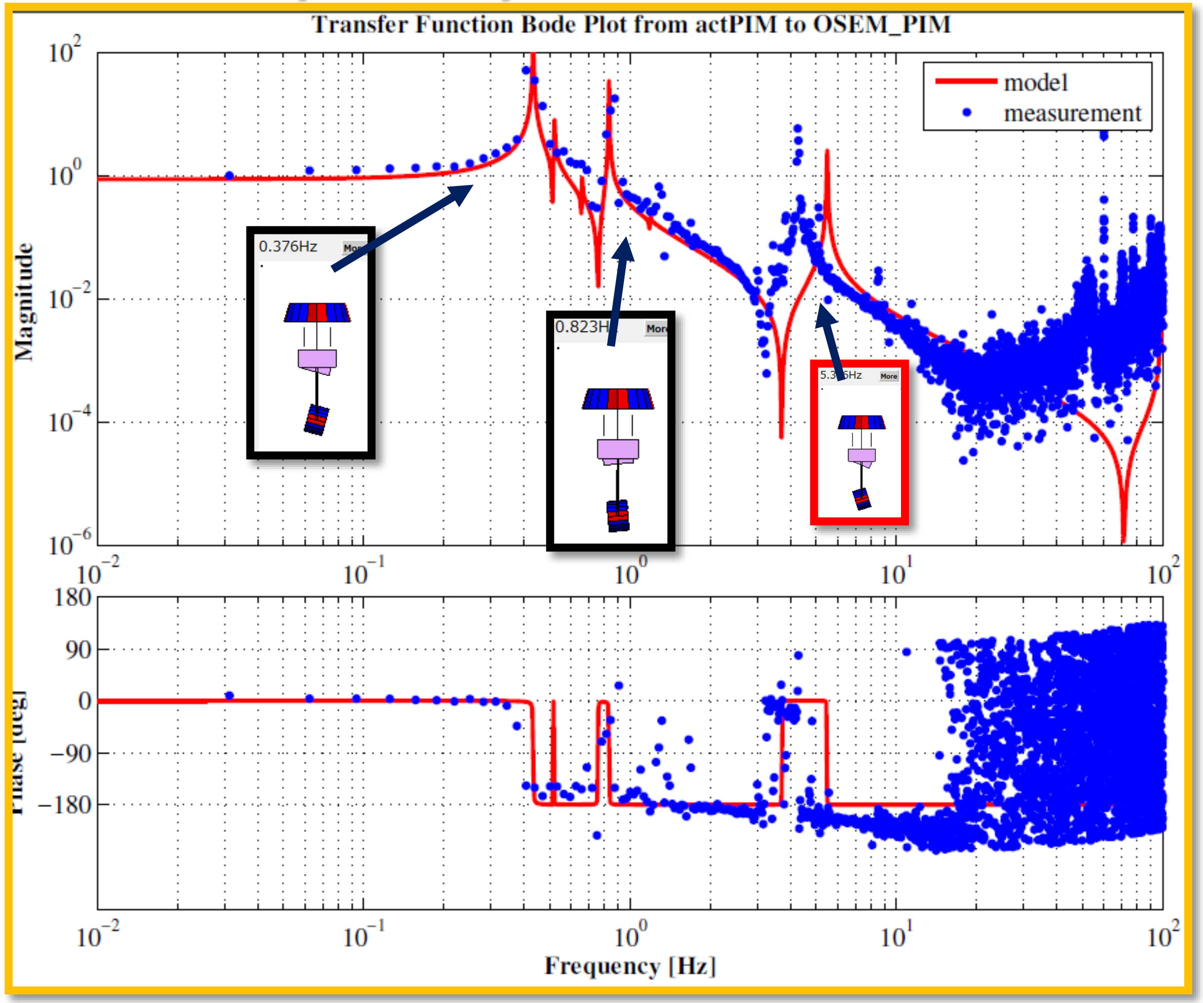


REF : LIM (OSEM) TF of 20 m SAS

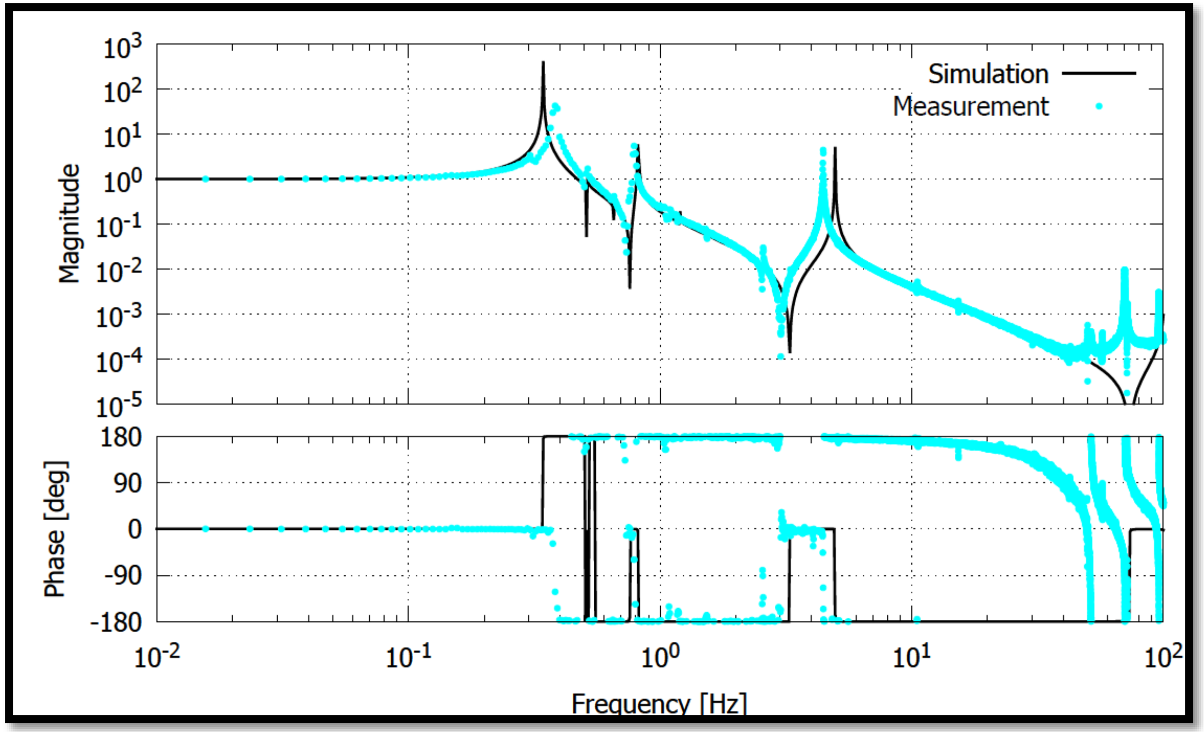


❖ Investigation of TypeBpp Frequency response

PIM (OSEM) TF

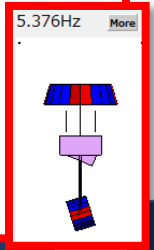


REF : PIM (OSEM) TF of 20 m SAS



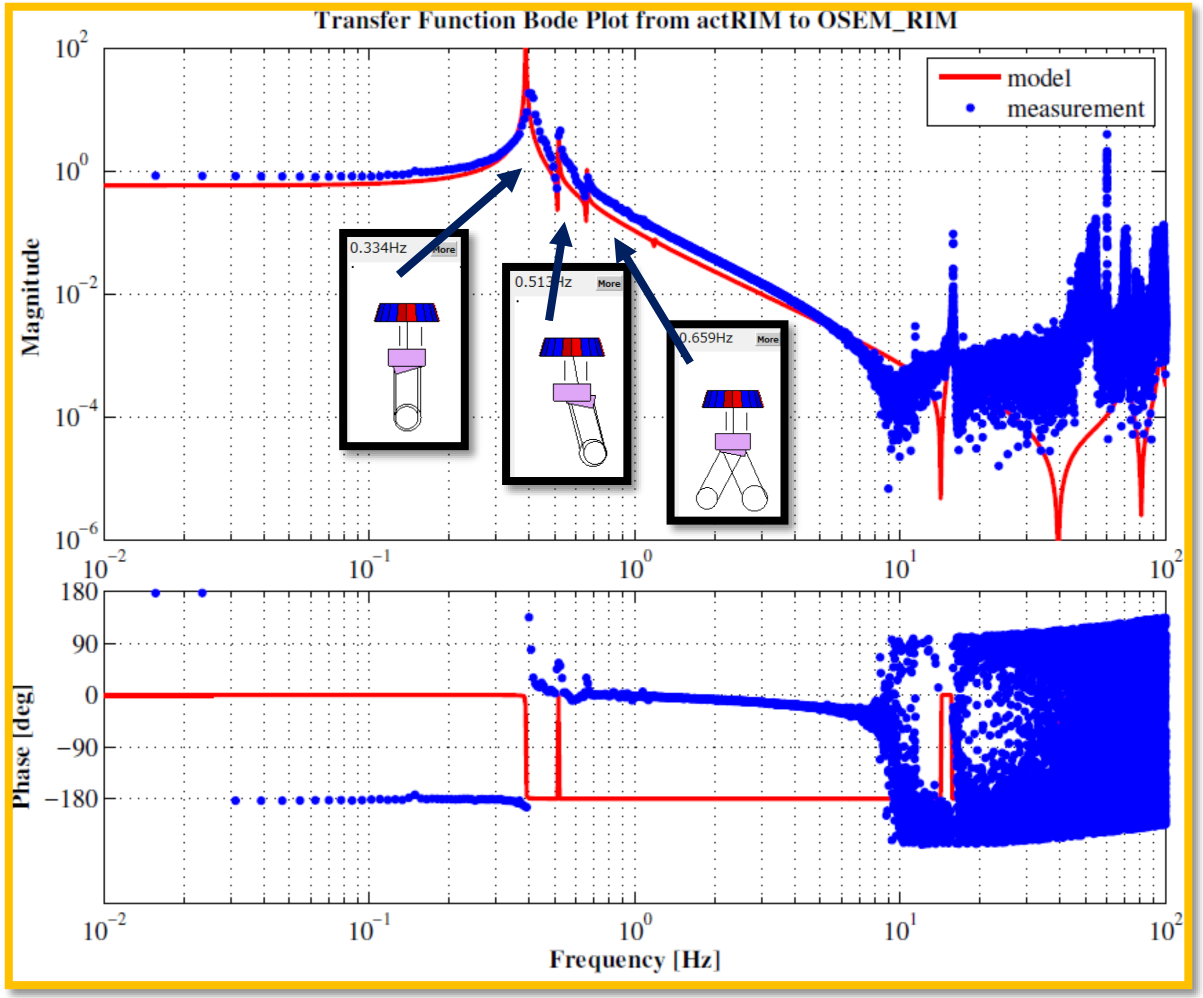
Resonance frequency is still lower than its prediction by around 1 Hz.

➡ **To be investigated.**

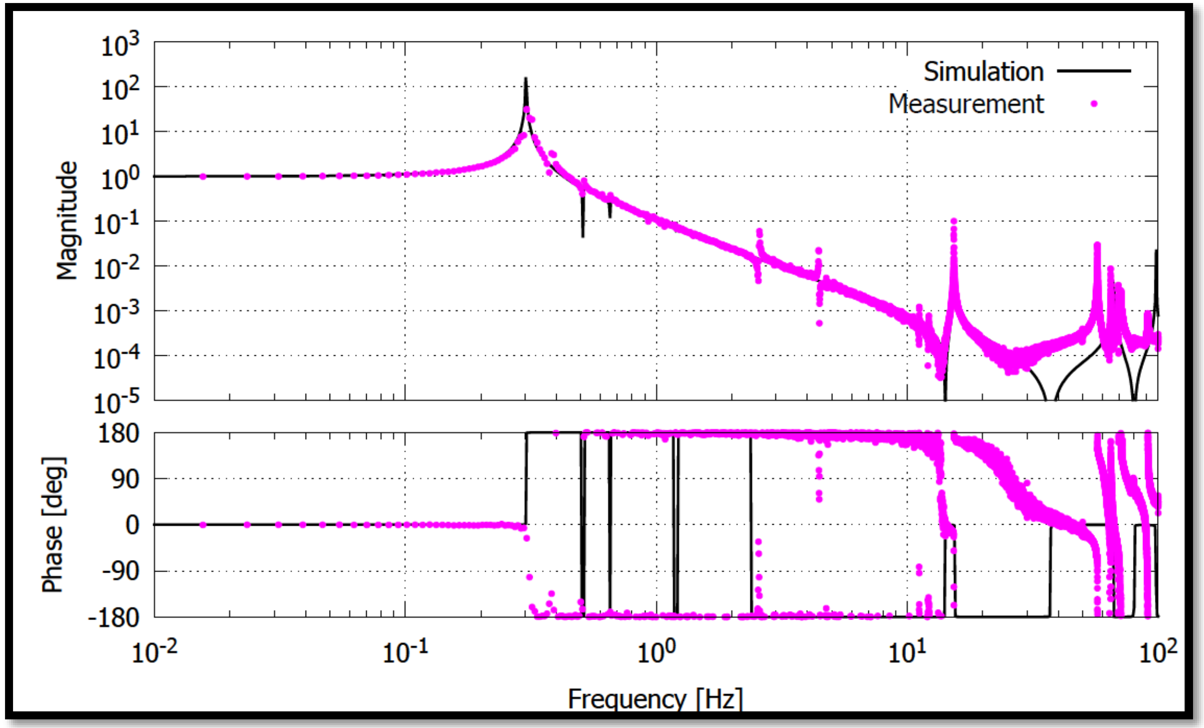


❖ Investigation of TypeBpp Frequency response

RIM (OSEM) TF

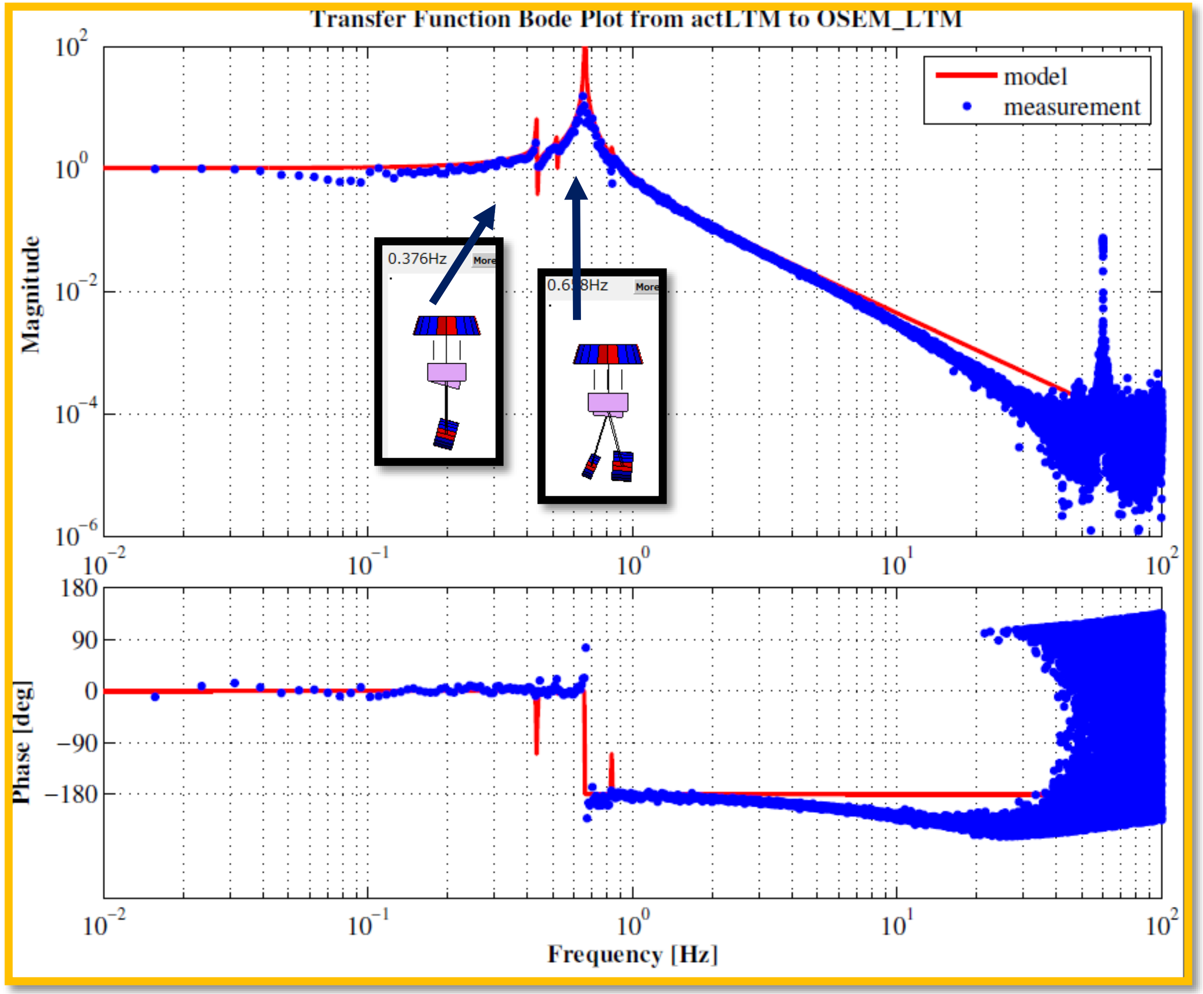


REF : RIM (OSEM) TF of 20 m SAS

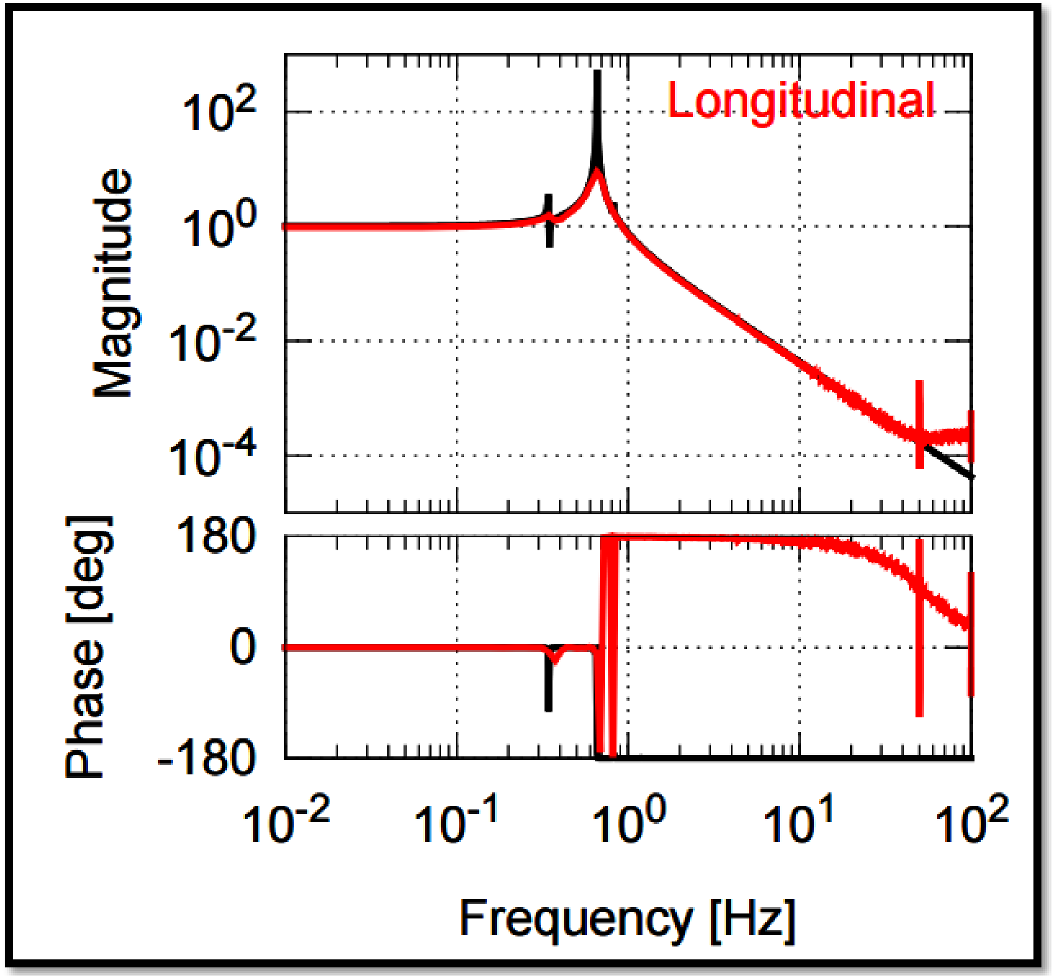


❖ Investigation of TypeBpp Frequency response

LTM (OSEM) TF

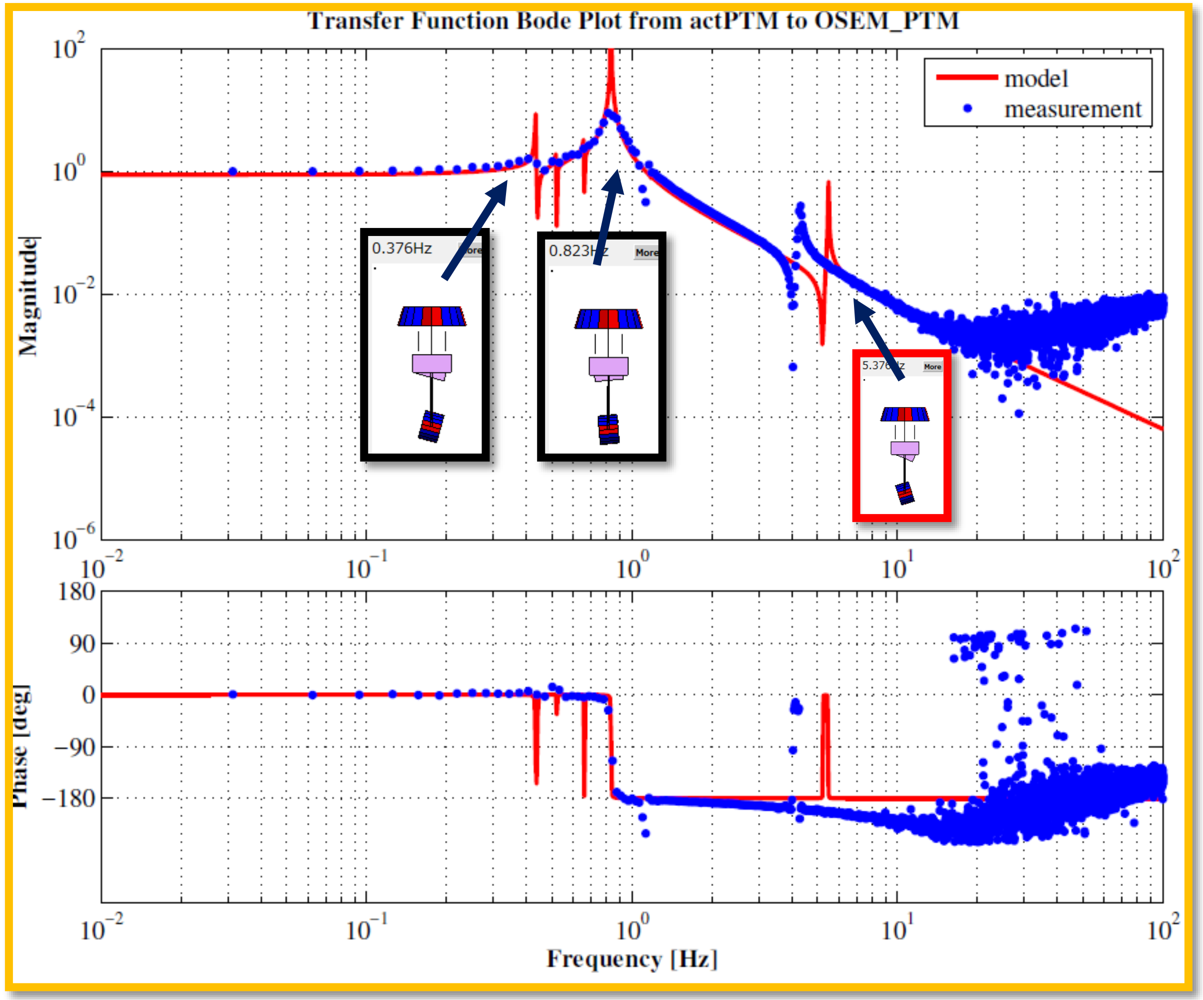


REF : LTM (OSEM) TF of 20 m SAS

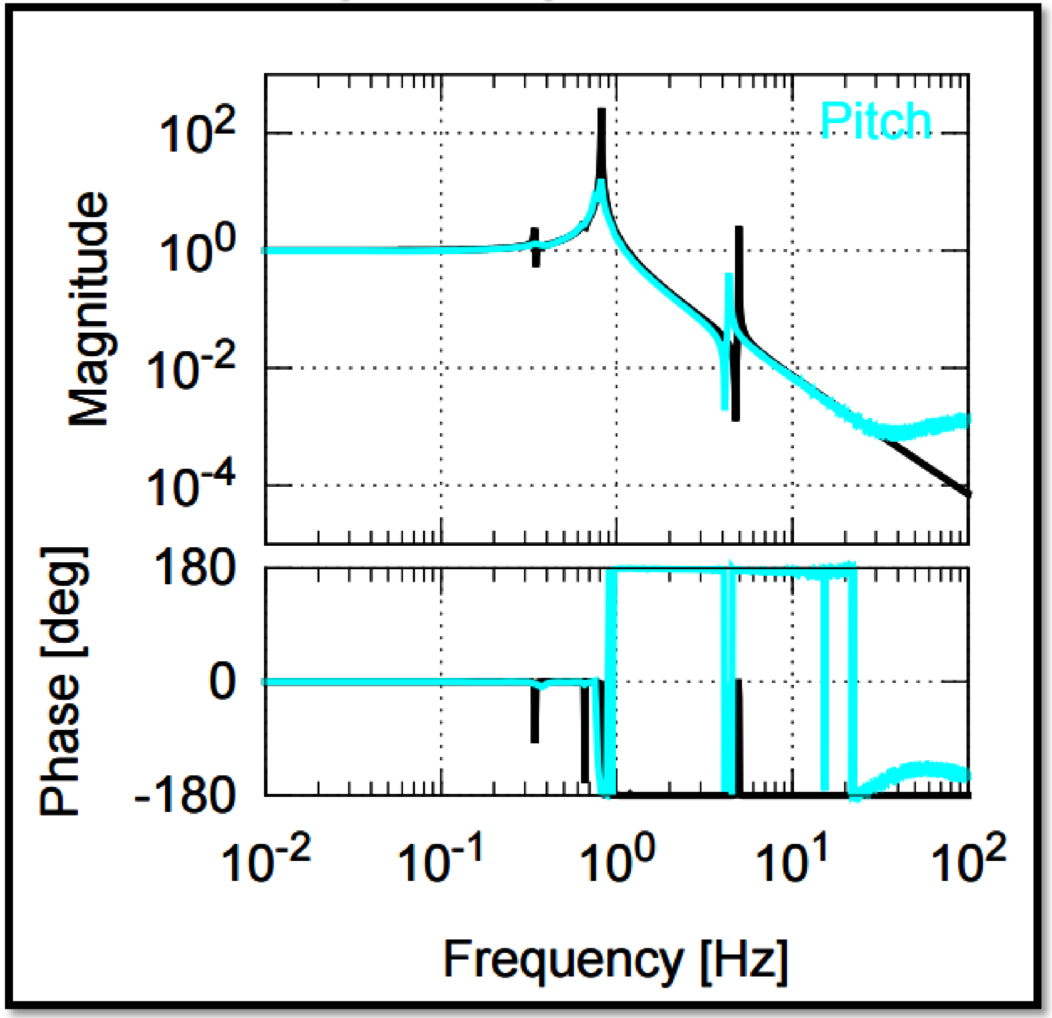


Investigation of TypeBpp Frequency response

PTM (OSEM) TF

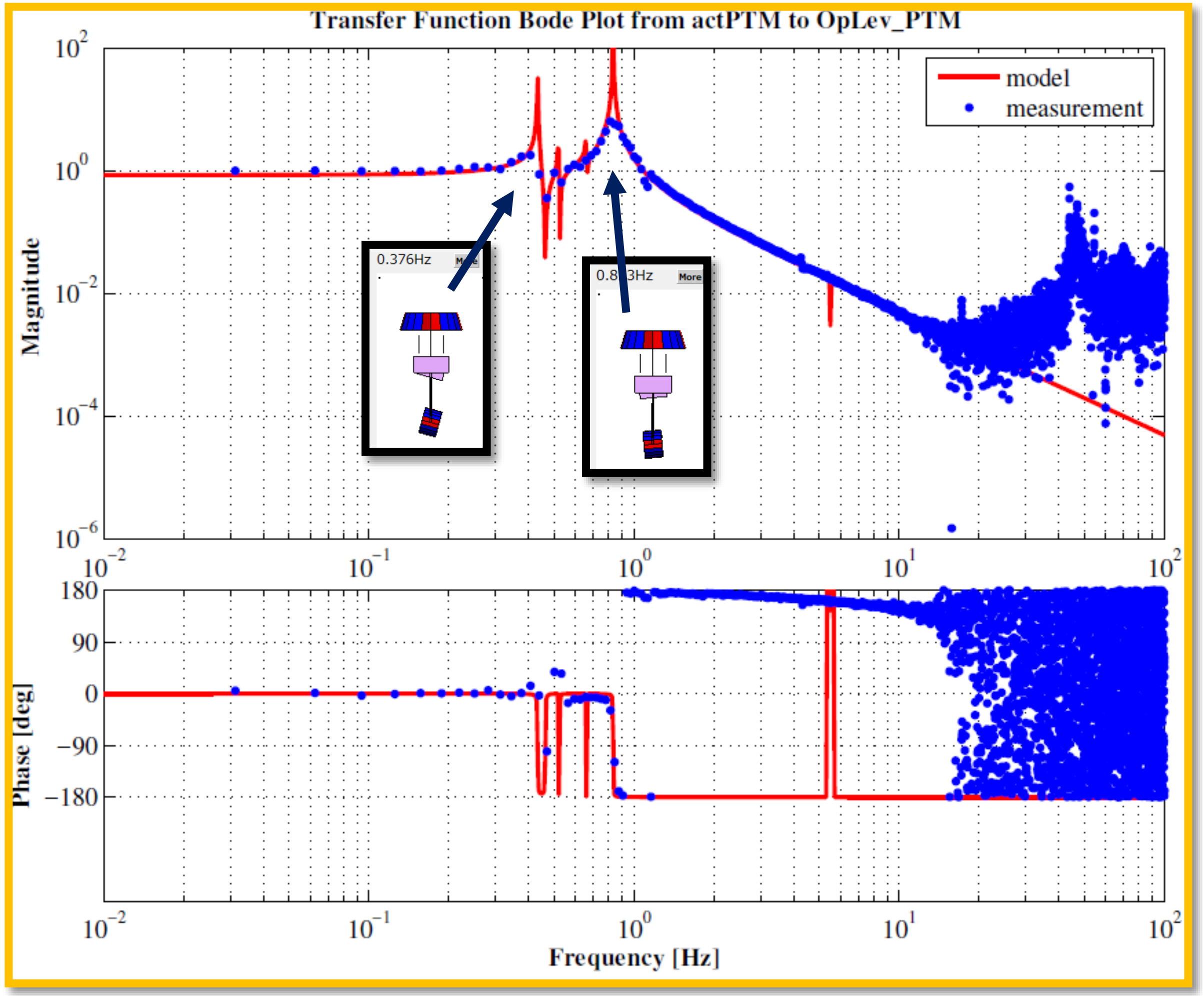


REF : PTM (OSEM) TF in 20 m SAS

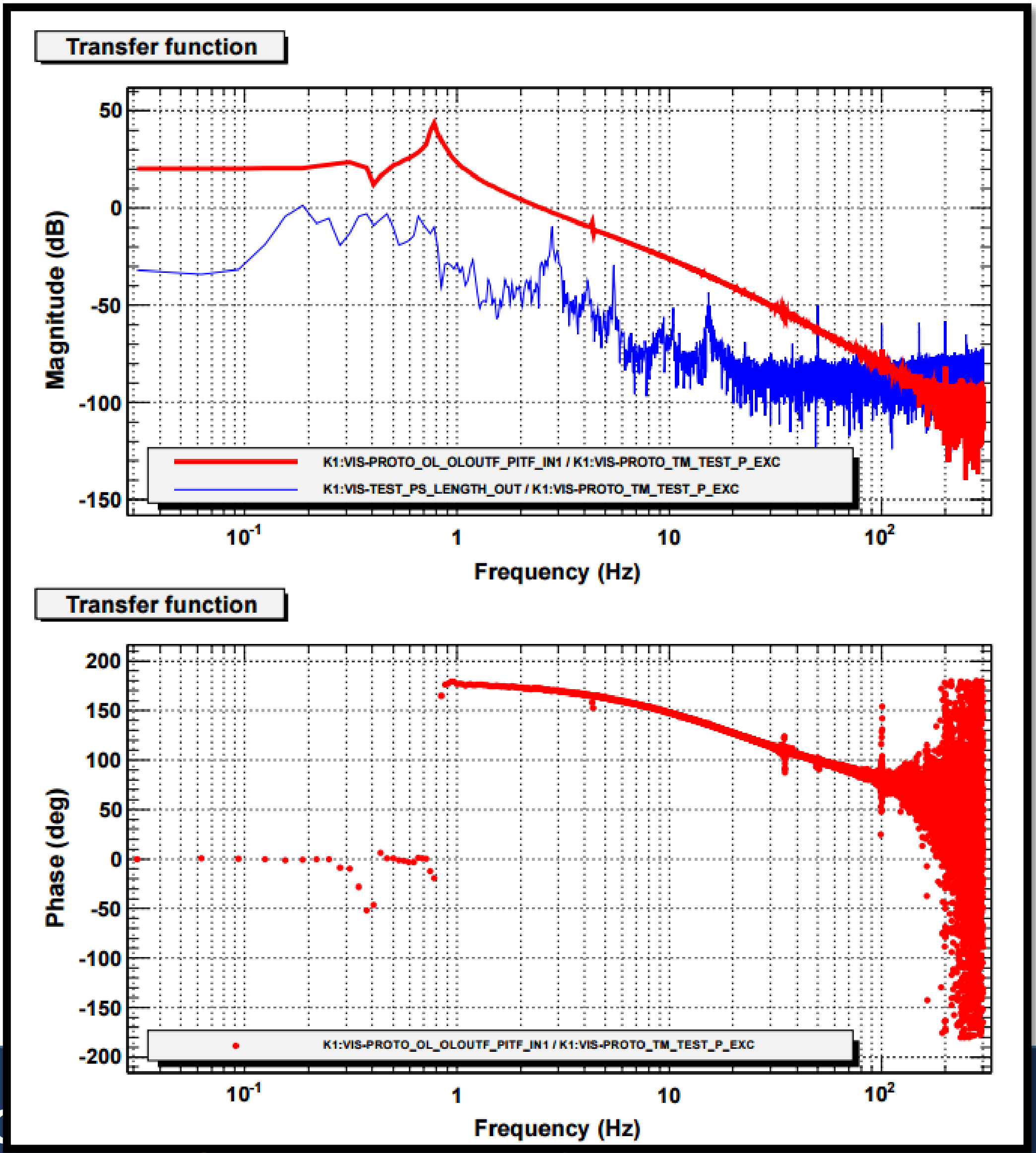


❖ Investigation of TypeBpp Frequency response

PTM (Oplev) TF

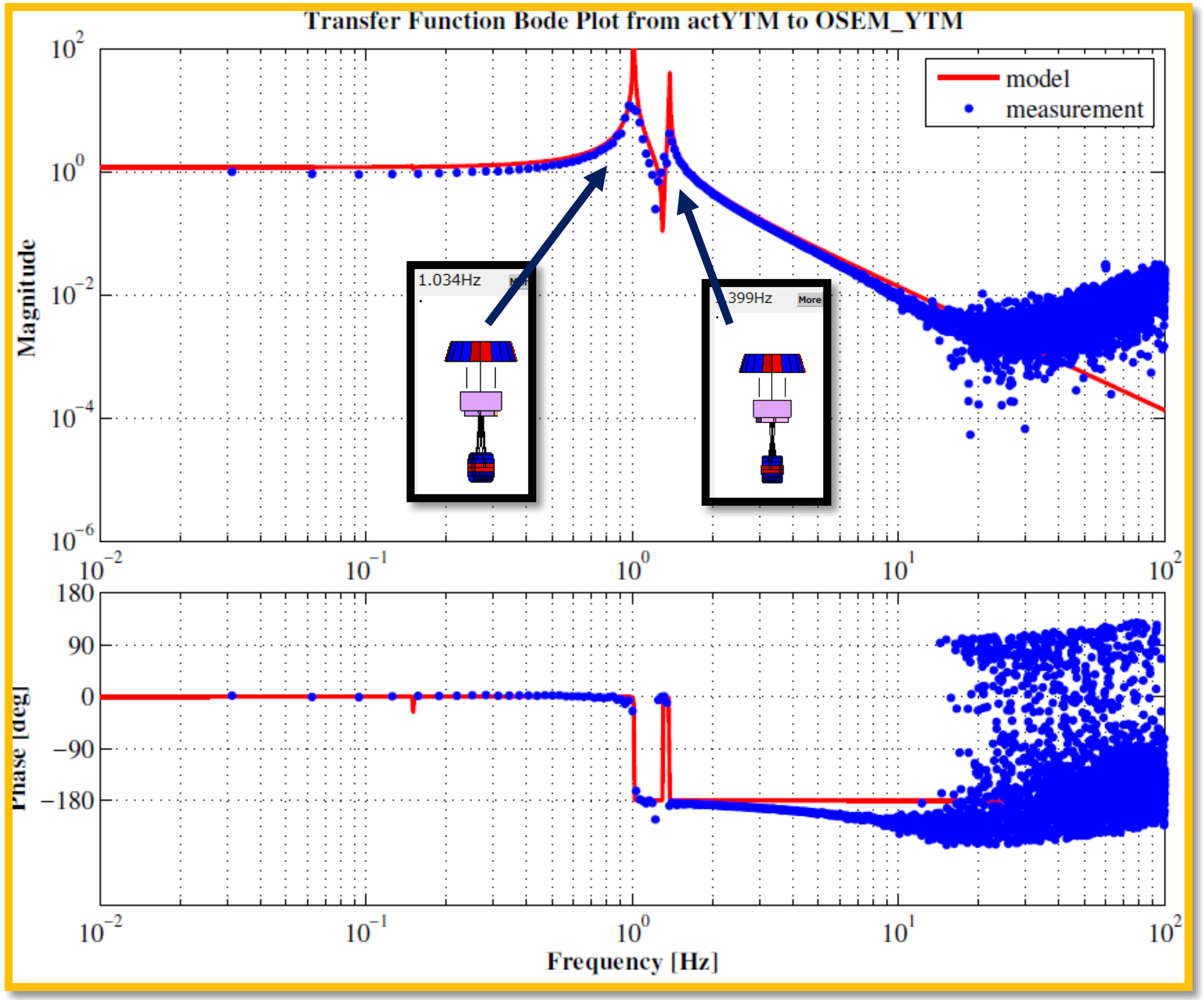


REF : PTM (Oplev) TF of Type B1

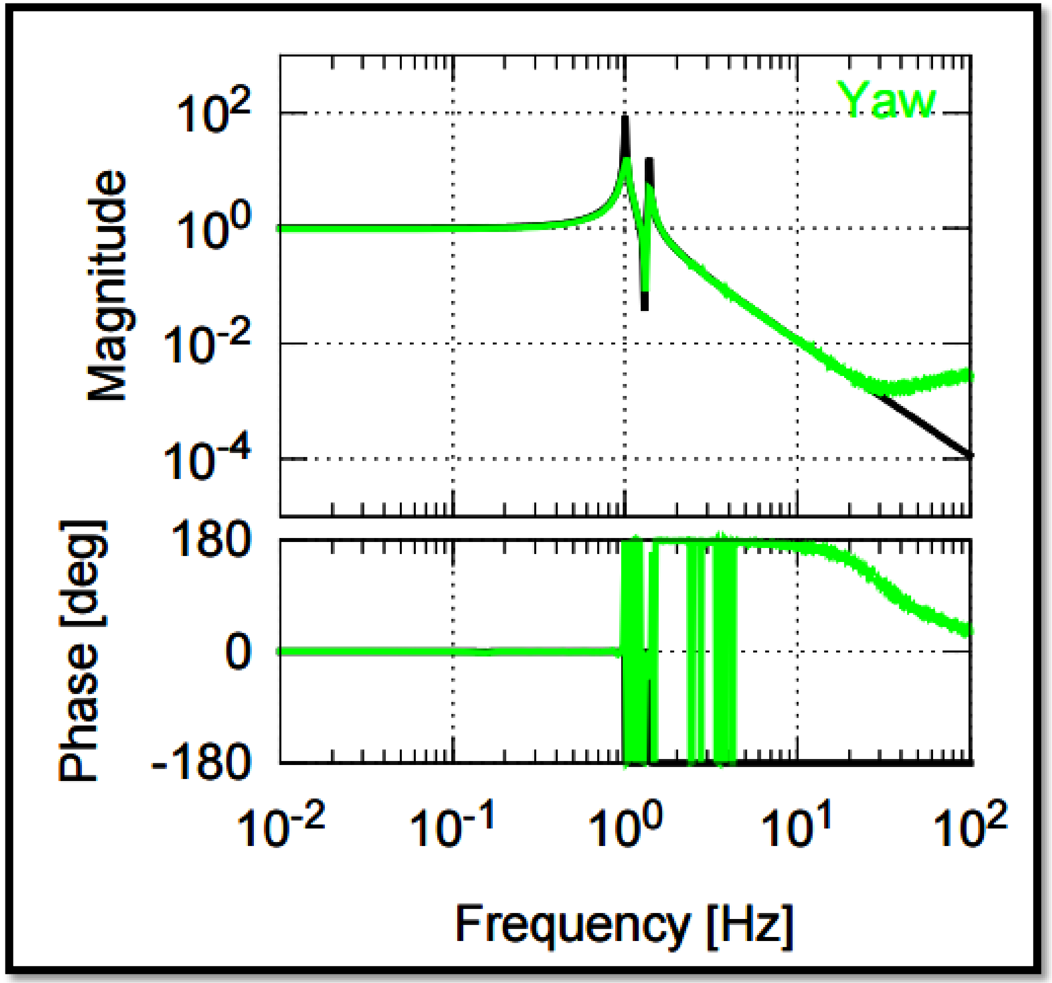


❖ Investigation of TypeBpp Frequency response

YTM (OSEM) TF

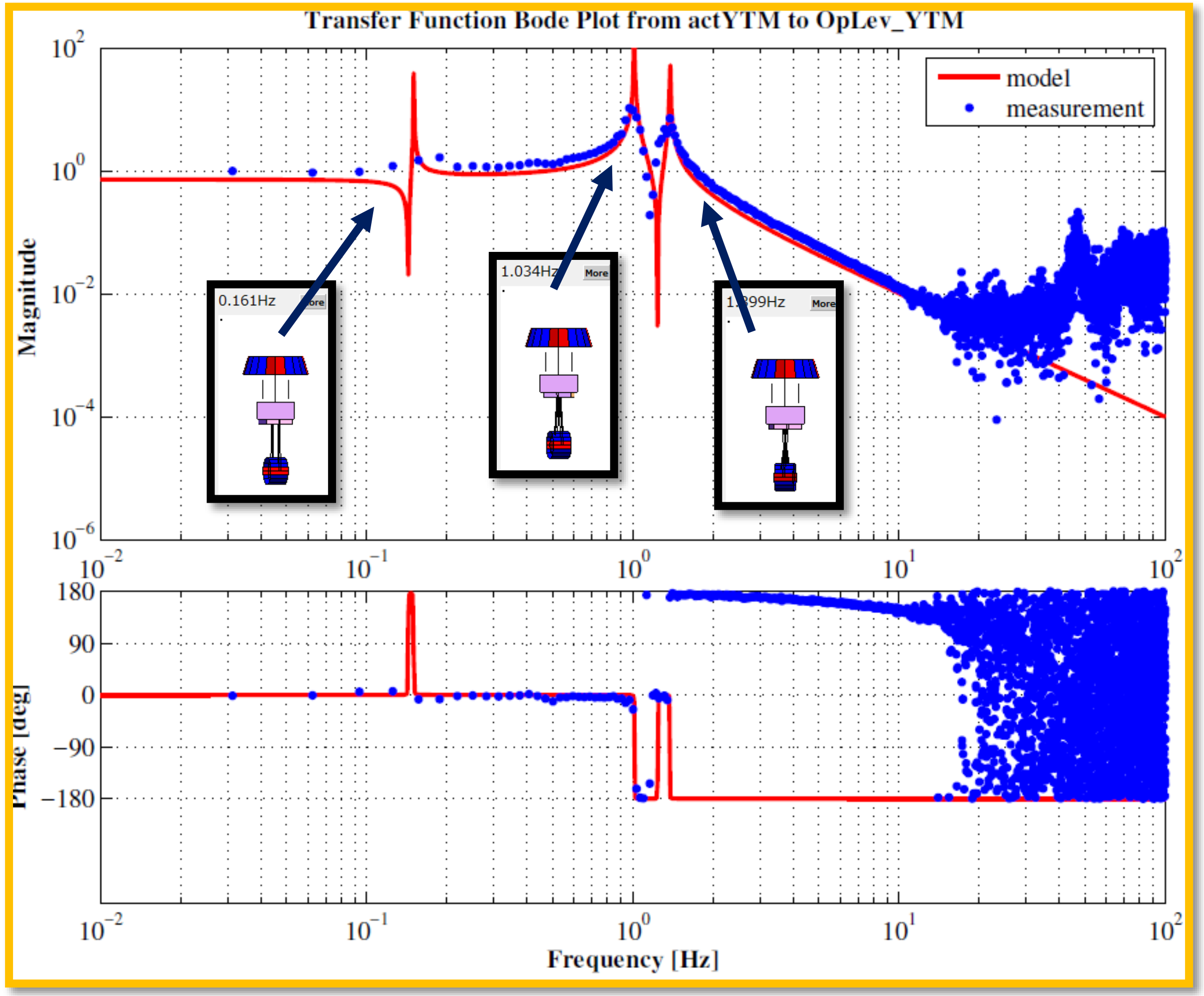


REF : LTM (OSEM) TF of 20 m SAS

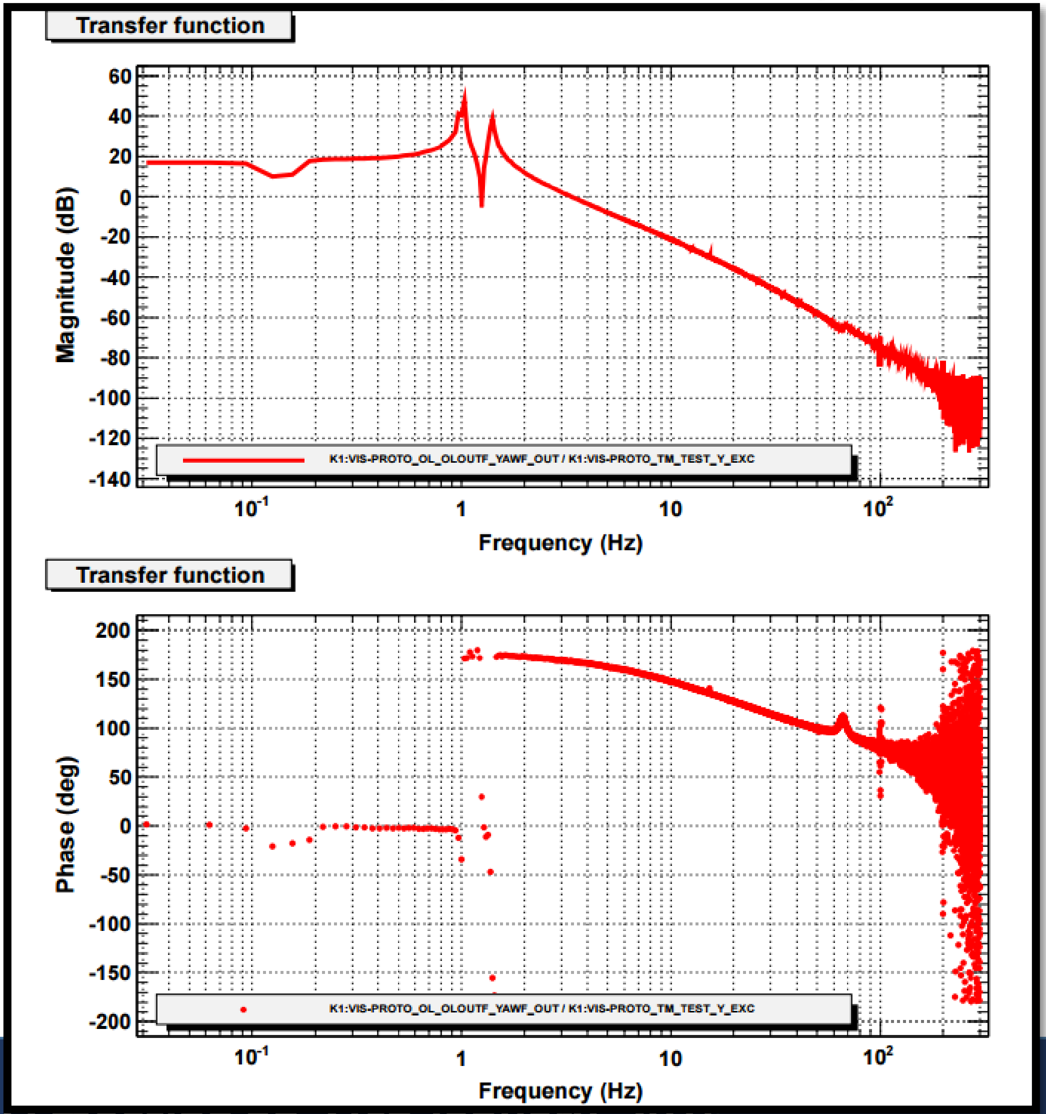


Investigation of TypeBpp Frequency response

YTM (Oplev) TF

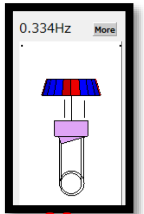


REF : YTM (Oplev) TF of Type B1



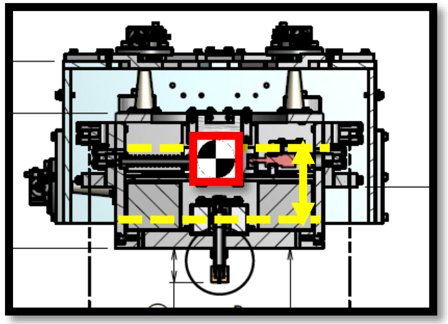
❖ Investigation of TypeBpp Frequency response

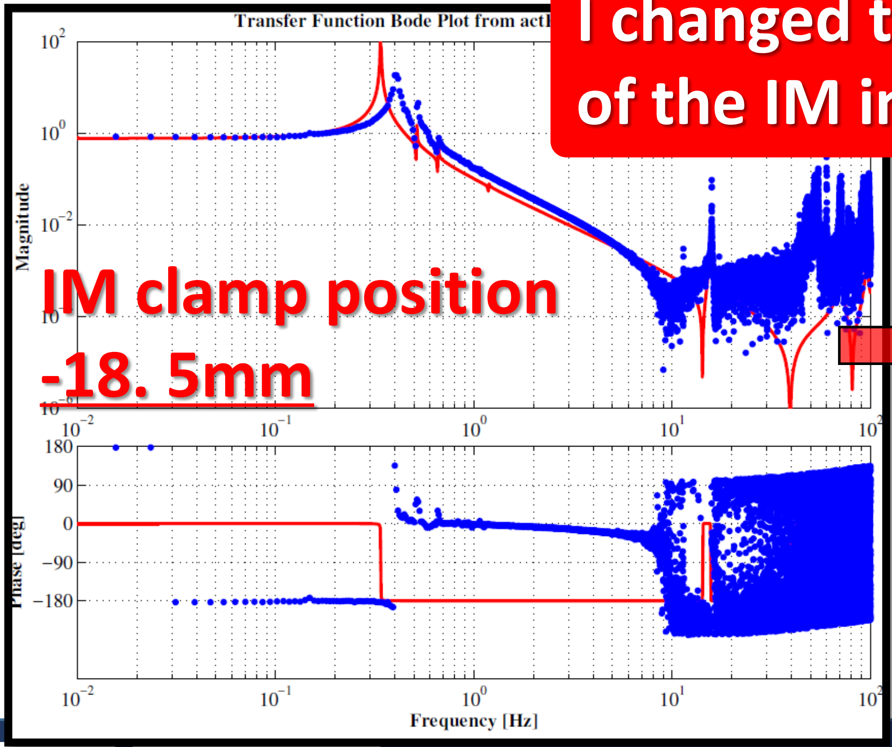
Note : Transfer function (measured in the chamber)

- ❐ **Resonance frequency shift :**
  - ❐ 

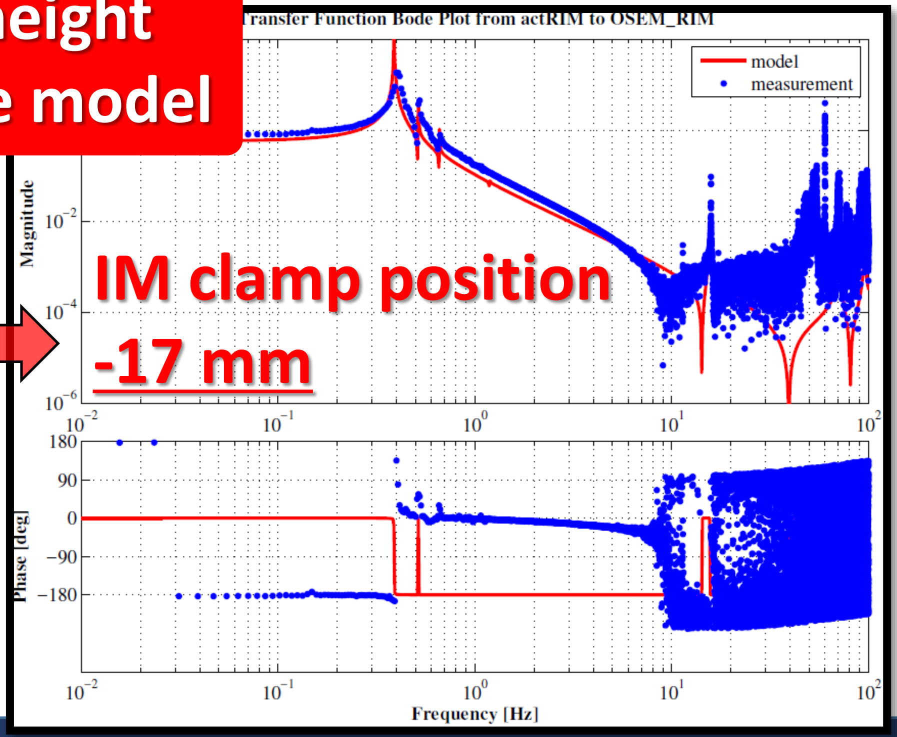
→ CoM position of the IM.

Roll IM





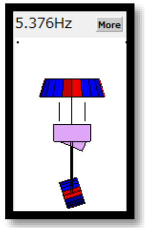
I changed the height of the IM in the model



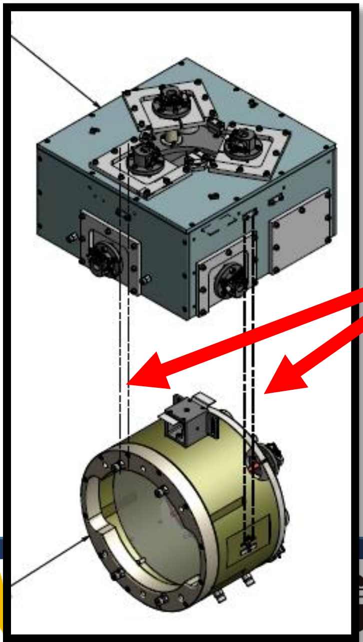
❖ Investigation of TypeBpp Frequency response

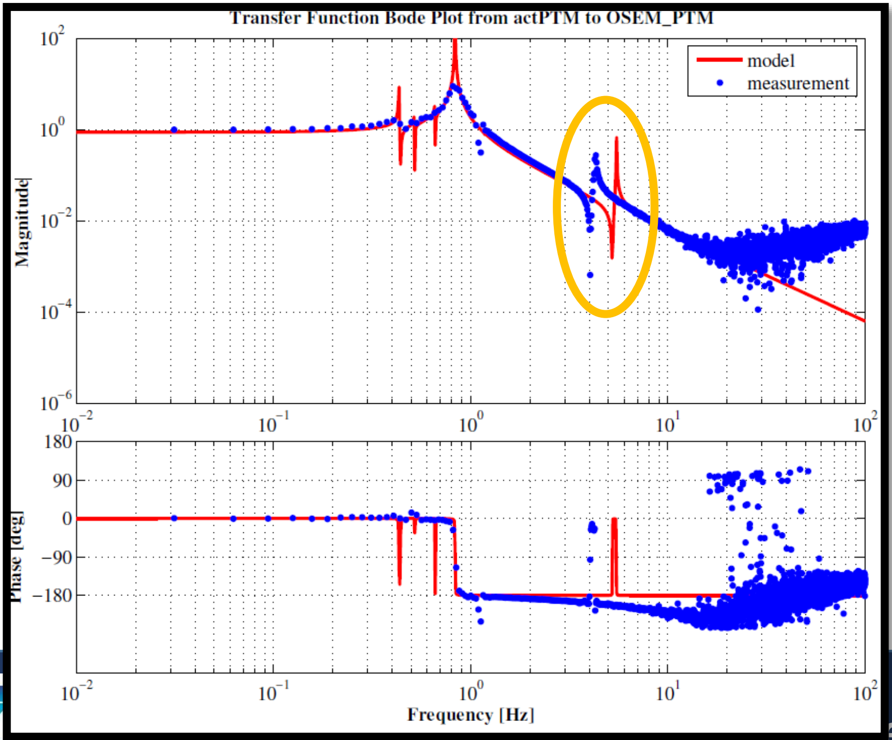
Note : Transfer function (measured in the chamber)

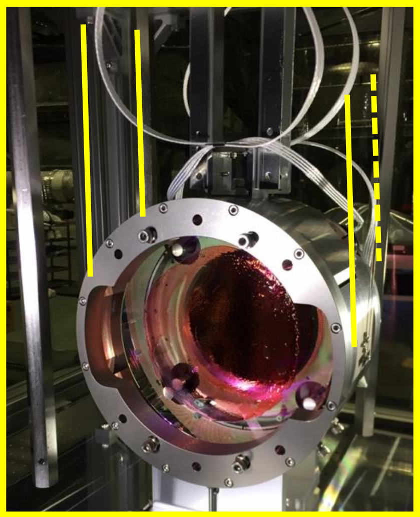
- **Resonance frequency shift :**
  - → we changed the wire diameter to thicker one (600 -> 650 um) to increase the resonance frequency for robust control, (after TypeB proto exp.) However, the frequency is still low, for some reason.



Pitch RM



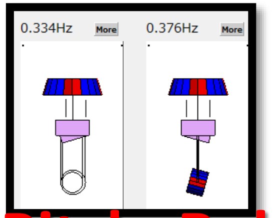


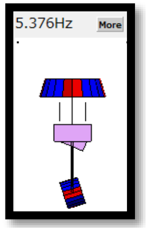


suspended by 3 wires?

❖ Investigation of TypeBpp Frequency response

Note : Transfer function (measured in the chamber)

- Resonance frequency shift :
  - 

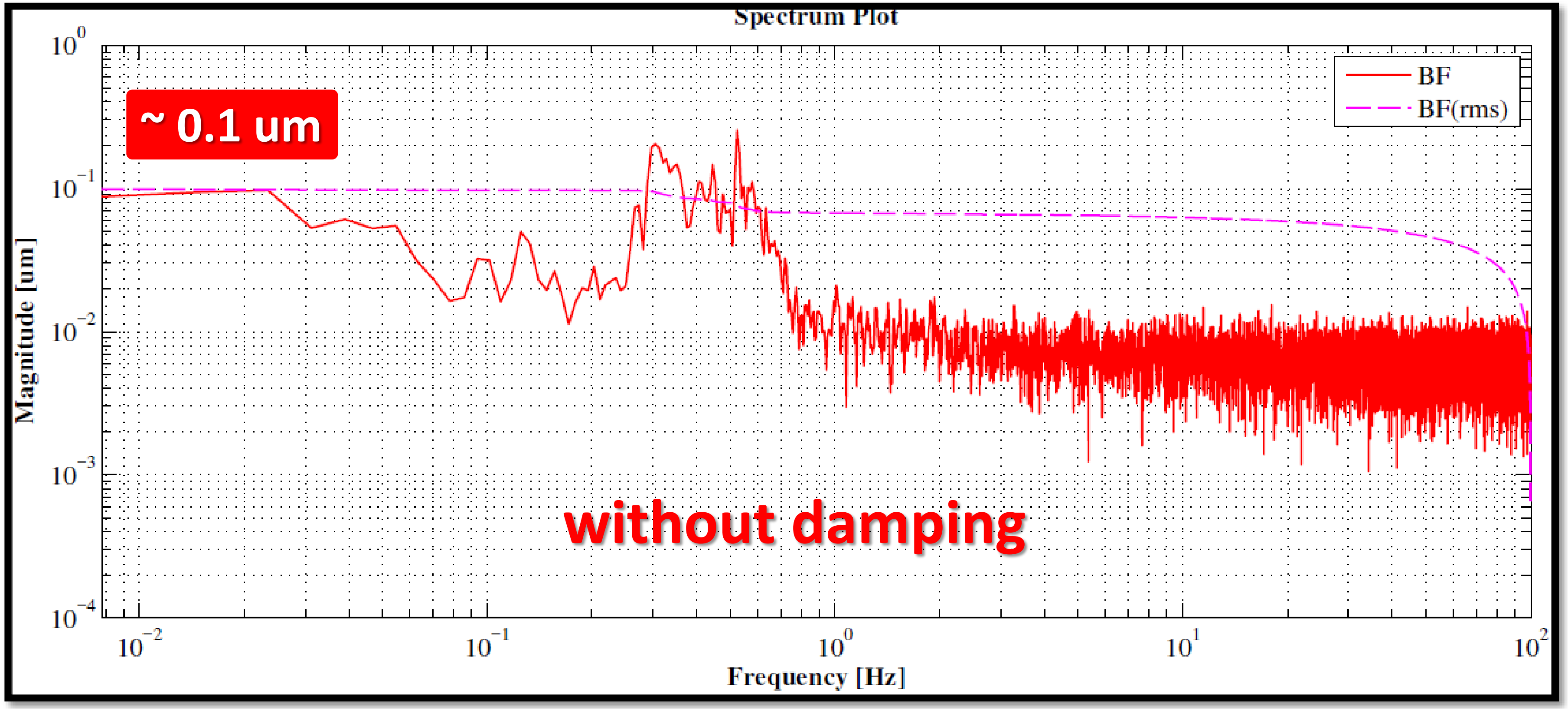
    Pitch, Roll IM
    → IM was suspended at higher position by 1.5 mm.
  - 

    Pitch RM
    → Though wire diameter was increased, the resonance frequency is still lower than its prediction by 1 Hz . (suspended by 3 wires?)

- Small mechanical Q factor? → to be investigated, resonance by resonance.

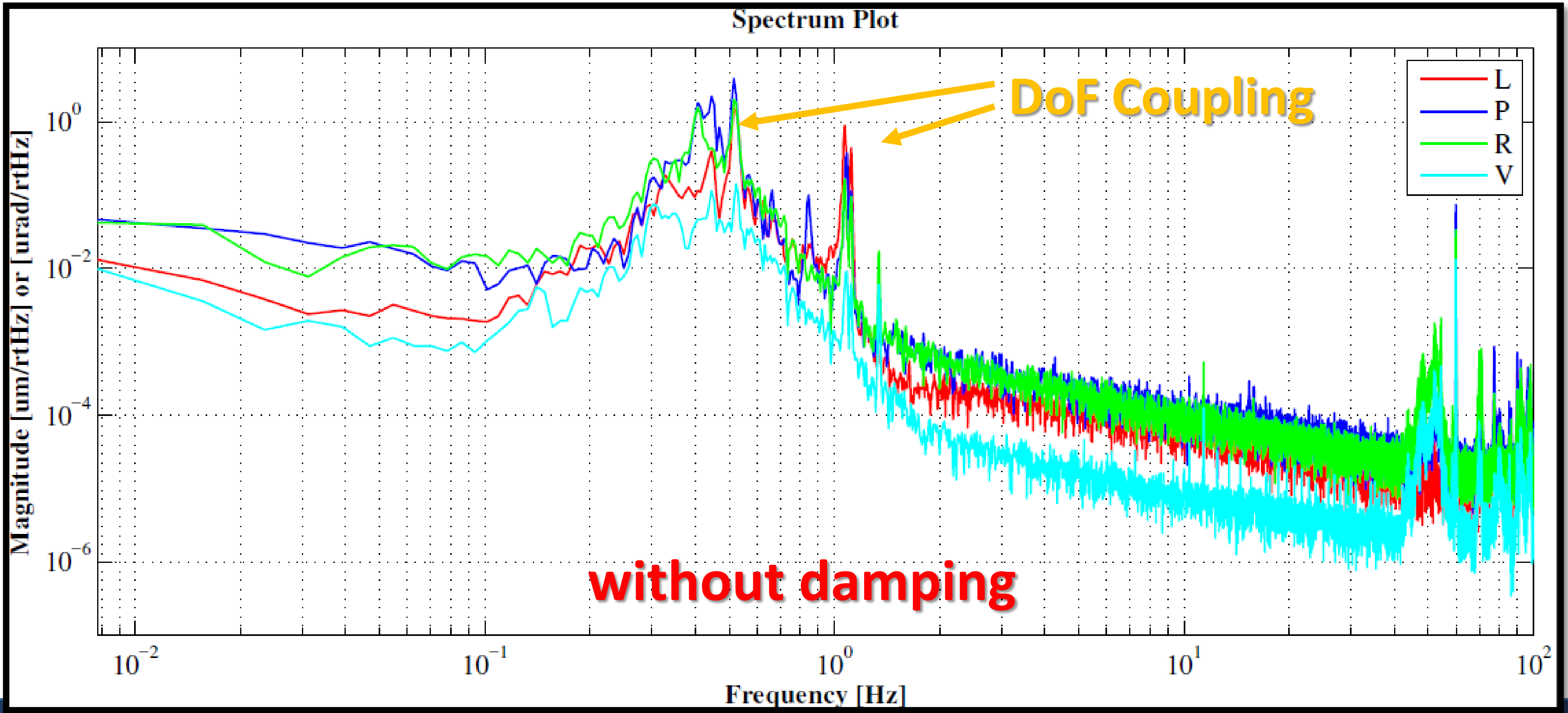
❖ Investigation of TypeBpp Frequency response

BF (LVDT) Spectrum



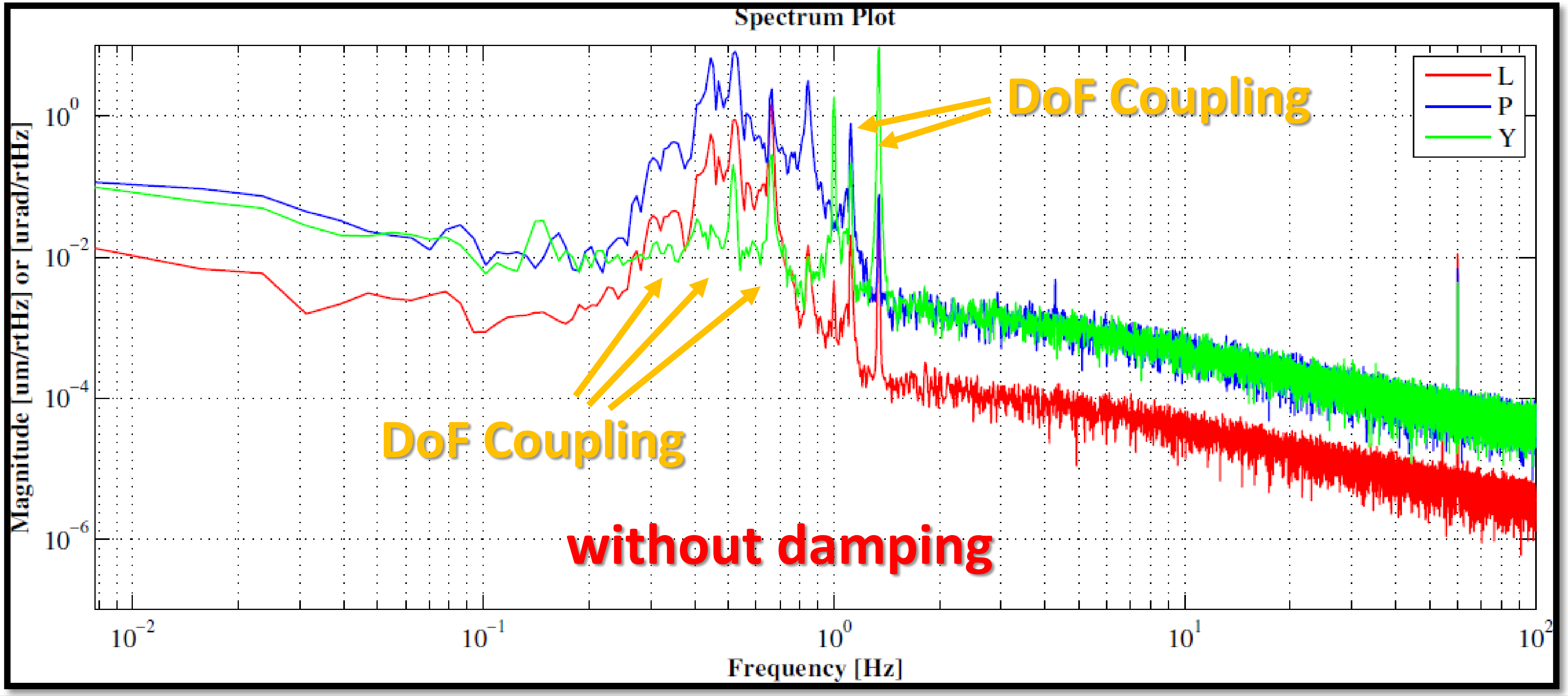
❖ Investigation of TypeBpp Frequency response

IM (OSEM) Spectrum



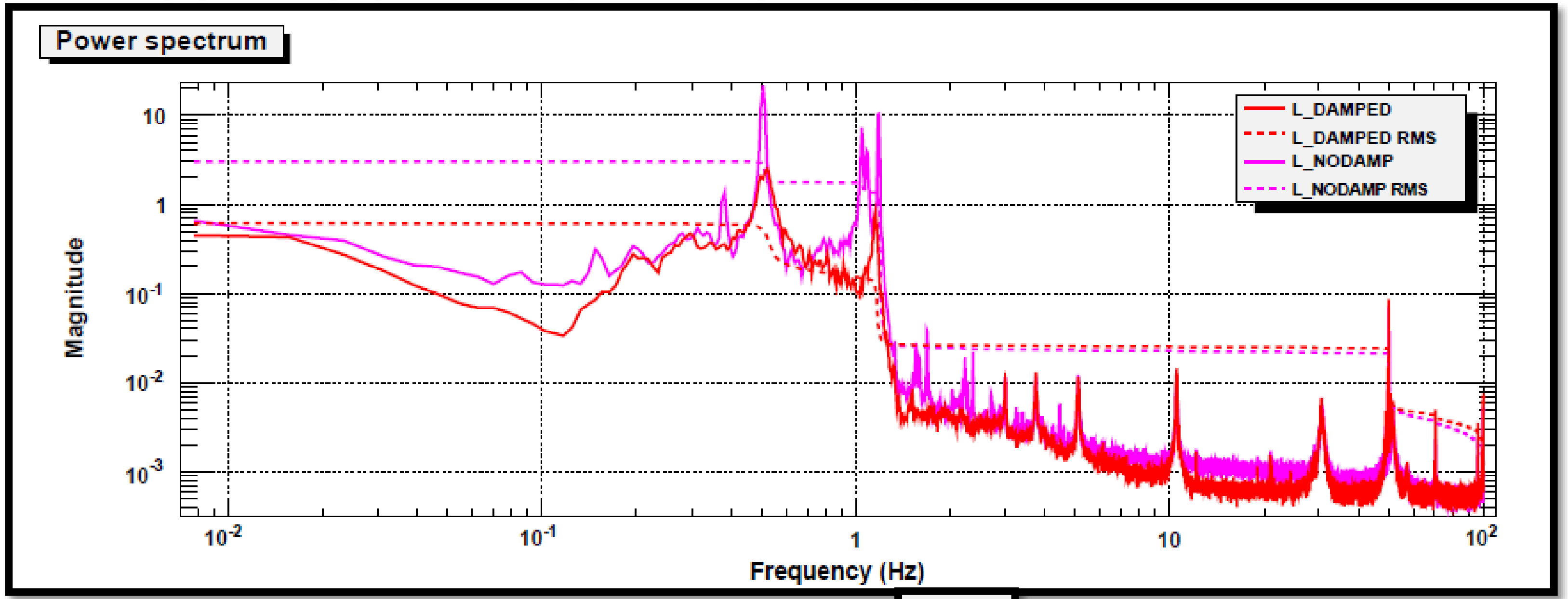
❖ Investigation of TypeBpp Frequency response

TM (OSEM) Spectrum

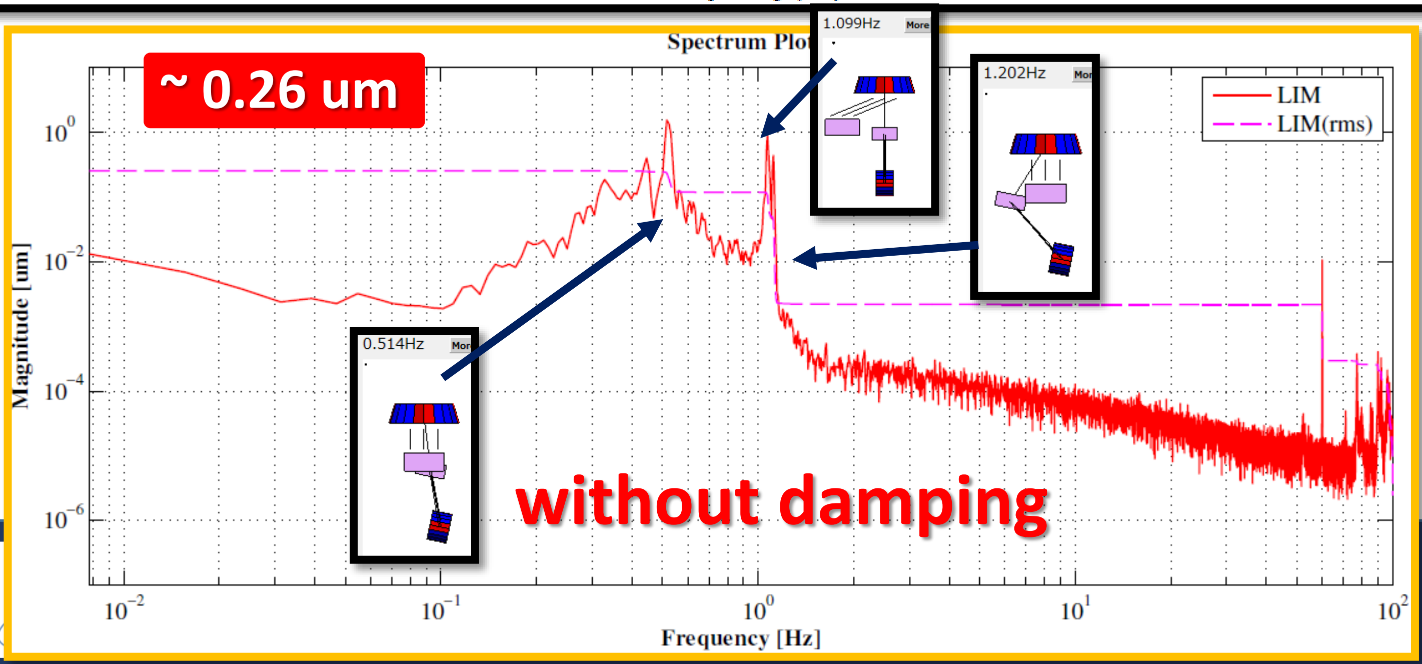


❖ Investigation of TypeBpp Frequency response

REF : LIM (OSEM) Spectrum of 20 m SAS

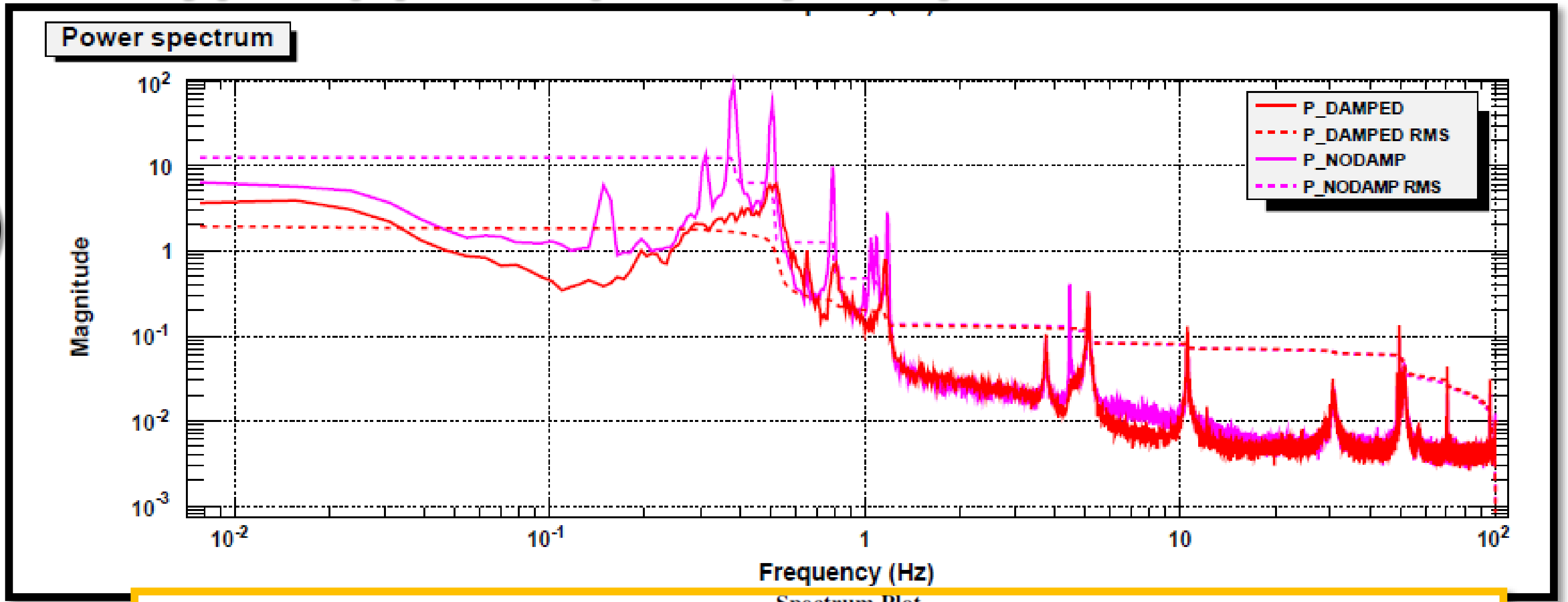


LIM (OSEM) Spectrum of PR3 SAS

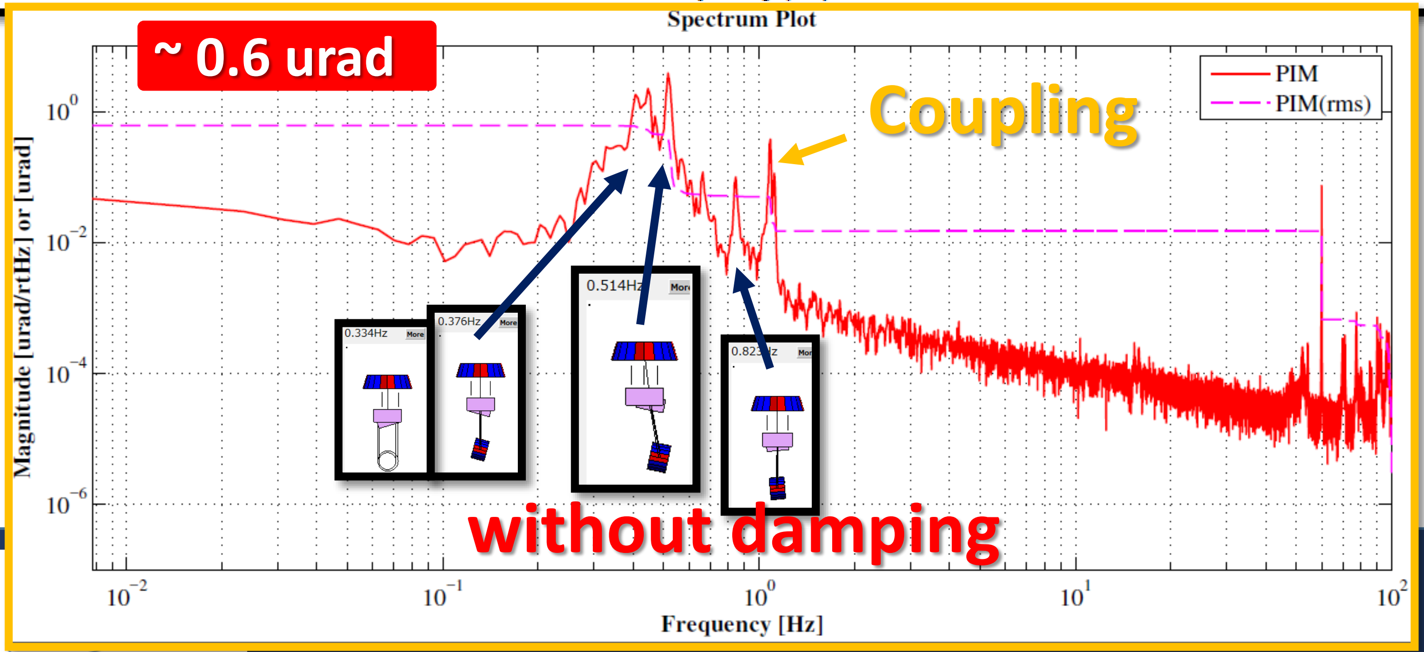


❖ Investigation of TypeBpp Frequency response

REF : PIM (OSEM) Spectrum of 20 m SAS



PIM (OSEM) Spectrum of PR3 SAS



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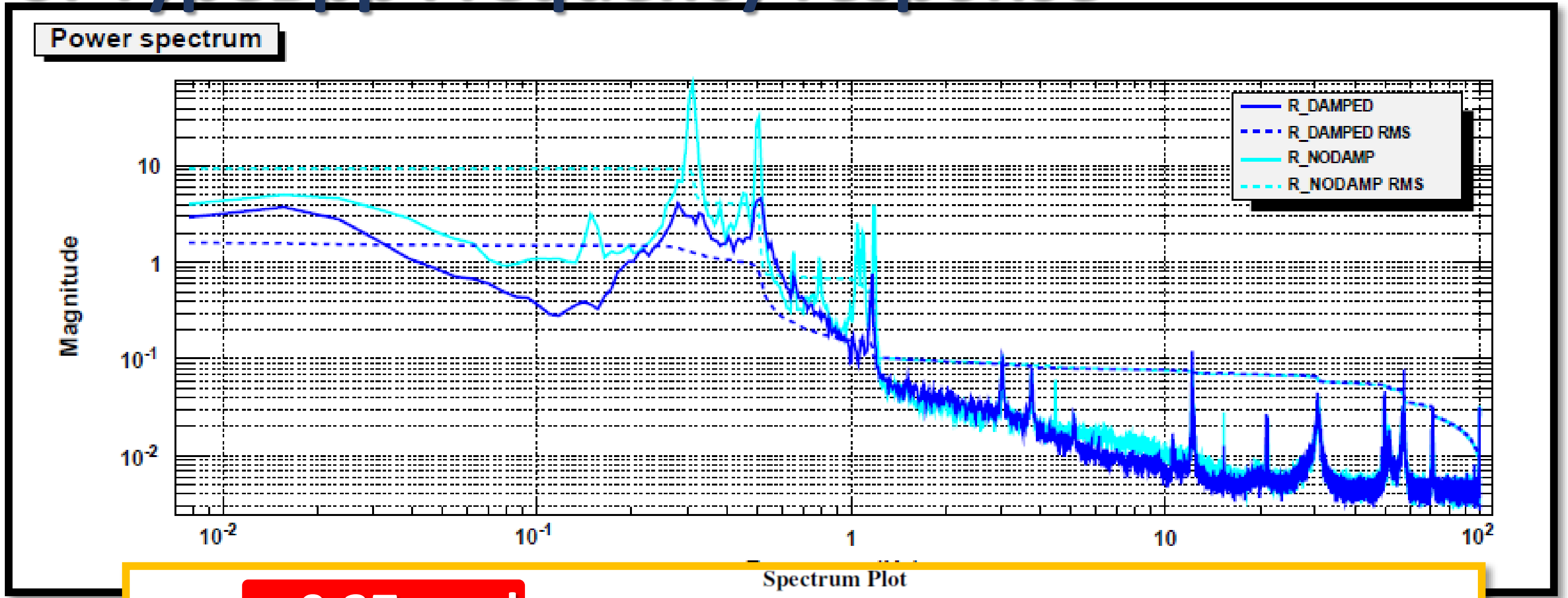
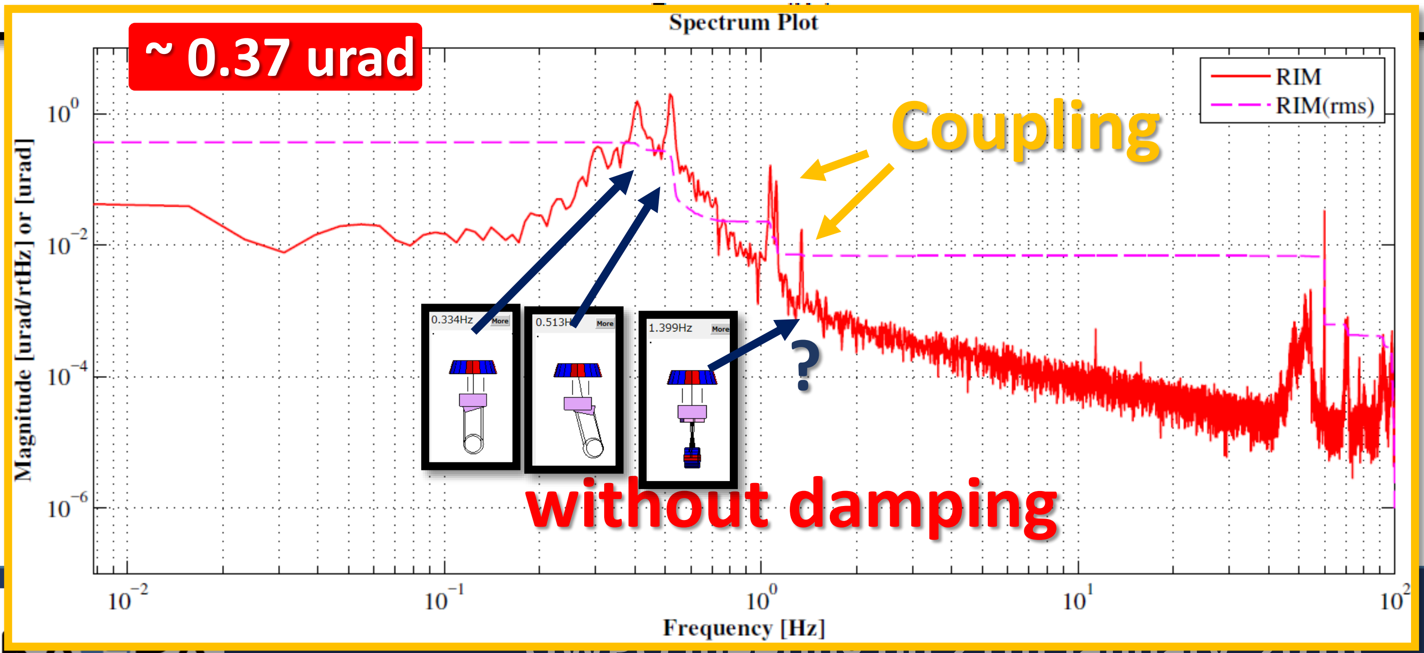
国立天文台 NAOJ National Astronomical Observatory of Japan

❖ Investigation of TypeBpp Frequency response

REF : RIM (OSEM) Spectrum of 20 m SAS

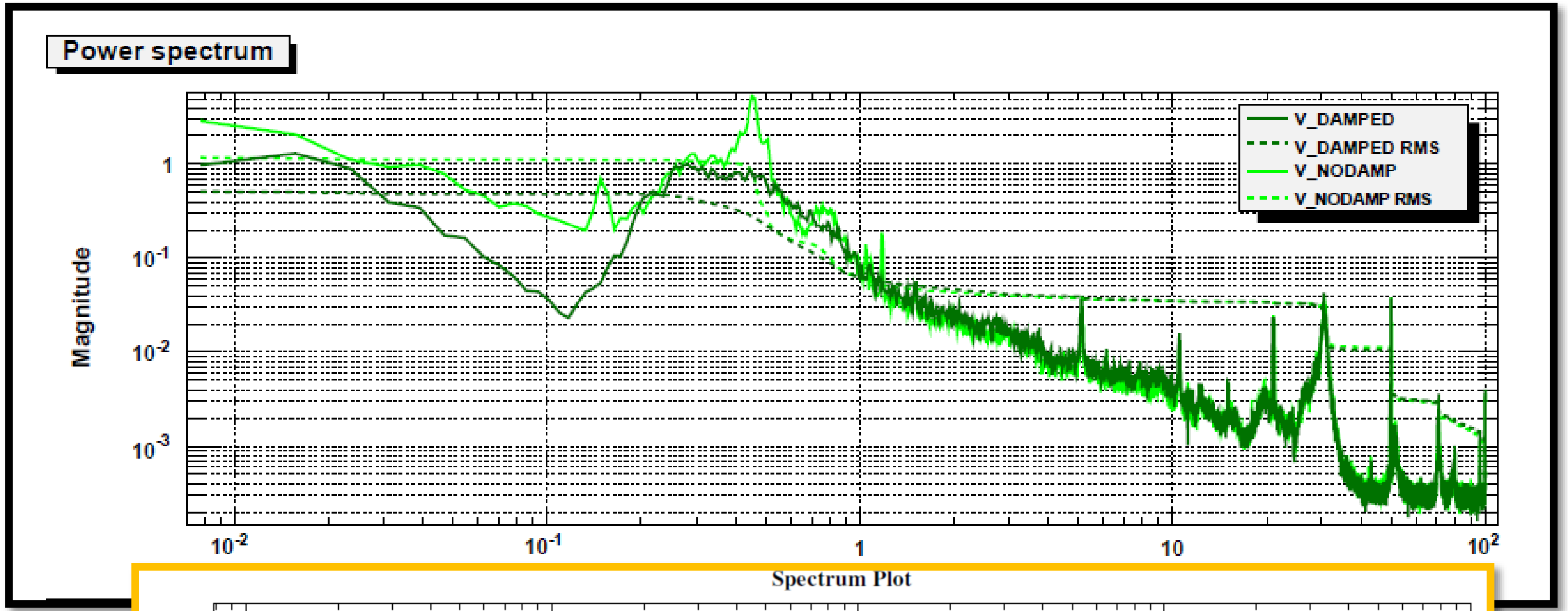


RIM (OSEM) Spectrum of PR3 SAS

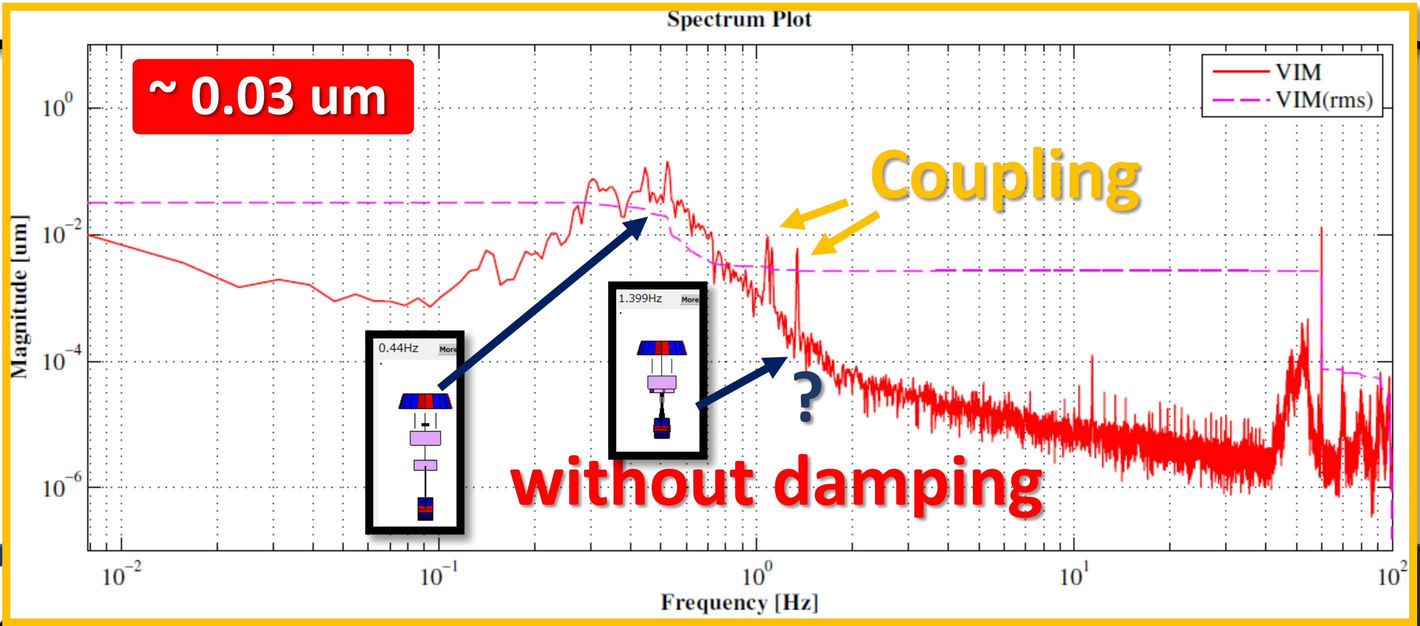


❖ Investigation of TypeBpp Frequency response

REF : VIM (OSEM) Spectrum of 20 m SAS

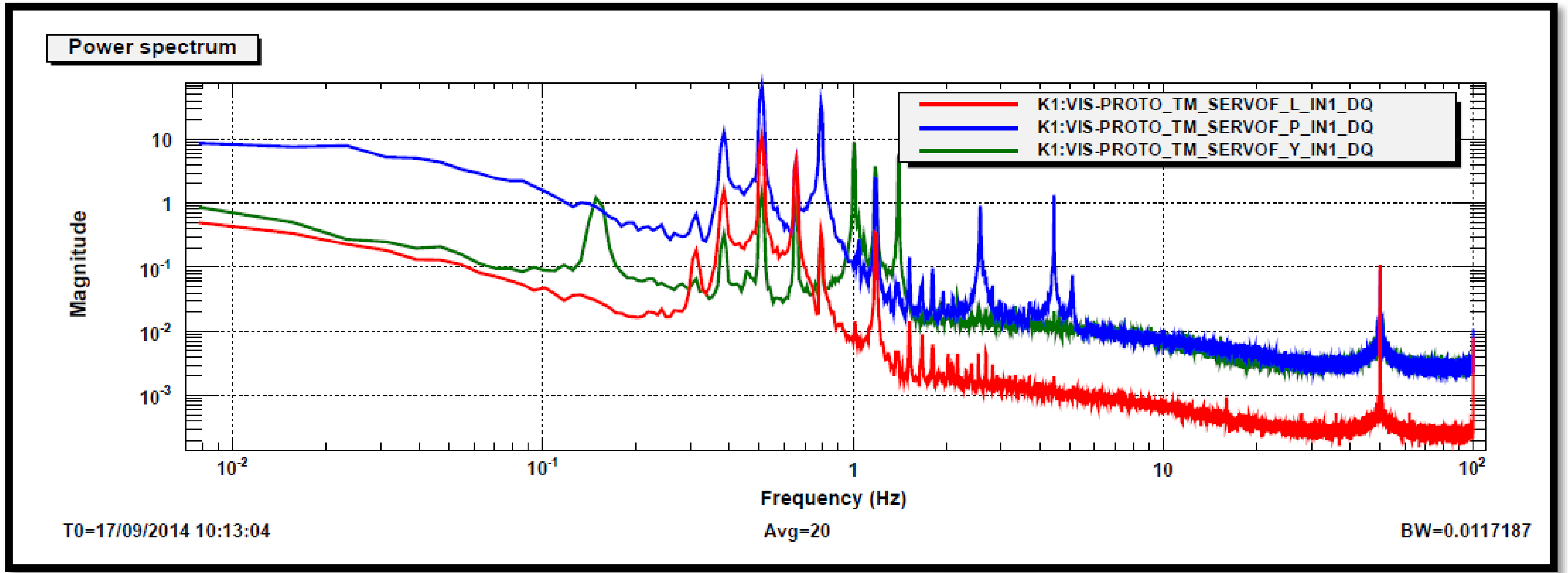


VIM (OSEM) Spectrum of PR3 SAS

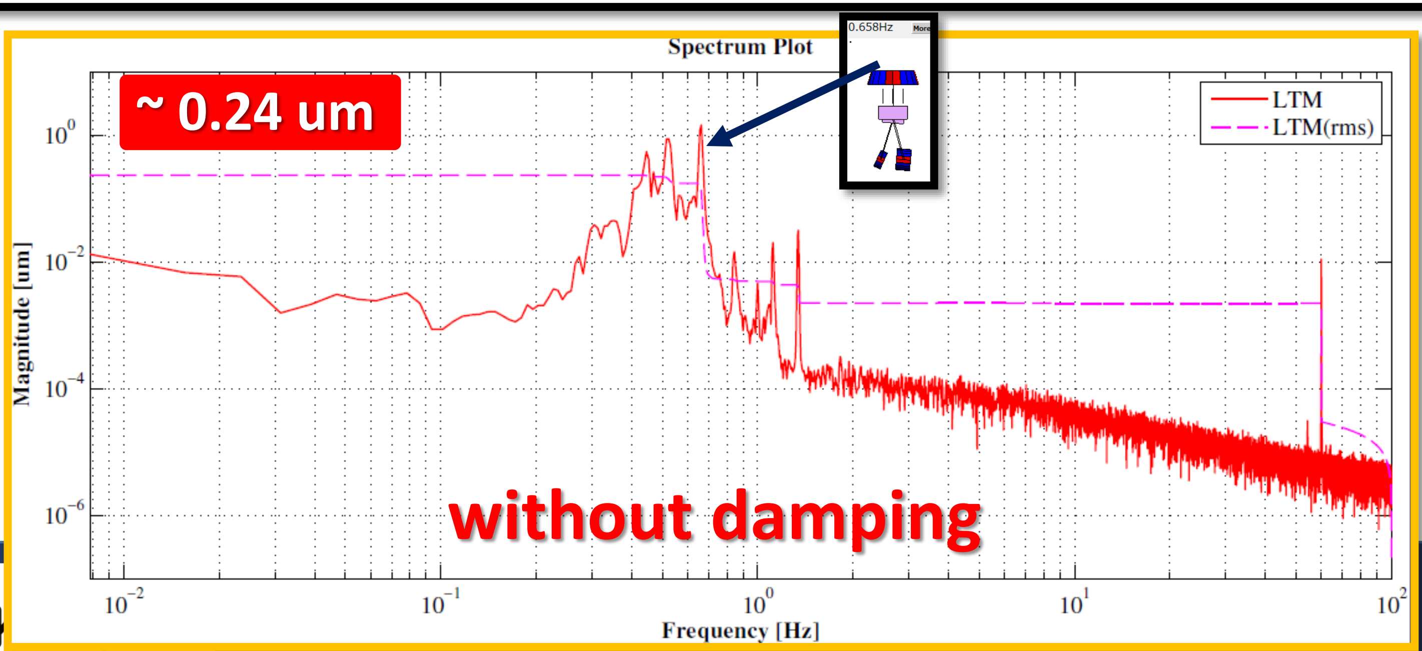


❖ Investigation of TypeBpp Frequency response

REF : TM (OSEM) Spectrum of 20 m SAS

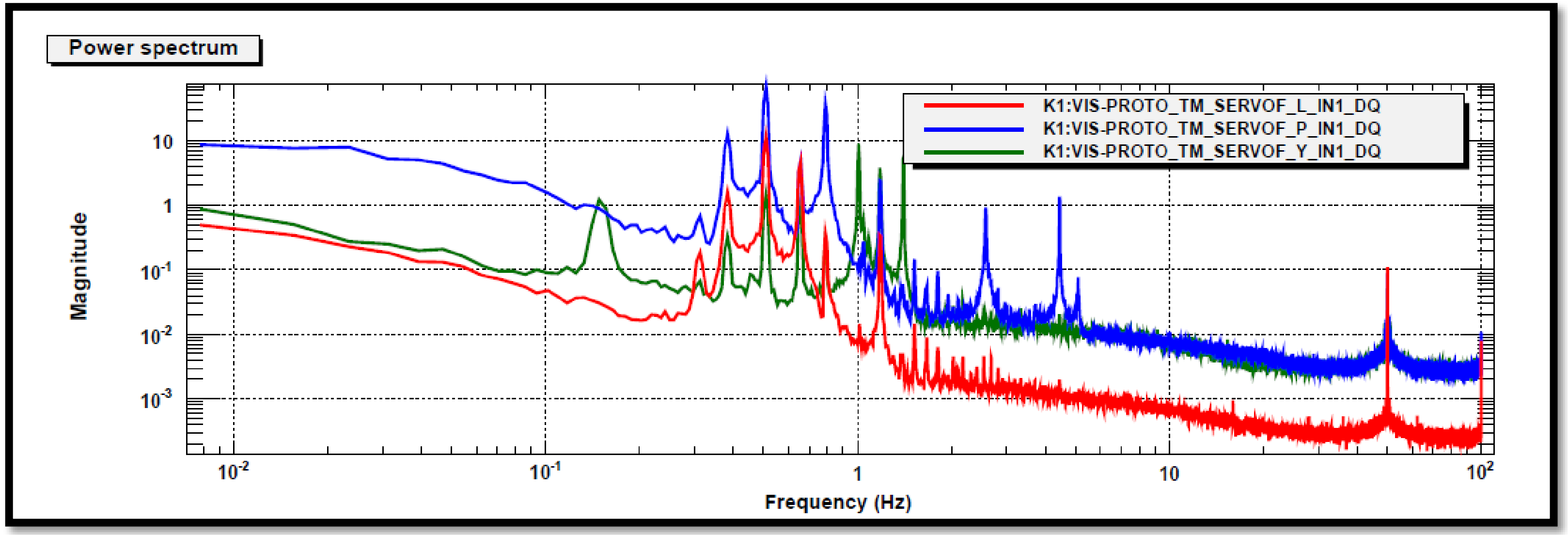


LTM (OSEM) Spectrum of PR3 SAS

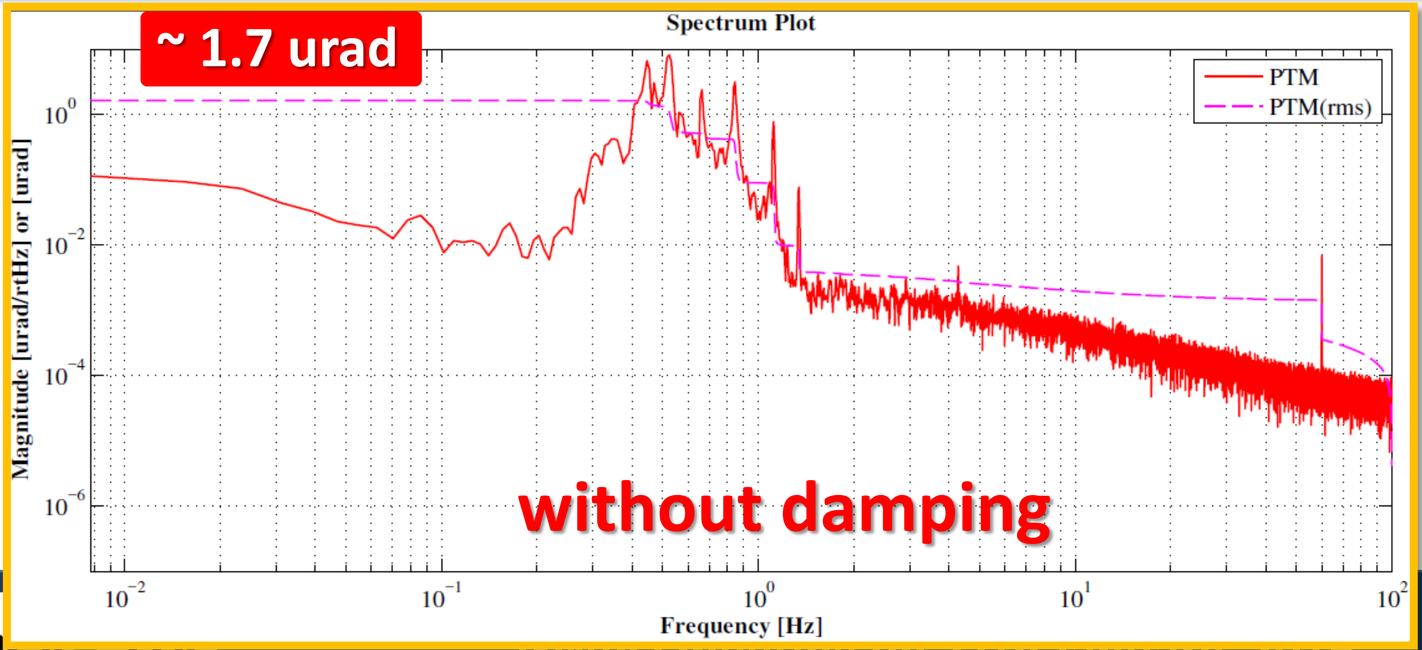


❖ Investigation of TypeBpp Frequency response

REF : TM (OSEM) Spectrum of 20 m SAS

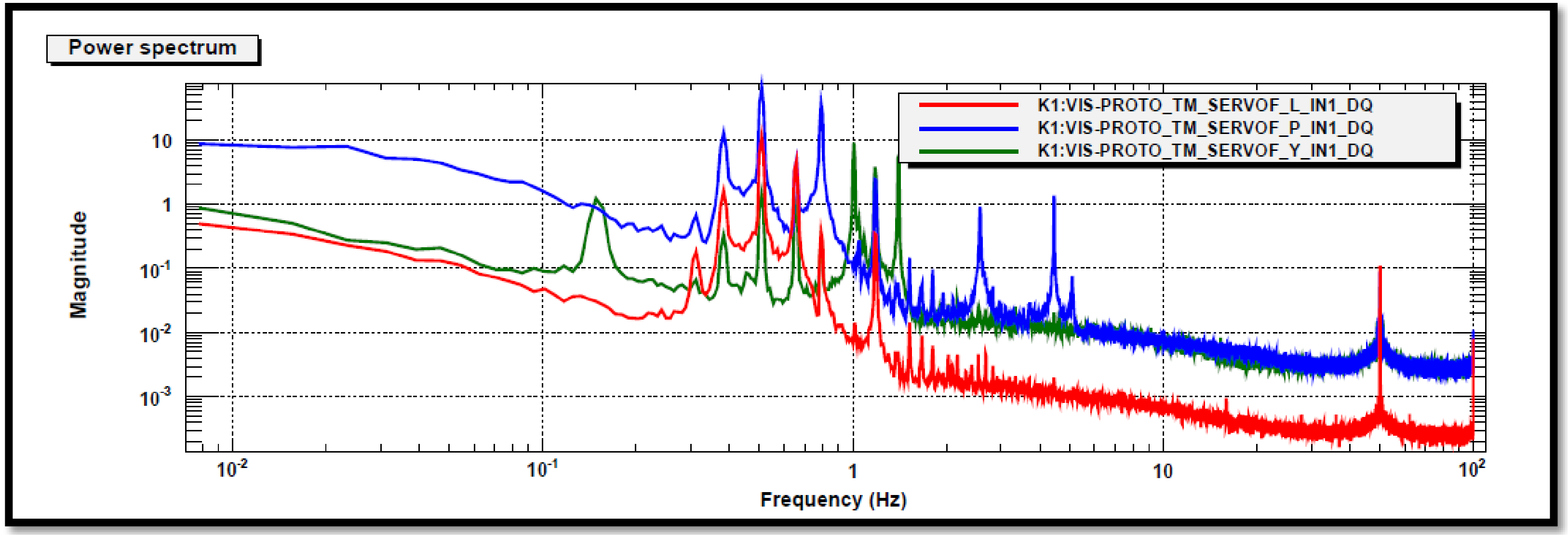


PTM (OSEM) Spectrum of PR3 SAS

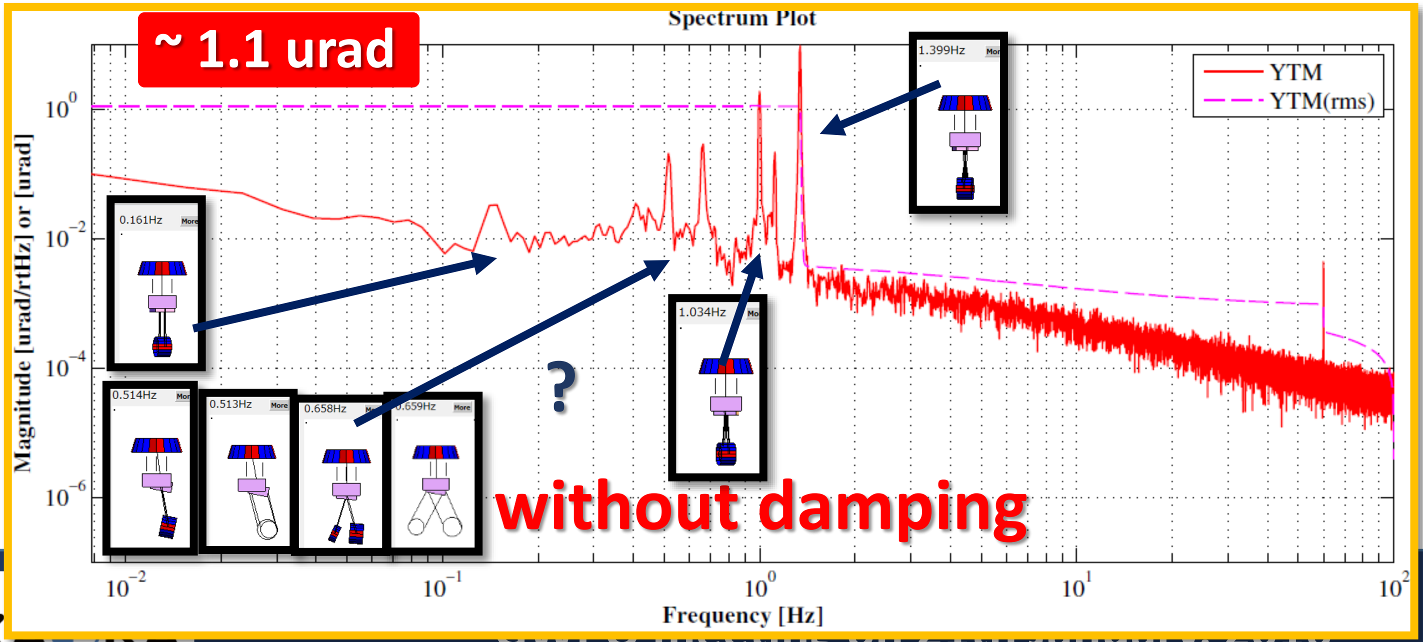


❖ Investigation of TypeBpp Frequency response

REF : TM (OSEM) Spectrum of 20 m SAS

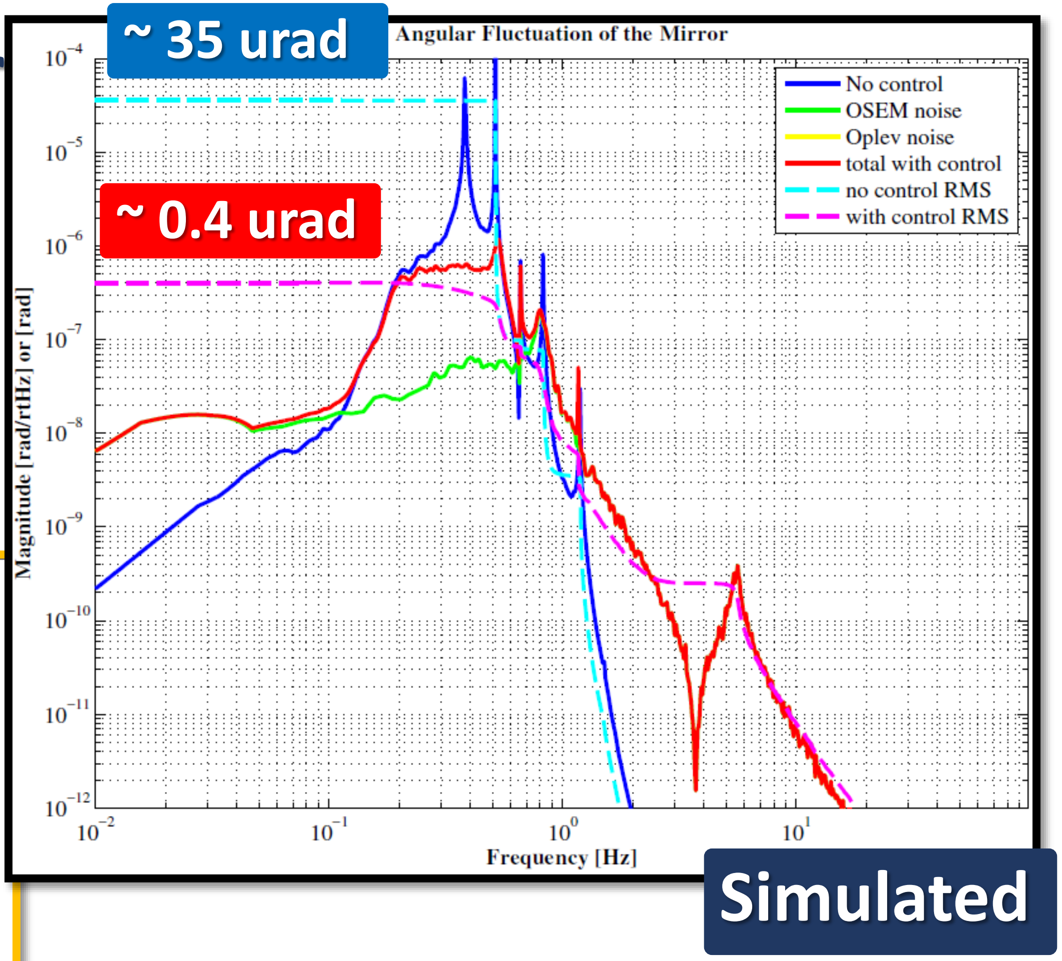


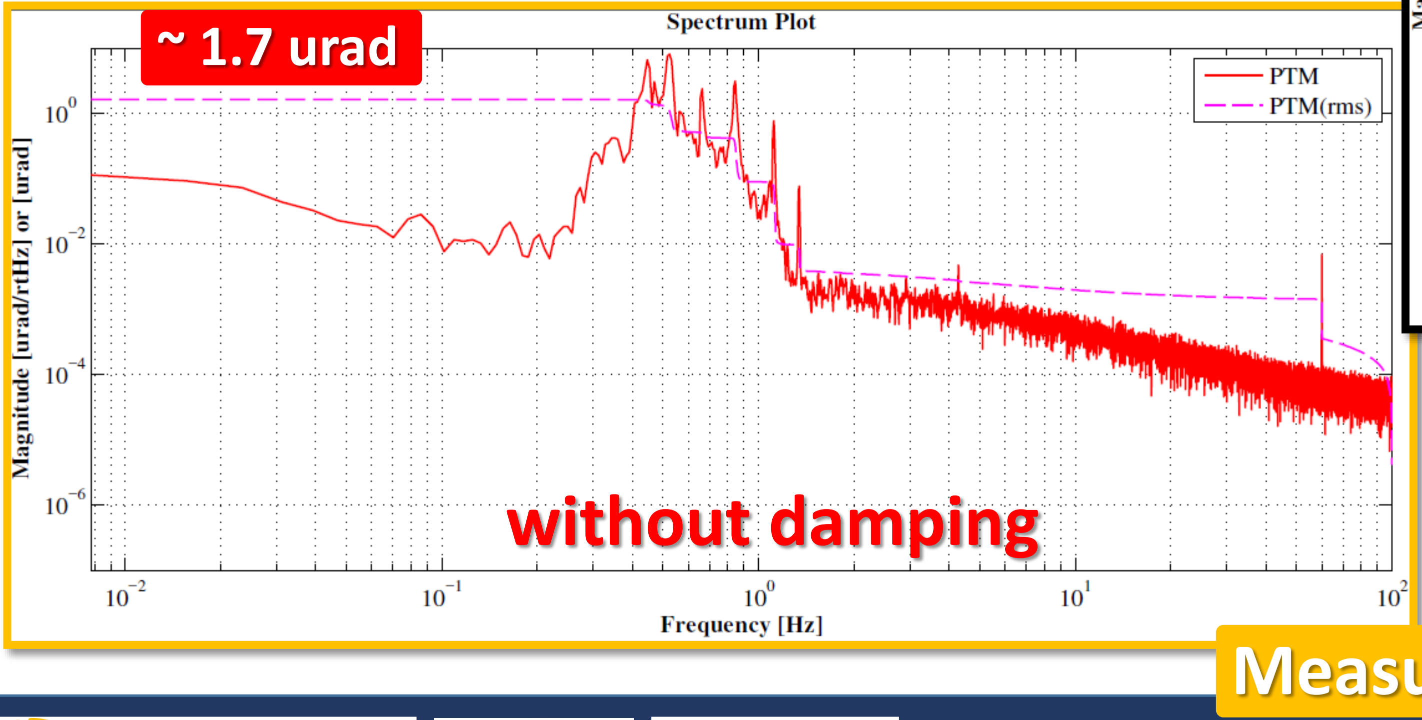
YTM (OSEM) Spectrum of PR3 SAS



❖ Investigation of TypeBpp Frequency r

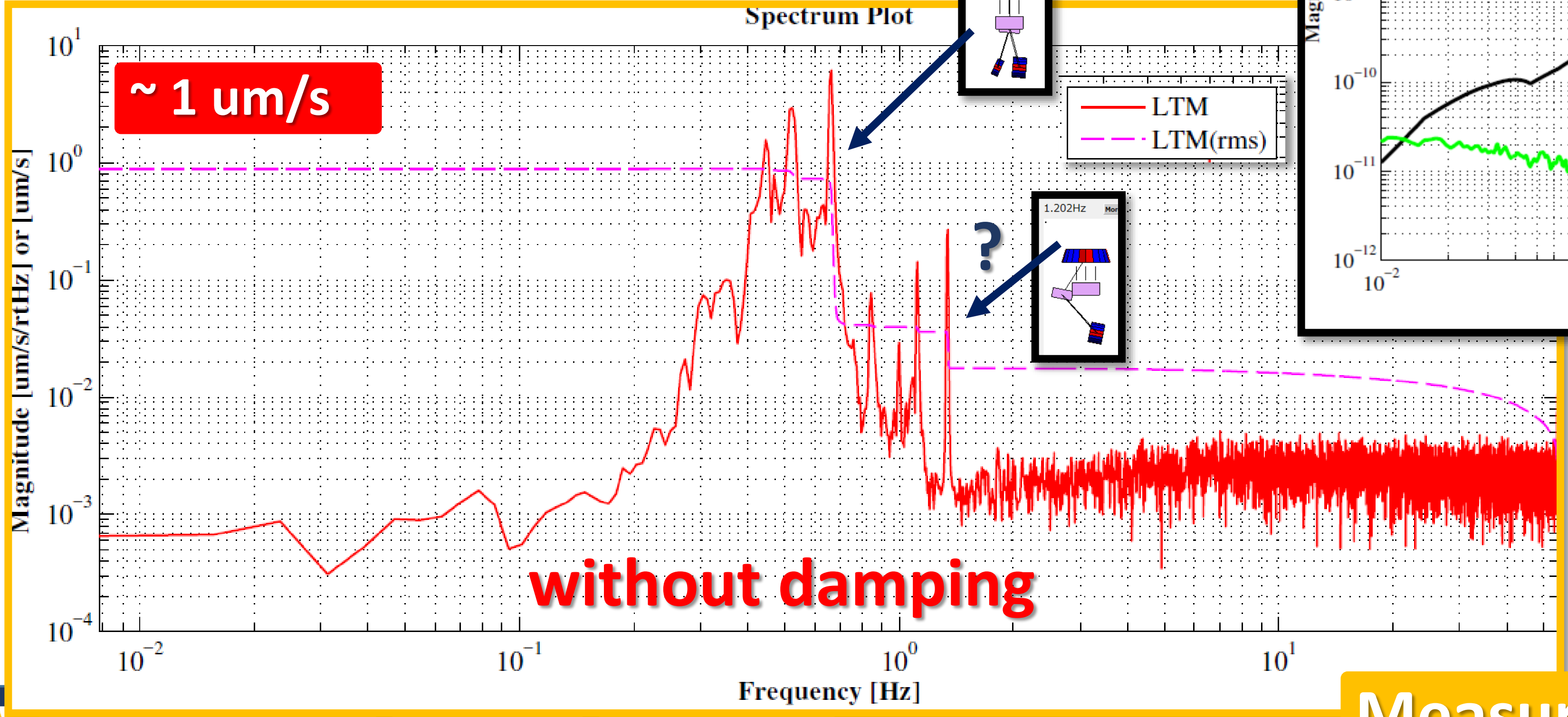
PTM (OSEM)
Spectrum of PR3 SAS



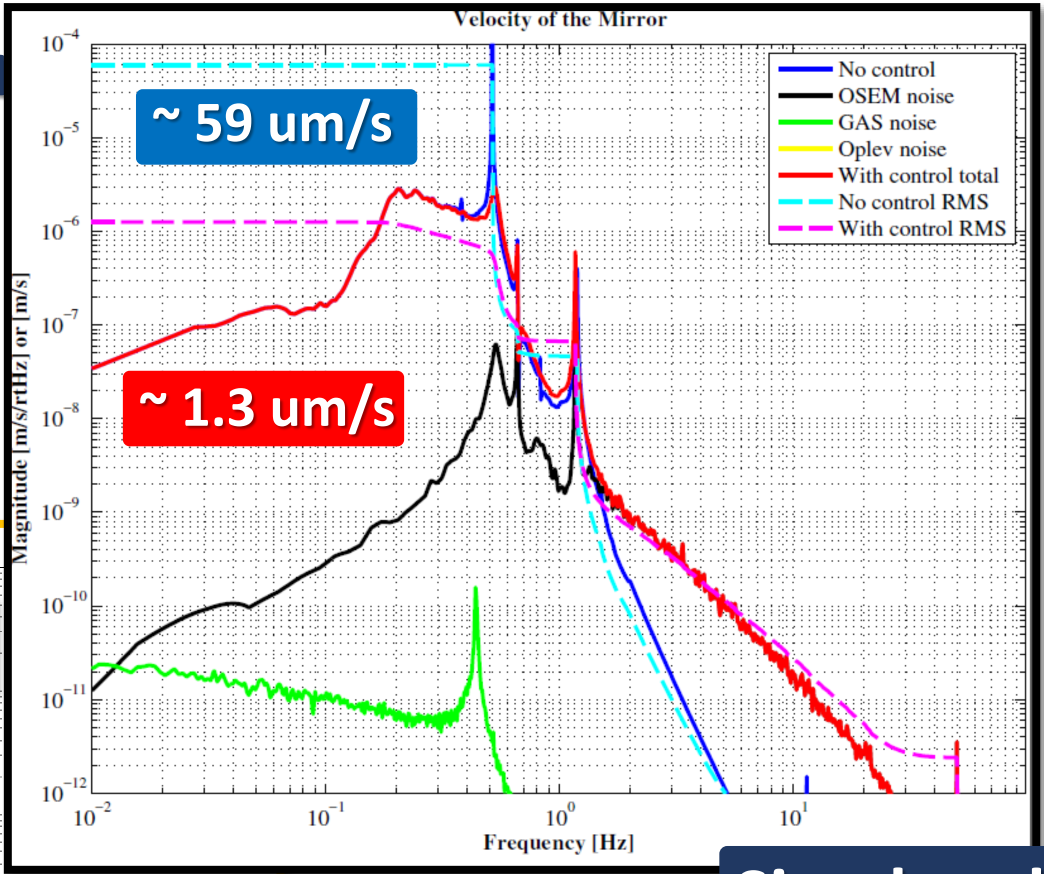


❖ Investigation of TypeBpp Frequency r

LTM velocity (OSEM)
Spectrum of PR3 SAS



Measured



Simulated

❖ Investigation of TypeBpp Frequency response

Spectrum (measured in the chamber)

- The difference in factor can be occurred due to rough calibration.
- LTM peak at around 1.3 Hz ?
-
-
-

❖ Investigation of TypeBpp Frequency response

- Mostly, measured frequency responses follow their predictions.

- Quality factors of mechanical resonances seem to be small.
  → Quality factors (decay time, etc) should be investigated more in detail.

Contents

- ❒ Intro : PR SAS
  - ❒ TypeBp / TypeBpp
- ❒ Investigation of TypeBpp SAS frequency response
  - ❒ Transfer functions / Spectrums
- ❖ One modification idea for bKAGRA
  - ❖ Requirement
  - ❖ TypeBp with IP

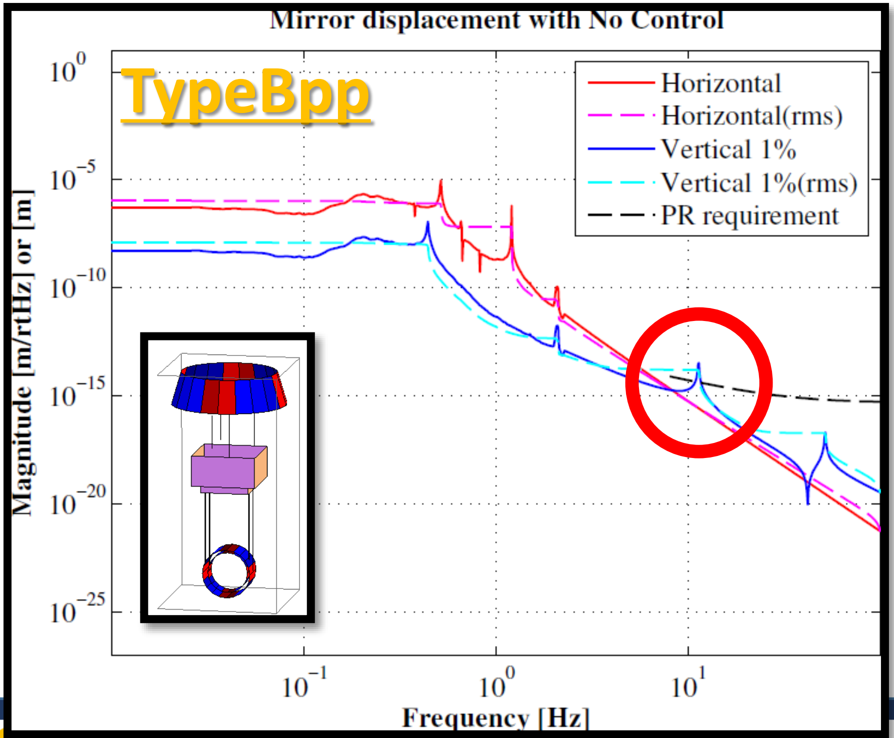
❖ One modification idea for bKAGRA / Requirement

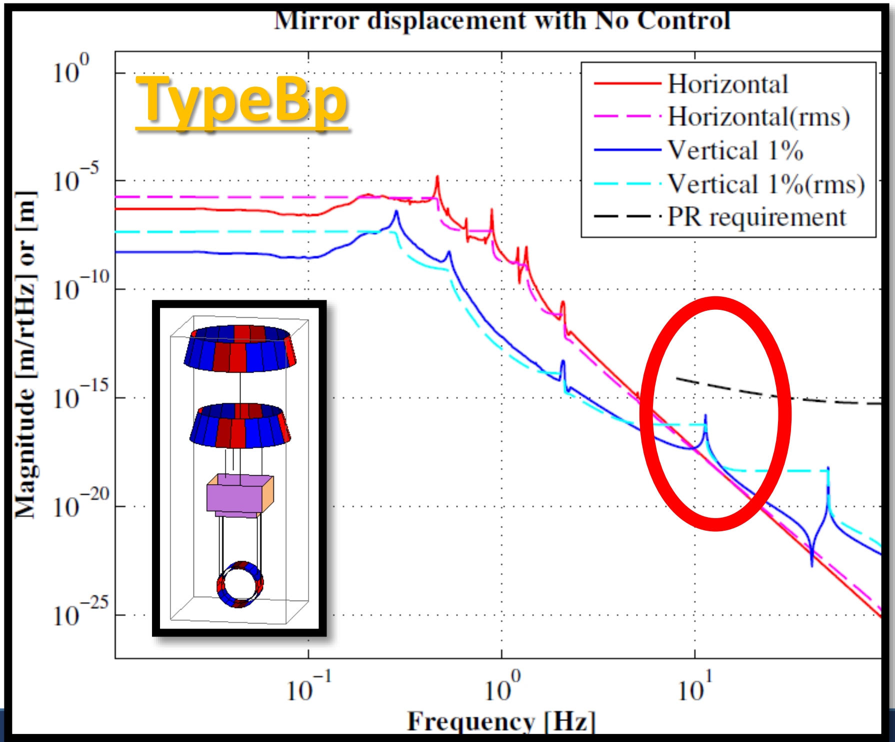
PR TMs are required :

1) disp. < 10^{-15} m/rtHz at 10 Hz
2) RMS velocity < 0.5 um/s
3) RMS angular fluct. < 1 urad

TypeBpp	TypeBp
Not meet	meet
~ 1 um/sec (with ctrl)	~ 5 um/sec (with ctrl)
~ 0.4 urad (with ctrl)	~ 1.4 urad (w ctrl)

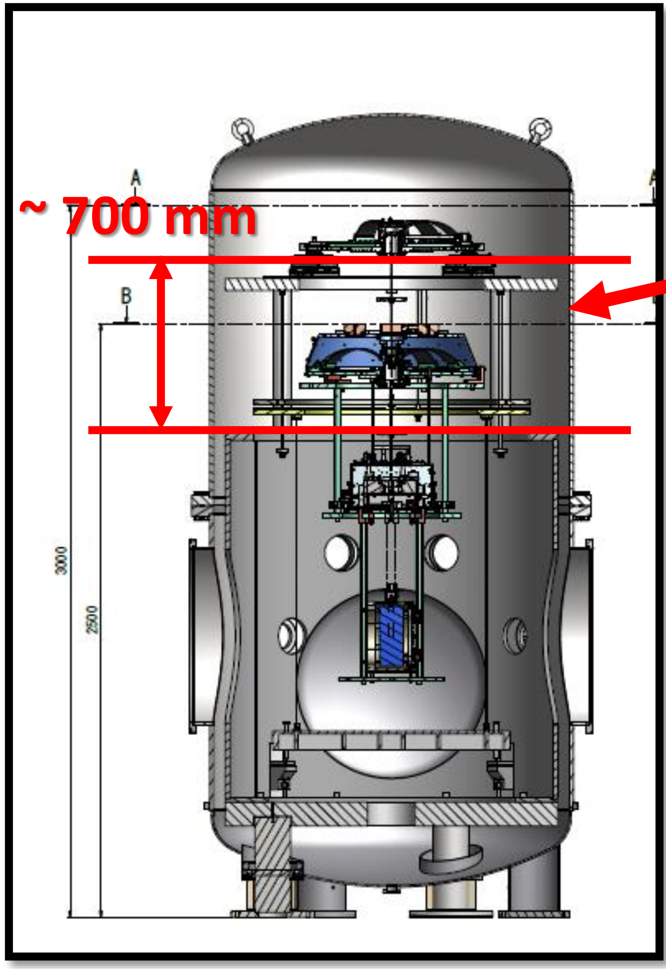
Also, RMS seismic velocity can be ~ 0.7 um/sec

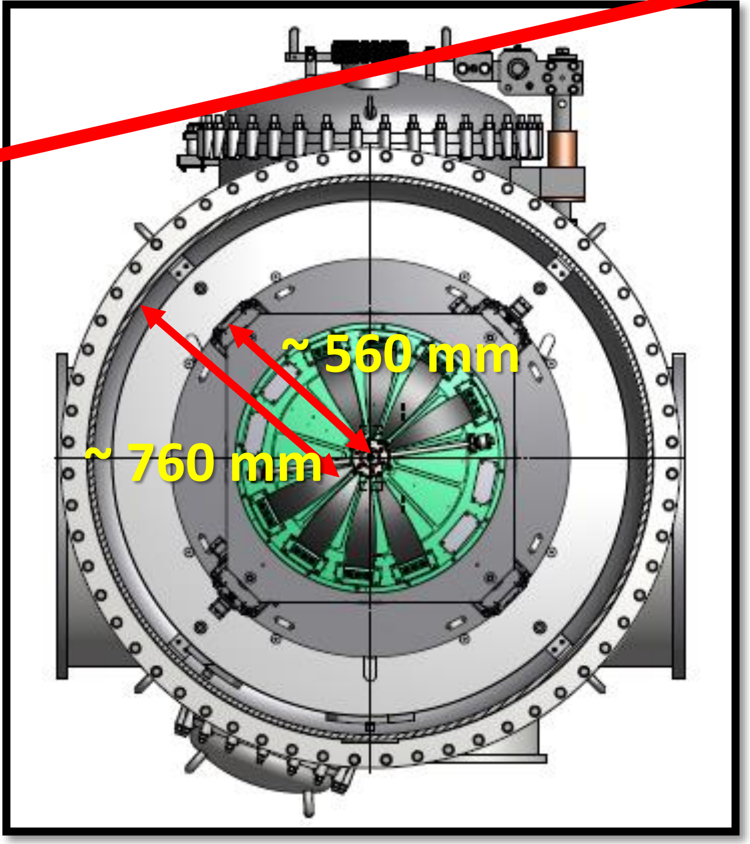


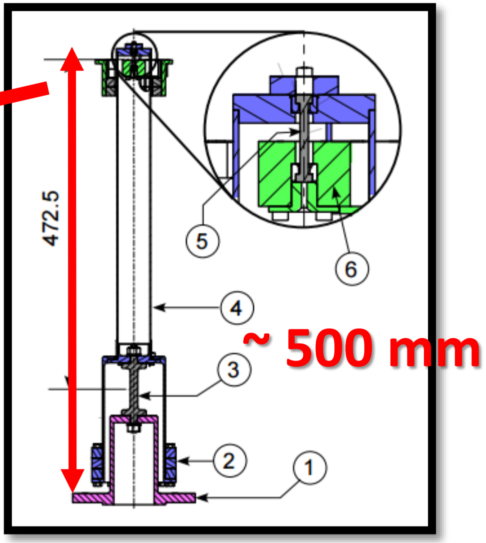


❖ One modification idea for bKAGRA / TypeBp with IP

To attenuate the micro seismic noise → Add Inverted Pendulum (IP)





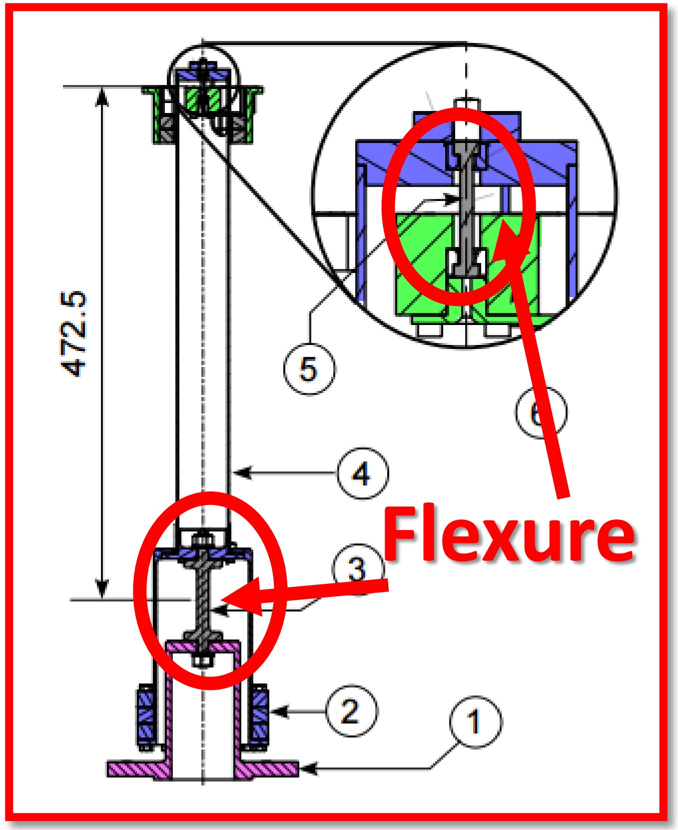


In principle,

the IP, such as used in TypeB1,
(its length is ~ 500 mm)
will be able to be implemented.

❖ One modification idea for bKAGRA / TypeBp with IP

IP modeling parameter :



1) Load on IP
2) Horizontal distance of leg from CoM
3) Leg length
4) L,T resonant frequency (→ depends on bottom flexure)
5) Q factor of bottom flexure
6) Saturation level
7) Additional torsion stiffness (→ depends on top flexure)

Contributes to IP Yaw

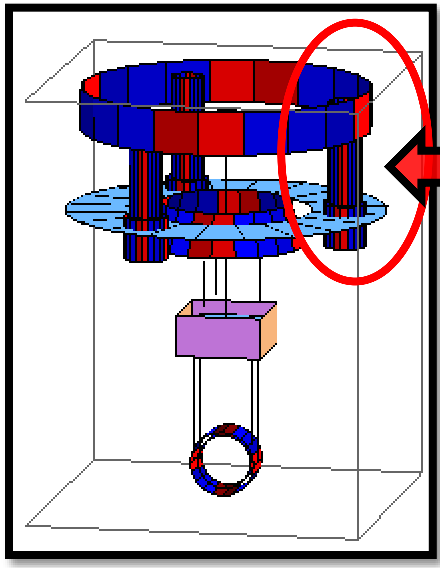
Note

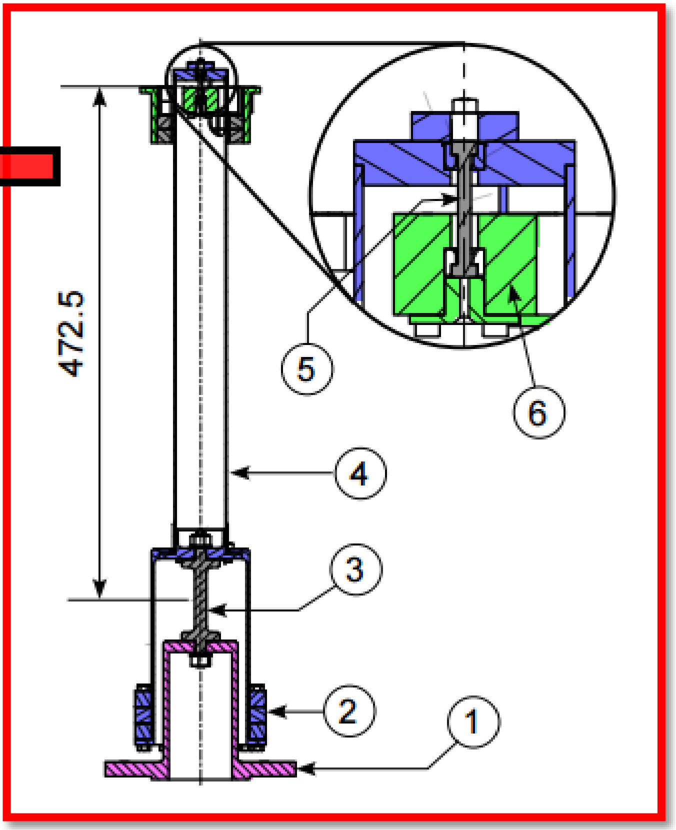
❒ If the TypeB1 IP will be implemented,
Load have to be added more (~ 500 kg) to current TypeBp.

❒ Or, we should re-design the flexure (and also the weight).

❖ One modification idea for bKAGRA / TypeBp with IP

To attenuate the micro seismic noise → Add Inverted Pendulum (IP)



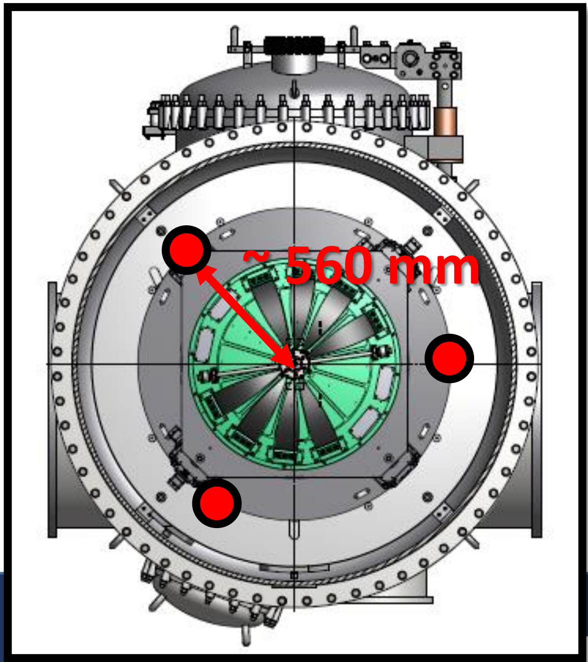


typeB1 IP

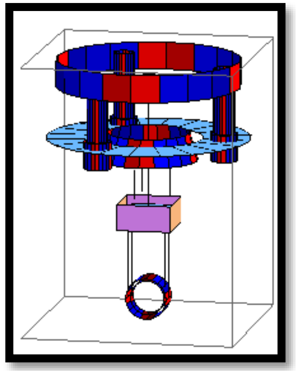
This time, I added "typeB1 IP" to typeBp.
assuming,

1) **with adding weight of 572 kg**
2) **Set IP at position of 560 mm from the CoM**

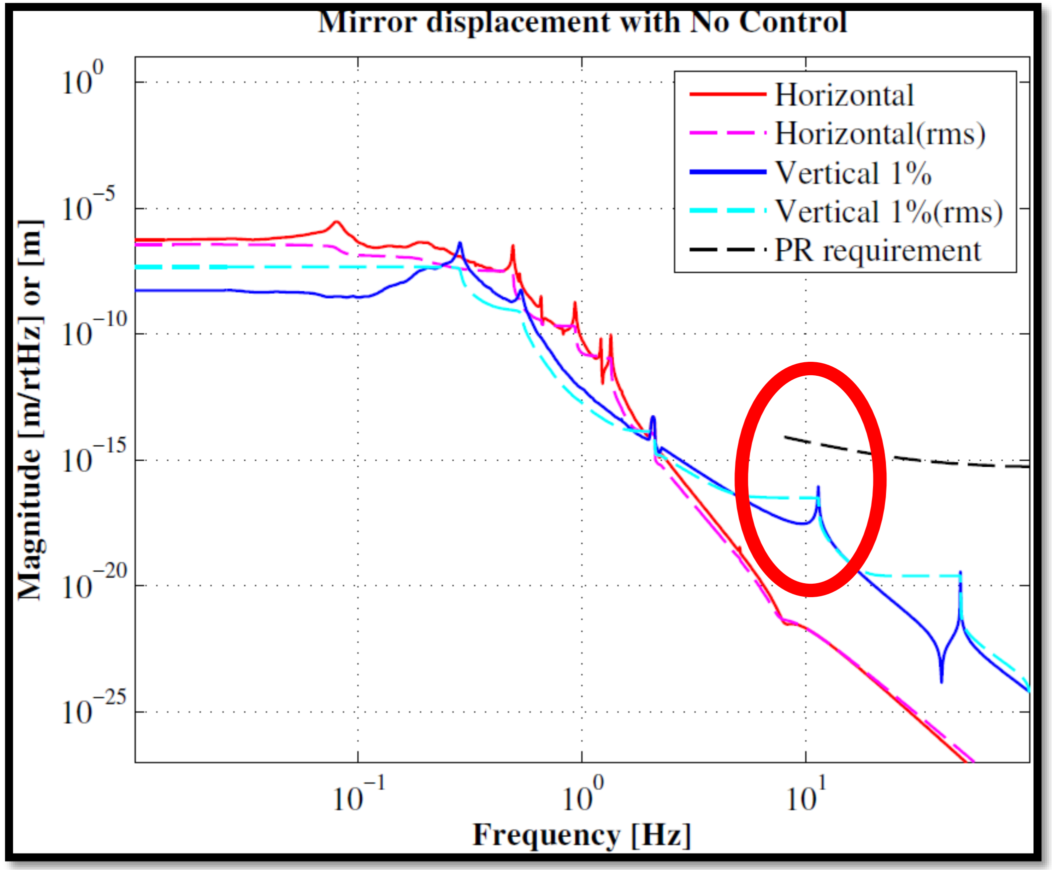
(In TypeB1 -> 610 mm)



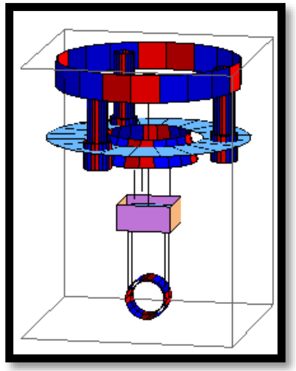
❖ One modification idea for bKAGRA / TypeBp with IP



= IP + SF + BF + IR/IM + RM/TM

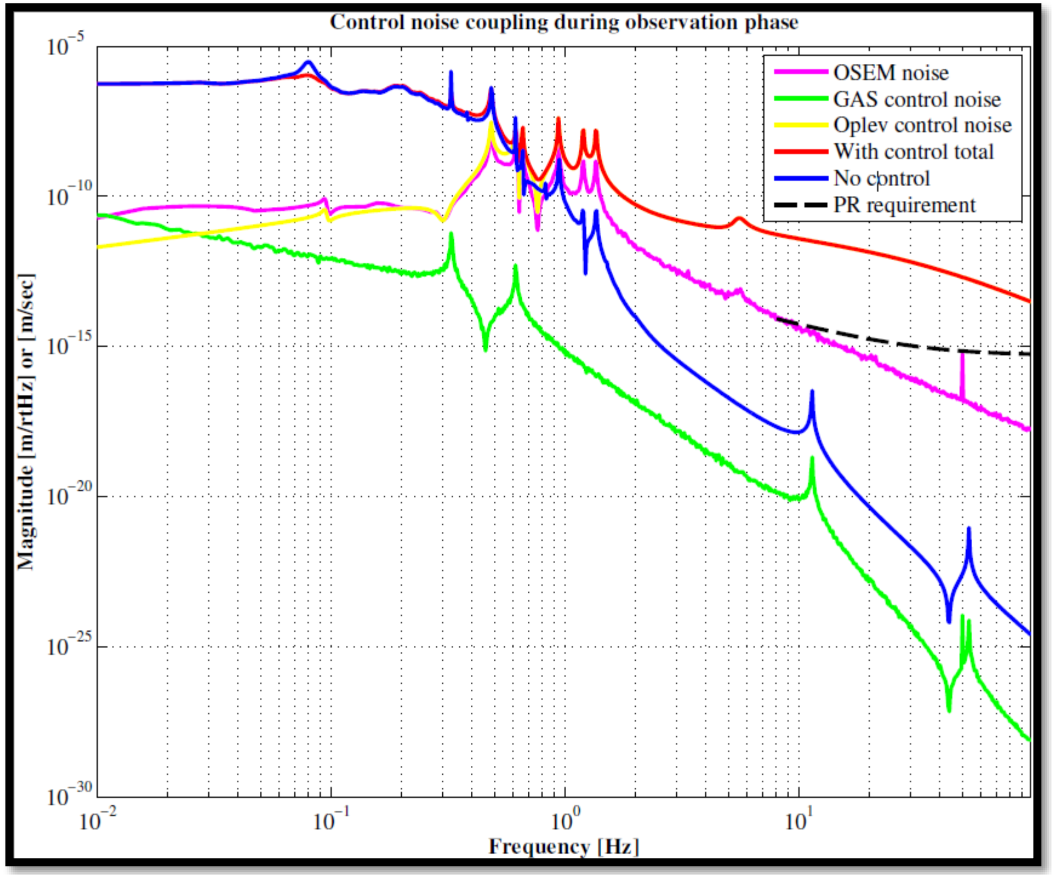


❖ One modification idea for bKAGRA / TypeBp with IP

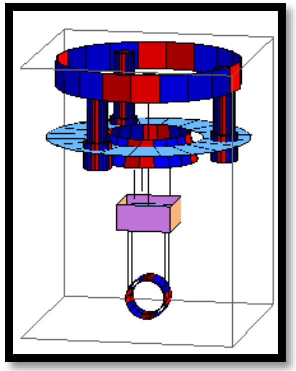


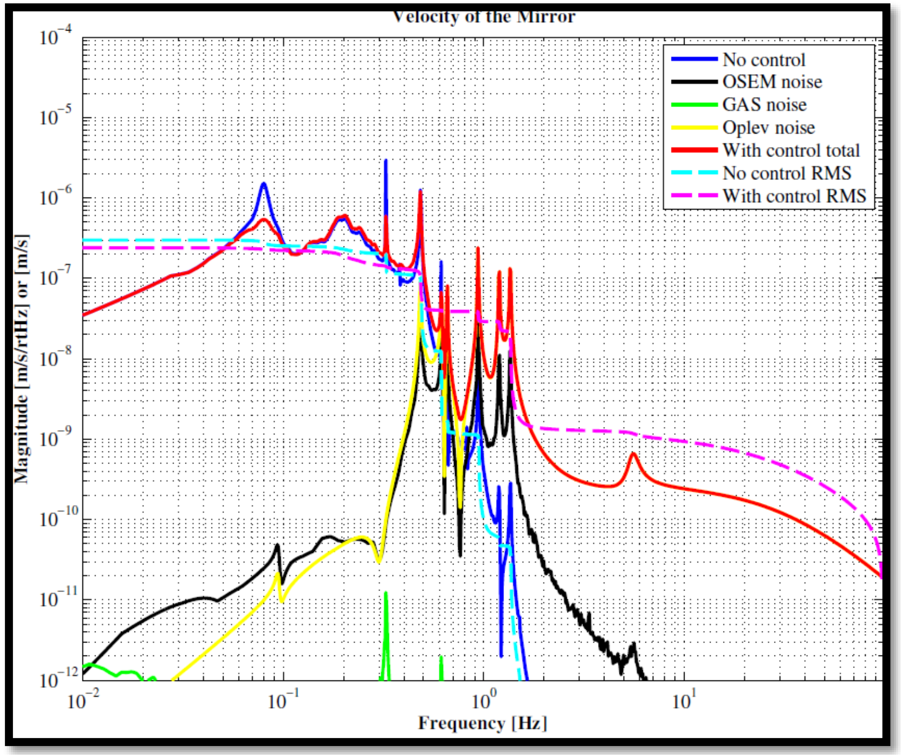
= IP + SF + BF + IR/IM + RM/TM

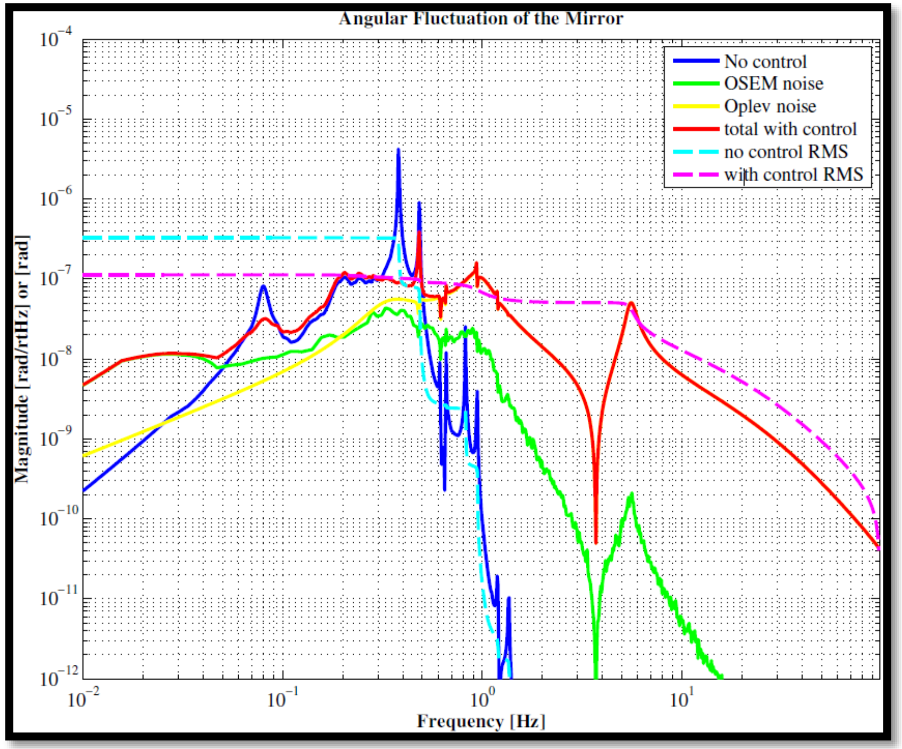
IP	SF	BF	IR/IM	RM/TM
Damping by LVDT	Dc Damp By LVDT		Damping by OSEMs & Oplev	Damping by OSEMs



❖ One modification idea for bKAGRA / TypeBp with IP







RMS velocity ~ 0.24um/sec

RMS pitch ~ 0.11 urad

This SAS seems to meet all the three PR SAS requirements.

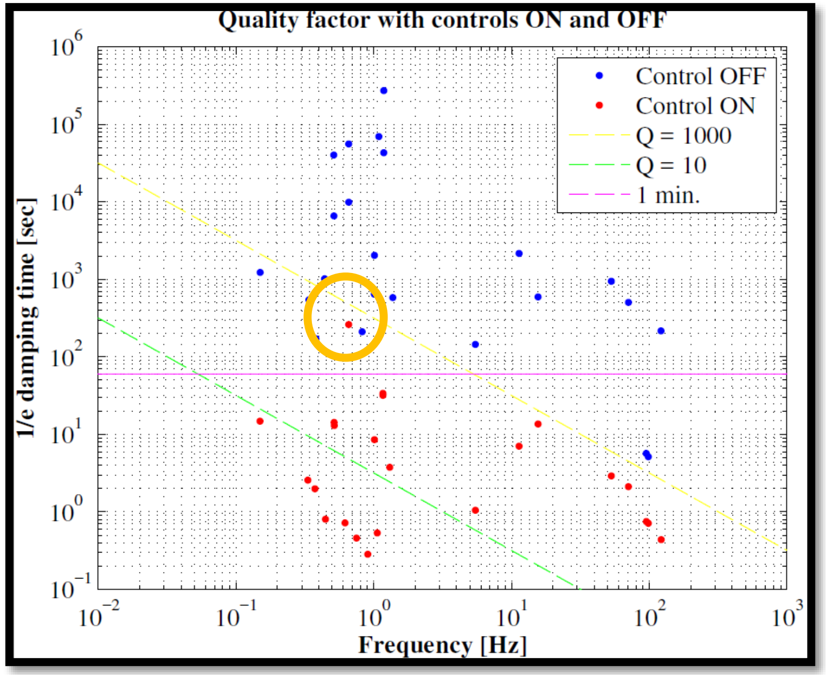
If geophones are added, the RMS can be reduce.

❖ One modification idea for bKAGRA

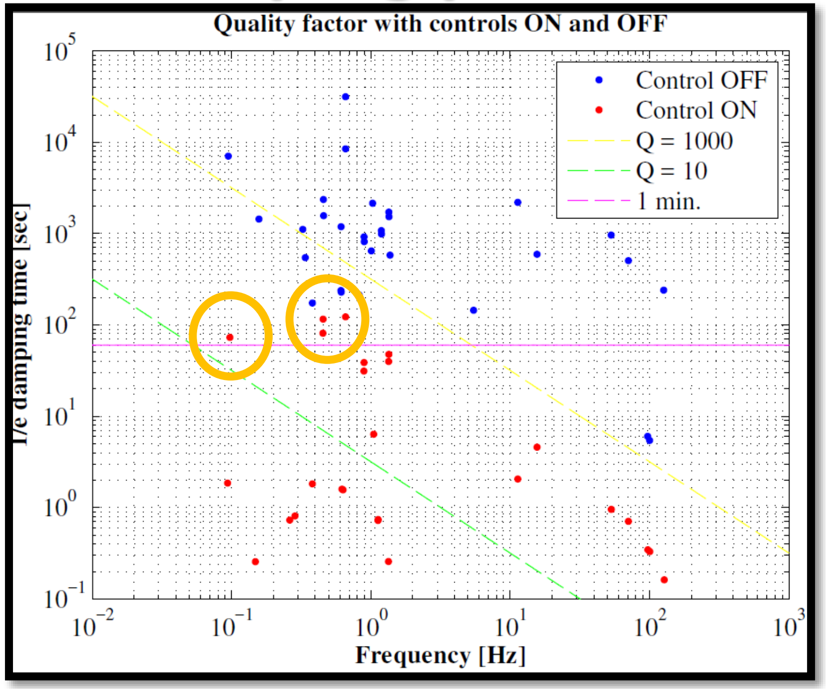
In addition,
Damping performance in damping phase

PR TMs are required :

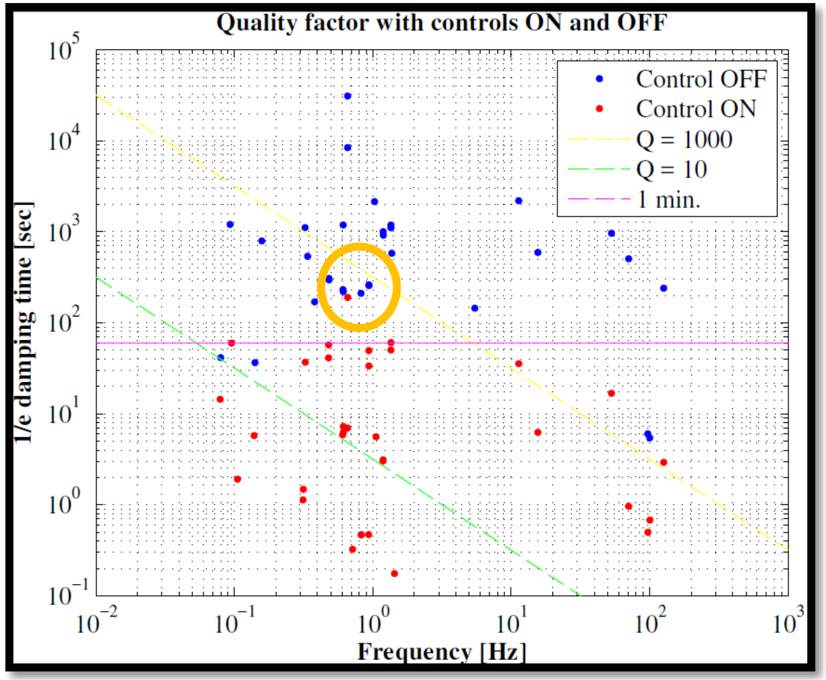
1/e damping time < 1 min.



TypeBpp



TypeBp



TypeBp with IP

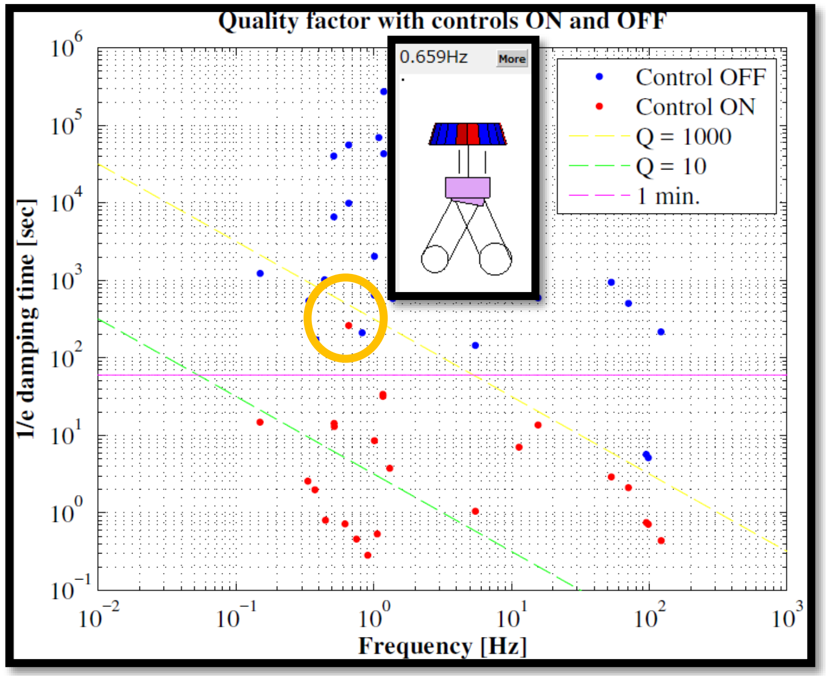
❖ One modification idea for bKAGRA

In addition,

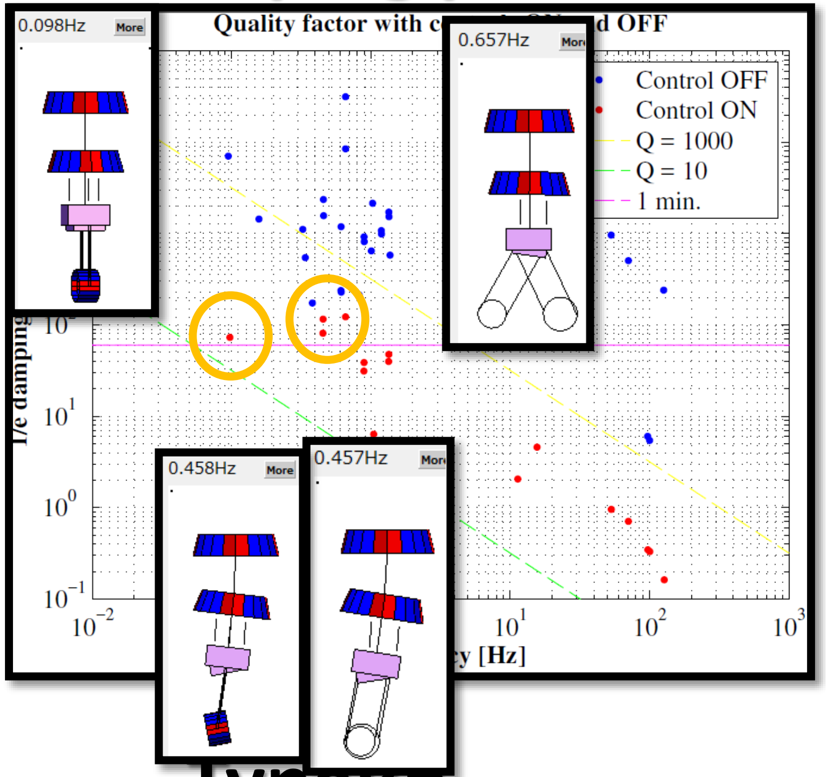
Damping performance in damping phase

PR TMs are required :

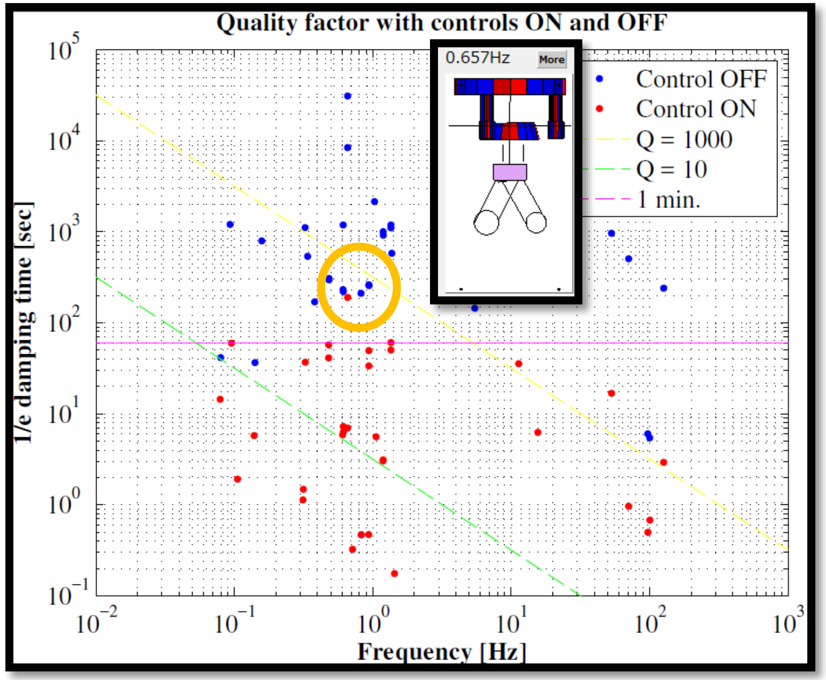
1/e damping time < 1 min.



TypeBpp



TypeBp



TypeBp with IP

❖ Summary

- ❒ TypeBpp SAS frequency responses are investigated.
  → Mostly, the responses follow their predictions.
  (RM Pitch problem is still remains.)
  → Quality factors should be investigated more in detail.

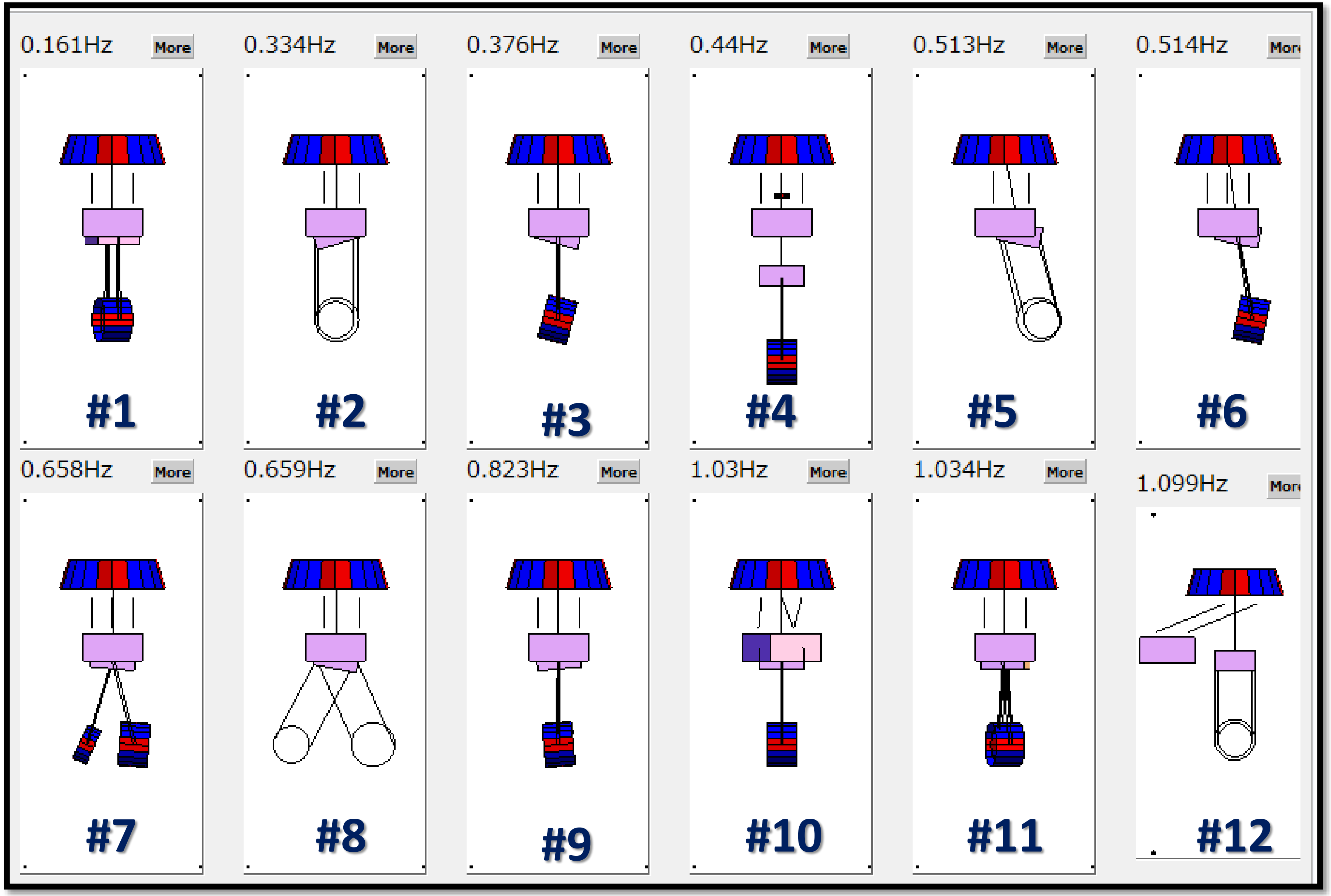
- ❒ We have to modify the current TypeBp SAS.
  → If TypeB IP is implemented to the current TypeBp SAS, the SAS can meet the PR SAS requirements.

Thank you for your attention.

Back up

Eigen Mode Shape

TypeBpp



#1 : YPen
YIM, YRM, YTM

#2 : RPen
RIM, RRM, RTM

#3 : PTM
PIM, -PRM, -PTM

#4 : VPen
VIM, VRM, VTM

#5 : TPen
Pendulum

#6 : LPen
Pendulum

#7 : PTM
LTM, -PTM

#8 : TTM,-RM
TM, -TRM, etc

#9 : PTM
PTM

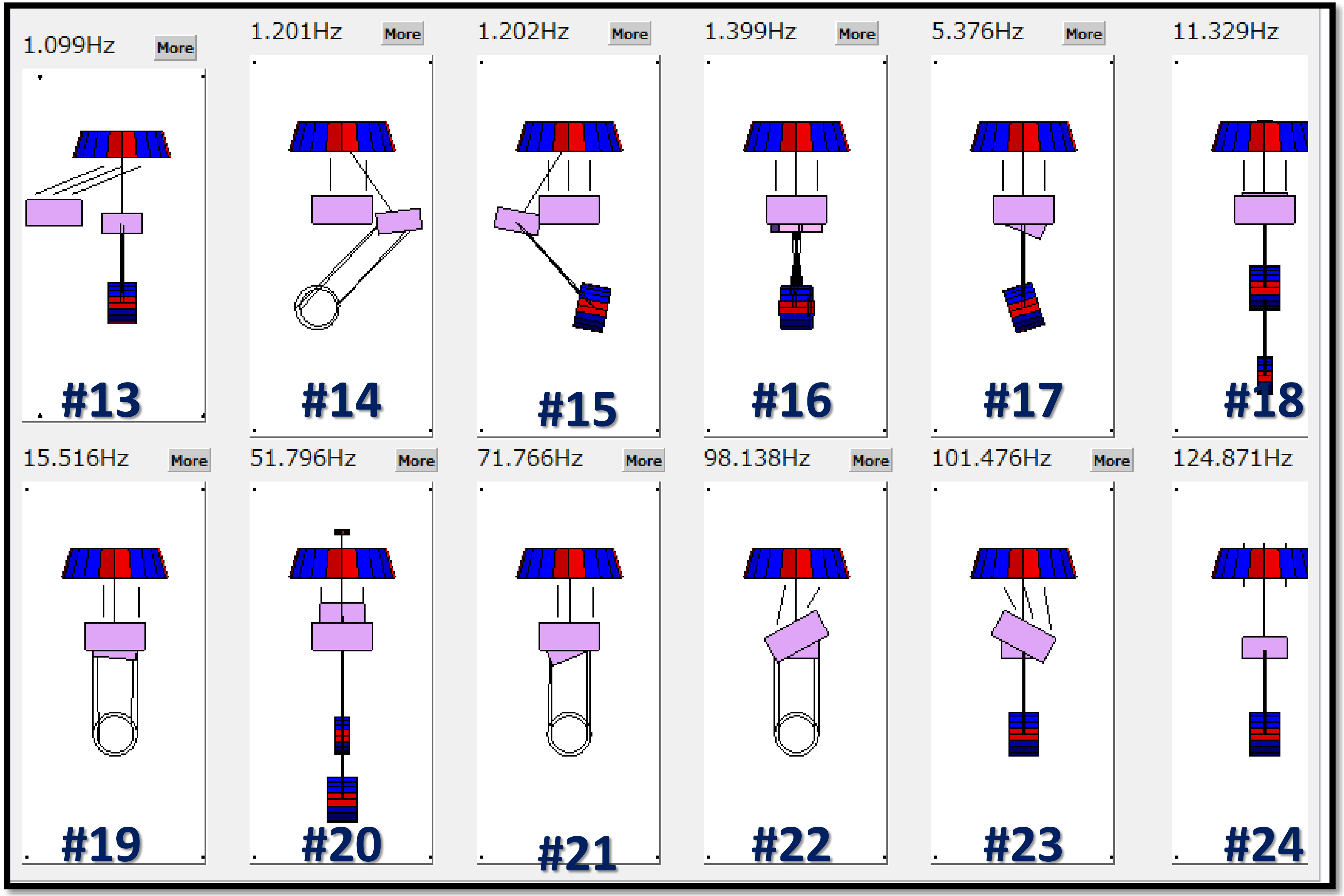
#10 : YIR
YIR

#11 : YTM
-YIM, YRM YTM

#12 : TRM
TRM

Eigen Mode Shape

TypeBpp



#13 : LRM

LRM

#14 :TIM

TIM, etc

#15 : LIM

LIM, etc

#16 : YTM

YIM, -YRM, -YTM

#17 : PIM

PIM, -PRM

#18 : VTM

-VIM, -VRM, VTM

#19 : RTM

RRM, -RTM

#20 :VIM

VIM, VRM

#21 : RIM

RIM, -RRM

#22 : RIR

RIR

#23 : PIR

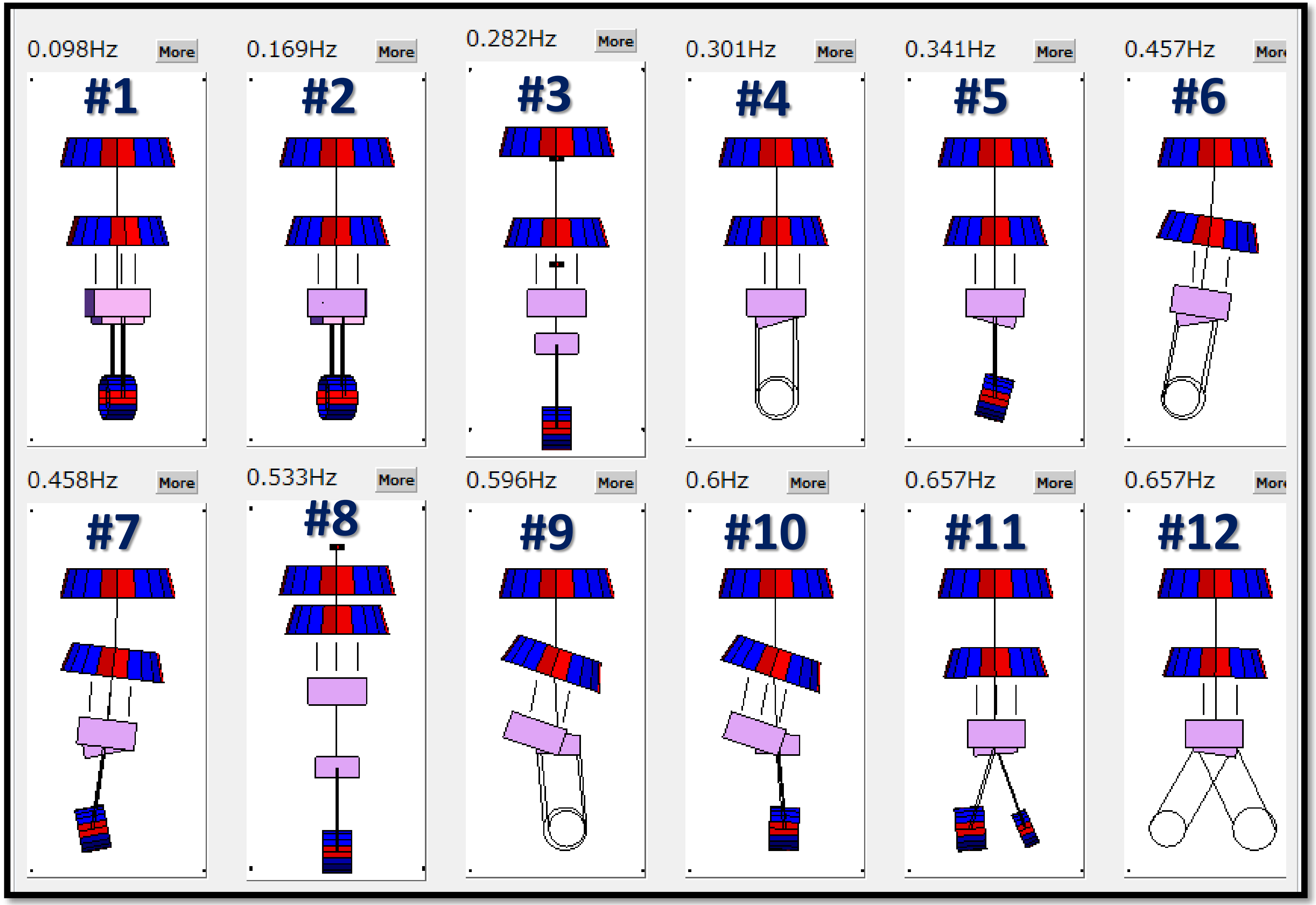
PIR

#24 : VIR

VIR

Eigen Mode Shape

TypeBp



#1 : YPen
YIM, YRM, YTM, YF2, YIR

#2 : YPay
YIM, YRM, YTM

#3 : VPay
VIM, VRM, VTM

#4 : RPay
RIM, RRM, RTM

#5 : PPay
PIM, PRM, PTM

#6 : TPen
Pendulum

#7 : LPen
Pendulum

#8 : VF2, VIR
VF2, VIR, VPay

#9 : RF2, RIR
RF2, RIR, TIP

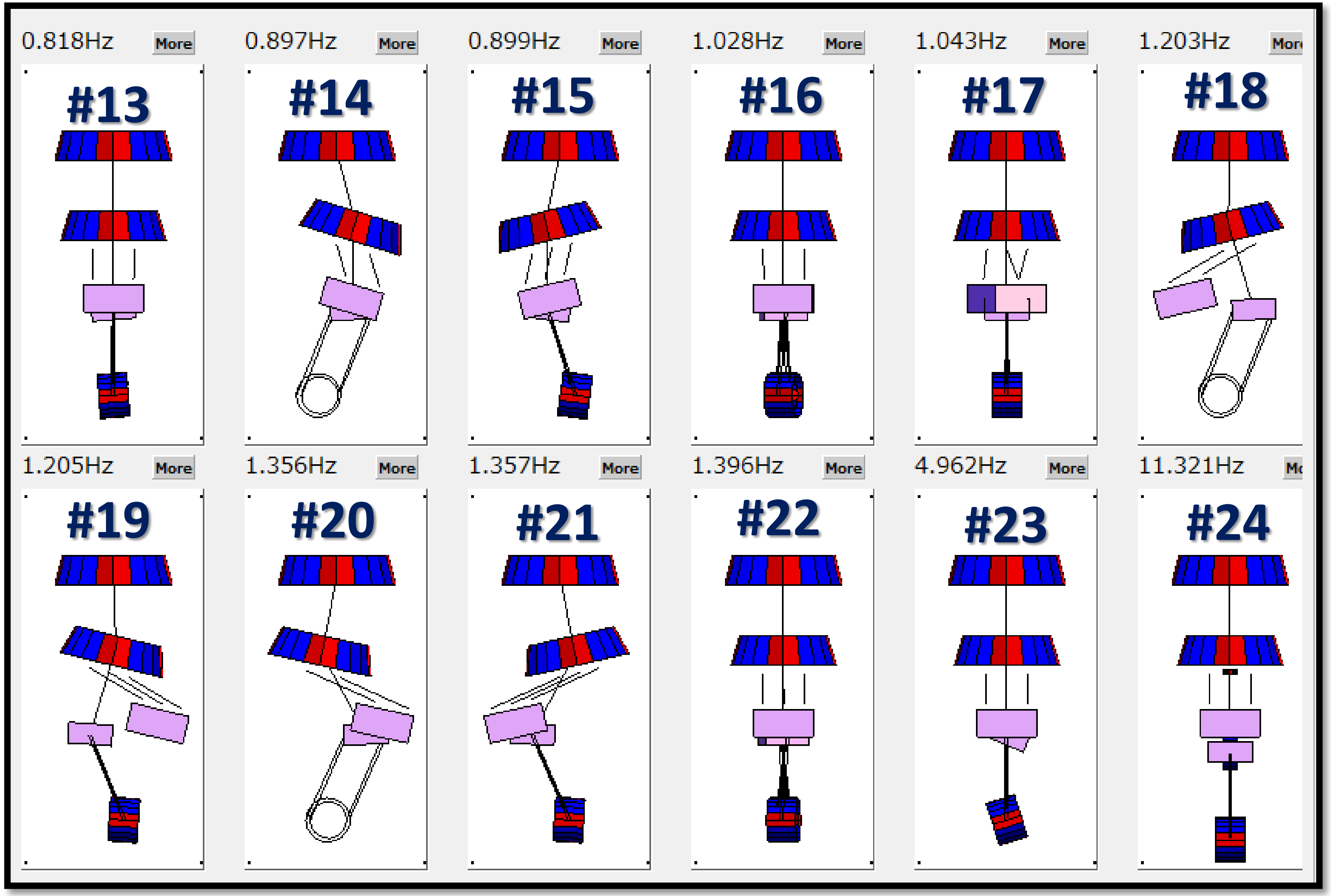
#10 : PF2, PIR
PF2, PIR, LIR

#11 : L deff
LRM, -LTM PTM

#12 : T deff
TRM, -TTM, RIM, RRM, RTM

Eigen Mode Shape

TypeBp



#13 : PTM
PTM

#14 :TPen
Pendulum

#15 : LPen
Pendulum

#16 : YTM
YIM, -YRM, YTM

#17 : YIR
YIR,

#18 : TPen
Pendulum

#19 : LPen
Pendulum

#20 : TPen
Pendulum

#21 : LPen
Pendulum

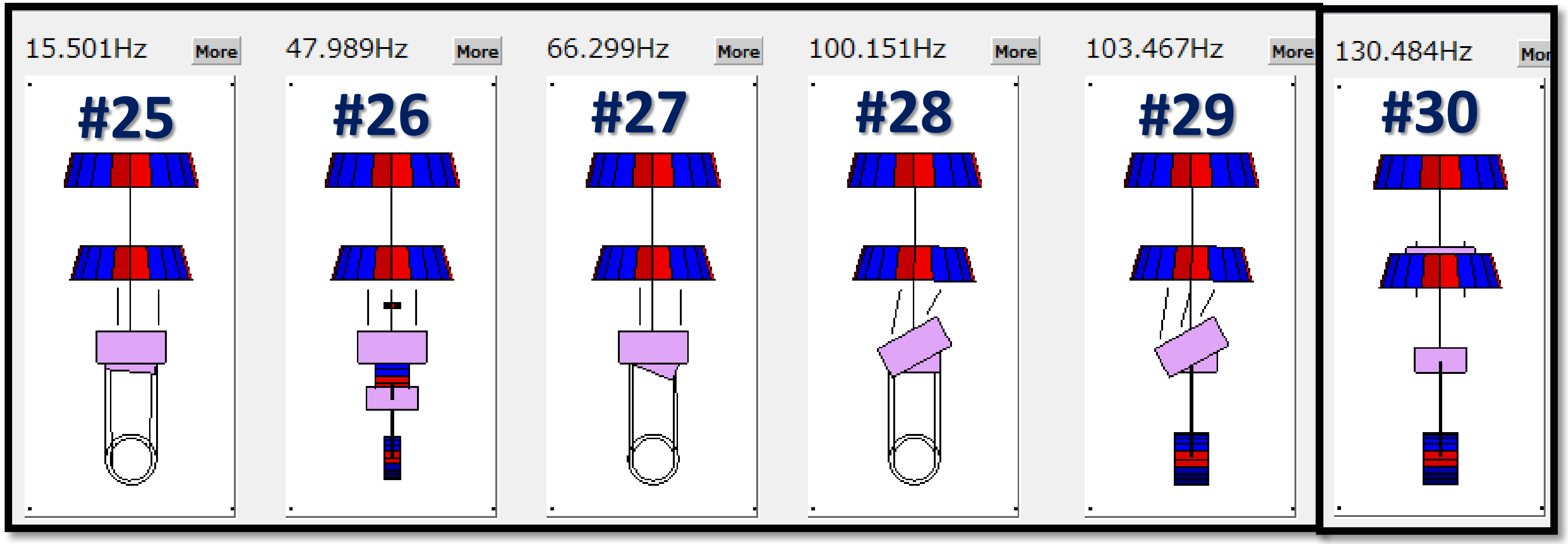
#22 : YTM
YIM, -IRM, -YTM

#23 : PIM
-PIM, PRM

#24 : VTM
-VIM, -VRM, VTM

Eigen Mode Shape

TypeBp



#25 : RTM

-RRM, RTM

#26 : VRM

-VIM, VRM

#27 : RIM

-RIM, RRM

#28 : YTM

YIM, -YRM, -YTM

#29 : PIM

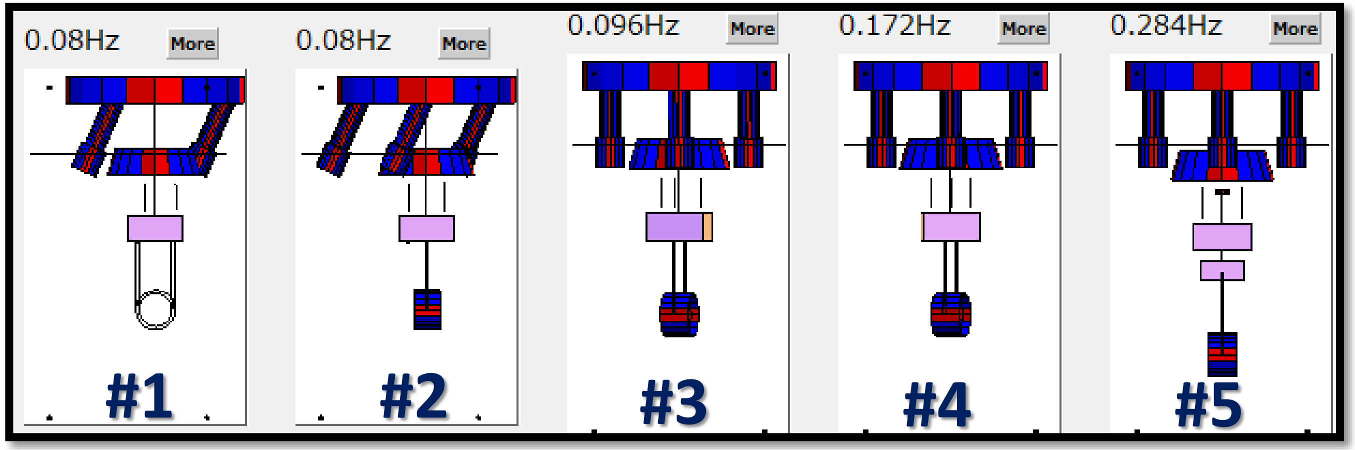
PIM, -PRM

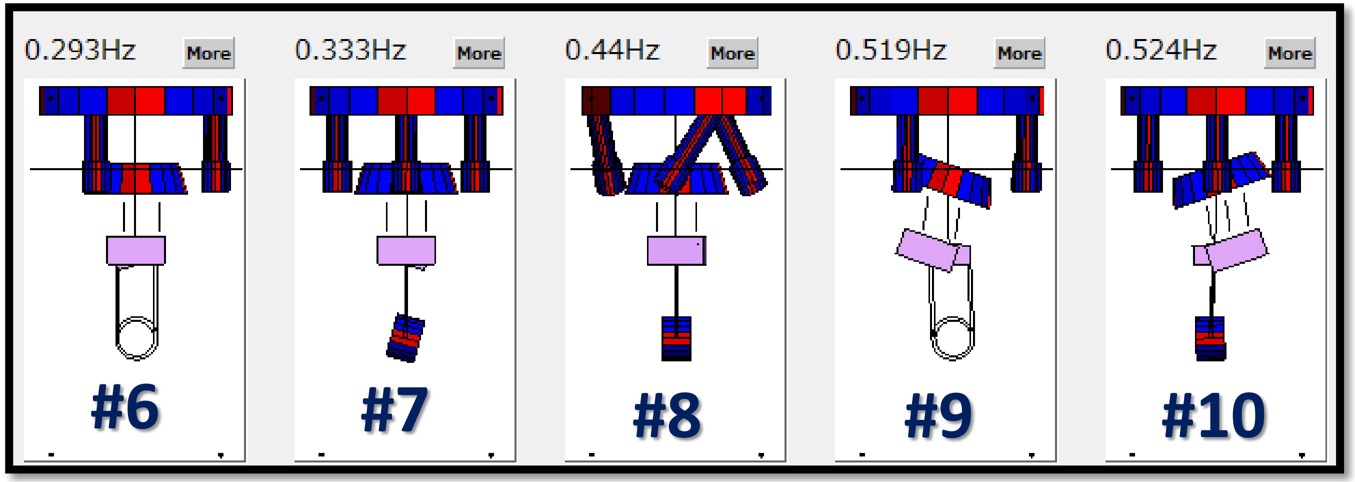
#30 : VTM

-VIM, -VRM, VTM

Eigen Mode Shape

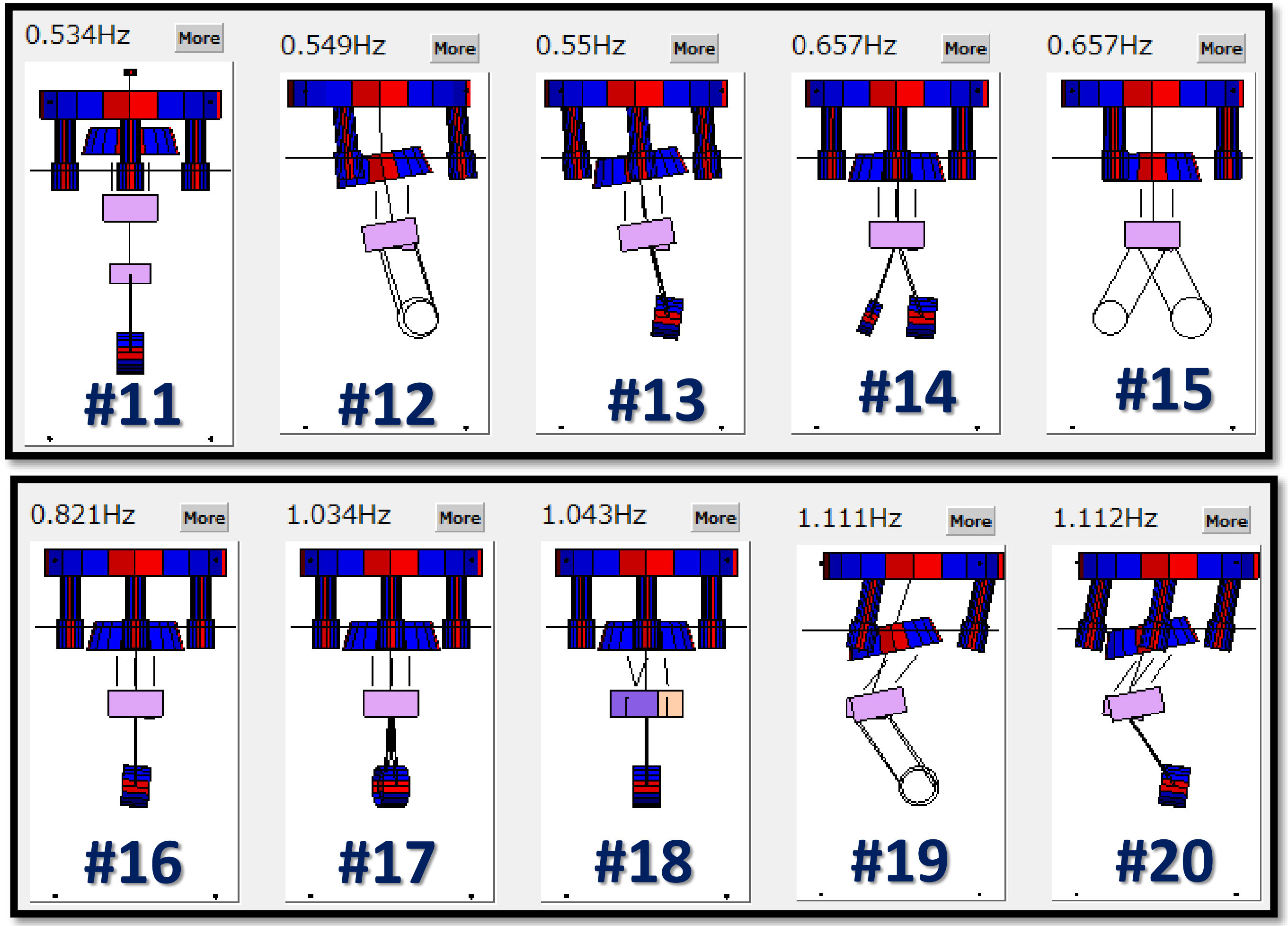
TypeBp with IP





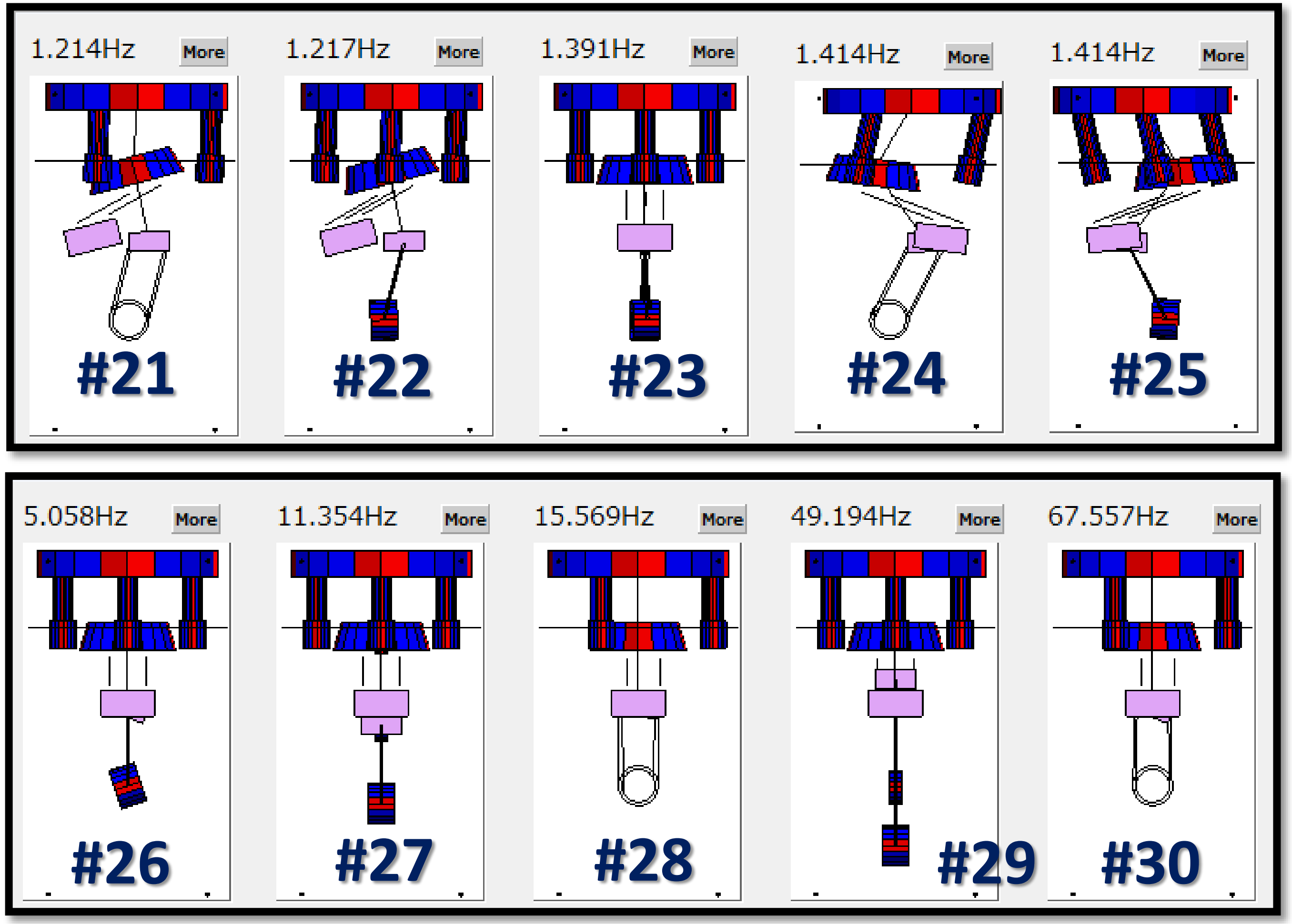
Eigen Mode Shape

TypeBp with IP



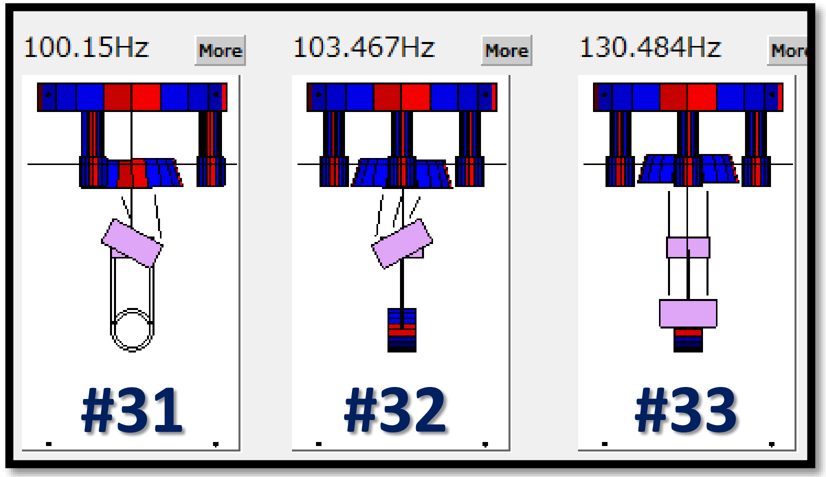
Eigen Mode Shape

TypeBp with IP



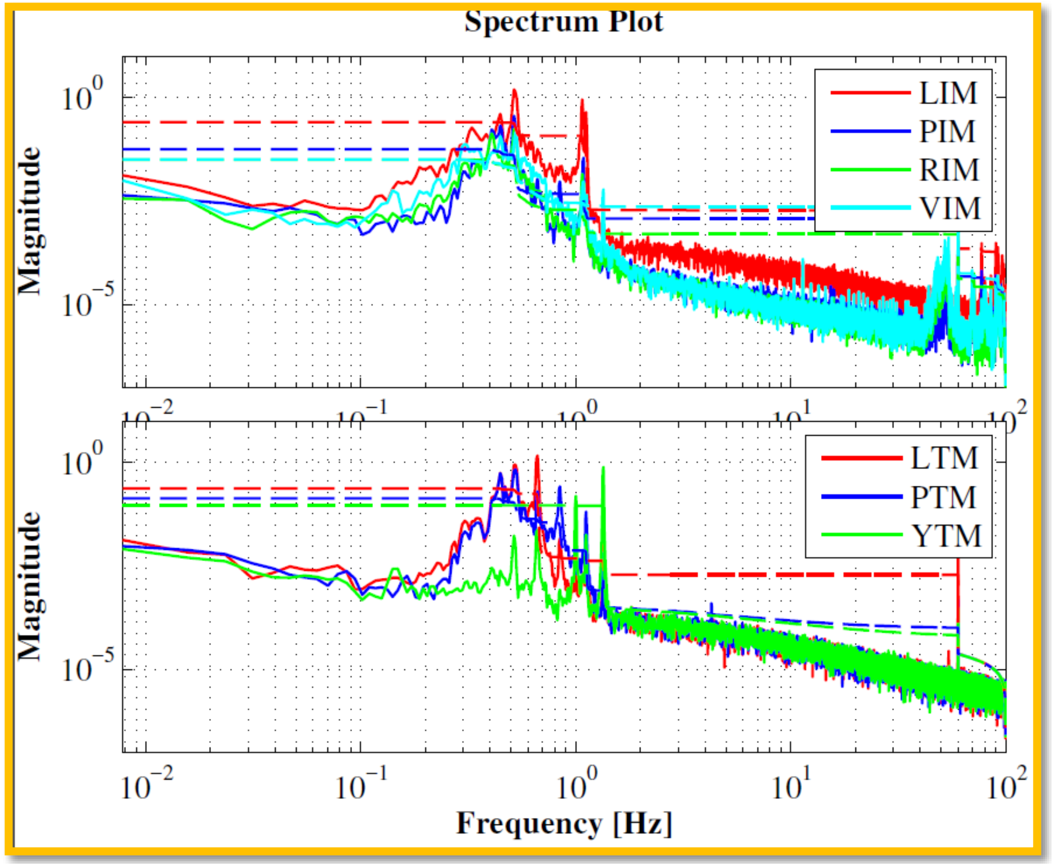
Eigen Mode Shape

TypeBp with IP



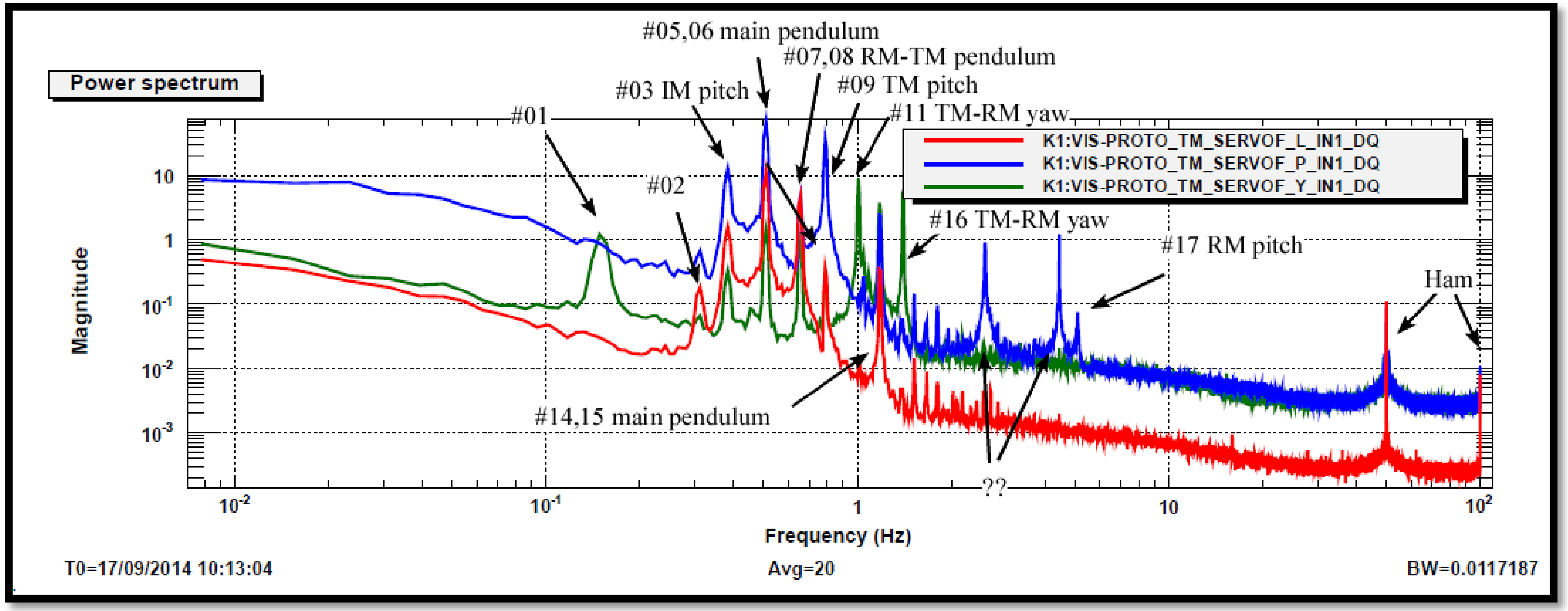
Measurement

IM, TM (OSEM) Spectrum in iKAGRA with no control

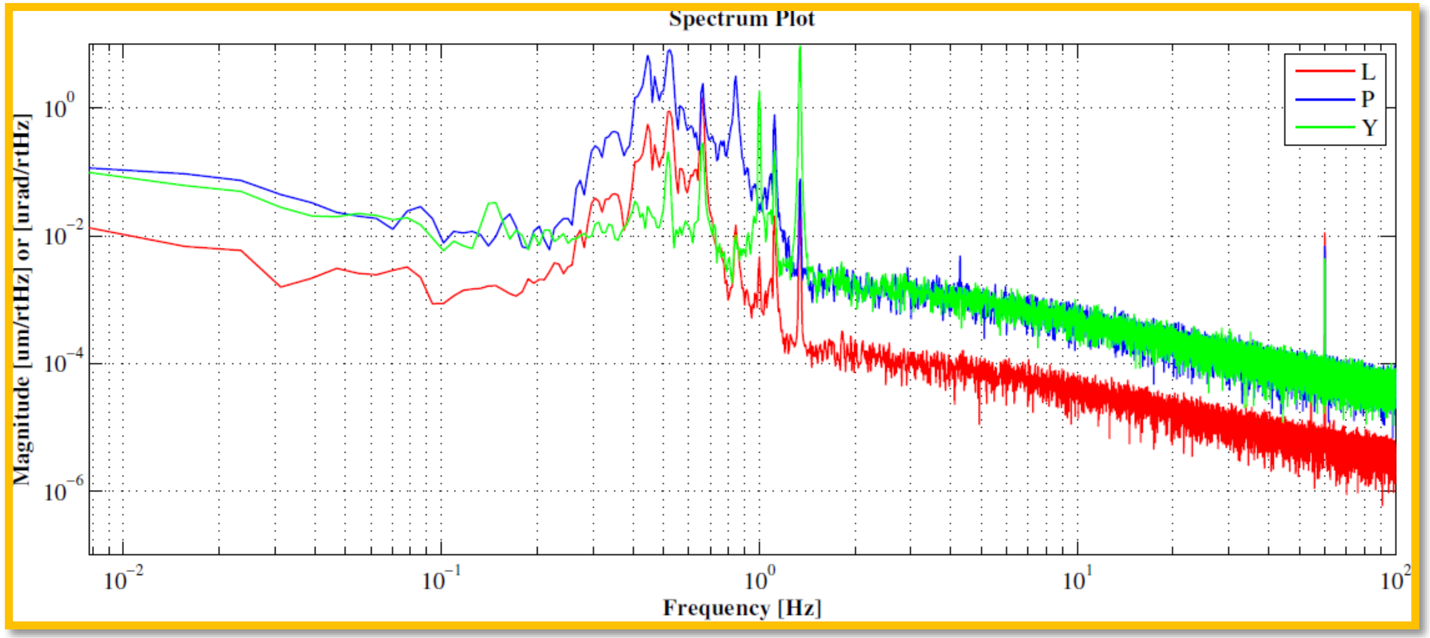


Measurement

REF : TM (OSEM) Spectrum in 20 m

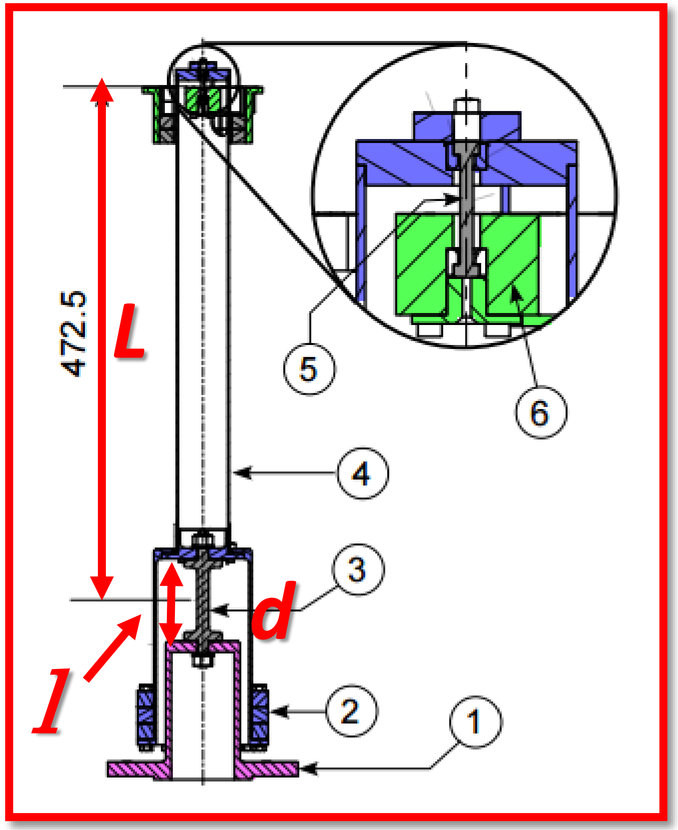


TM (OSEM) Spectrum in iKAGRA



❖ One modification proposal for bKAGRA / TypeBp with IP

IP modeling parameter :



Load on IP M **[kg]**

Leg length L **[m]**

Resonant frequency ω_{IP} **[rad/s]**

Additional torsion stiffness k_t