

Control system and DAQ system using Real time computers and Analog electronics

KAGRA Program Advisory Board
@ Toyama University
2015/7/25(Sat.)

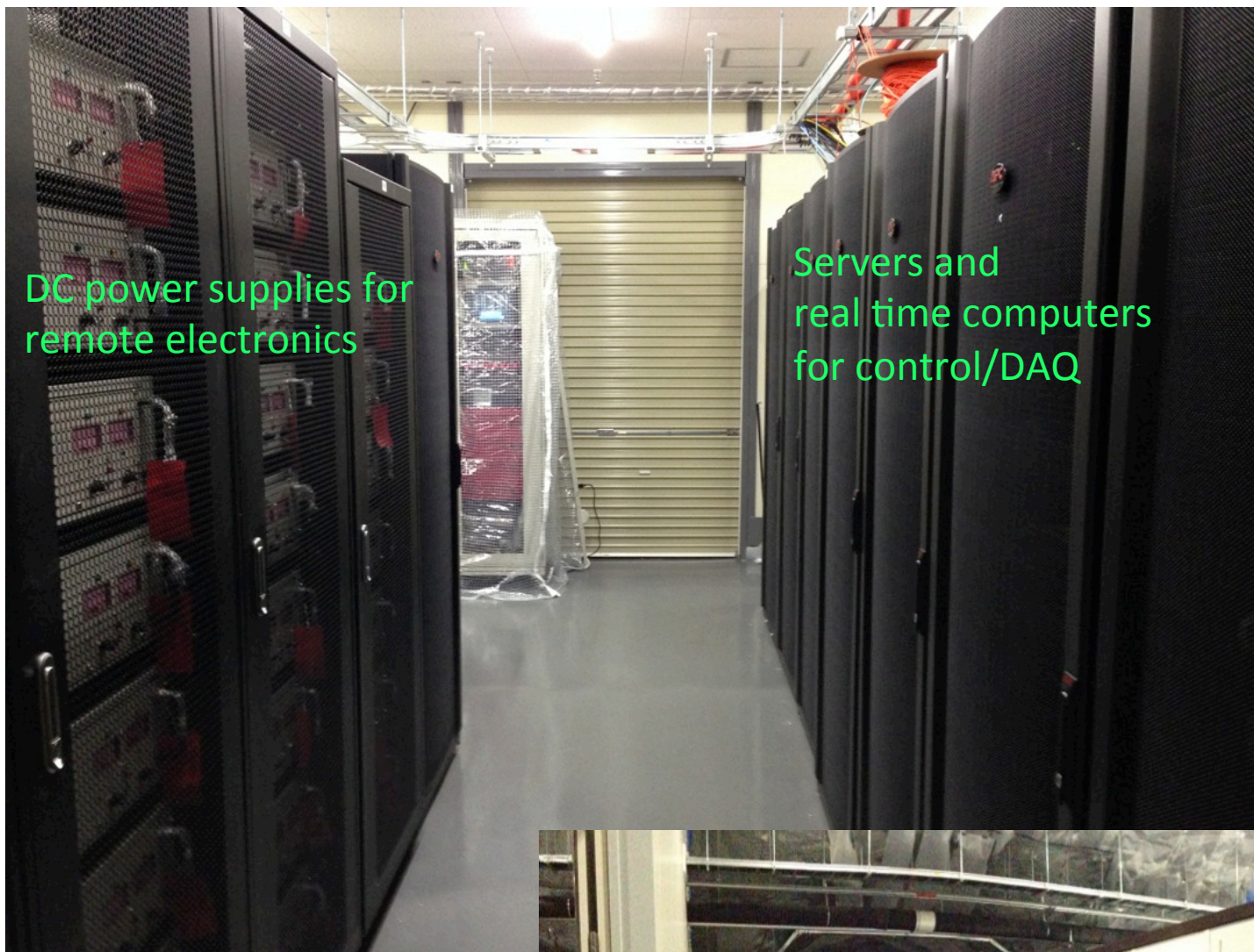
Osamu Miyakawa
ICRR, University of Tokyo

- DGS (DiGital control System):
 - provides a platform to establish control systems for an interferometer and subsystems of KAGRA.
 - provides a DAQ (data acquisition) system.
 - provides many flexible functions like monitors/diagnostics/human interfaces.
- AEL (Analog ELectronics):
 - manufactures necessary circuits for subsystems of KAGRA.
 - connects subsystem and computers for flexible control .

- Provided real time control software from LIGO.
- Constructed hardware and networks step by step at Kamioka site.
 - A. 2009-2010 prototype test @ CLIO
 - Basic IFO operation and noise performance
 - B. 2010~ standalone system for KAGRA subsystems
 - C. 2011 Small network test with 1 master and 2 RT PCs
 - D. 2012-2013 Full test@ Kamioka new building
 - Closer to real scale PCs and network

	Stand alone FY2010-	Small network FY2011	Large network FY2012, 2013	Full system FY2014~
Real time PC	1	2	5	~30
IO chassis	1	2	5	~30
ADC	1	2	~10	~65
DAC	1	1	~10	~45
Binary Output	1	0	~10	~85
Long distance RFM	0	1	2	3
Short distance RFM	0	1	2	2
DAQ network switch	0	1	4	4
Timing switch	0	1	3	3
Boot server	0	1	3	3
Network file system		0	1	1
Build server	0	0	1	1
NAT	0	0	2	2
Data concentrator	0	0	1	1
NDS distributer	0	0	2 (redundant)	2 (redundant)
Frame writer	0	0	2 (redundant)	4 (redundant)
IRIG-B switch	0	0	1	3
Data storage	1TB (local)	1TB (local)	~20TB x2 (ext.)	~200TB (ext.)

Red: New items Green: increment



DC power supplies for
remote electronics

Servers and
real time computers
for control/DAQ

Computer room
in the mine

JGW-G1503843



Diagram of KAGRA controls system

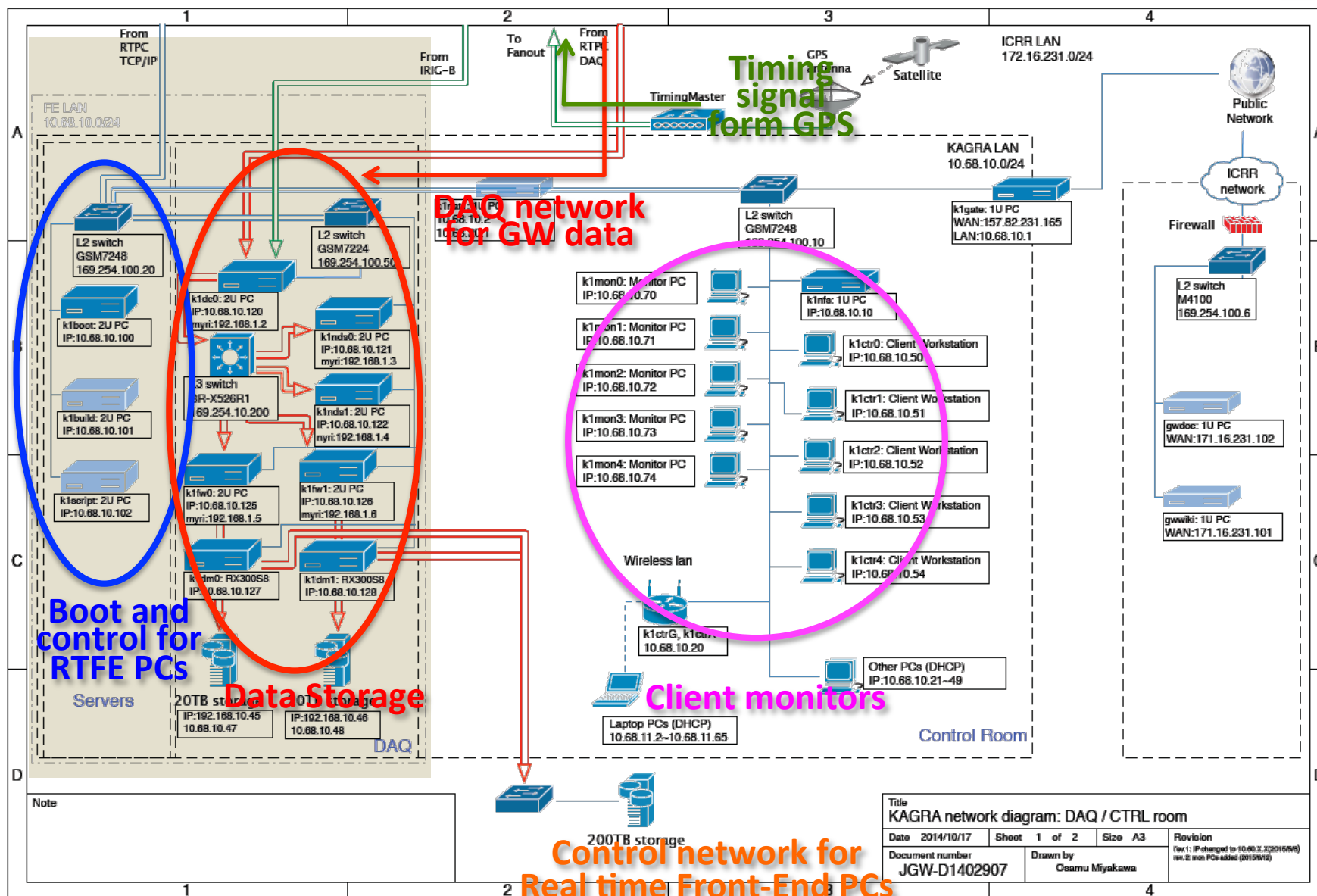
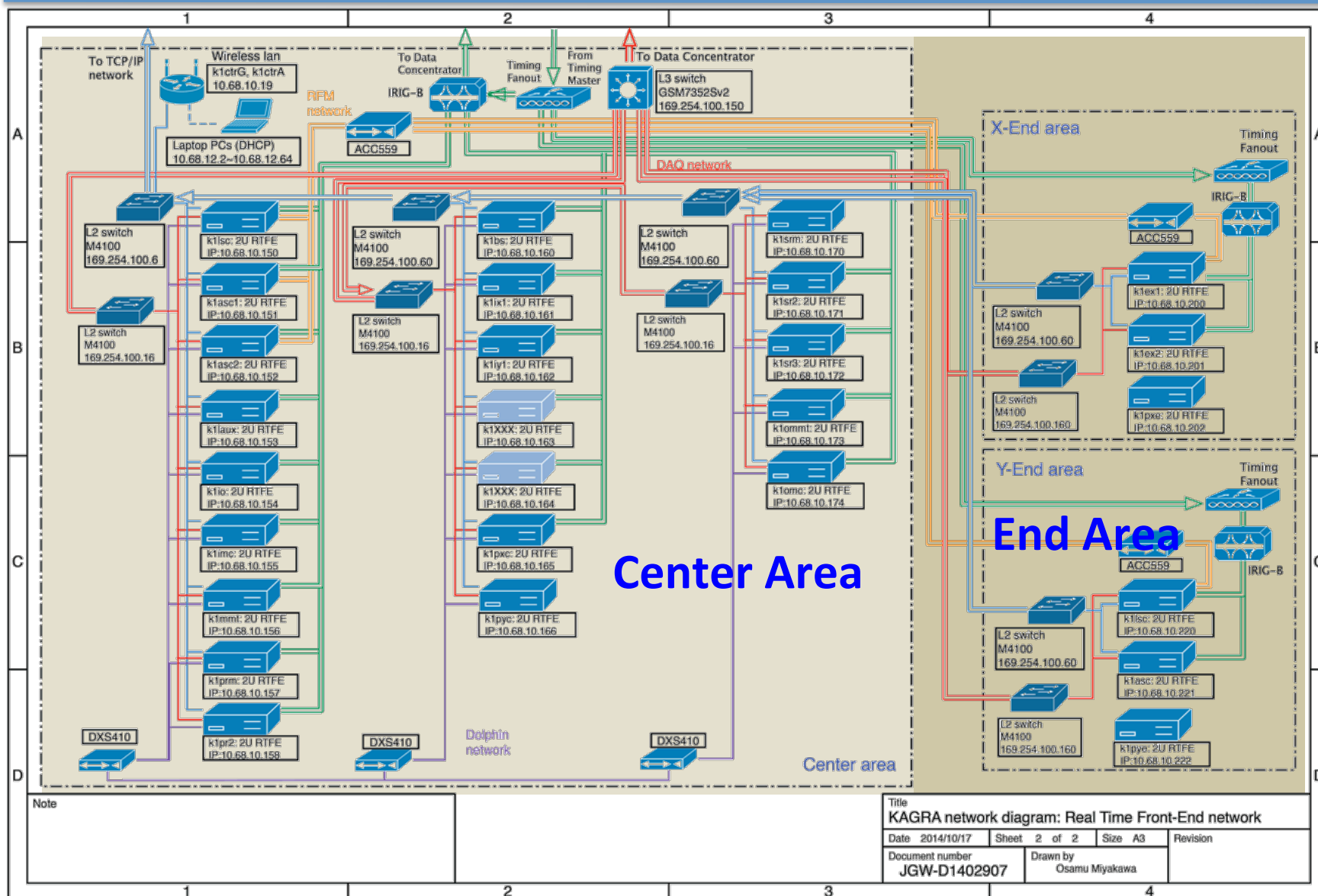
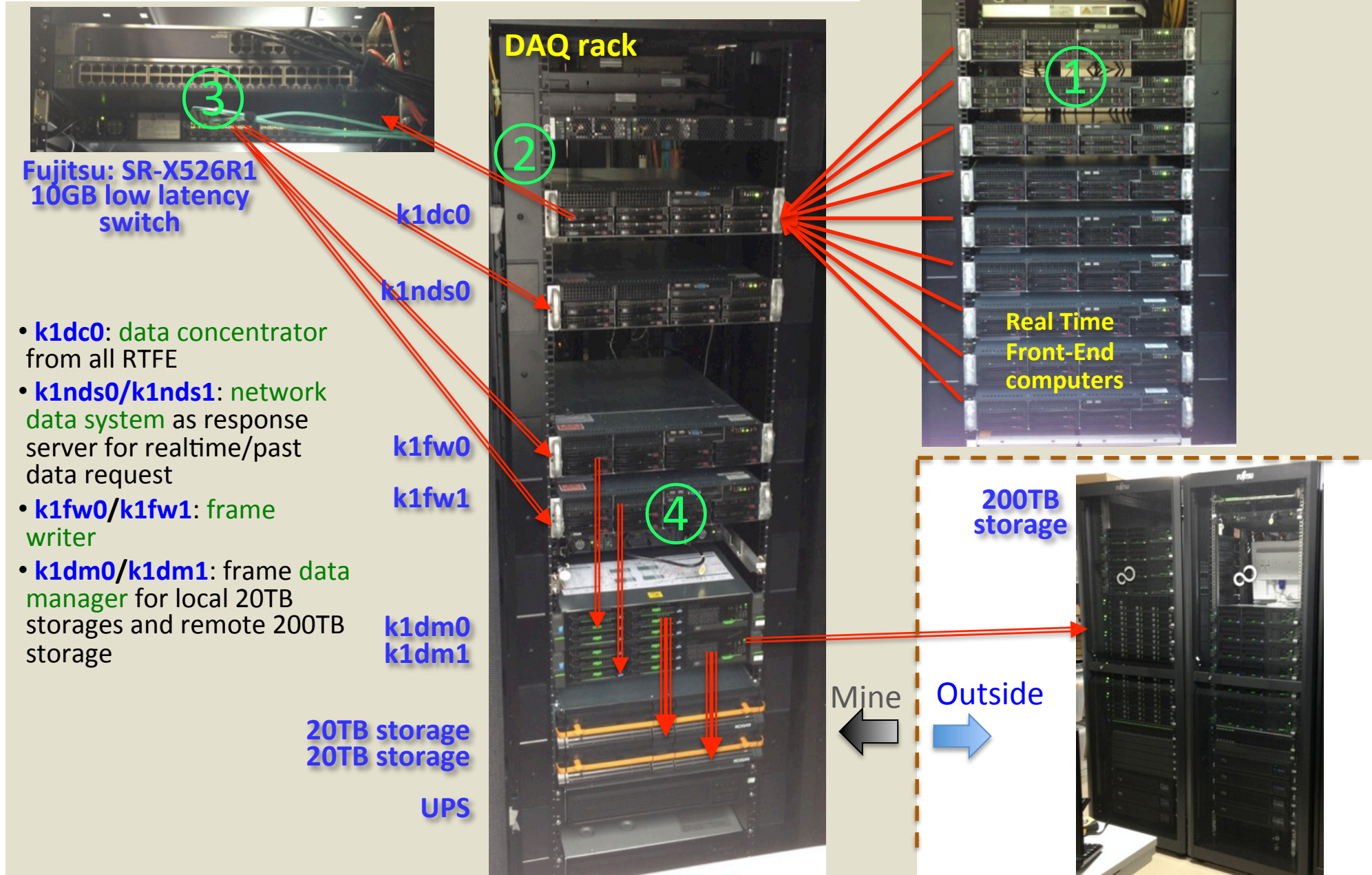
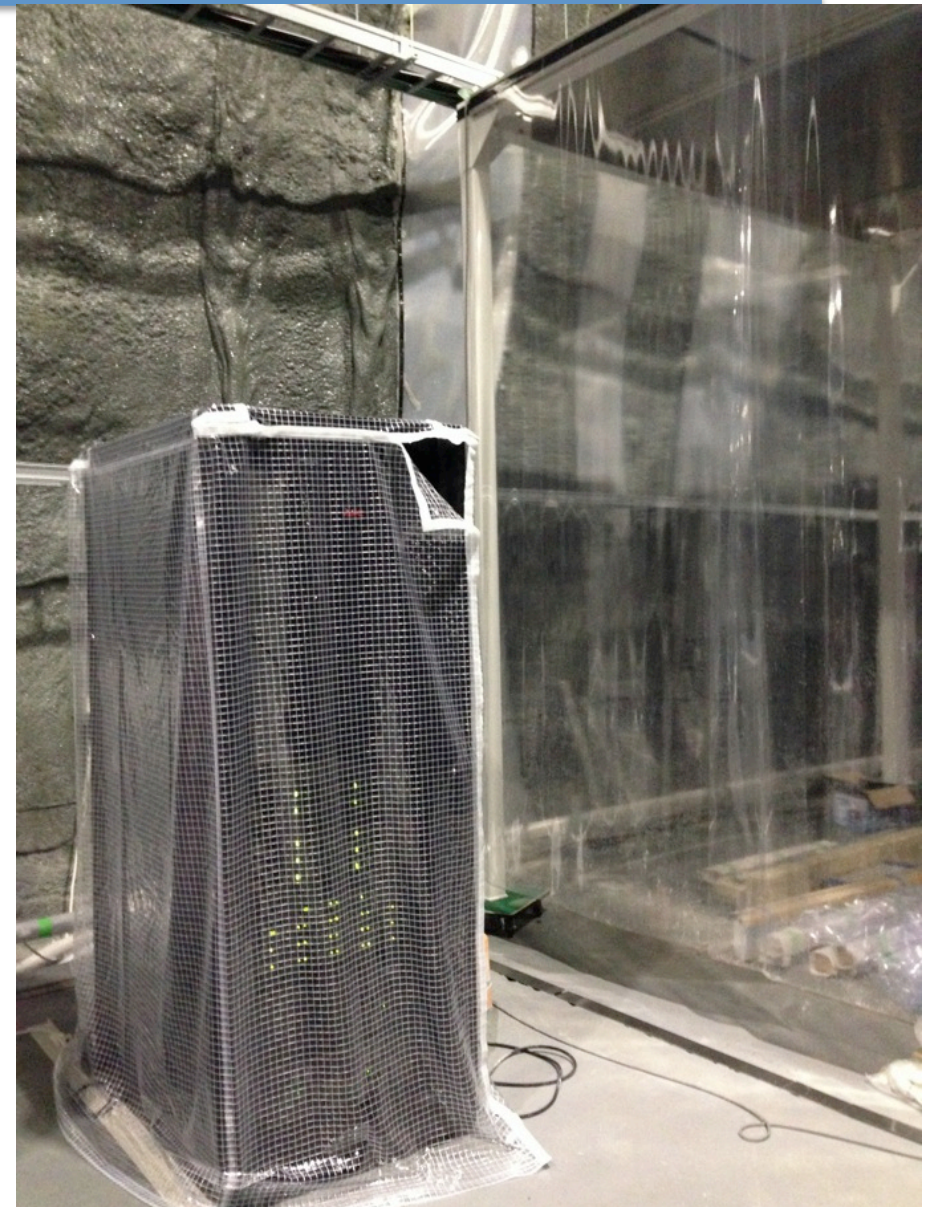


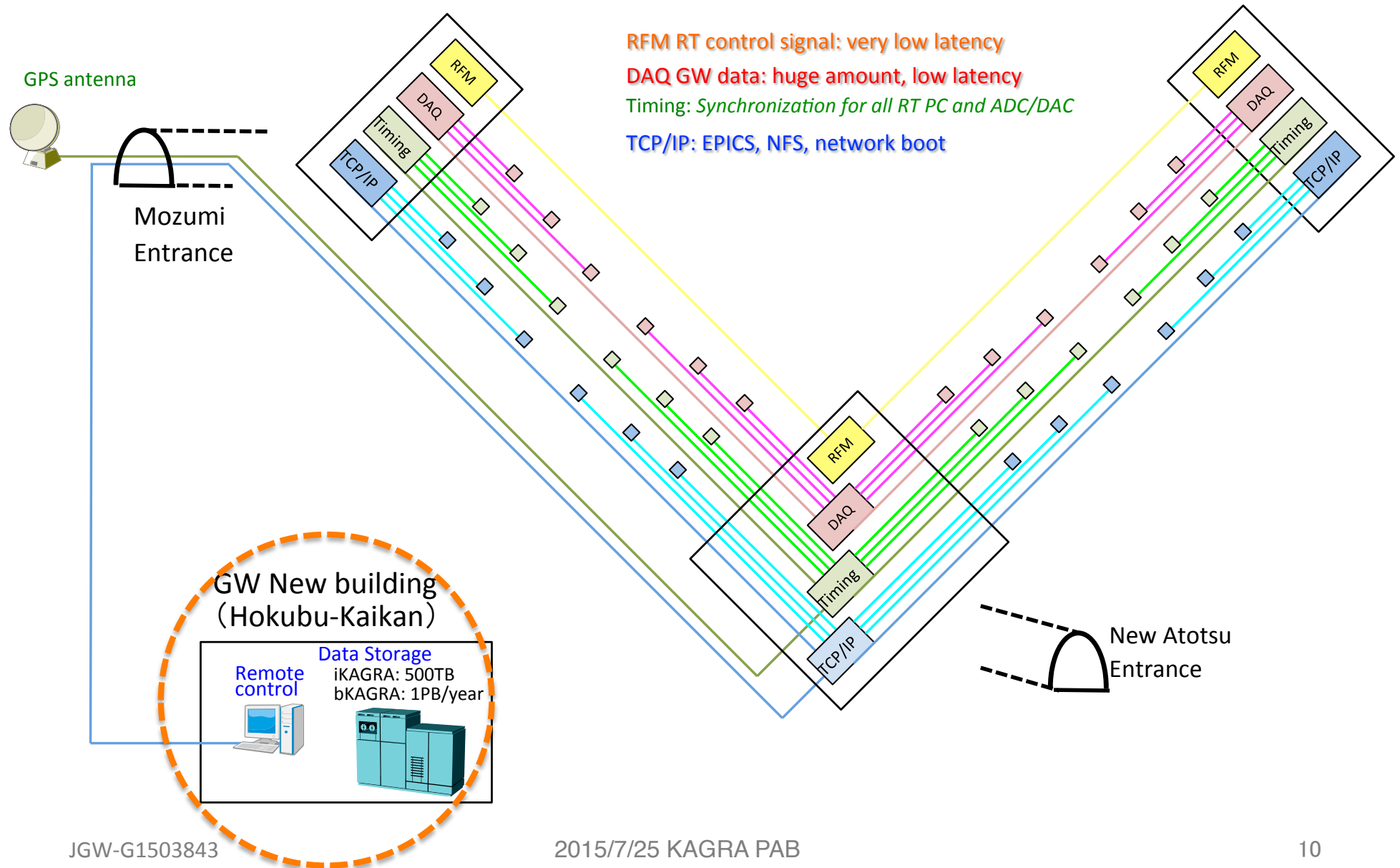
Diagram of KAGRA controls system for Real Time Front-End





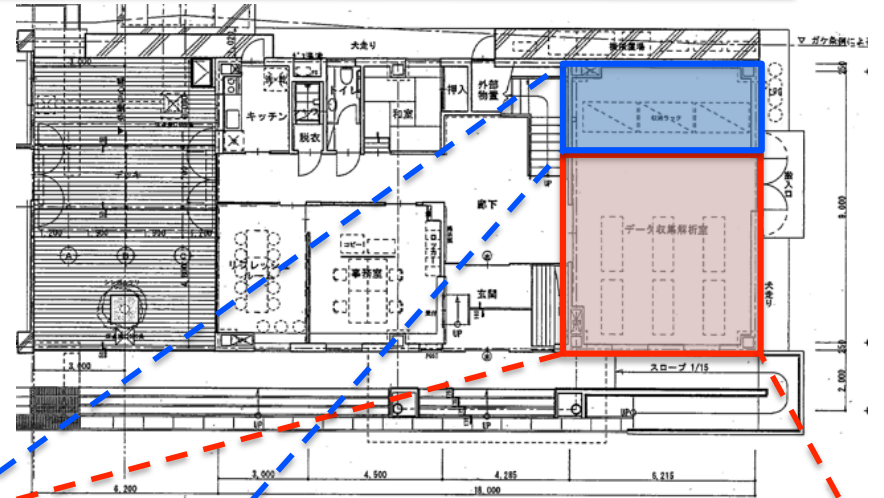
- A Field rack includes
 - IO chassis with ADC/DAC
 - AA/AI filter chassis
 - whintieng filter chassis
 - electronic circuit chassis
 - **no** Real time PCs
 - **no** DC power supplies
- Field racks are located in the laboratory area with a plastic cover to avoid humidity by heating of electronics
 - inside temp. : 25~30°C
 - inside humidity: 45~35%
 - outside humidity: 70~90%





KAGRA Remote control room

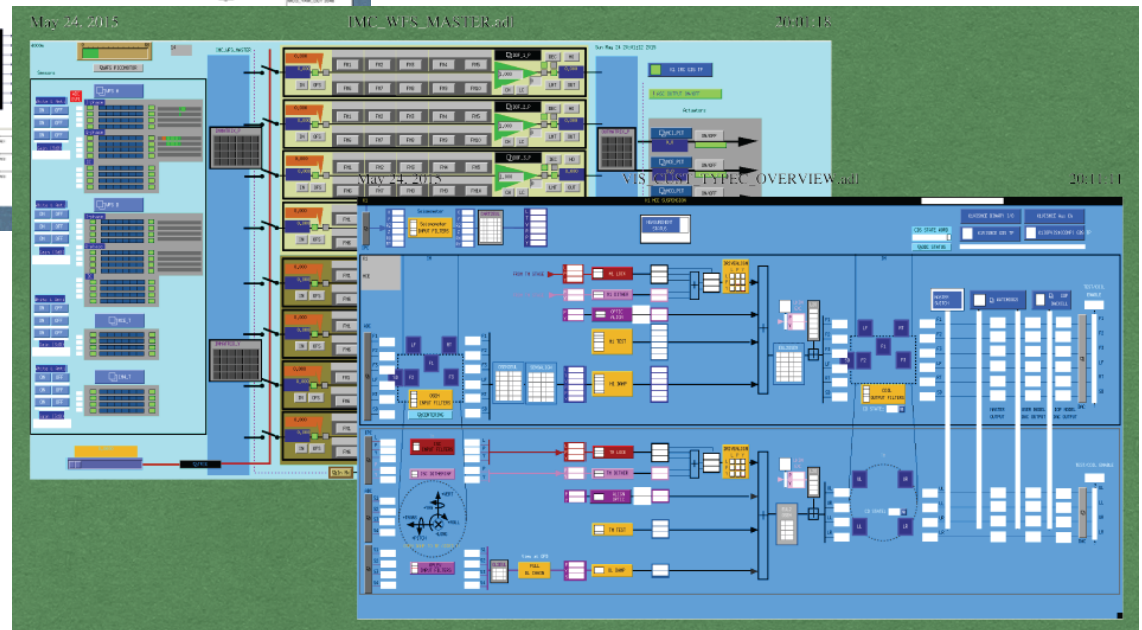
- 5 desks with 3 monitors
- 7 large monitors for sensitivity etc.
- 3 middle monitors for detailed information.
- 7 small monitors for beam spots.
- 200TB storage in the small server room.





- ADC/DAC channel are assigned here.
- Built on Matlab, Simlink

- MEDM on EPICS as a human interface



- Initial models are being developed by DGS referring to LIGO models. PSL, MC SUS, ASC, LSC
- VIS group are developing a model for Type B suspension.

- Real time models and MEDM screens for all subsystems
 - Basically this task should be assigned to each subsystem, but DGS may provide a typical initial model and screens.
- Installing Gurdian (script, diagnostic manager).
- 3km connection and delay test.

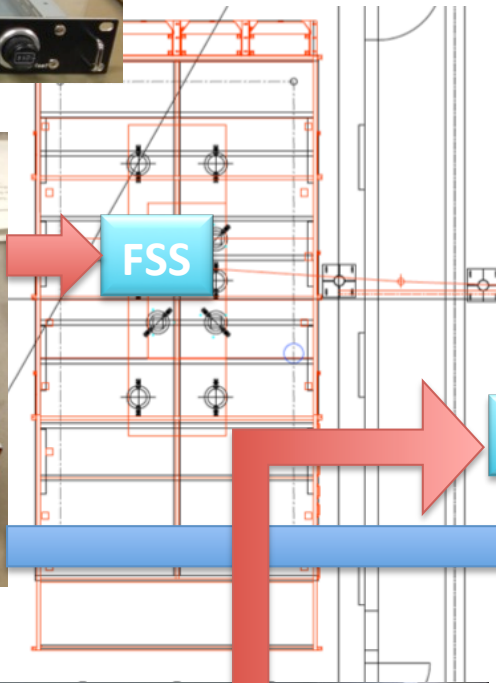
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- Manufacturing almost of electronics for KAGAR
- Basically design is provided by each subgroup, but AEL may propose some appropriate designs .
 - Using LIGO design as possible.
- Expected number of circuits: 150 kinds of item, 800 boxes!
 - May increase x1.5 times if actual drivers or interfaces are considered.
 - Prototype: 95 boxes, iKAGRA: 456 boxes, bKAGRA: 253 boxes
- Very serious problem: human resource
 - Osamu Miyakawa
Chief, contact to subsystem for design and concept
 - Masahiro Kamiizumi
Sub chief, Drawing diagram and board, Parts ordering, Assembling
 - Kyosuke Awai
Joined from this February, working at other place during June to October.
- Started asking outside company from ordering parts, but still tasks are too many.

Assigned tasks in FY2015

Current task	Sub system	Qty.	achievement	status
LVDT driver	VIS	20	100%	Completed
LVDT distributor	VIS	20	100%	Completed
High power coil driver	VIS	6	80%	Being assembled to chassis
Low power coil driver	VIS	20	80%	Being assembled to chassis
Satellite box	VIS	10	90%	Being assembled to chassis, partially completed and being tested.
Satellite box	VIS	20	0%	Not started.
MC servo	IOO	1	90%	Being assembled and tested
RF PD	MIF	30	40%	Ordered to company, being manufactured
RF QPD	MIF	5	40%	Ready to be manufactured
RF PD interface	MIF	5	20%	Being Designed
RF QPD interface	MIF	5	20%	Being Designed
I&Q demodulator	MIF	5	100%	Completed
Whitening filter	MIF/GIF/DGS	10	100%	Done, being inspected
24V DC power strip	AEL	30	60%	Being manufactured

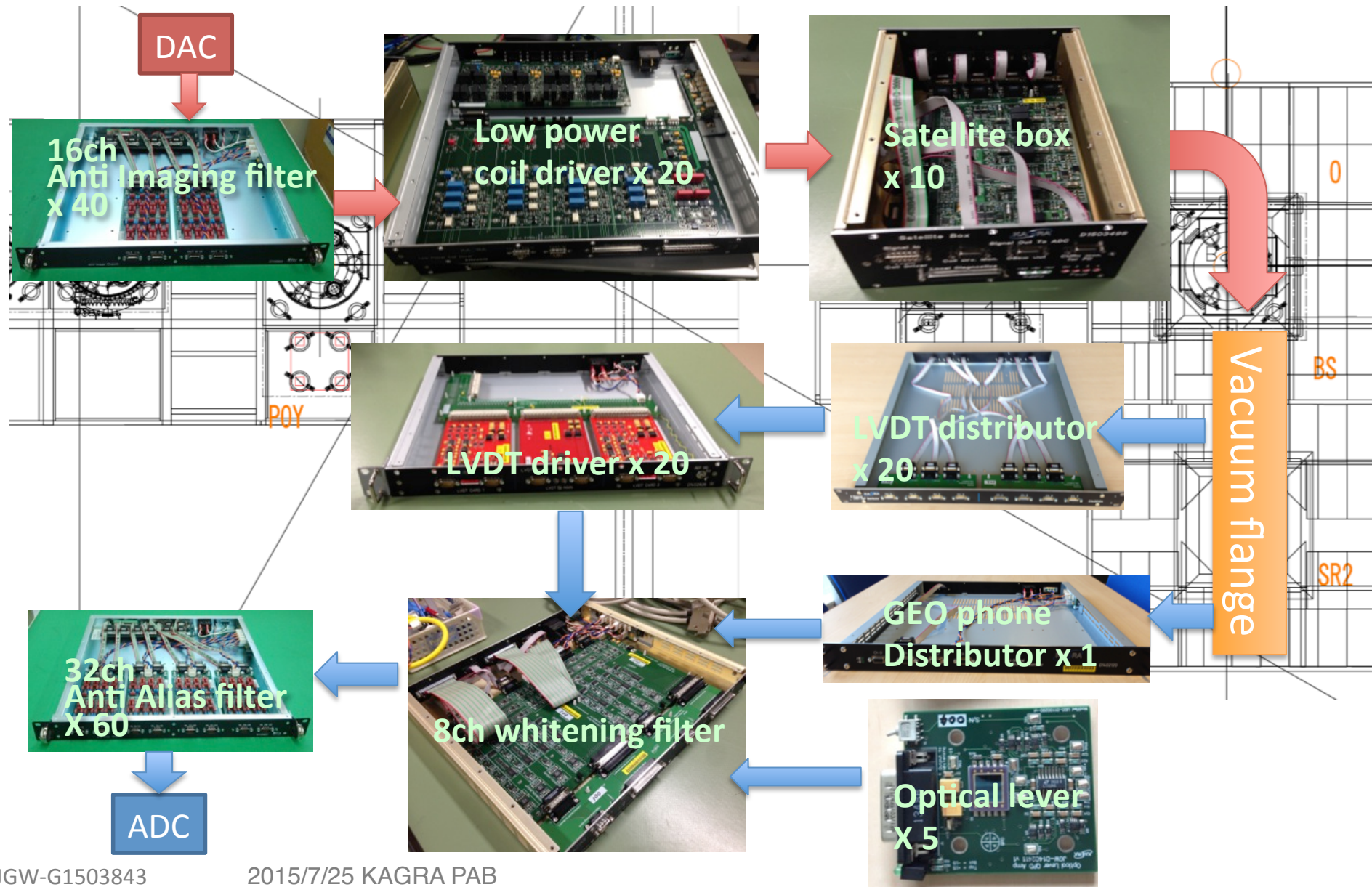
Manufactured electronic circuits for control



ADC



Manufactured electronic circuits for suspensions



Whitening filter:

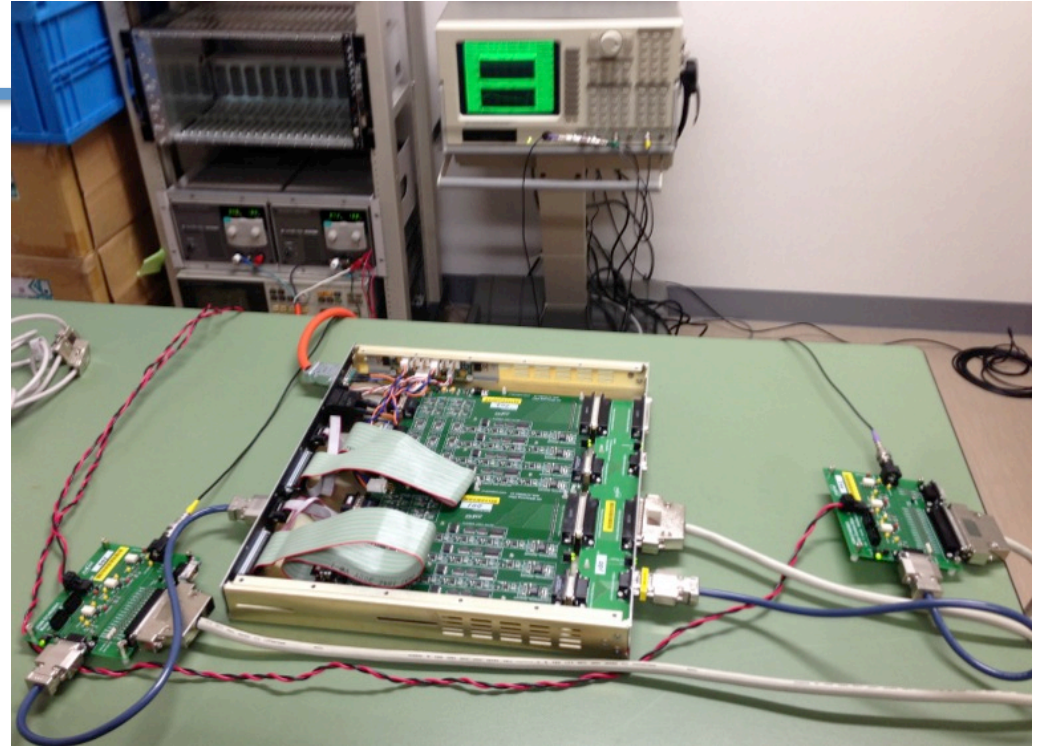
- 4bit for 0-45dB variable gain, 3dB step
- 3bit for 3 orders whitening with 1Hz zero: 10Hz pole
- 8ch in 1U chassis

Test for whitening filter:

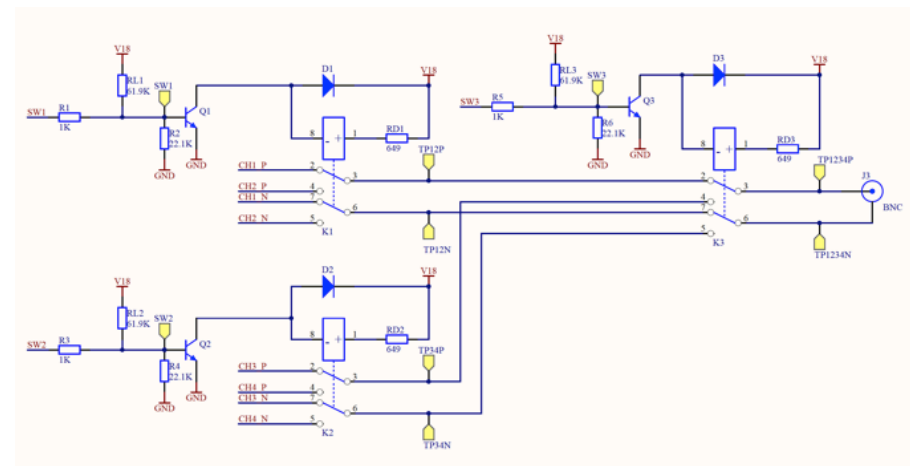
T.F. : 8ch x (4x4)bit x 3bit = 384

Noise: 8ch x (4x4)bit x 3bit x 4span = 1536

Total: 1920 measurements!

**Automated inspection:**

- Measurement using a SR785 controlled by python code on a remote computer through GPIB.
- Remote controlled relay switch box to measure D-SUB 9pin 4ch signals at once using a single channel SR785.



DGS:

- Quite going well.
- Real time models and MEDM screens should be prepared.

AEL:

- We are continuously manufacturing analog circuits, but human resource is a very serious issue.