Non-parametric Bayes clustering による 重力波検出器の非定常大型雑音の特徴づけ

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Clustering of Glitches

Classification of non-stationary large noises (broadband noise, known as glitches, triggers) is useful for diagnosis of interferometer.

An un-supervised learning problem \rightarrow clustering.

Recognized by Mukherjee (2006) Class. Quant. Grav.:

- Input from kleine Welle: duration, central scale, SNR, and 15 highest wavelet coefficients → each glitch is a 18-dimensional vector.
- Dissimilarity matrix (probably) by Euclidean distance.
- Visualization by multidimensional scaling.
- Hierarchical clustering (UPGMA?).

Clustering of Glitches (cont.)

Improvement by Mukherjee, et al. (2012) Phys. Rev. D:

- For the waveform, distances based on the length of the longest common sub-sequence (local alignment by dynamic programming).
- ► Non-hierarchical clustering (k-means). The number of clusters, *K*, is chosen such that the minimizer of intra/inter distances.
- Within a cluster, hierarchical clustering by central frequency, amplitude, SNR, and quality score.

Our proposal:

- Clustering by power spectral density (PSD), which is a functional data.
- Reformulate the problem in terms of Bayesian non-parametric clustering (density estimate, Lo, 1984), which captures probabilistic nature of the problem.

Bayesian Paradigm: the beta-binomial model

Suppose *s* successes in *Bernoulli(p)* trial of the length *n*. The binomial likelihood *Binom*(*n*, θ) with the beta prior *Beta*(θ , θ) yields posterior *Beta*(*s* + θ , *n* - *s* + θ), because

$$\pi(p|s) \propto \mathbb{P}(s|p)\pi_{\theta}(p) \propto p^{s}(1-p)^{n-s}p^{\theta-1}(1-p)^{\theta-1}$$

The beta prior is conjugate. A Bayesian estimate of the parameter is

$$\hat{p}_{Bayes} = \mathbb{E}(p|s) = rac{n}{n+2 heta}\hat{p}_{MLE} + rac{2 heta}{n+2 heta}rac{1}{2}, \qquad \hat{p}_{MLE} = rac{s}{n}.$$

Thus θ , the hyperparameter, is a strength of the prior belief. The marginal likelihood is

$$\mathbb{P}_{\theta}(s) = \int_{0}^{1} \mathbb{P}(s|p) \pi_{\theta}(p) dp = \binom{n}{s} \frac{(\theta)_{s}(\theta)_{n-s}}{(2\theta)_{n}}.$$

Frequently used empirical estimate of the hyperparameter is the maximizer of the marginal likelihood.

Bayesian Clustering

Suppose sampling from a 2-components (cluster) mixture model. The likelihood is

$$\pi(x_1,...,x_n|p) = \prod_{i=1}^n \{p\pi(x_i|c_i=1) + (1-p)\pi(x_i|c_i=2)\}$$

and set the beta prior for p. In Bayesian clustering, our target is the joint posterior of memberships $\mathbb{P}(c_1, ..., c_n | x_1, ..., x_n)$. For the Gibbs sampler, we need $\mathbb{P}(c_i | c_{-i}, x_1, ..., x_n)$. By Bayes' rule,

$$\mathbb{P}(\boldsymbol{c}_i|\boldsymbol{c}_{-i},\boldsymbol{x}_1,...,\boldsymbol{x}_n) \propto \pi(\boldsymbol{x}_i|\boldsymbol{c}_1,...,\boldsymbol{c}_n,\boldsymbol{x}_{-i})\mathbb{P}(\boldsymbol{c}_i|\boldsymbol{c}_{-i},\boldsymbol{x}_{-i}),$$

where $\pi(\mathbf{x}_i|\mathbf{c}, \mathbf{x}_{-i}) = \pi(\mathbf{x}_i|\mathbf{c}_i)$ and $\mathbb{P}(\mathbf{c}_i|\mathbf{c}_{-i}, \mathbf{x}_{-i}) = \mathbb{P}(\mathbf{c}_i|\mathbf{c}_{-i})$. Moreover, noting exchangeability in sampling, we have

$$\mathbb{P}(c_i = 1 || \{j : c_{j \neq i} = 1\}| = s) = \frac{\mathbb{P}_n(s+1)}{\mathbb{P}_{n-1}(s)} \frac{s+1}{n} = \frac{\theta+s}{2\theta+n-1}.$$

Bayesian Non-parametric Clustering

Extension to k-components is straightforward, the Dirichlet-multinomial model, where p is sampled from the k-dimensional Dirichlet distribution. But we have interest in the number of clusters.

Sampling from an "infinite-dimensional" Dirichlet distribution is possible by replacing the Dirichlet distribution by the Dirichlet process (random measure). This is non-parametric, since we do not use a fixed prior. The Dirichlet process is a conjugate prior.

Definition (Ferguson, 1973)

Let μ be a finite measure on (X, \mathcal{B}) . A random measure **D** on X is called a Dirichlet process if for every finite measureable partition $\{B_1, ..., B_k\}$ of $X, (D(B_1), ..., D(B_k)) \sim Dirichlet(\mu(B_1), ..., \mu(B_k)).$

Bayesian Non-parametric Clustering (cont.)

For the Dirichlet process, ℙ(c_i|c_{-i}), which is needed in the Gibbs sampler, is given by the Chinese restaurant process (CRP):

- We set π(x_i|c_i) ~ MVN(μ_i, σ), where μ_i are sampled by the Metropolis-Hastings algorithm.
- Empirical estimate of θ are chosen as the maximizer of the marginal likelihood with the MCMC estimate

$$\pi_{\theta}(\mathbf{x}) = \sum_{c} \pi(\mathbf{x}|c) \mathbb{P}_{\theta}(c) = \frac{1}{M} \sum_{i=1}^{M} \pi(\mathbf{x}|c^{(i)}), \qquad c^{(i)} \sim CRP(\theta).$$

Preprocessing



 $PSD \rightarrow B$ -spline regression coefficients (10 basis) $\rightarrow PCA$ (94.8% variance explained by only the 2 PCs).

Visualization



Glitches are projected onto PCs. This is a snapshot. A clustering is a realization of a random event, in contrast to the k-means. Empirical estimate $\hat{\theta} = 0.007$.

Number of Clusters and Memberships



The number of clusters and memberships are random variables. The posterior probability of membership is given for each cluster for each glitch.

Summary

- Classification of broadband noises are useful for diagnosis of interferometer.
- Regarding PSD of glitches as a functional data a non-parametric Bayesian clustering was proposed.
- The method provides posterior distributions of the number of clusters and memberships for each cluster for each glitch.
- The posterior probability gives magnitude of confidence of the assignment. In fact, our result shows that irregular glitches accumulate in some specific period and then the lock will be lost.

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