

# Simulation for understanding what will happen in dithering

Daisuke TATSUMI

NAOJ

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- (1) Signal of interest  
a sinusoidal wave of  
amplitude: **a0**  
frequency: **f<sub>sig</sub>**

$$v_{\text{sig}}(t) = a0 * \cos(2 * \pi * f_{\text{sig}} * t)$$

- (2) White gauss noise  
standard deviation of the noise = **Vn**  
average of th noise = 0.0

random number generator: **gsl\_ran\_gaussian**  
in Gnu Science Library

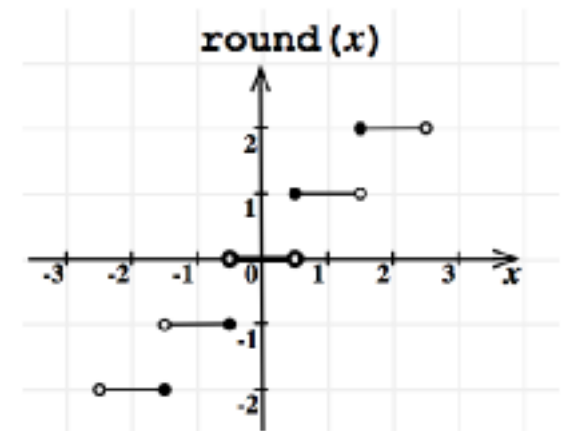
- (3) Quantization

$$Vq(t) = \text{round}( V(t) / \Delta ) * \Delta$$

**Δ**: quantization step

The round function in C language has a response as a left figure.

**f<sub>sample</sub>**: sampling frequency of the quantizer.





## Simulation Example 0 :

$$\Delta = 1 \text{ volt}$$

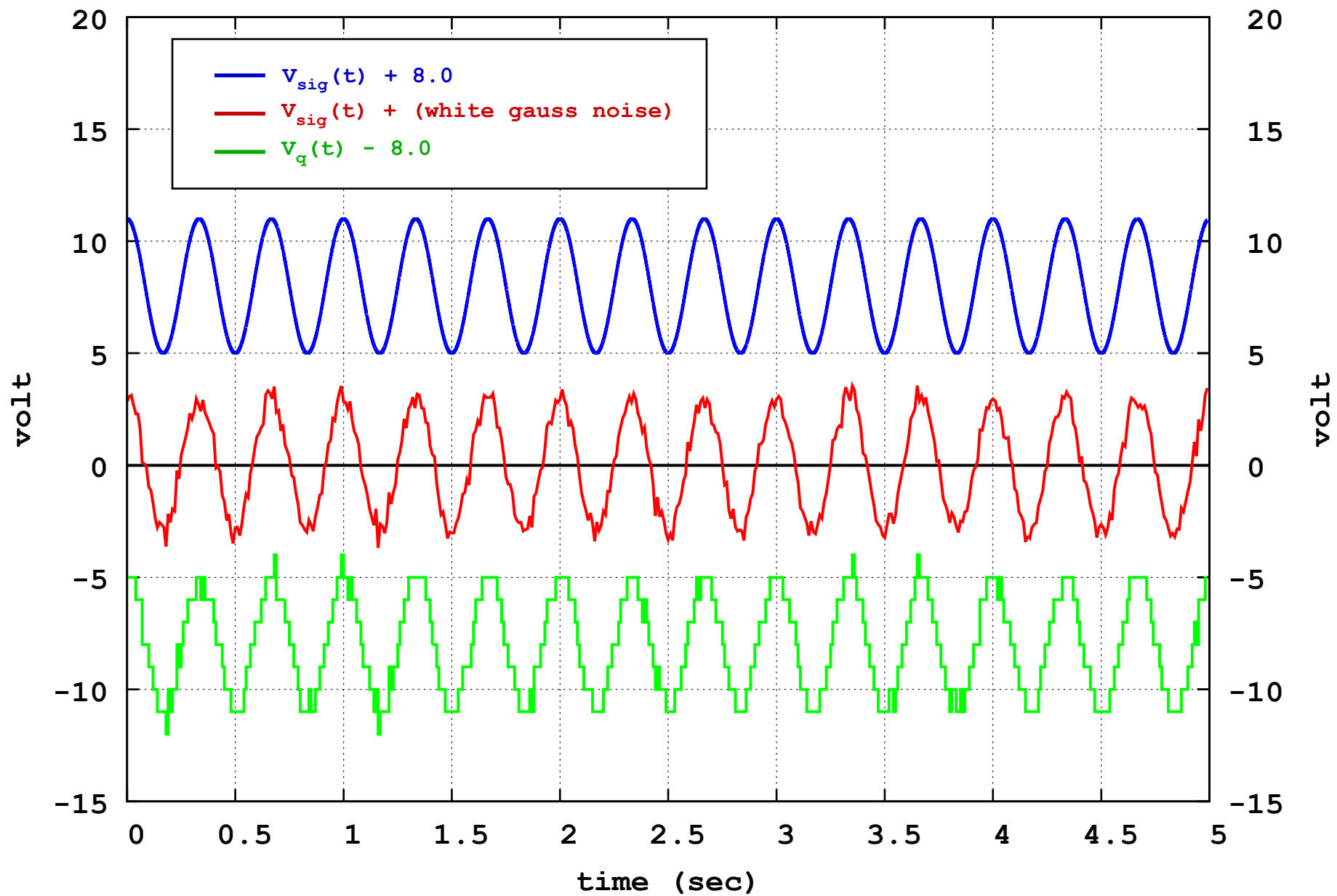
$$\mathbf{a0 = 3.0 Vpeak}$$

$$f_{\text{sig}} = 3 \text{ Hz}$$

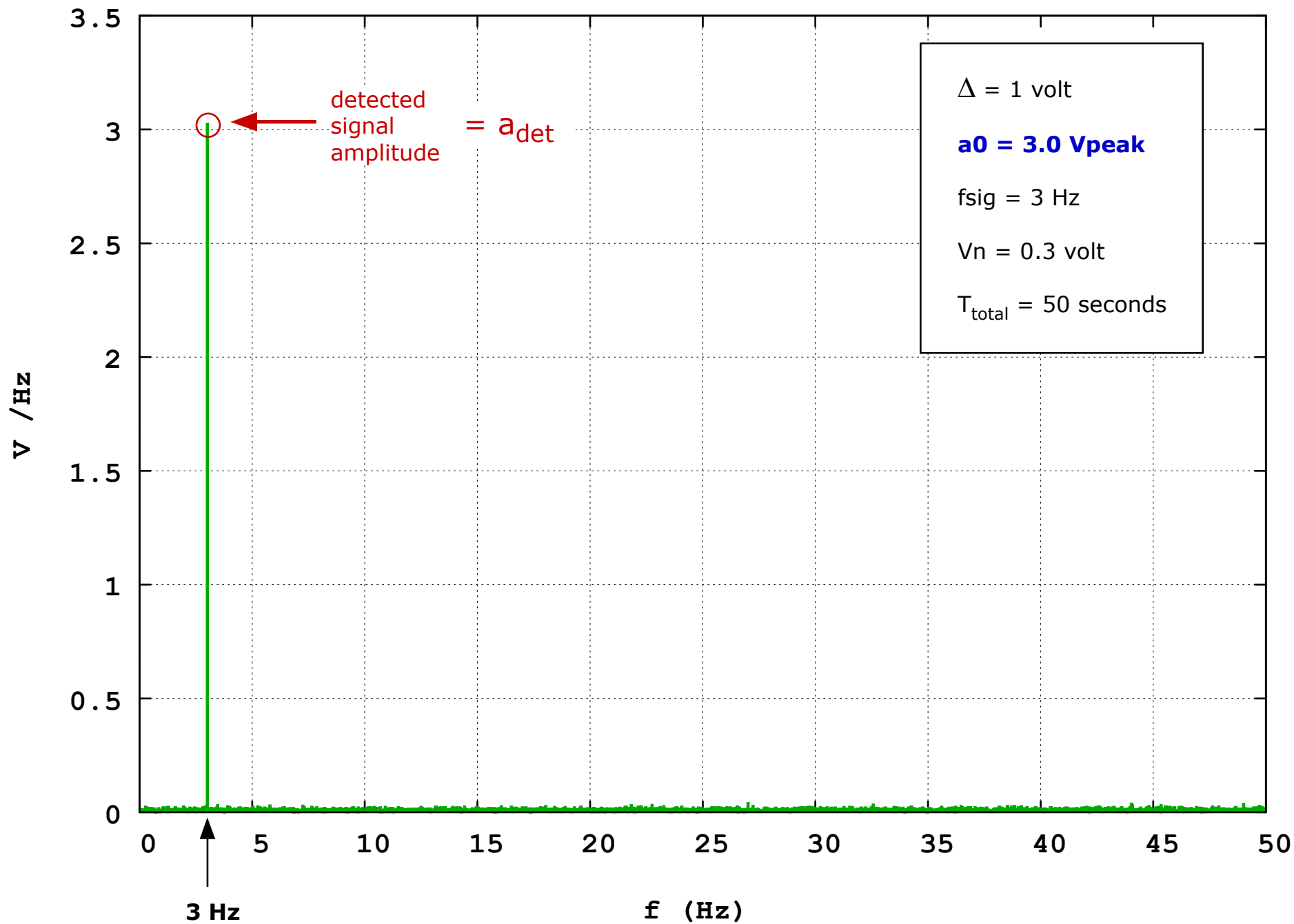
$$\mathbf{Vn = 0.3 \text{ volt}}$$

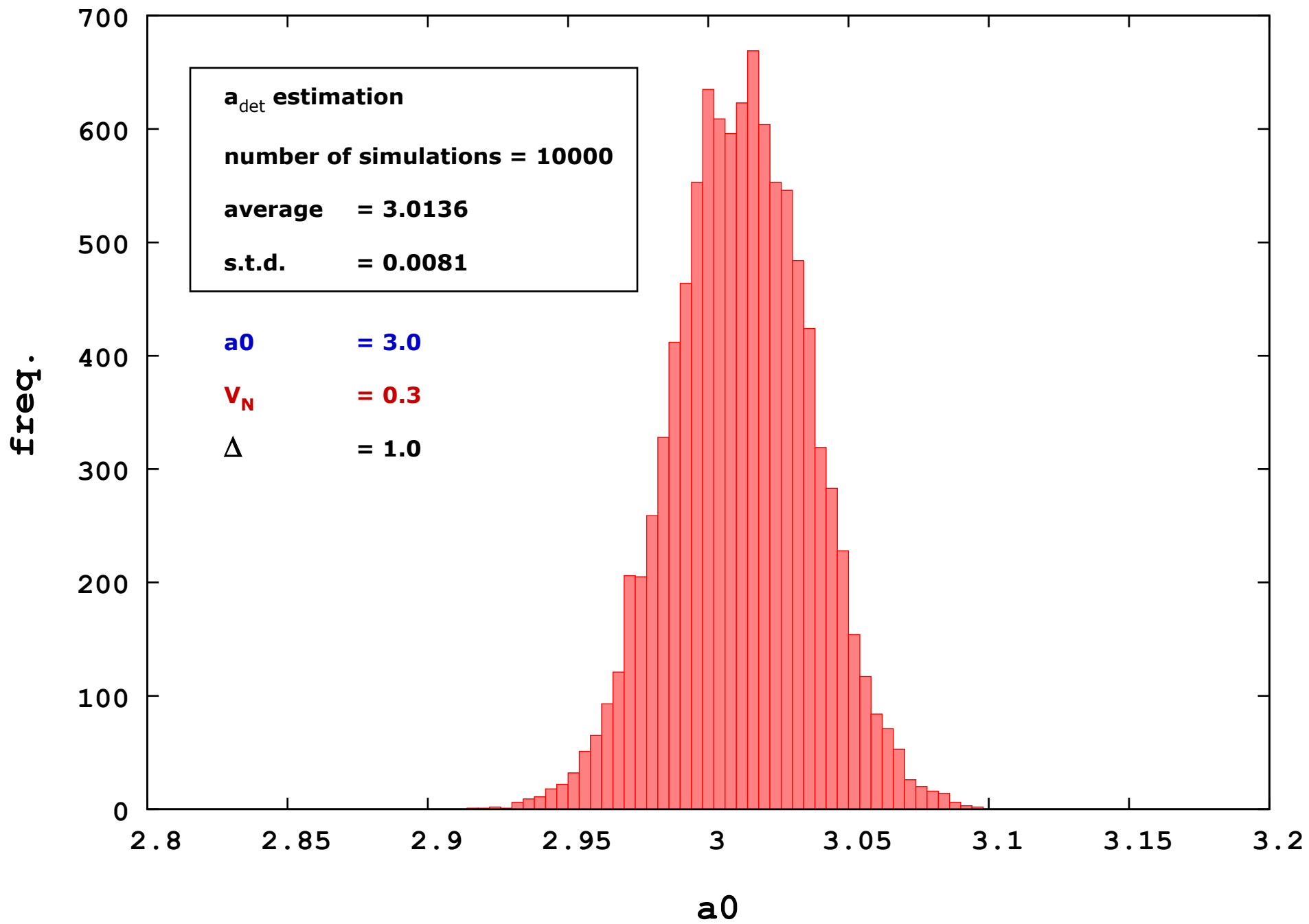
$$T_{\text{total}} = 50 \text{ seconds}$$

dithering simulation: example 0



# Power spectrum of the quantized signal with dithering





## Simulation Example 1 :

$$\Delta = 1 \text{ volt}$$

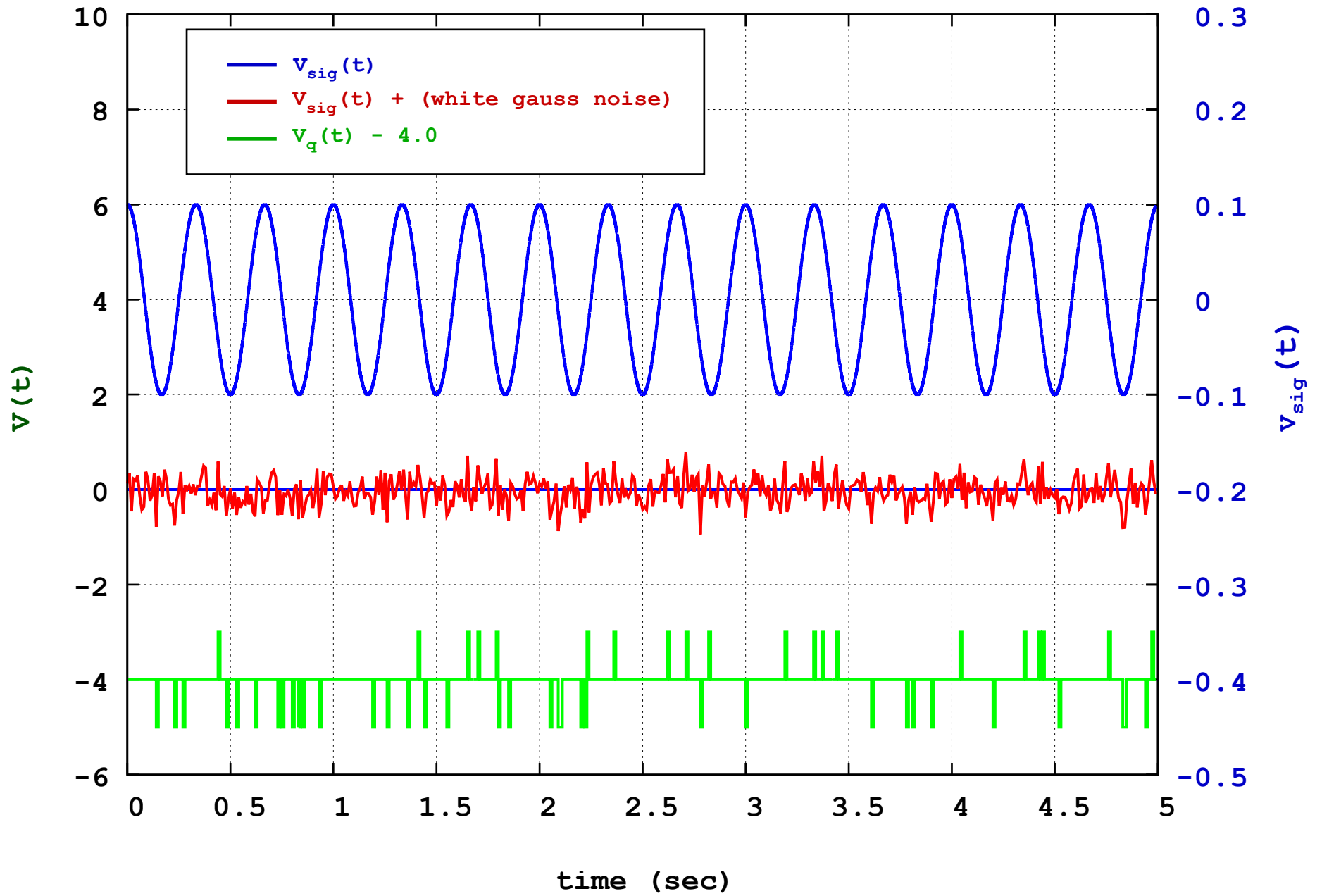
$$\mathbf{a0 = 0.1 V_{peak}}$$

$$f_{sig} = 3 \text{ Hz}$$

$$\mathbf{Vn = 0.3 \text{ volt}}$$

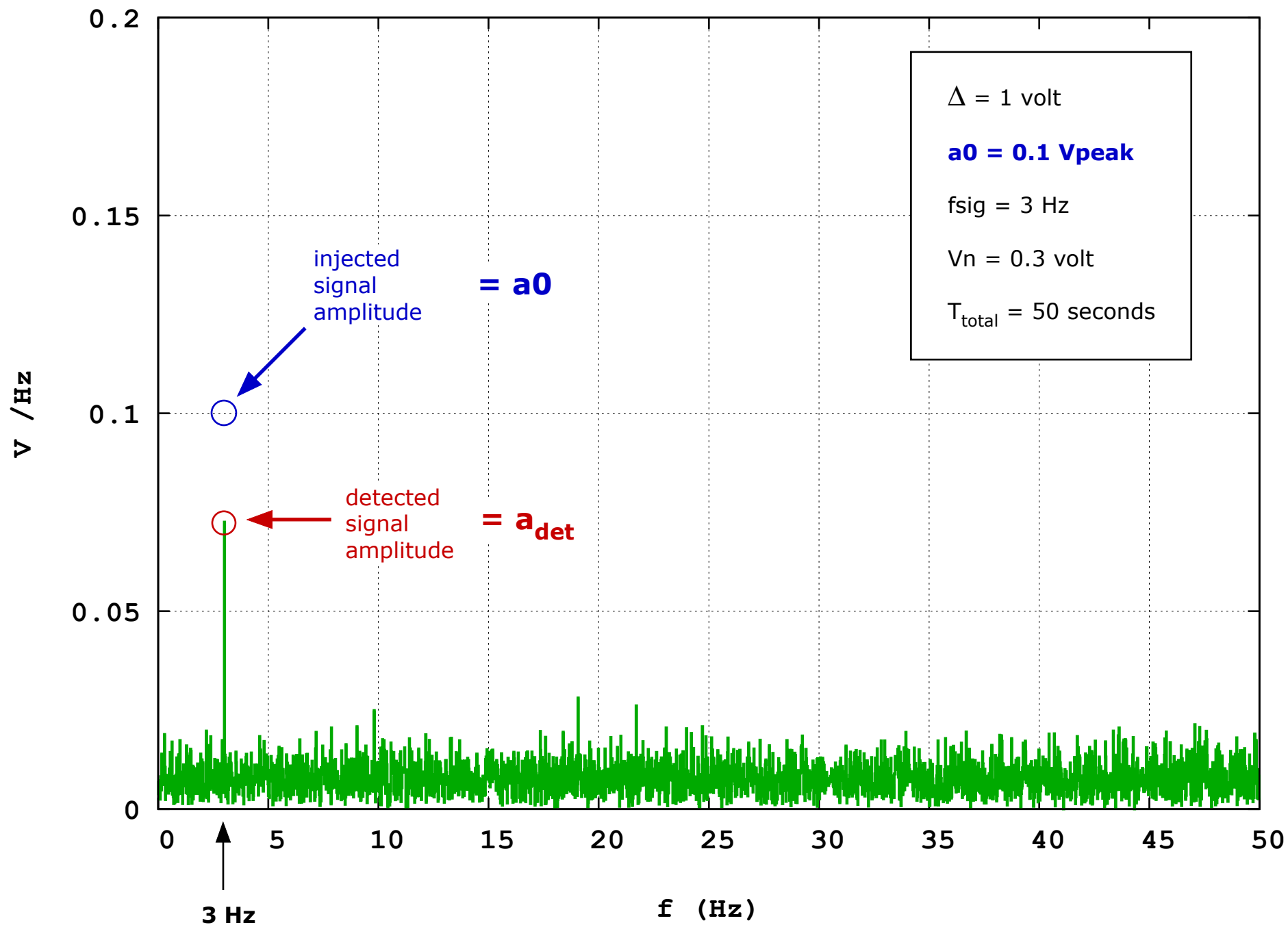
$$T_{total} = 50 \text{ seconds}$$

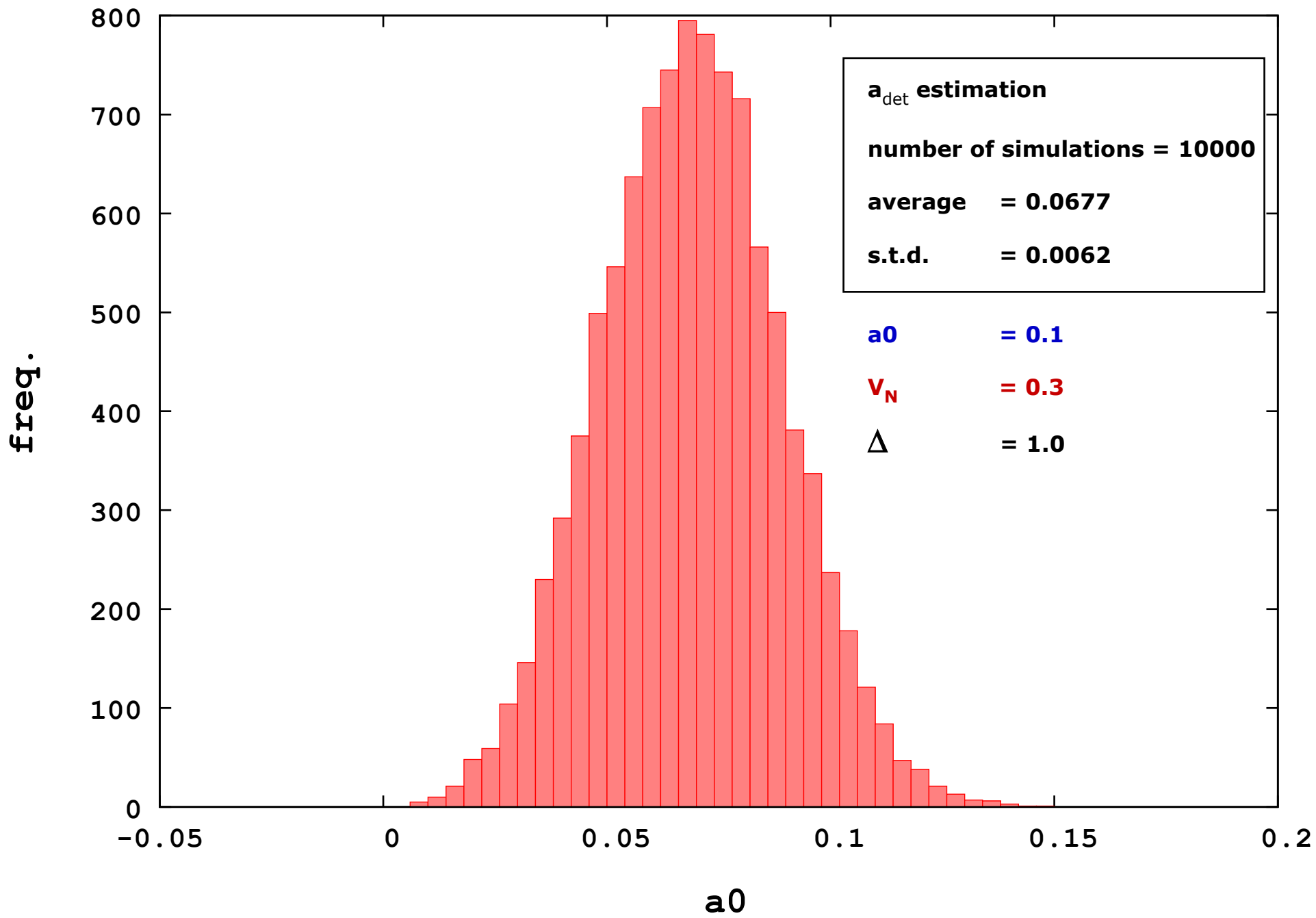
# dithering simulation: example 1



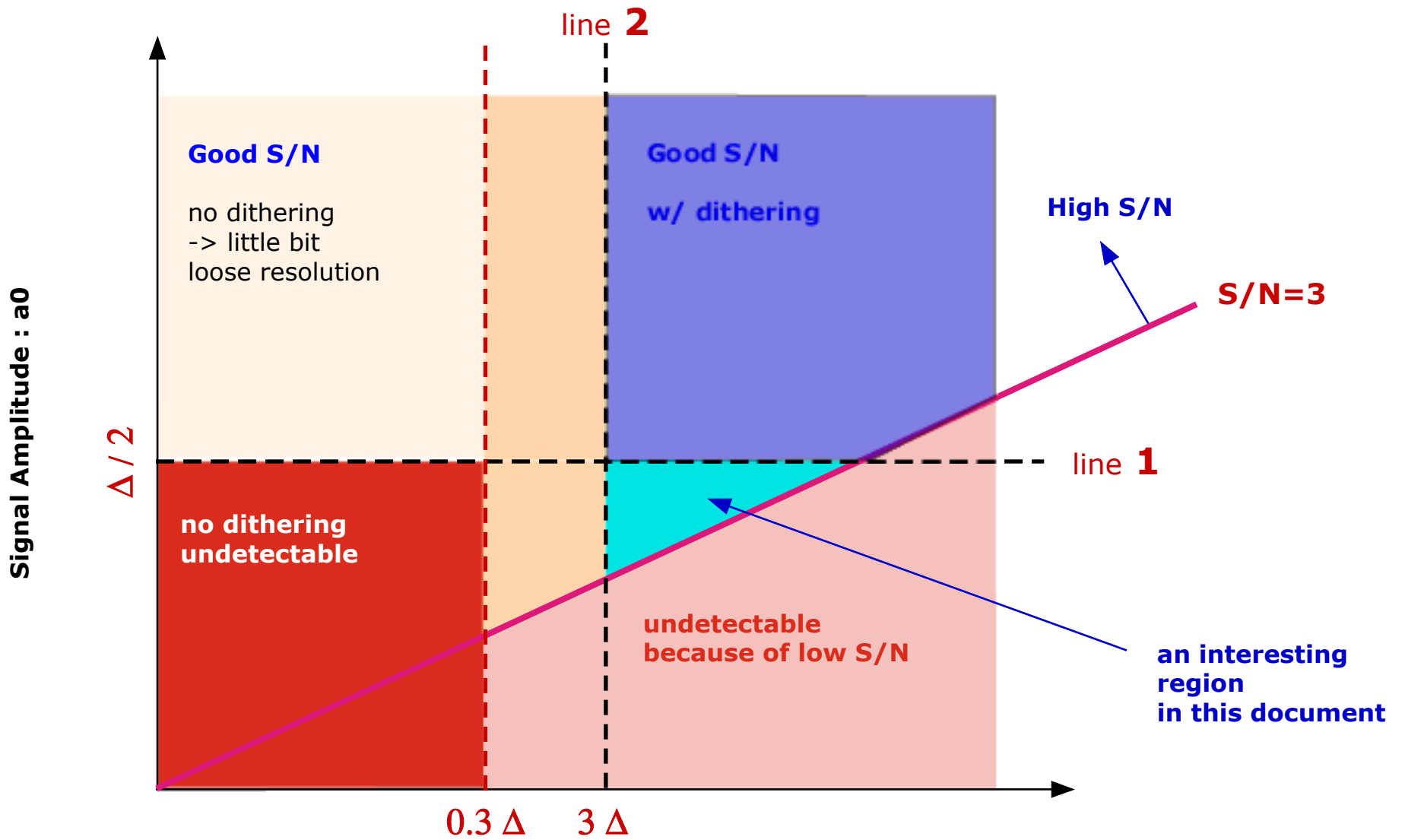


# Power spectrum of the quantized signal with dithering









**white noise level :  $V_n$**

\*\* standard deviation of the noise

## To set simulation parameters

When  $G=1$ ,  $V_n * G = V_n = 0.3 \Delta$

$S/N = a_0 /$

# Intuitive speculations

Line 1:

It is obvious that a sinusoidal wave of amplitude less than  $\Delta / 2$  loses all of information in the case of no dithering by the quantization.

Line 2:

How large white noises are effective as dithering?

Answer;

$0.3 \Delta$  is a minimum amplitude for dithering. But it makes non-negligible signal loss.

$3 \Delta$  seems to be enough large and makes the signal loss small.

S/N=3

If there is no quantizer, we can calculate the expected S/N.

# White Gaussian Noise

$$V_n^2 \stackrel{\text{def}}{=} \frac{1}{T} \int_0^T v^2(t) dt$$

$$V_n^2 = 2 \int_0^{f_N} \widetilde{s}_n(f) df = 2f_N \widetilde{s}_n = f_s \widetilde{s}_n$$

$f_N$ : Nyquist freq.

$f_s$ : Sampling freq.

$$\widetilde{s}_n = \frac{V_n^2}{f_s}$$

Power Spectrum Density (PSD)  $V^2/\text{Hz}$

$$\sqrt{\widetilde{s}_n} = \sqrt{\frac{V_n^2}{f_s}}$$

Liner Spectrum Density (LSD)  $V/\sqrt{\text{Hz}}$

$$\widetilde{v}_n(f) = V_n \sqrt{\frac{2T}{f_N}}$$

Fourier Transform of  $v(t)$

$V/\text{Hz}$

$$a_{noise} = \widetilde{v}_n(f) \cdot \Delta f = \frac{2}{\sqrt{f_s T}} \times V_n$$

in a unit of Volt

$$a_{noise} = \widetilde{v}_n(f) \cdot \Delta f = \frac{2}{\sqrt{f_s T}} \times V_n$$

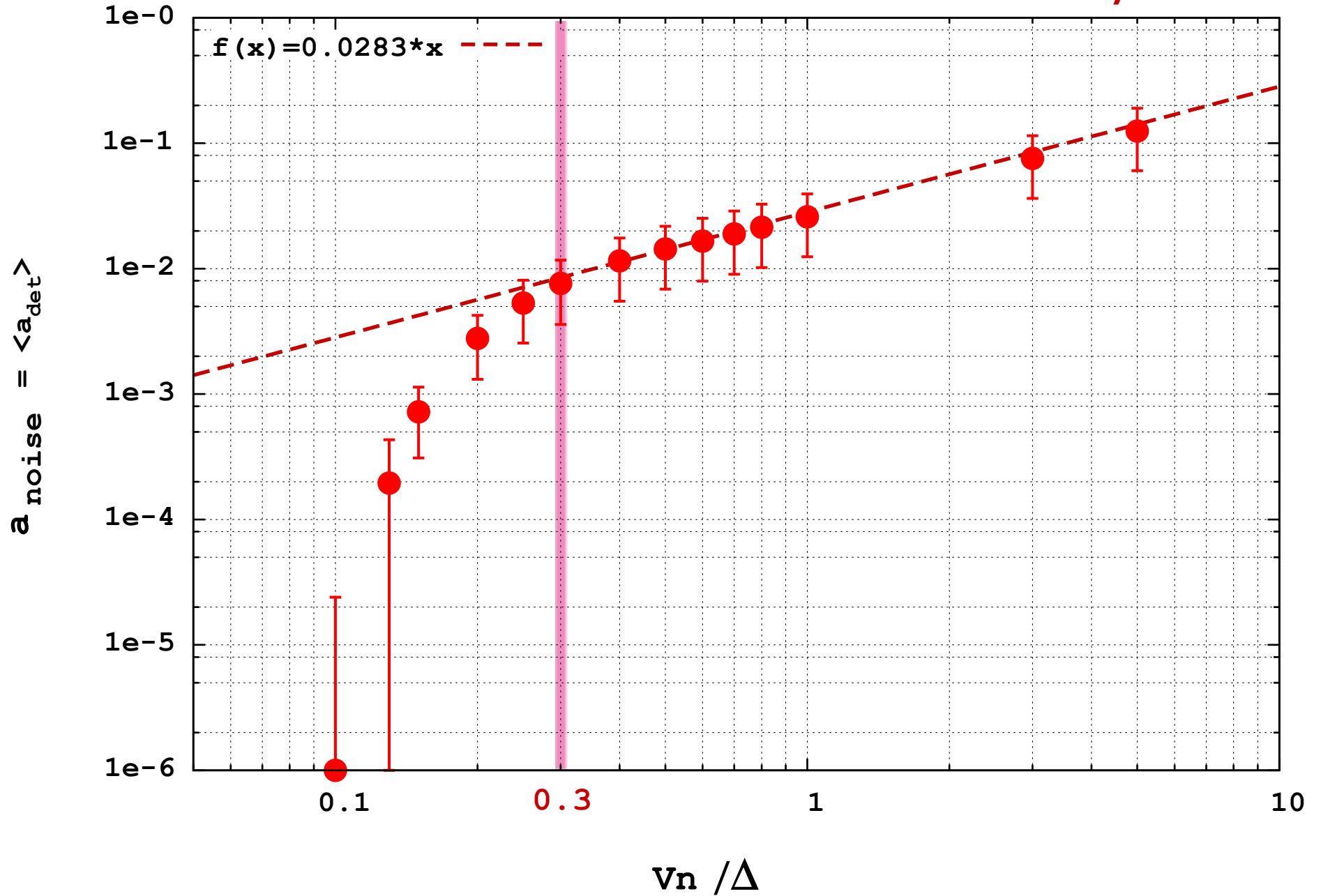
$$f_s = 100 \text{ Hz}, T = 50 \text{ sec}$$

$$\text{--> } \underline{a_{noise} = 0.0283 \times V_n}$$



# dithering noise amplitude estimation

$a_0 / \Delta = 0.0$

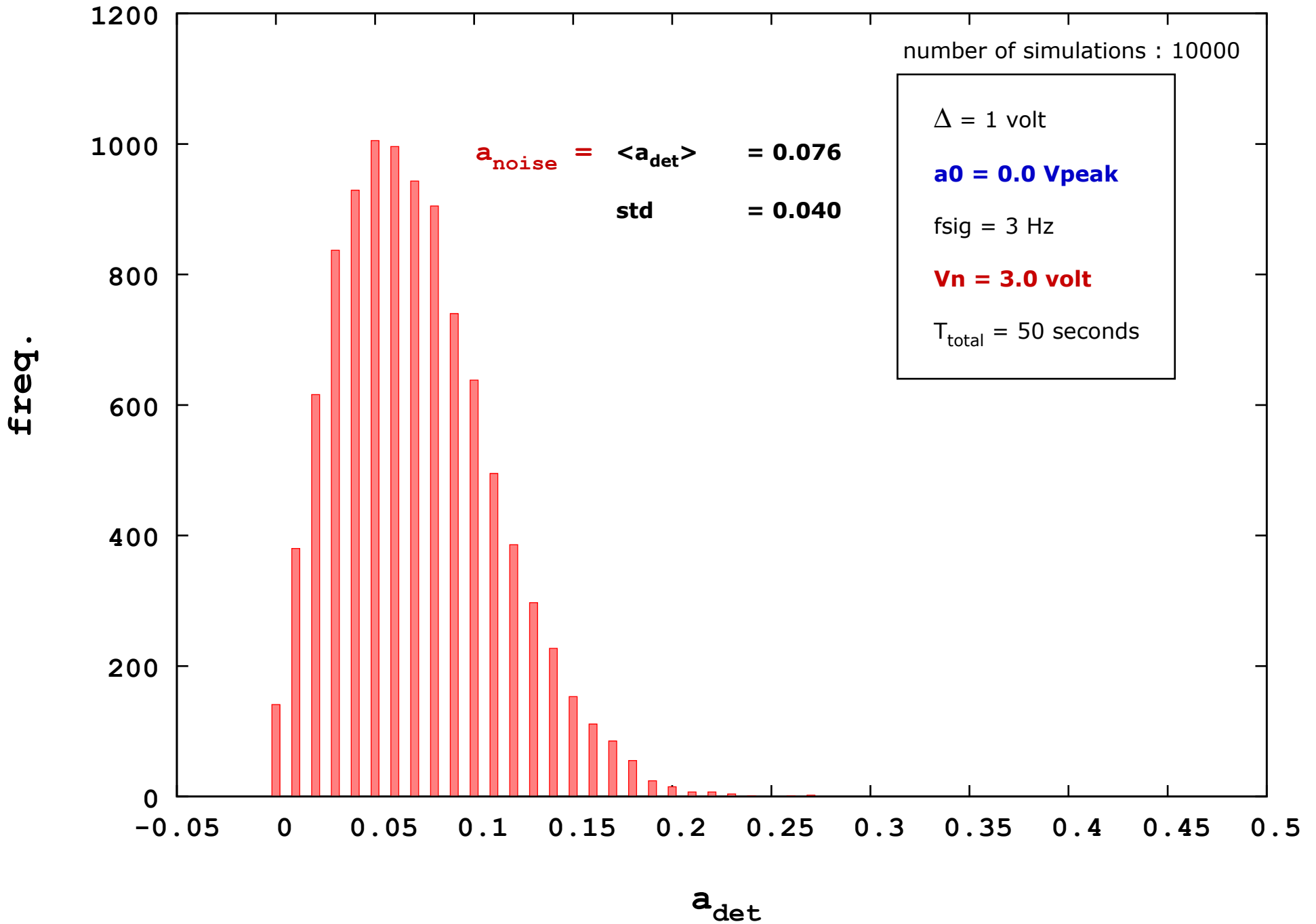


\*\*\*  $a_{noise}$  can be estimated as follows

$$a_{noise} = \widehat{v}_n(f) \cdot \Delta f = \frac{2}{\sqrt{f_s T}} \times V_n$$

The estimations are well consistent with dithered and quantized data.

# Rayleigh distribution



# Rayleigh function

$$PDF(x, \sigma) = \frac{x^2}{\sigma^2} \exp\left(-\frac{x^2}{\sigma^2}\right)$$

$$\text{Mean} = \sqrt{\frac{\pi}{2}} \sigma$$

$$\text{Deviation} = \left(2 - \frac{\pi}{2}\right) \sigma$$

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$$\text{Standard deviation} = \sqrt{\frac{4}{\pi} - 1} \times \text{Mean} = \boxed{0.523 \times \text{Mean}} = \sigma_R$$

 **0.523 x Mean**

 **0.70 x Mean**

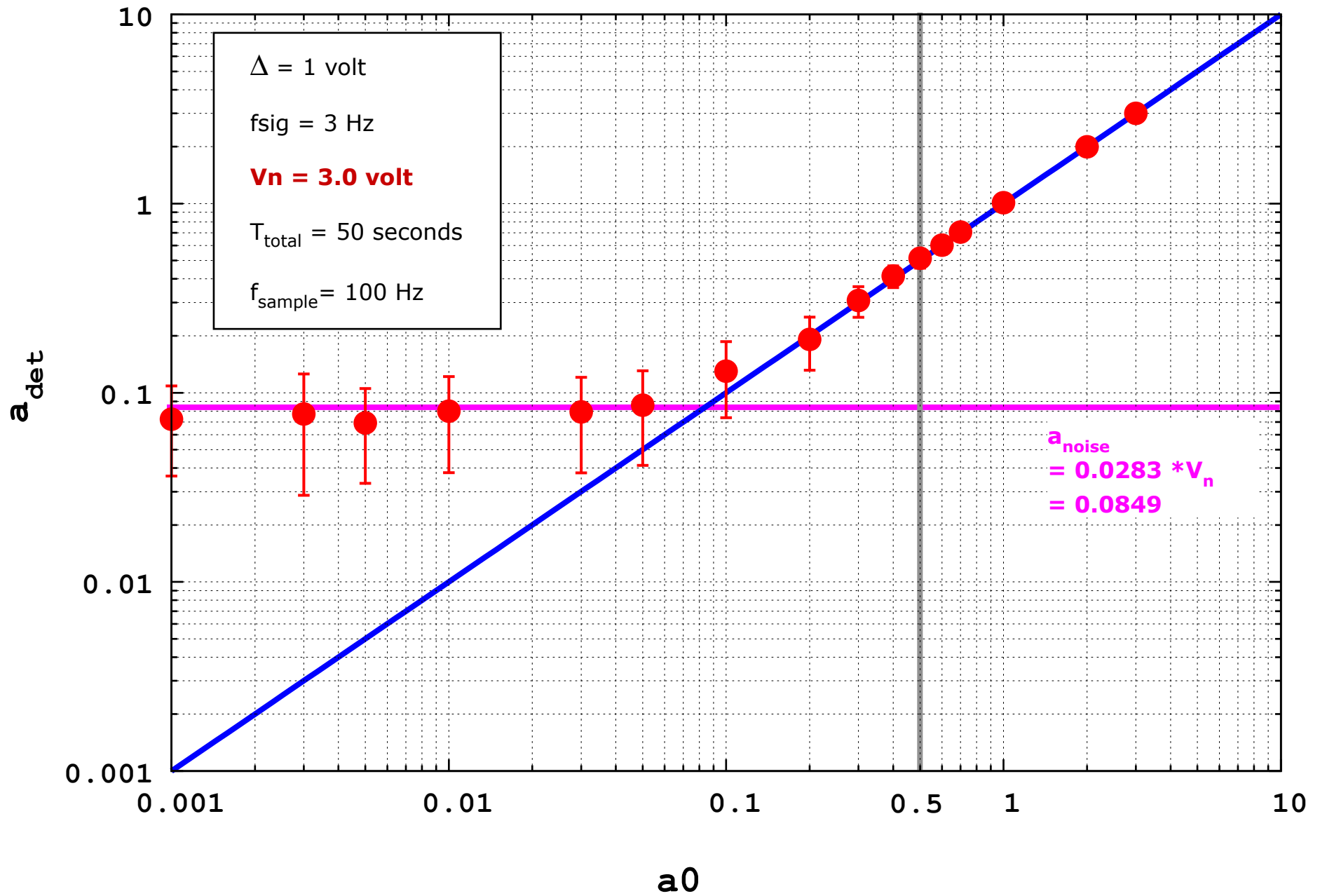
 **Mean**

## The standard deviation of the " $a_{\text{det}}$ "

In the case of  $a_0 = 0$ ,  
the probability density function obeys Rayleigh function.  
Therefore,

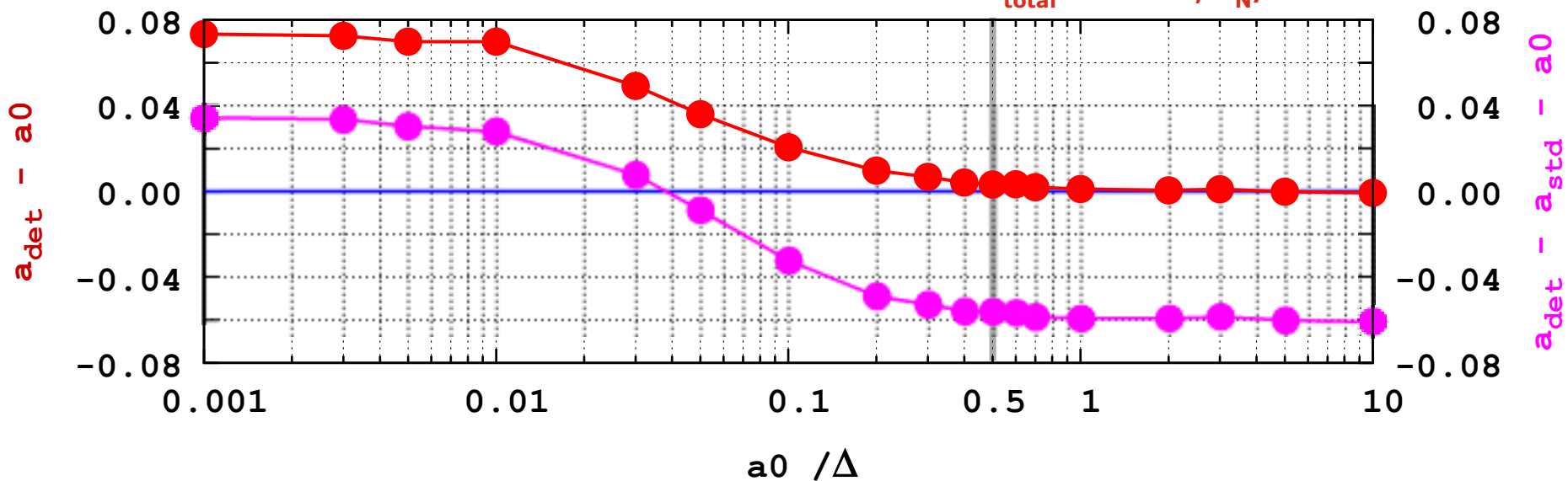
$$\begin{aligned}\text{std of } a_{\text{det}} &= 0.523 \times (\text{mean of } a_{\text{det}}) \\ &= 0.523 \times a_{\text{noise}}\end{aligned}$$

# dithering signal amplitude estimation

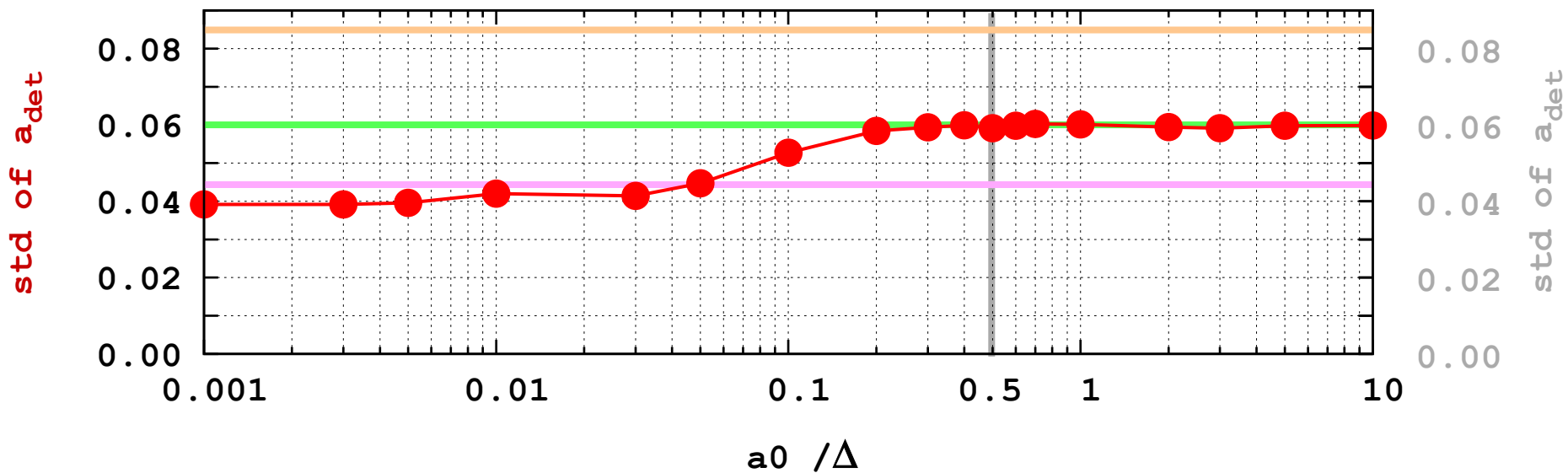


# dithering signal amplitude estimation

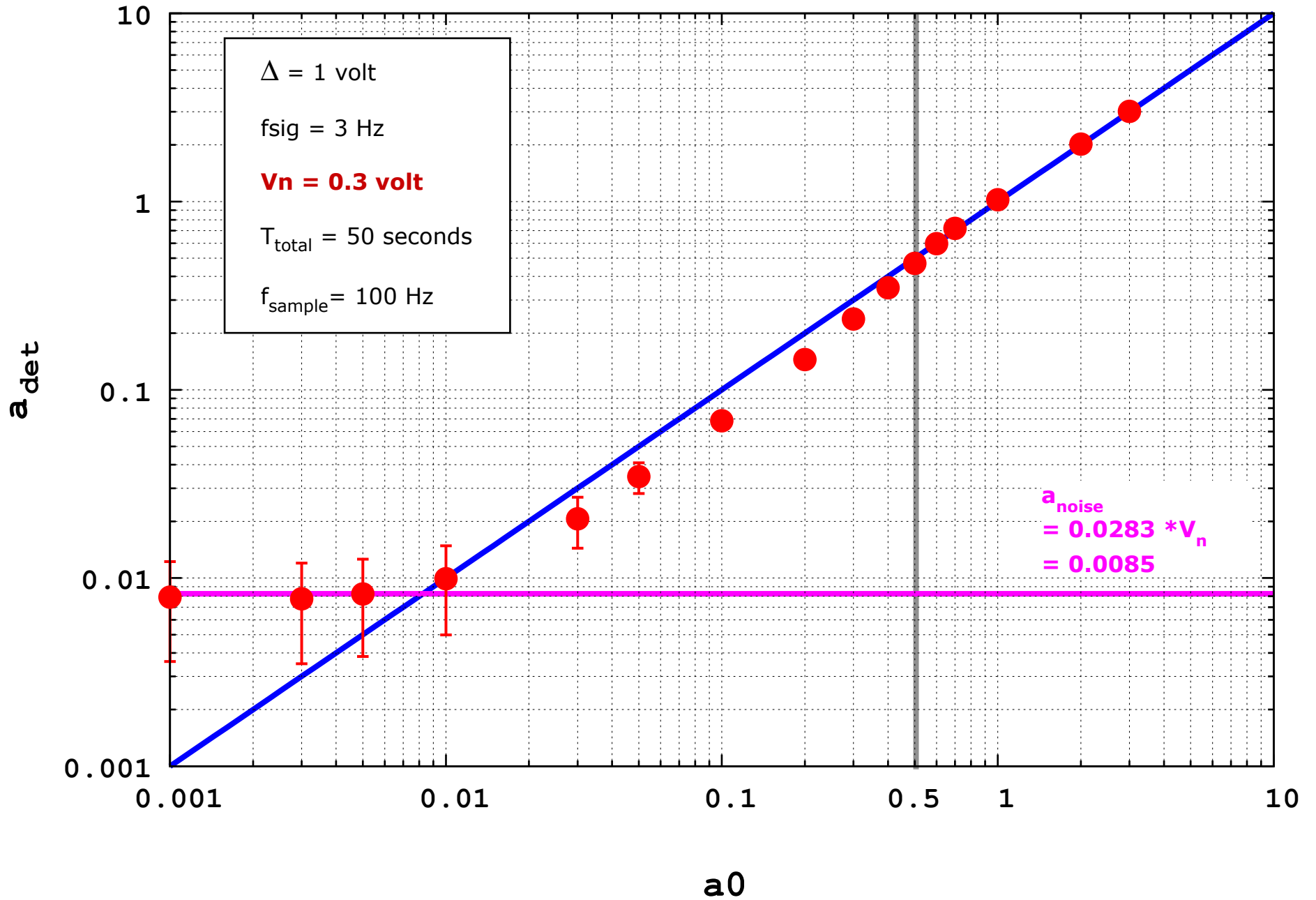
$t_{\text{total}} = 50 \text{ sec}, V_N/\Delta = 3.0$



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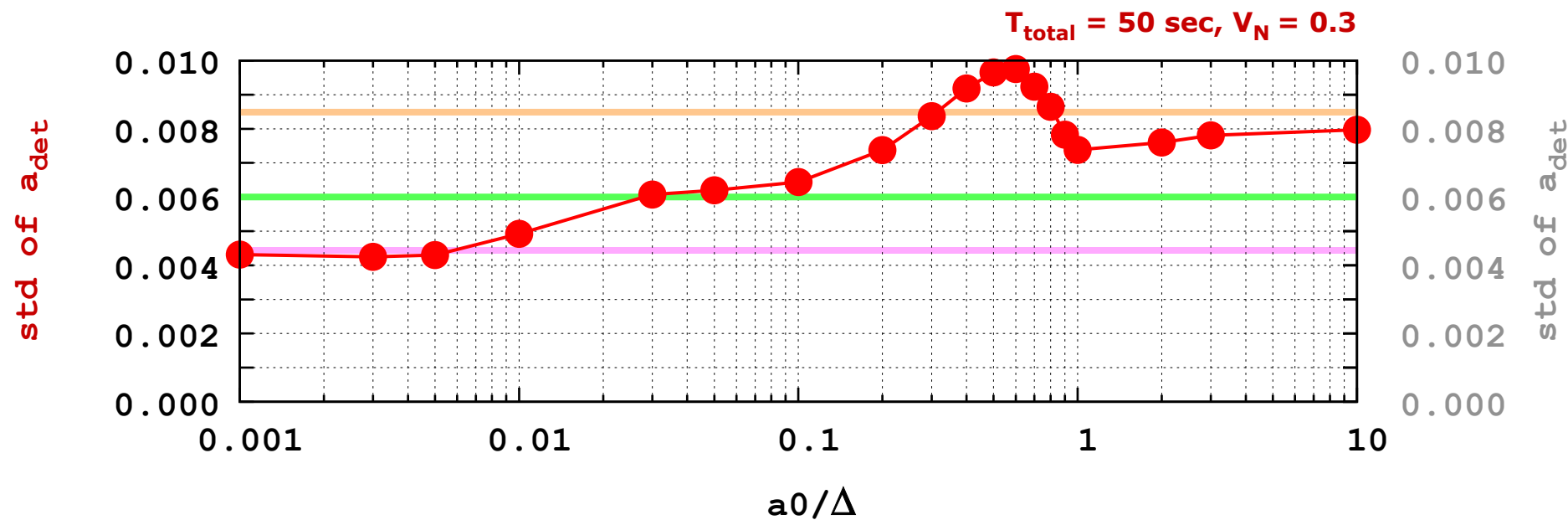
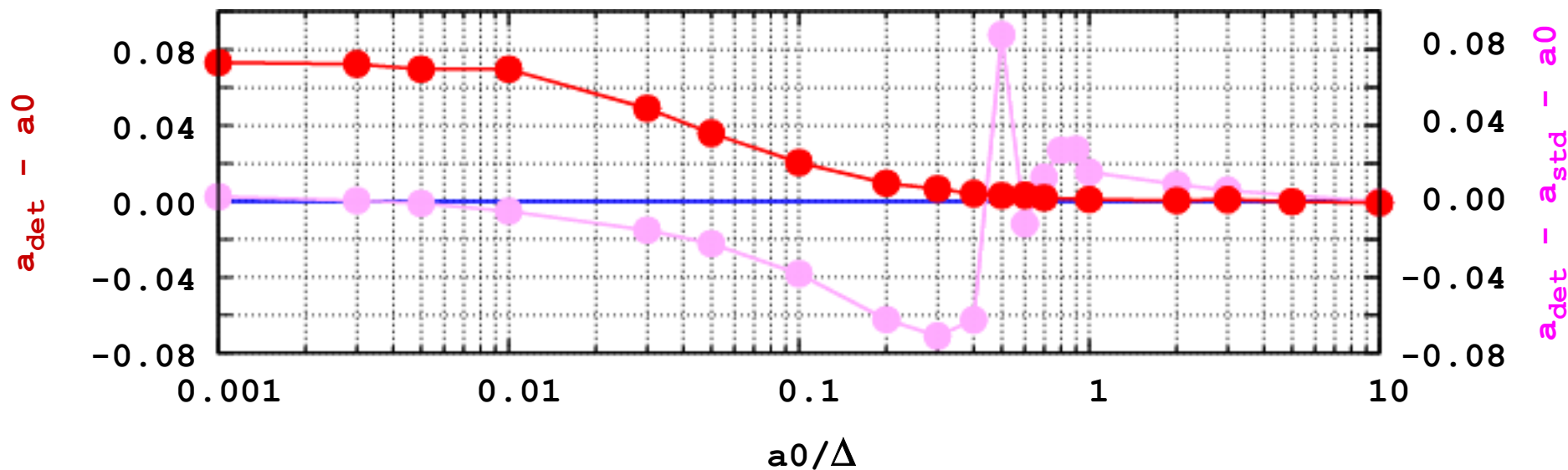
# dithering signal amplitude estimation



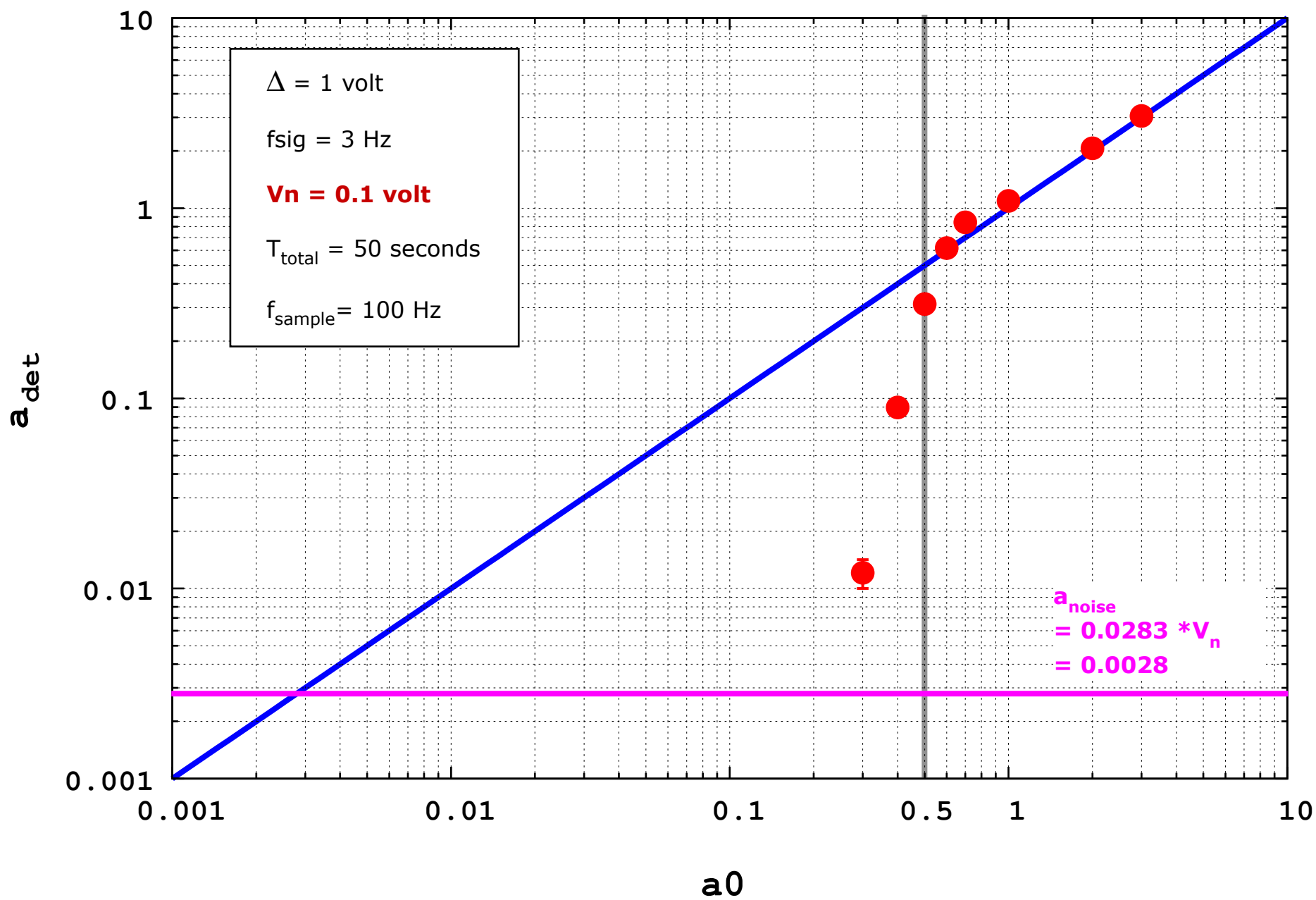


# dithering signal amplitude estimation

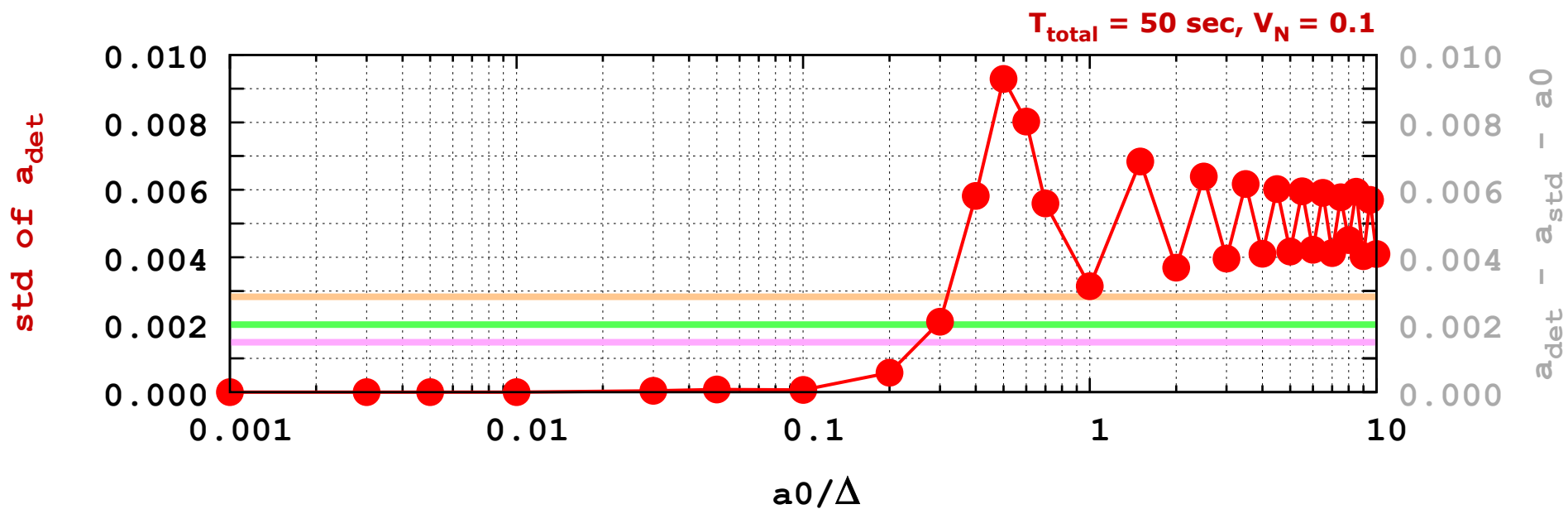
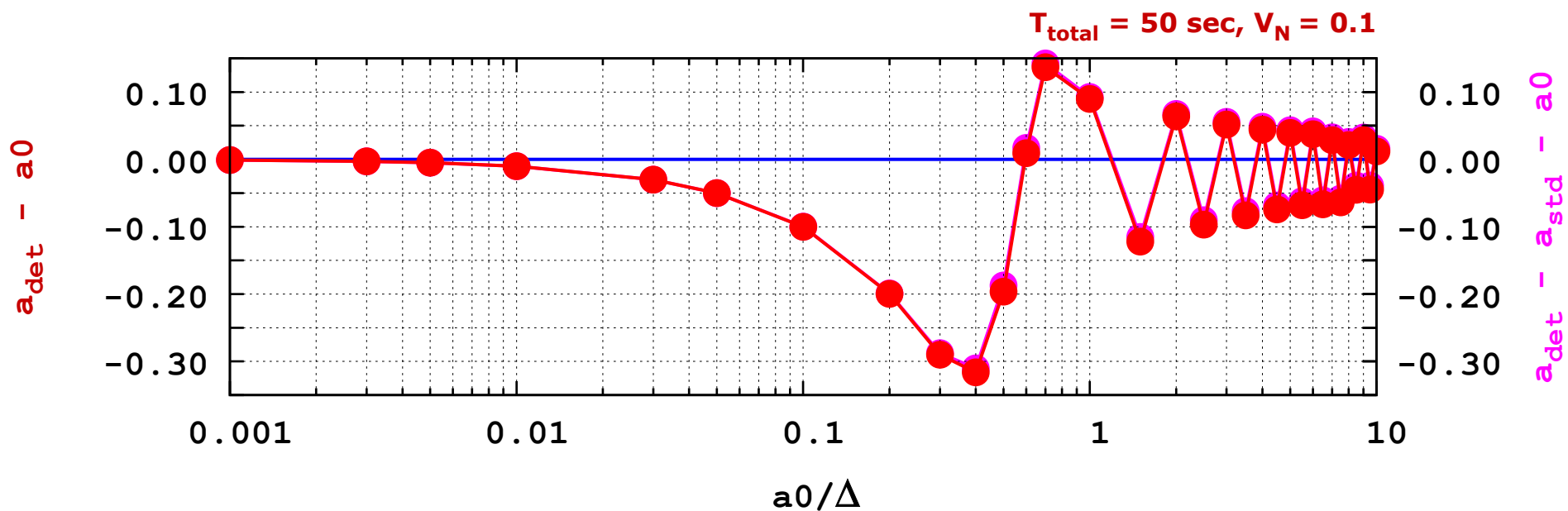
$T_{\text{total}} = 50 \text{ sec}, V_N = 0.3$



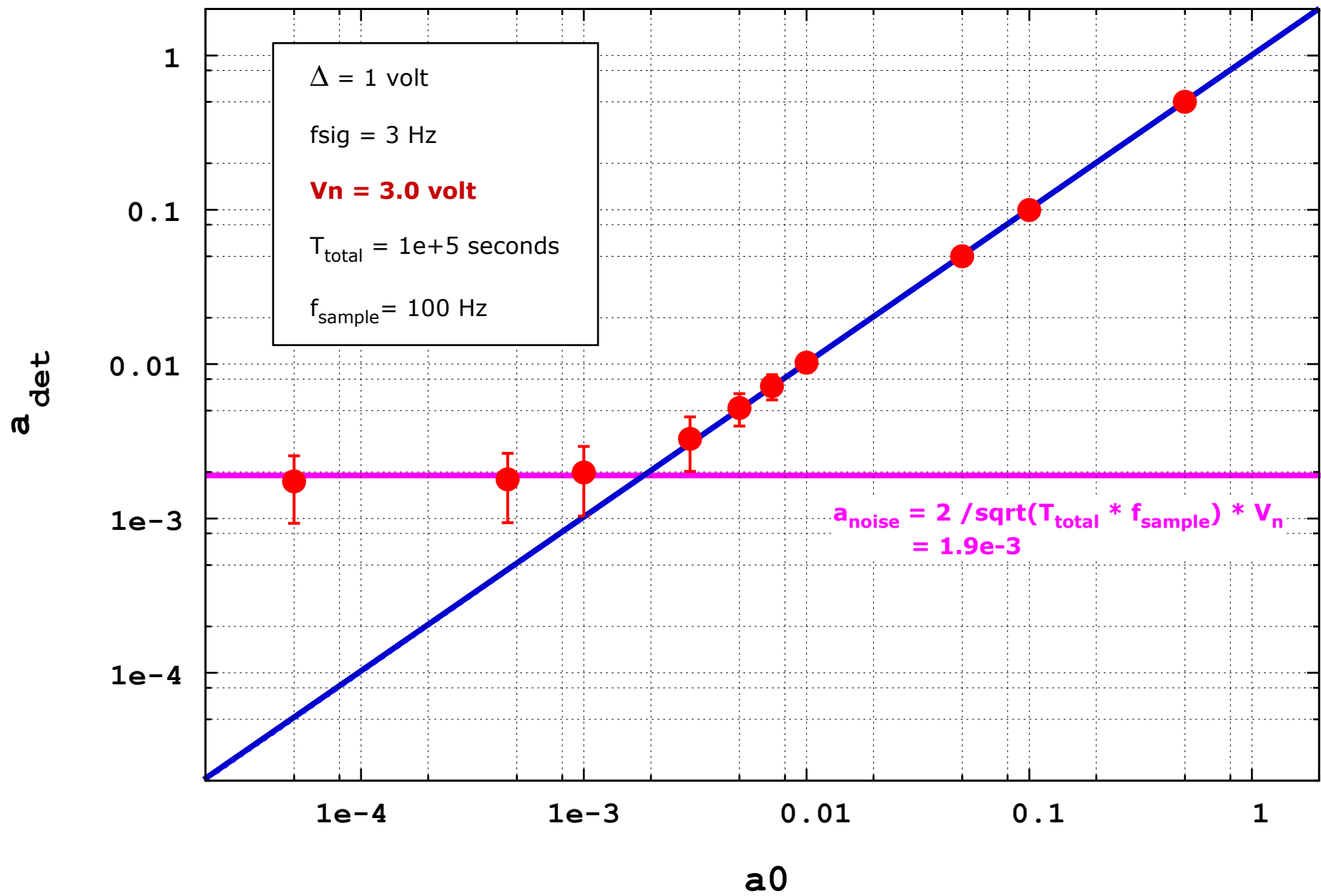
# dithering signal amplitude estimation



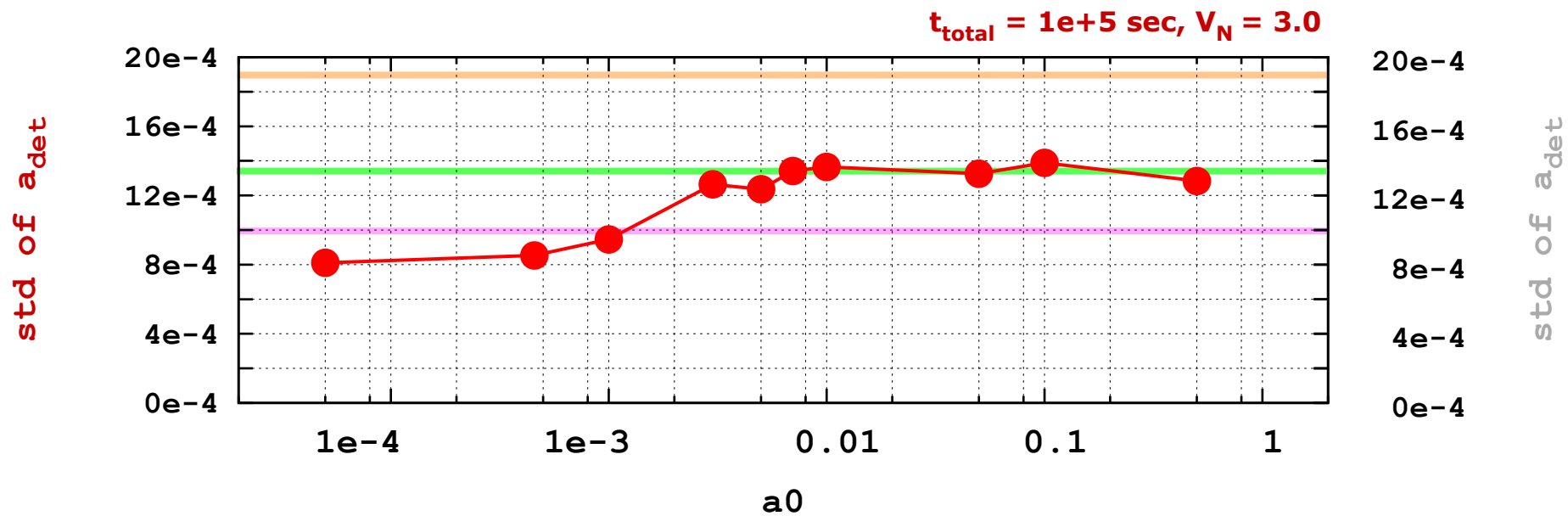
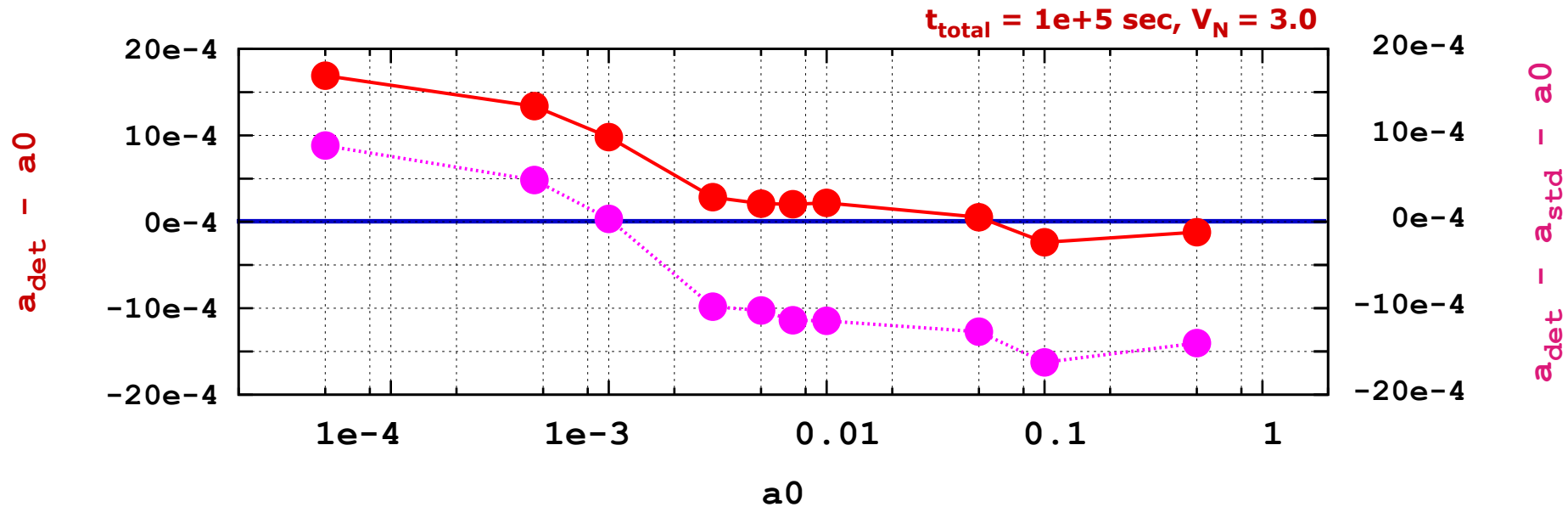
# dithering signal amplitude estimation



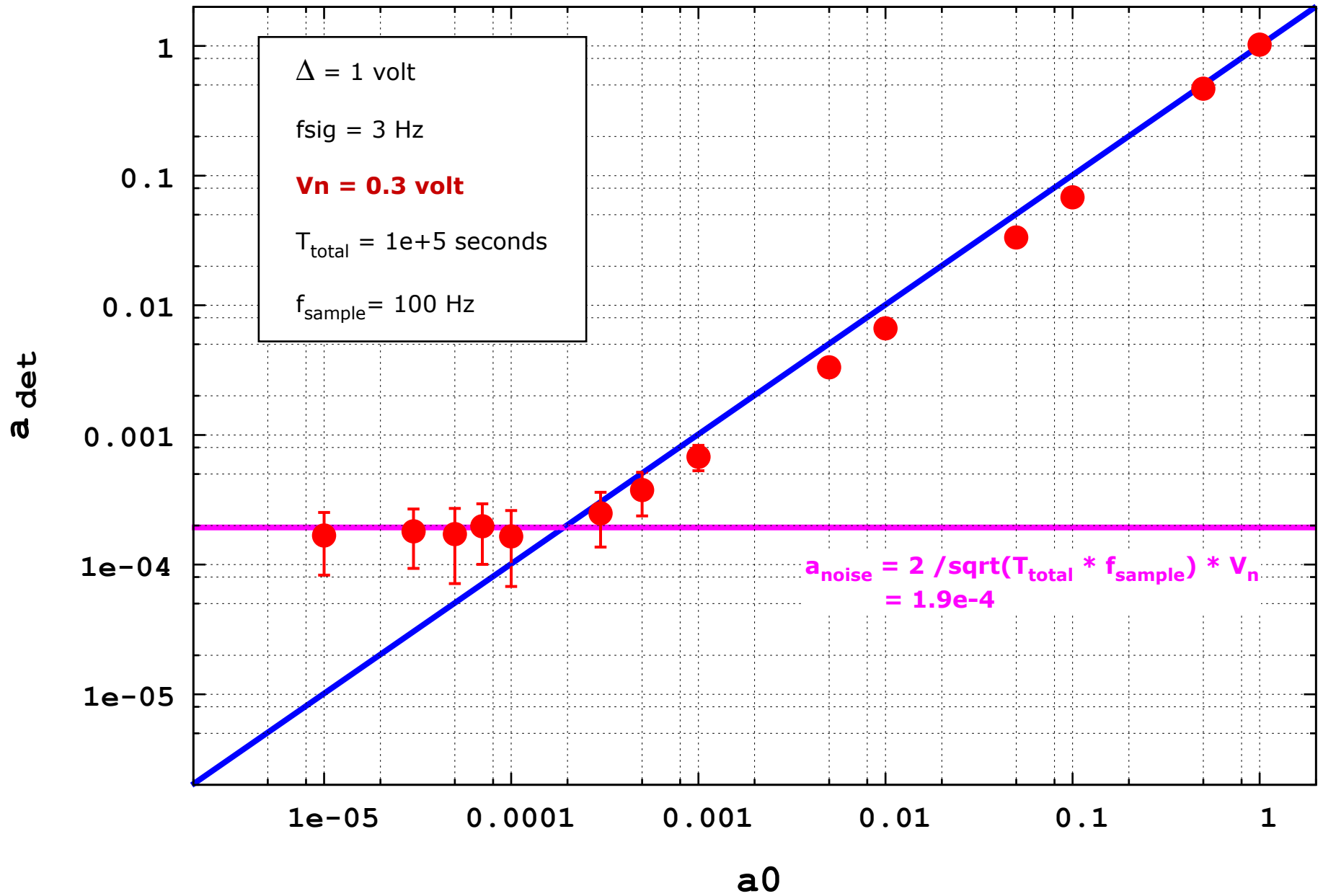
# dithering signal amplitude estimation



# dithering signal amplitude estimation



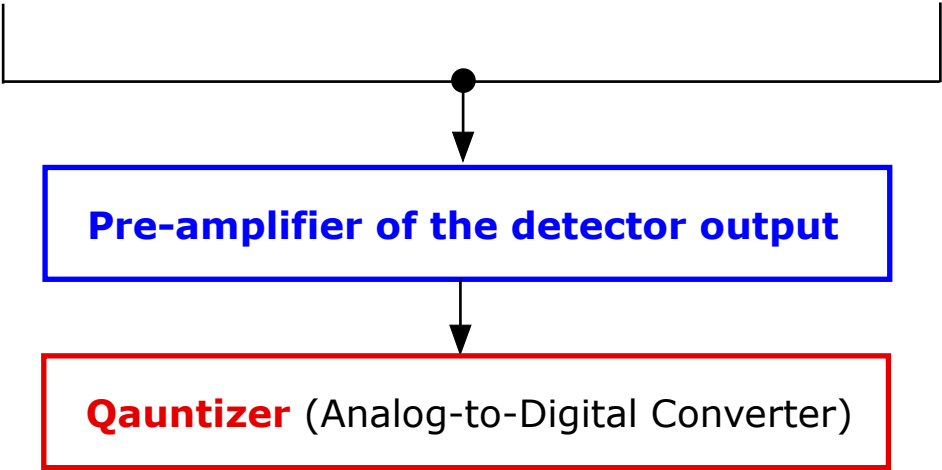
# dithering signal amplitude estimation



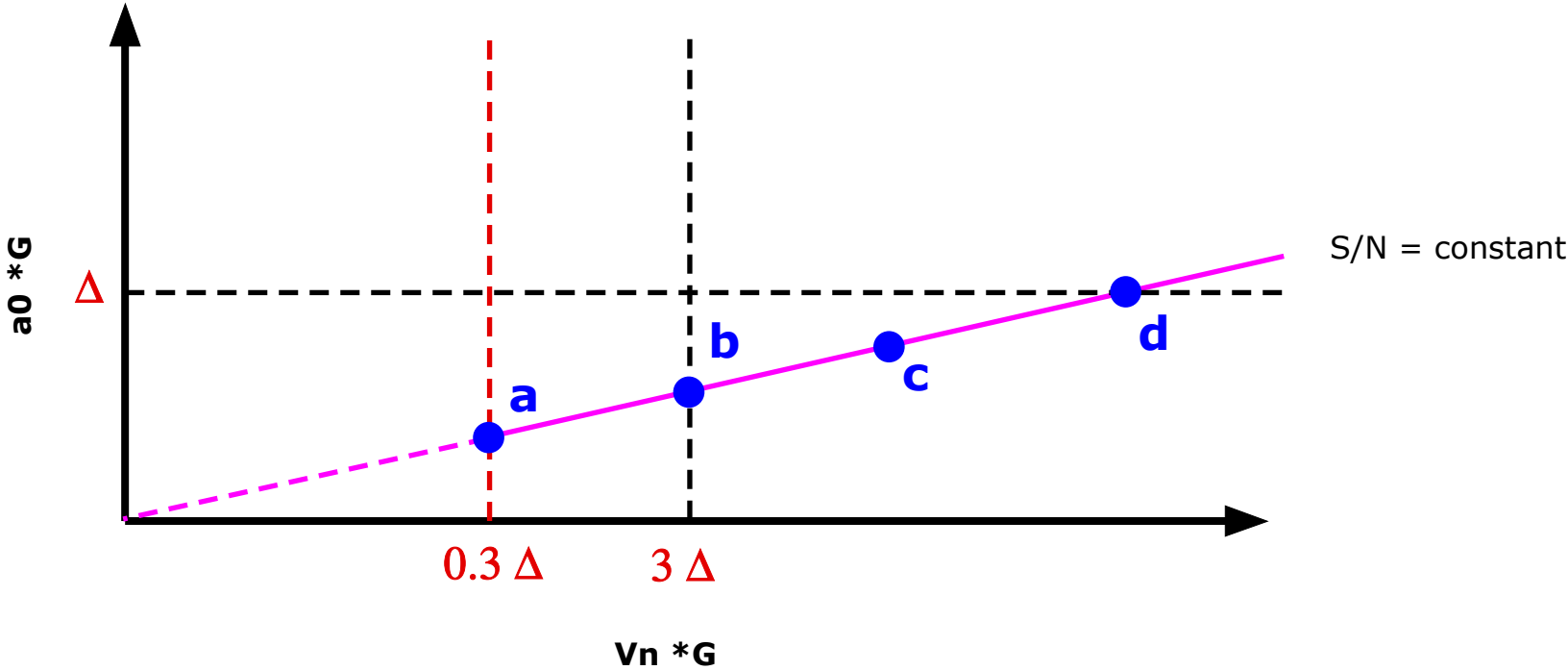
# Realistic situation for controlling dithering conditions

$a_0$ : continuous-wave signal of interest

$V_n$ : white gaussian noise due to the detector



It's Gain =  $G$



## To set simulation parameters

(0)  $\Delta = 1$ ,  $T_{\text{obs}} = 1.0\text{e}+5$  sec ( $\sim 1$  days),  $f_{\text{sample}} = 100$  Hz

(1) When  $G=1$ ,  $V_n * G = V_n = 0.3 \Delta$

(2) Set " $a_0$ "

$$S/N = \frac{a_0}{a_{\text{noise}}} = \frac{a_0 \sqrt{T_{\text{obs}} f_s}}{2 V_n}$$

$$a_0 = \frac{2 V_n (S/N)}{\sqrt{T_{\text{obs}} f_s}}$$

(3) Make simulation data and obtain the analysis results as follows.



## To set simulation parameters

(3) Make simulation data and obtain the analysis results " $a_{\text{det}}/G$ " as follows.

### 3.1 Loss of the signal

$$a' = a_{\text{det}}/G$$

$$a_{\text{measure}} = \text{sqrt} ( a'_{\text{det}}{}^2 - a'_{\text{std}}{}^2 )$$

$$\%loss = \frac{a_{\text{measure}} - a_0}{a_0} \times 100$$

### 3.2 Standard deviation

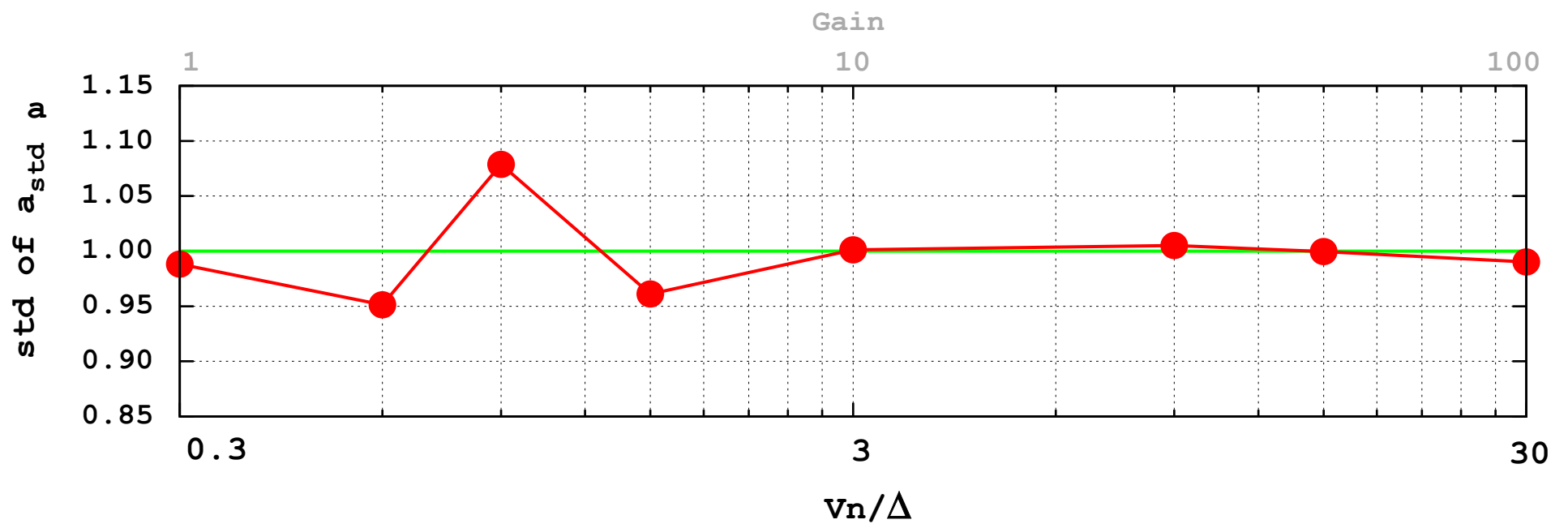
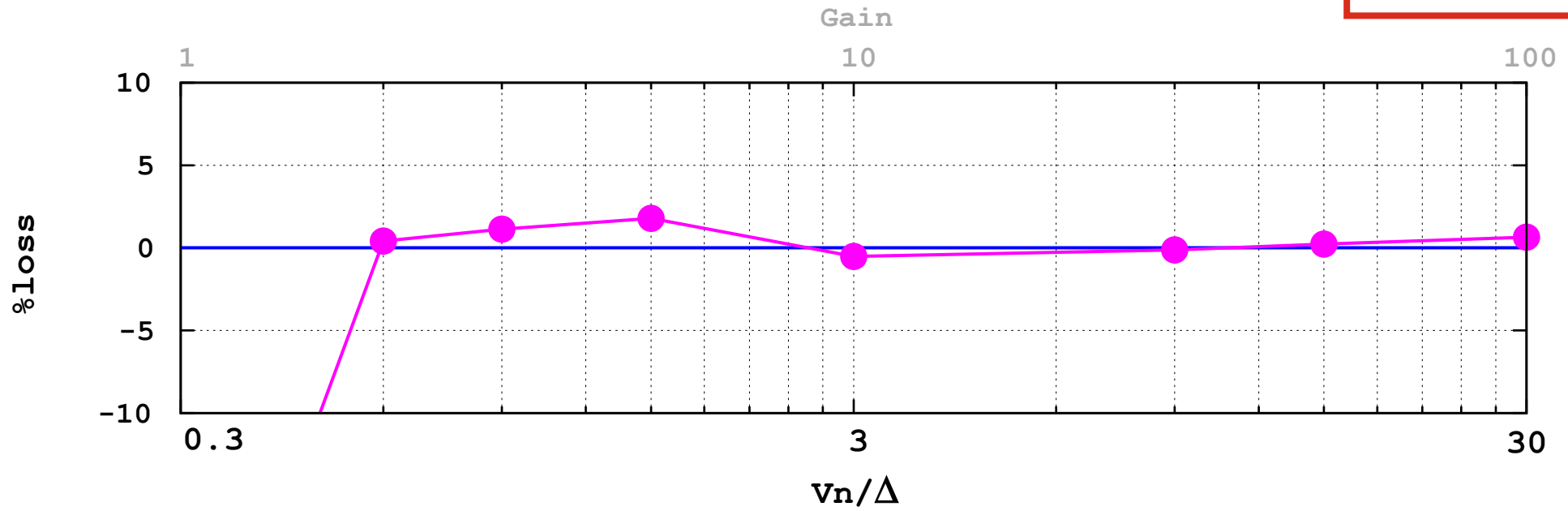
$$(\text{expected } a'_{\text{std}}) = \sqrt{\frac{2}{T_{\text{obs}} f_s}} V_n$$

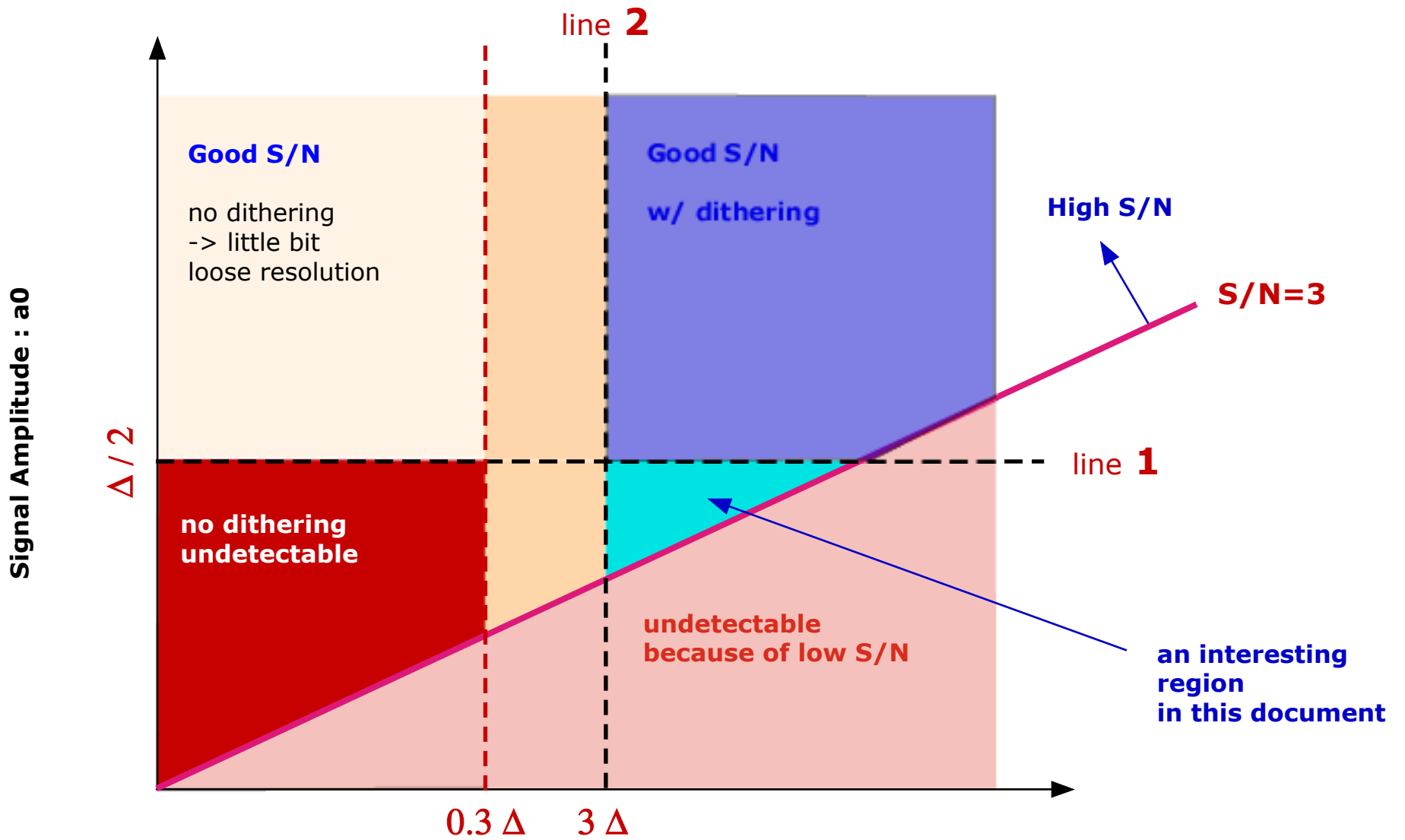
# dithering signal amplitude estimation

$$S/N = a_0/a_{\text{noise}} = 3$$

$$T_{\text{total}} = 1e+5 \text{ sec}$$

$$f_{\text{sample}} = 100 \text{ Hz}$$



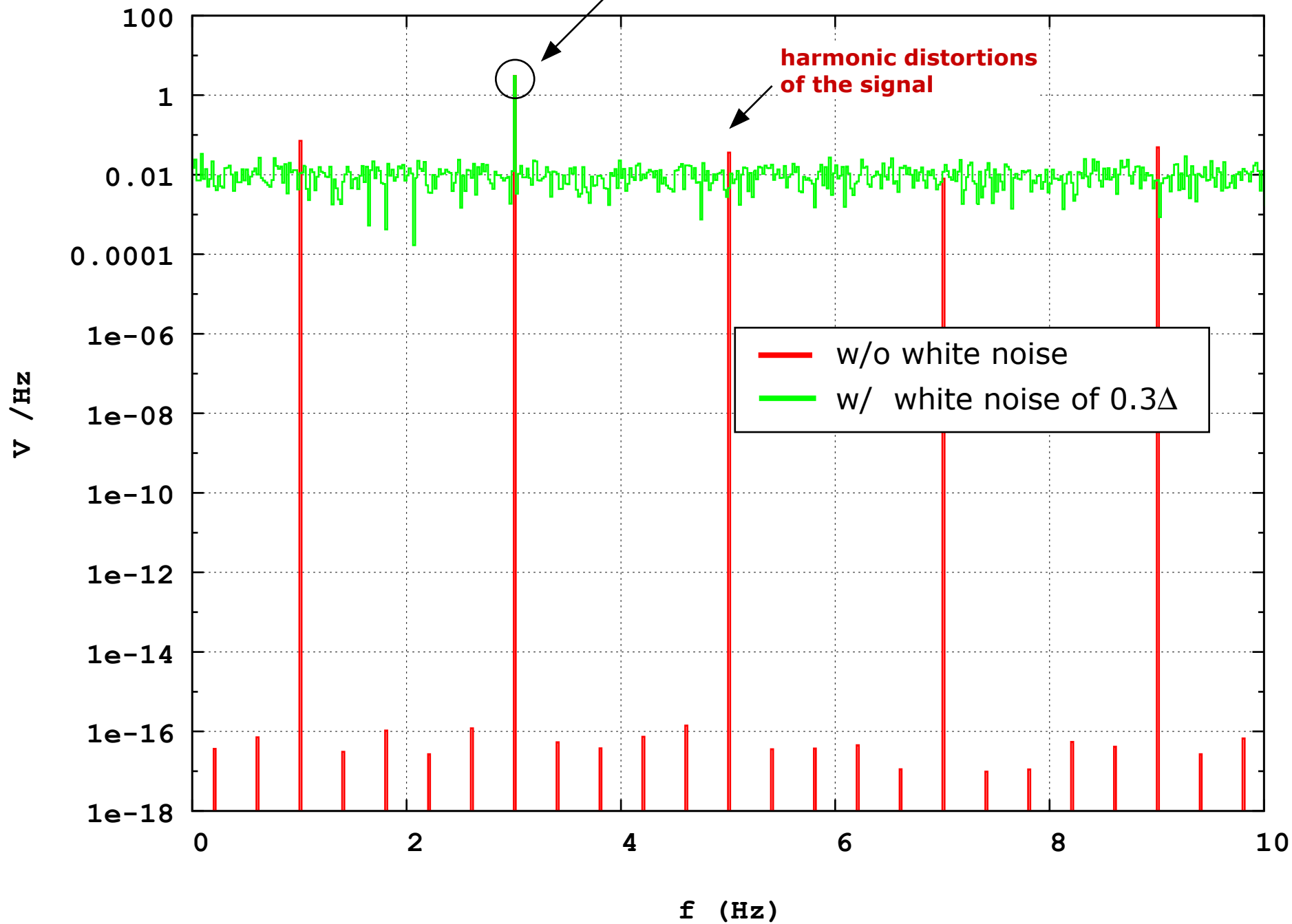


**white noise level :  $V_n$**

\*\* standard deviation of the noise



sinusoidal wave signal:  $a_0=3.0$



dither simulation  
sinusoidal-wave amplitude estimation error

