

# Simulation for understanding what will happen in dithering

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(1) Signal of interest

a sinusoidal wave of  
amplitude: **a0**  
frequency: **f<sub>sig</sub>**

$$v_{\text{sig}}(t) = a_0 * \cos(2 * \pi * f_{\text{sig}} * t)$$

(2) White gauss noise

standard deviation of the noise = **Vn**  
average of the noise = 0.0

random number generator: **gsl\_ran\_gaussian**  
in Gnu Science Library

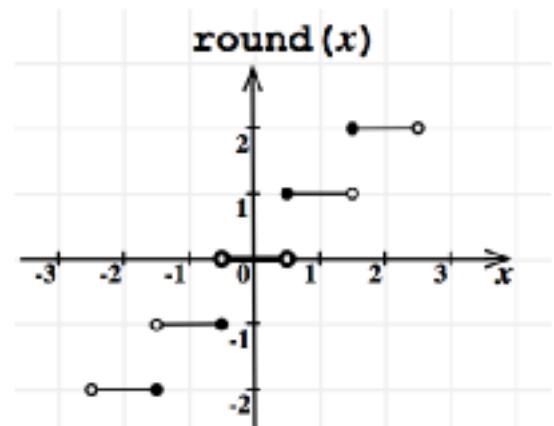
(3) Quantization

$$Vq(t) = \text{round}( V(t) / \Delta ) * \Delta$$

**Δ**: quantization step

The round function in C language has a response as a left figure.

**f<sub>sample</sub>**: sampling frequency of the quantizer.





## **Simulation Example 0 :**

$\Delta$  = 1 volt

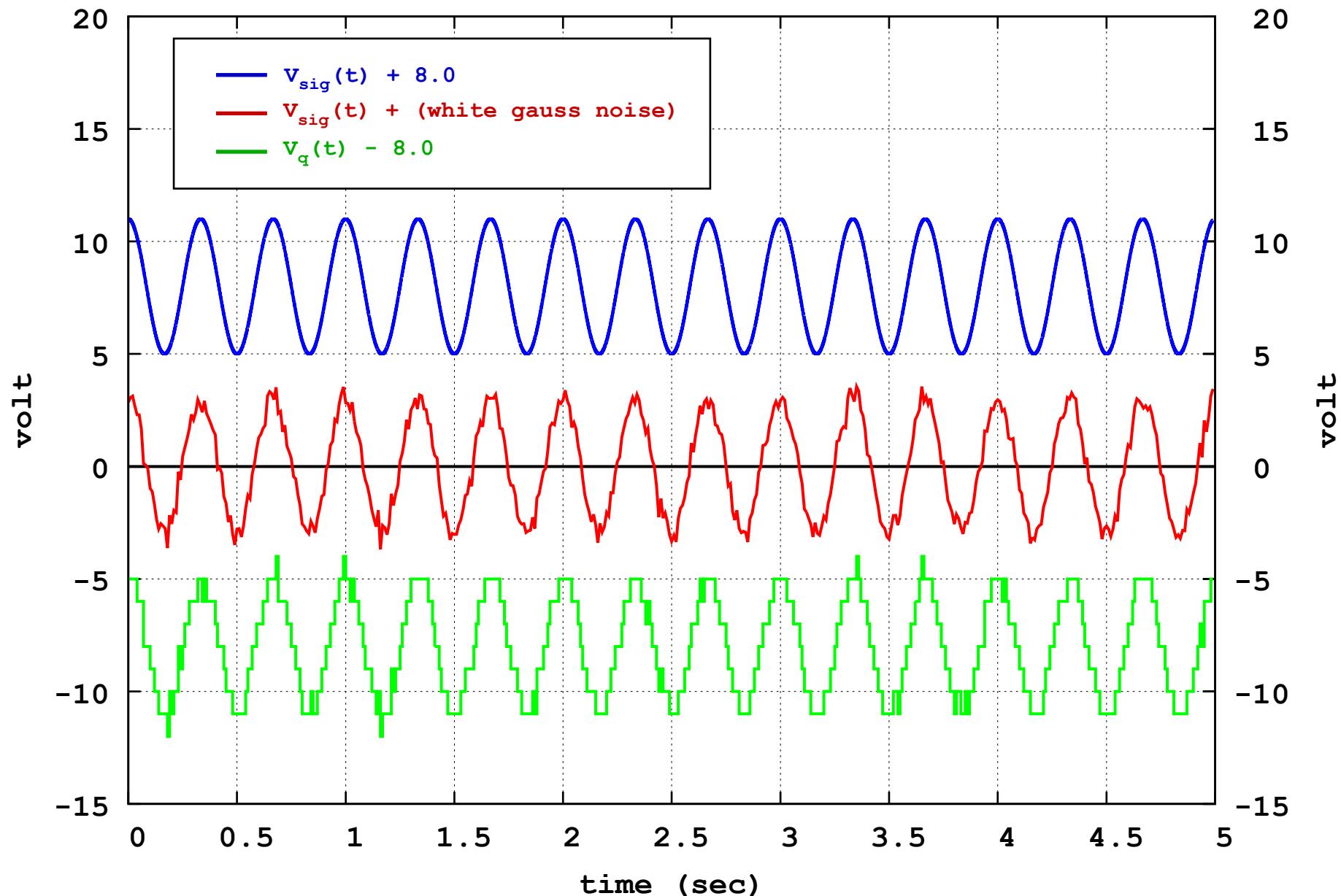
**a0 = 3.0 Vpeak**

fsig = 3 Hz

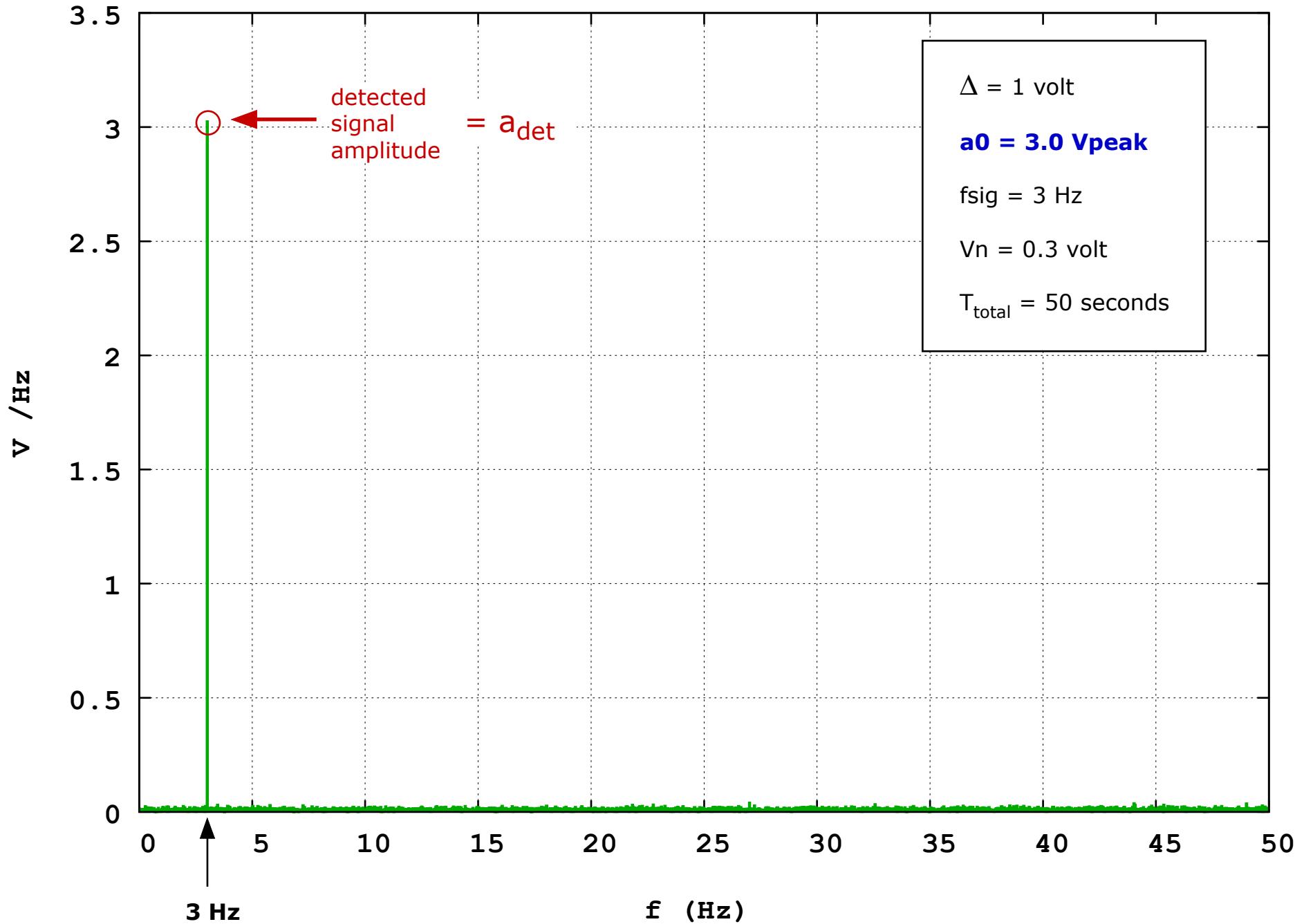
**Vn = 0.3 volt**

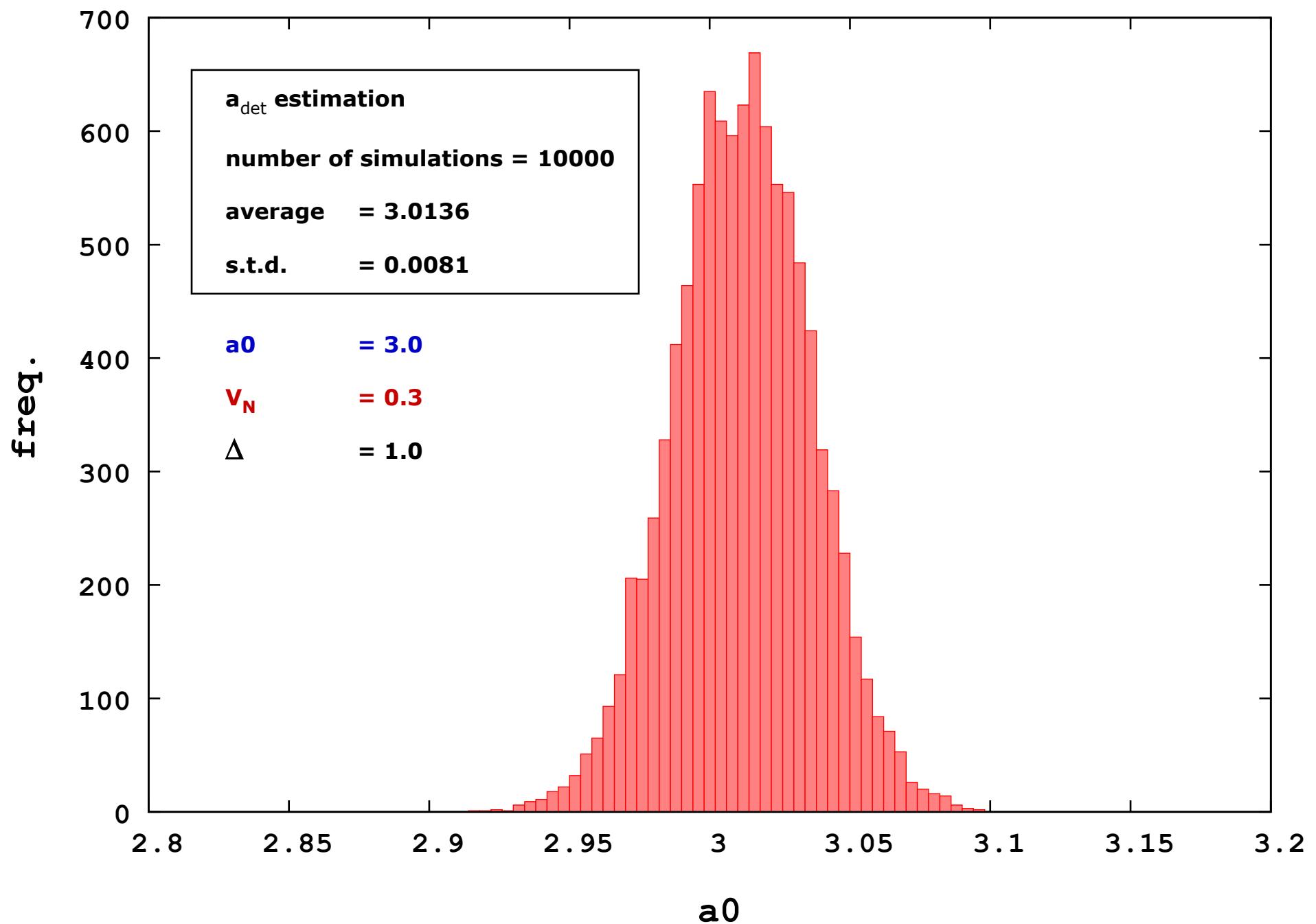
T<sub>total</sub> = 50 seconds

### dithering simulation: example 0



## Power spectrum of the quantized signal with dithering





## **Simulation Example 1 :**

$\Delta = 1$  volt

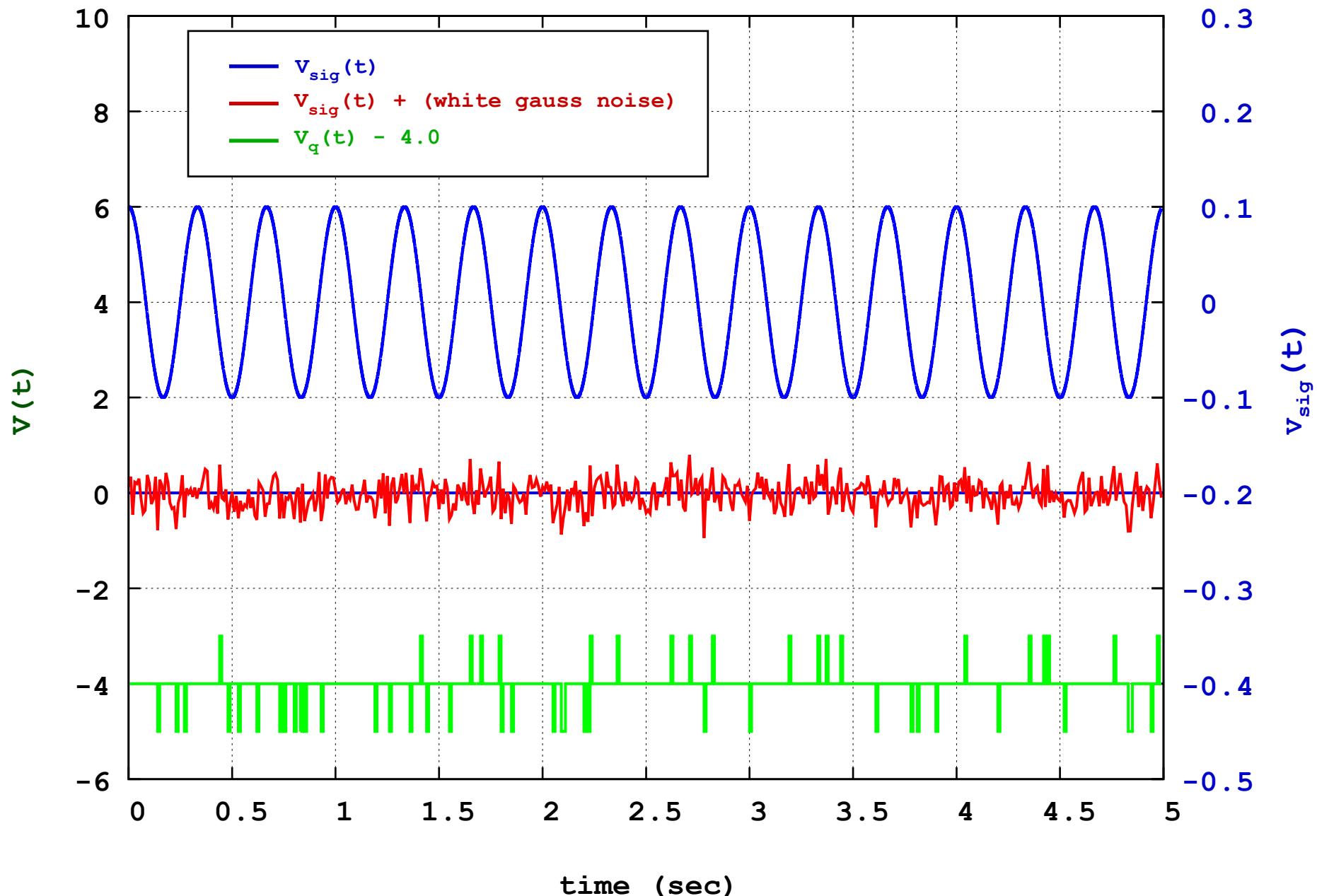
**a0 = 0.1 Vpeak**

fsig = 3 Hz

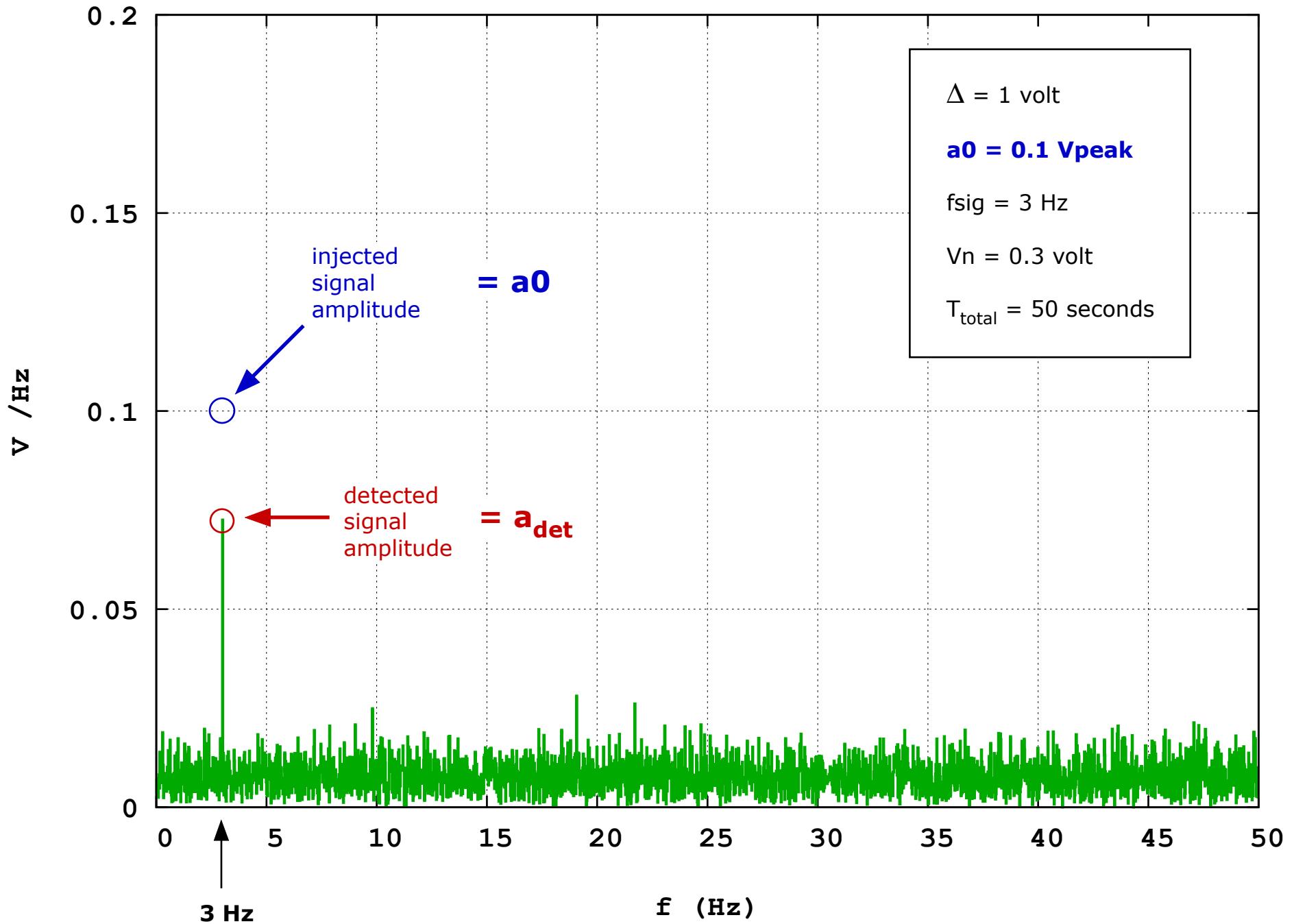
**Vn = 0.3 volt**

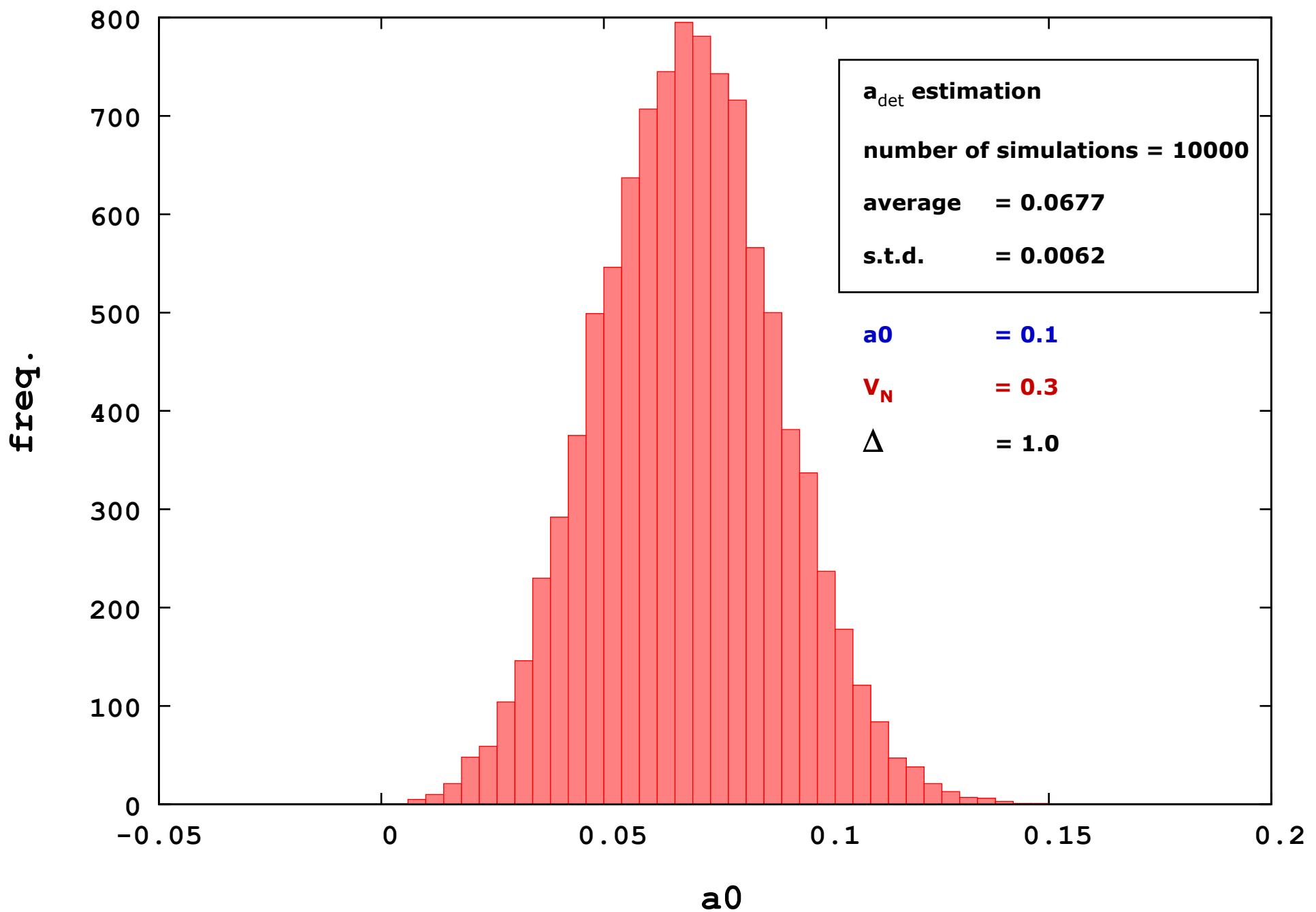
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### dithering simulation: example 1

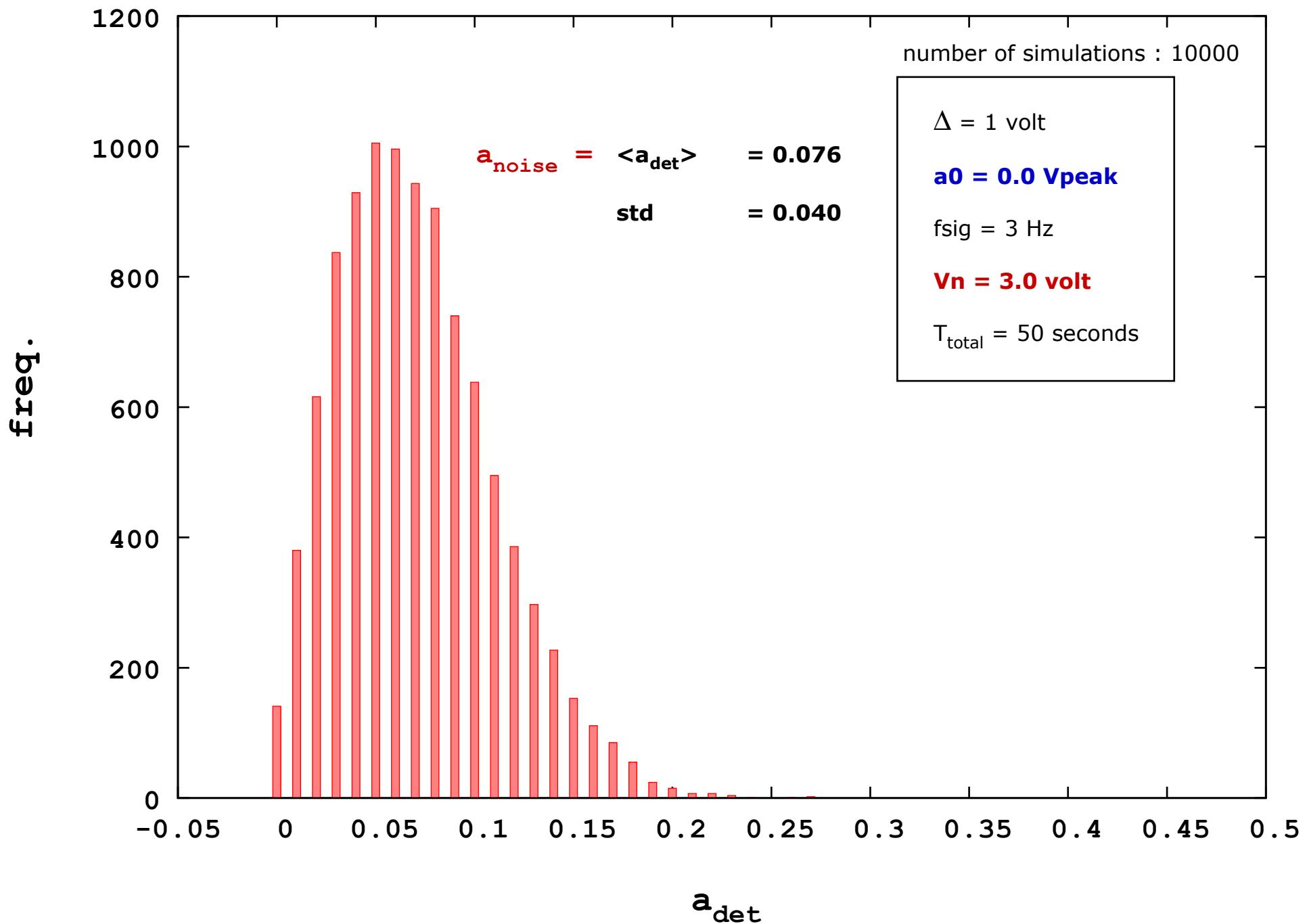


## Power spectrum of the quantized signal with dithering

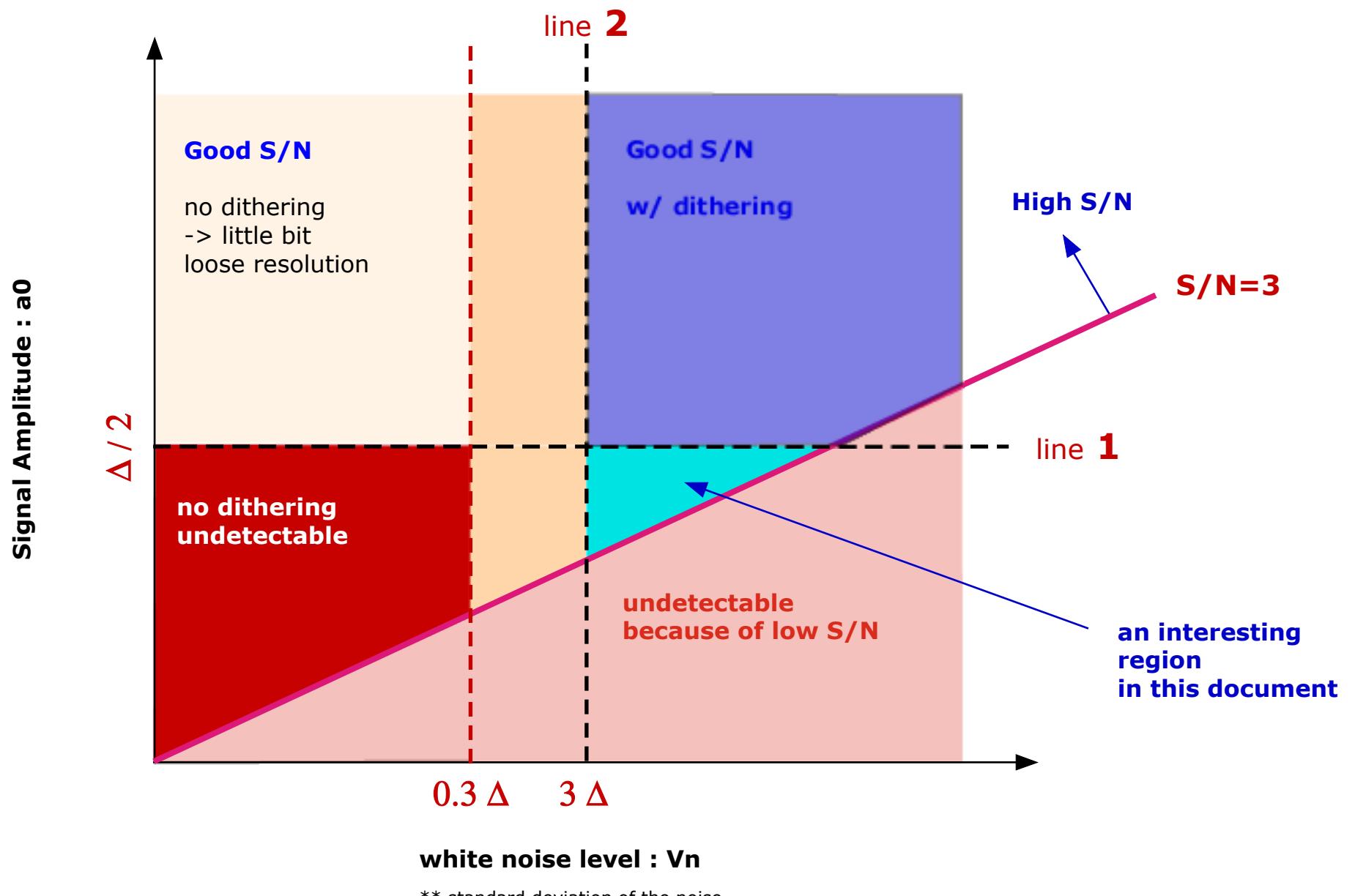




# Rayleigh distribution







# Intuitive speculations

Line 1:

It is obvious that a sinusoidal wave of amplitude less than  $\Delta /2$  loses all of information in the case of no dithering by the quantization.

Line 2:

How large white noises are effective as dithering?

Answer;

**0.3  $\Delta$**  is a minimum amplitude for dithering. But it makes non-negligible signal loss.

**3  $\Delta$**  seems to be enough large and makes the signal loss small.

S/N=3

If there is no quantizer, we can calculate the expected S/N.

\*\*\*  $a_{\text{noise}}$  can be estimated as follows

$$a_{\text{noise}} = \widetilde{\nu_n}(f) \cdot \Delta f = \frac{2}{\sqrt{f_s T}} \times V_n$$

The estimations are well consistent with dithered and quantized data.

## The standard deviation of the “ $a_{det}$ ”

In the case of  $a_0 = 0$ ,

the probability density function obeys Rayleigh function.

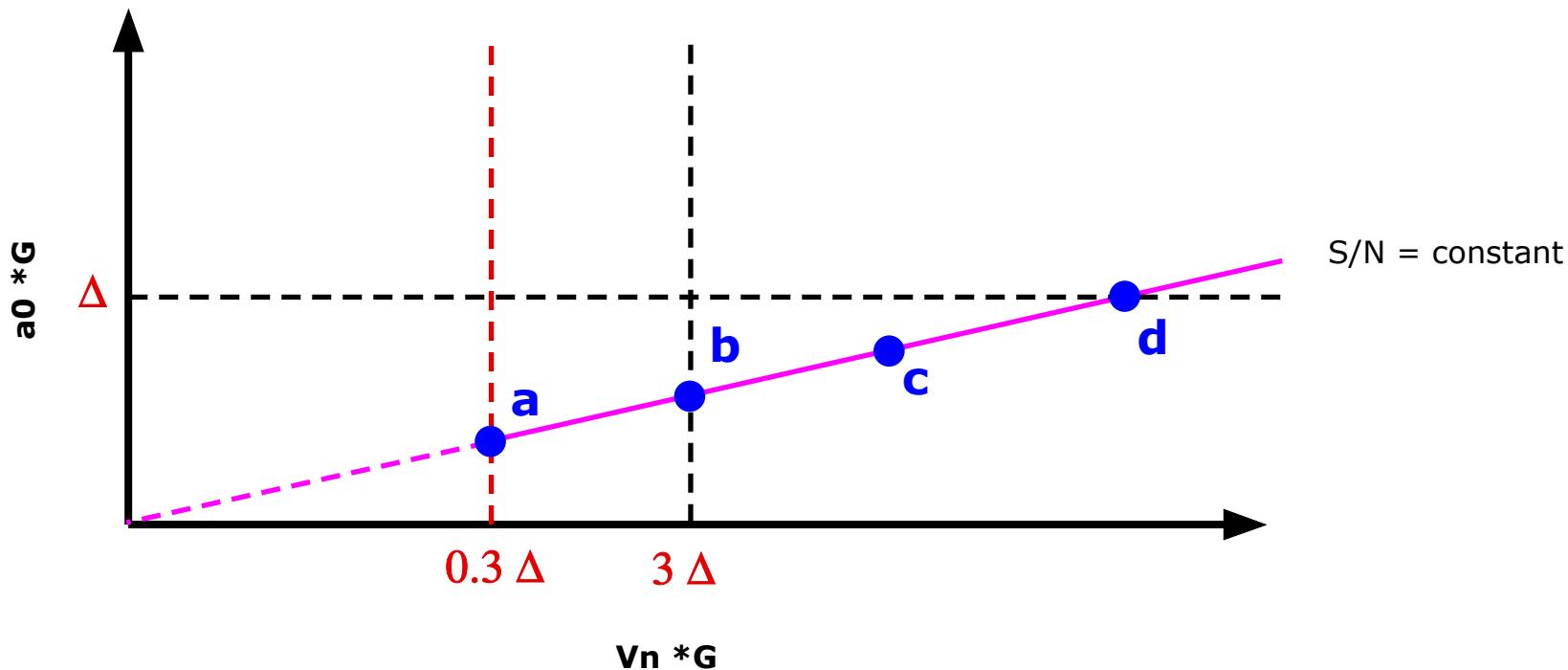
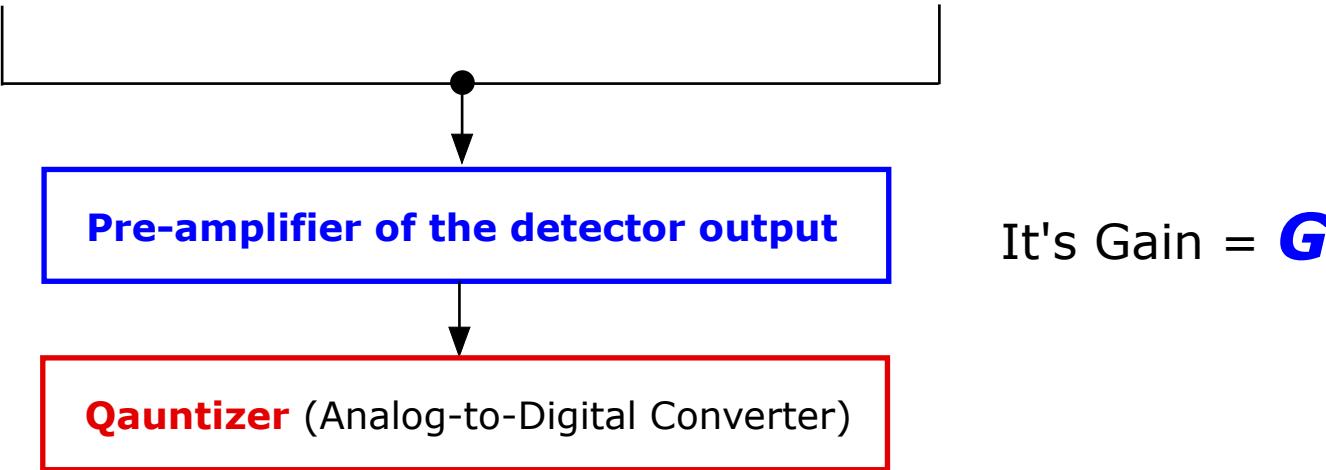
Therefore,

$$\begin{aligned}\text{std of } a_{det} &= 0.523 \times (\text{mean of } a_{det}) \\ &= 0.523 \times a_{noise}\end{aligned}$$

## Realistic situation for controlling dithering conditions

**a<sub>0</sub>**: continuous-wave signal of interest

**v<sub>n</sub>**: white gaussian noise due to the detector



## **To set simulation parameters**

When  $G=1$ ,  $V_n * G = V_n = 0.3 \Delta$

$S/N = a_0 /$

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# White Gaussian Noise

$$V_n^2 \stackrel{\text{def}}{=} \frac{1}{T} \int_0^T v^2(t) dt$$

$$V_n^2 = 2 \int_0^{f_N} \widetilde{s_n}(f) df = 2f_N \widetilde{s_n} = f_s \widetilde{s_n}$$

$f_N$ : Nyquist freq.

$f_s$  : Sampling freq.

$$\widetilde{s_n} = \frac{V_n^2}{f_s}$$

Power Spectrum Density (PSD)  $V^2/\text{Hz}$

$$\sqrt{\widetilde{s_n}} = \sqrt{\frac{V_n^2}{f_s}}$$

Liner Spectrum Density (LSD)  $V/\sqrt{\text{Hz}}$

$$\widetilde{v_n}(f) = V_n \sqrt{\frac{2T}{f_N}}$$

Fourier Transform of  $v(t)$   $V/\text{Hz}$

$$a_{noise} = \widetilde{v_n}(f) \cdot \Delta f = \frac{2}{\sqrt{f_s T}} \times V_n$$

in a unit of Volt

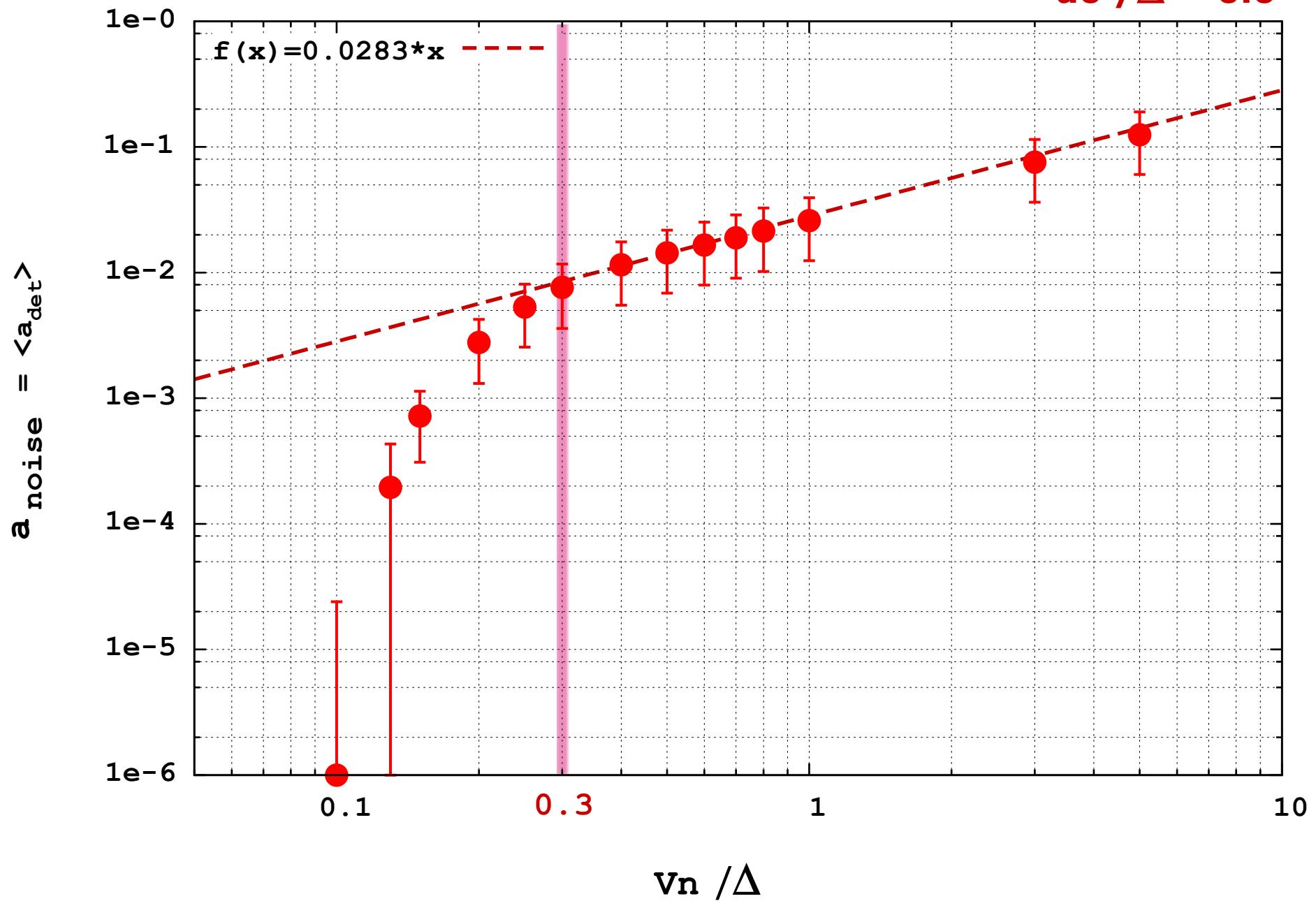
$$a_{noise} = \widetilde{v_n}(f) \cdot \Delta f = \frac{2}{\sqrt{f_s T}} \times V_n$$

$f_s = 100$  Hz,  $T = 50$  sec

-->  $a_{noise} = 0.0283 \times V_n$

# dithering noise amplitude estimation

$a_0 / \Delta = 0.0$



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the probability density function obeys Rayleigh function.

Therefore,

$$\begin{aligned}\text{std of } a_{det} &= 0.523 \times (\text{mean of } a_{det}) \\ &= 0.523 \times a_{noise}\end{aligned}$$

# Rayleigh function

$$PDF(x, \sigma) = \frac{x^2}{\sigma^2} \exp\left(-\frac{x^2}{\sigma^2}\right)$$

$$\text{Mean} = \sqrt{\frac{\pi}{2}} \sigma$$

$$\text{Deviation} = \left(2 - \frac{\pi}{2}\right) \sigma$$

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$$\text{Standard deviation} = \sqrt{\frac{4}{\pi} - 1} \times \text{Mean} = \boxed{0.523 \times \text{Mean}} = \sigma_R$$

—

0.523 x Mean

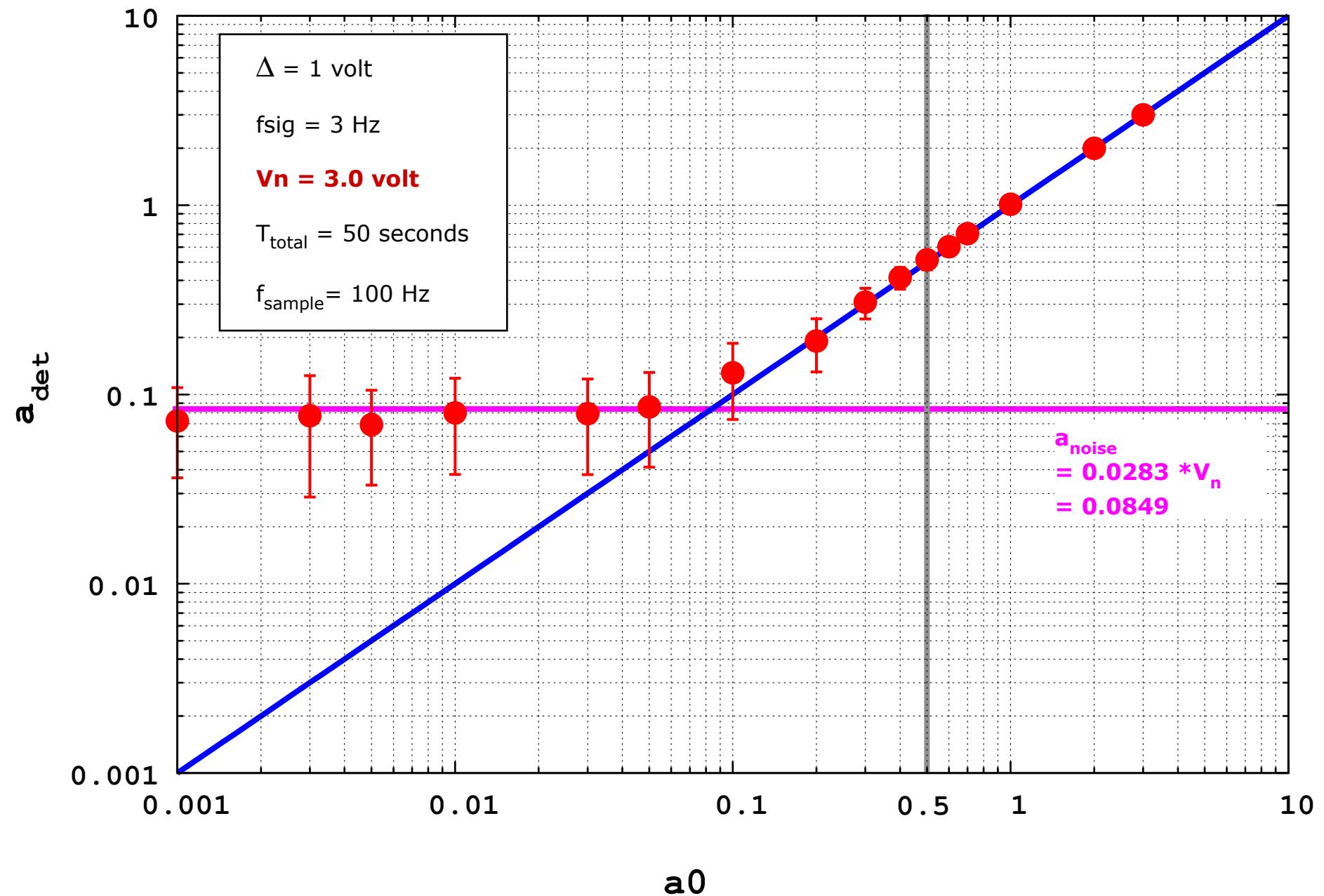
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0.70 x Mean

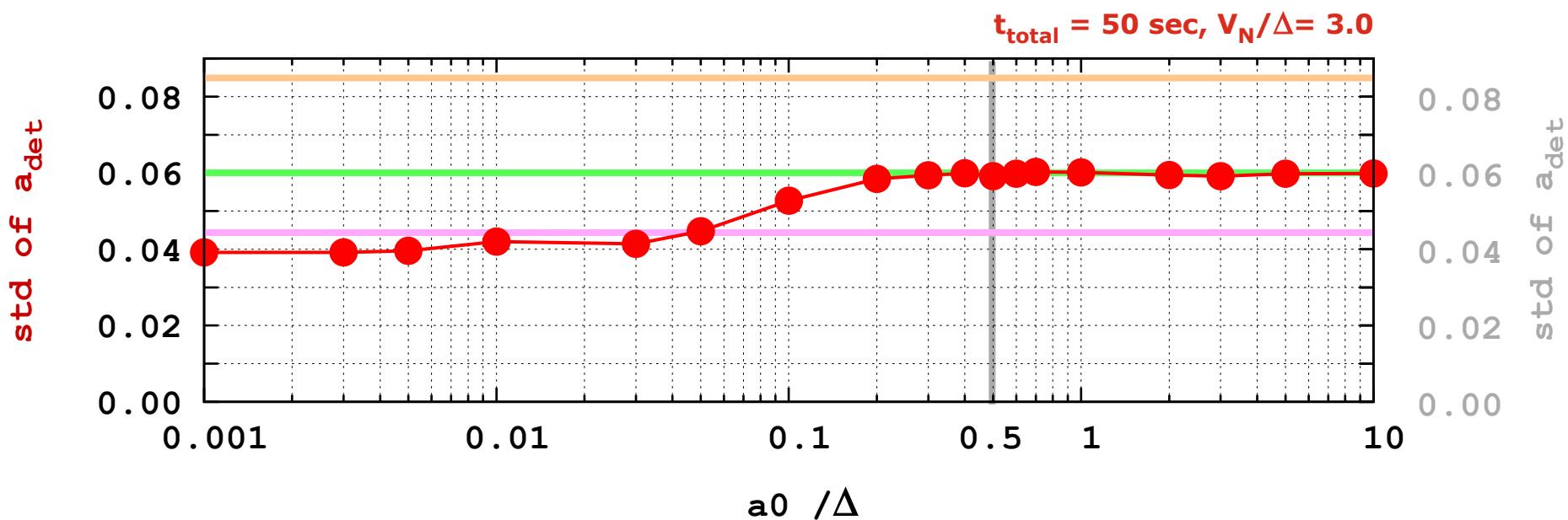
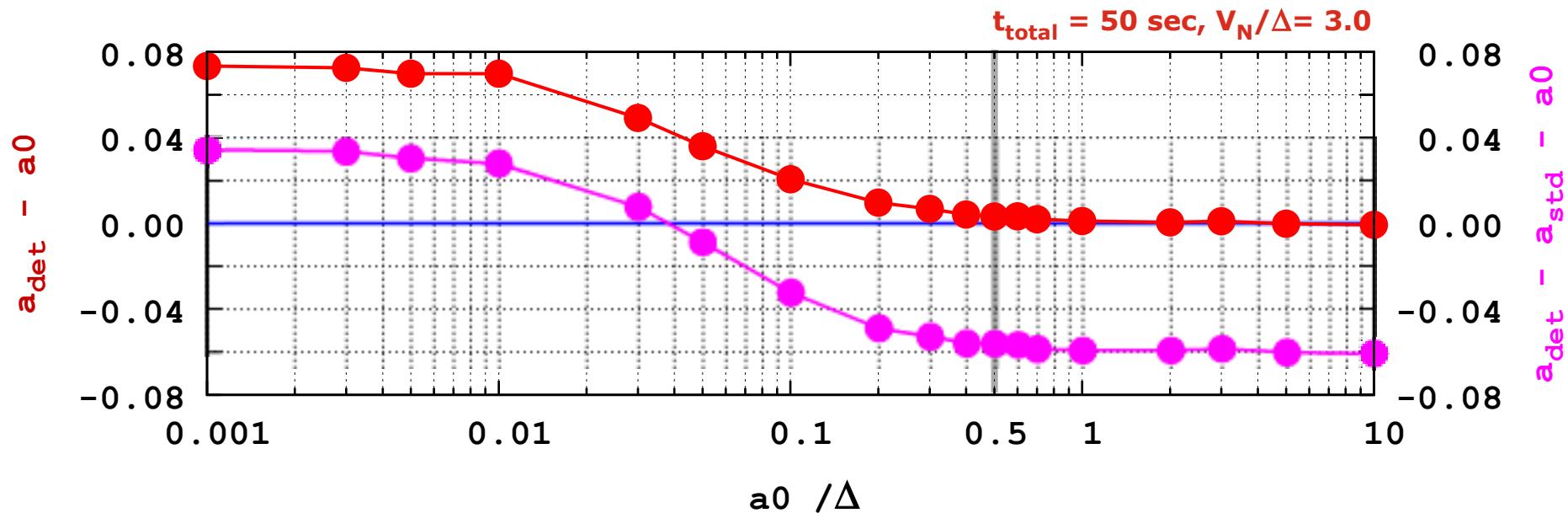
—

Mean

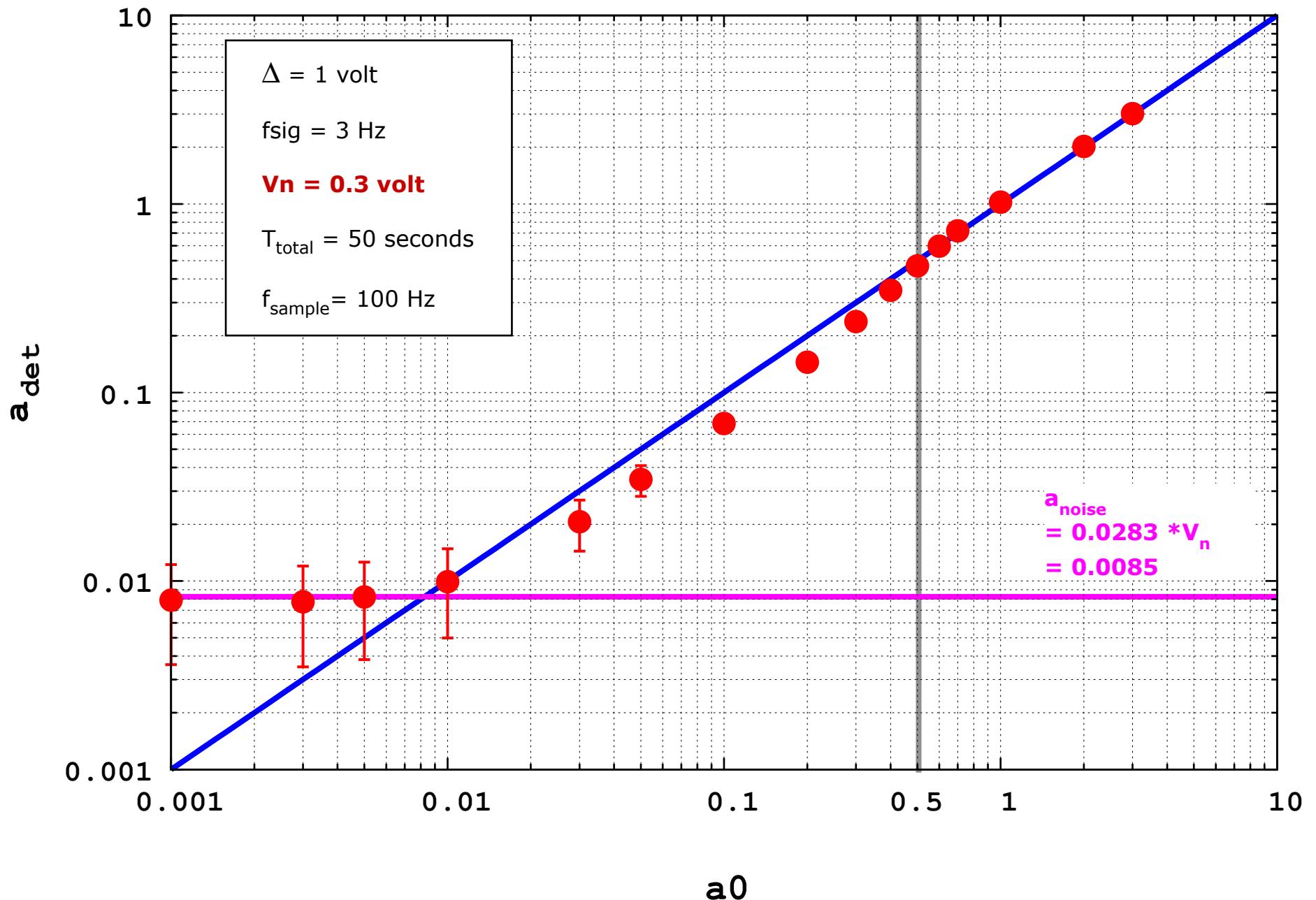
### dithering signal amplitude estimation



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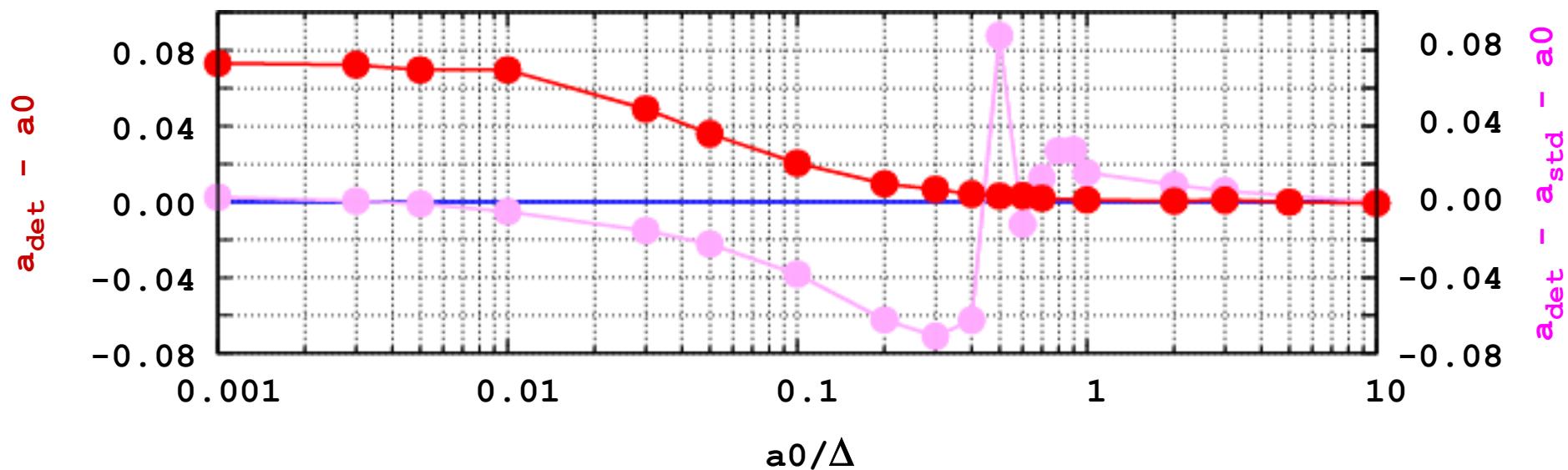


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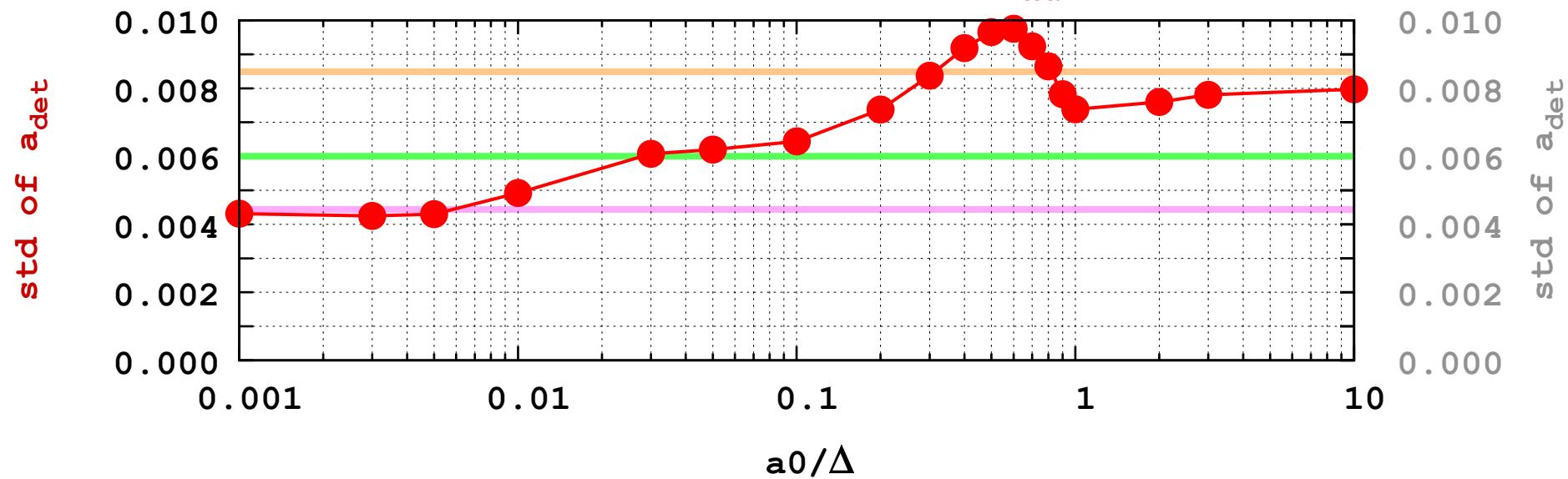


dithering signal amplitude estimation

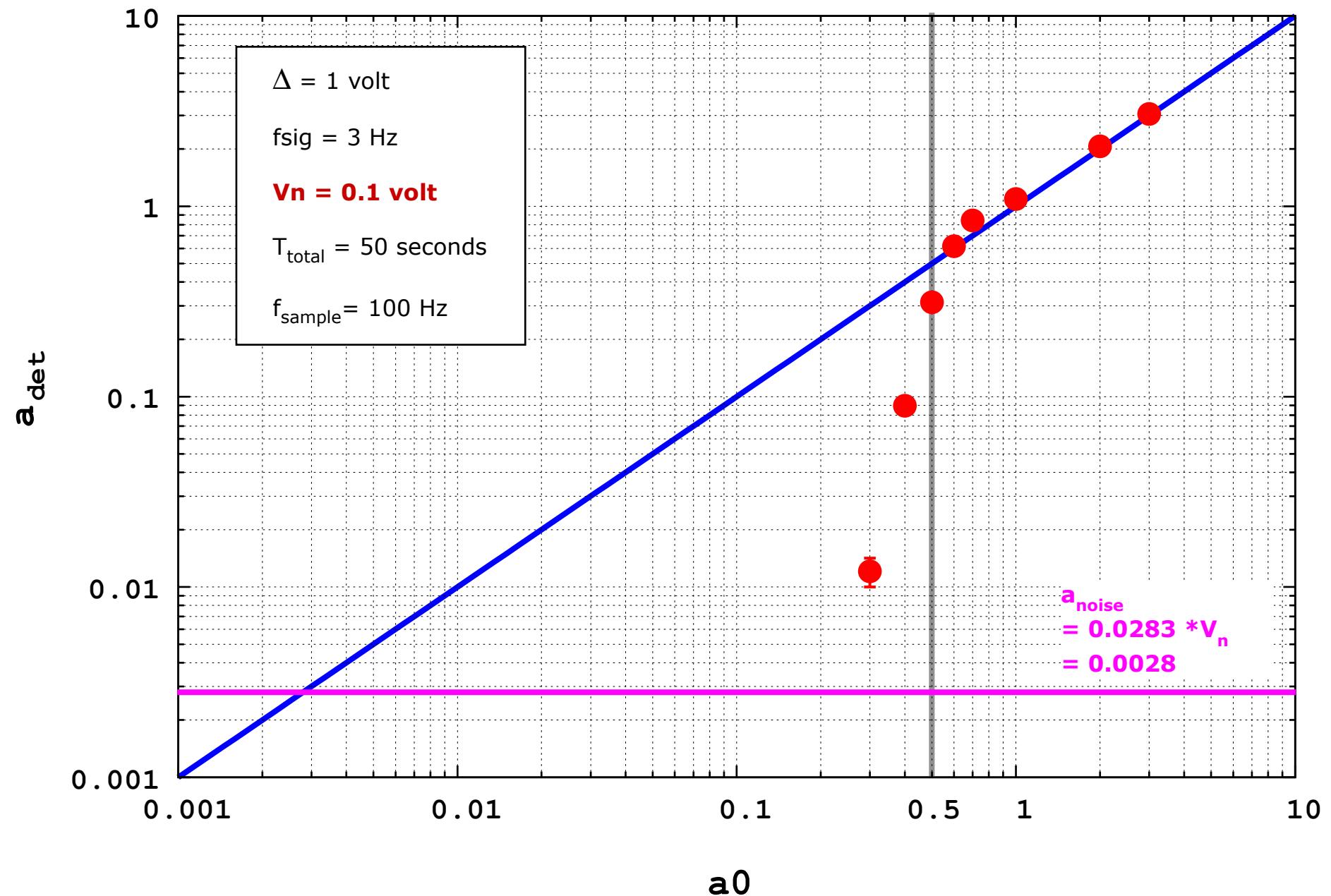
$T_{\text{total}} = 50 \text{ sec}, V_N = 0.3$



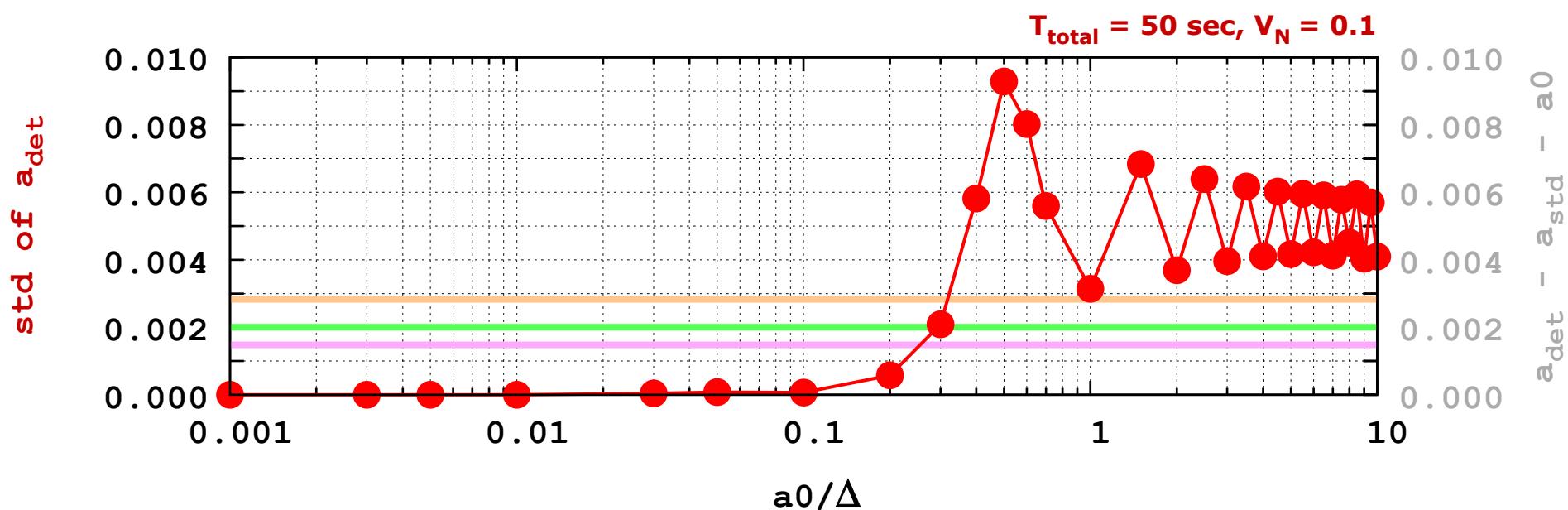
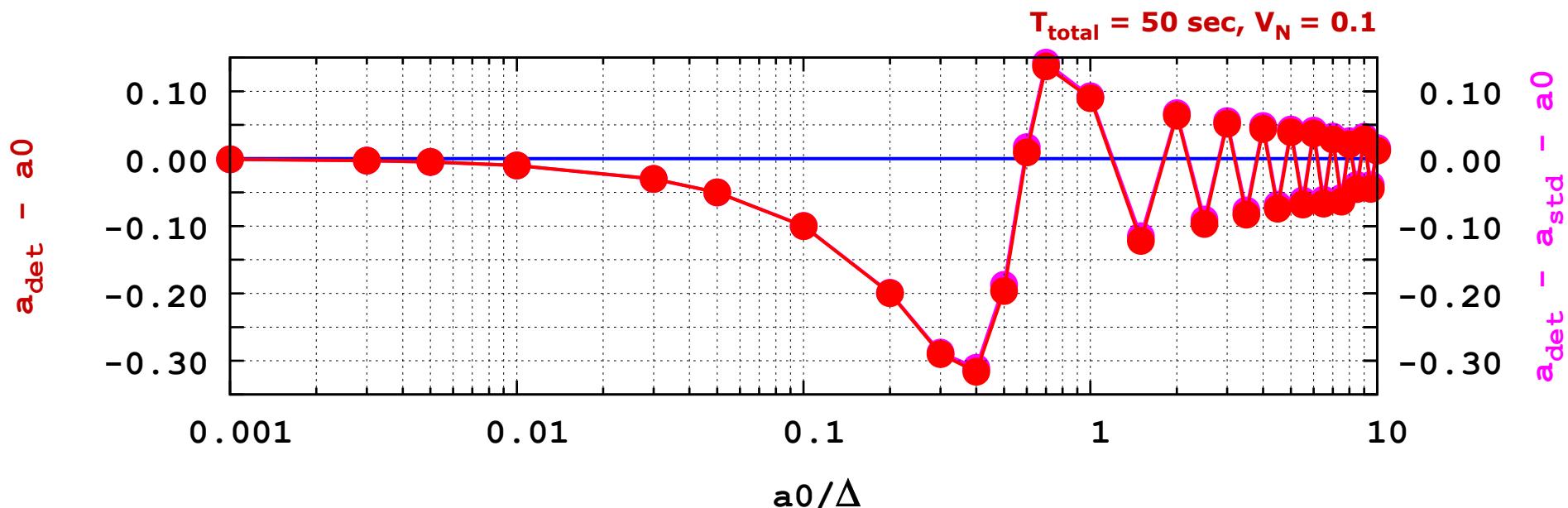
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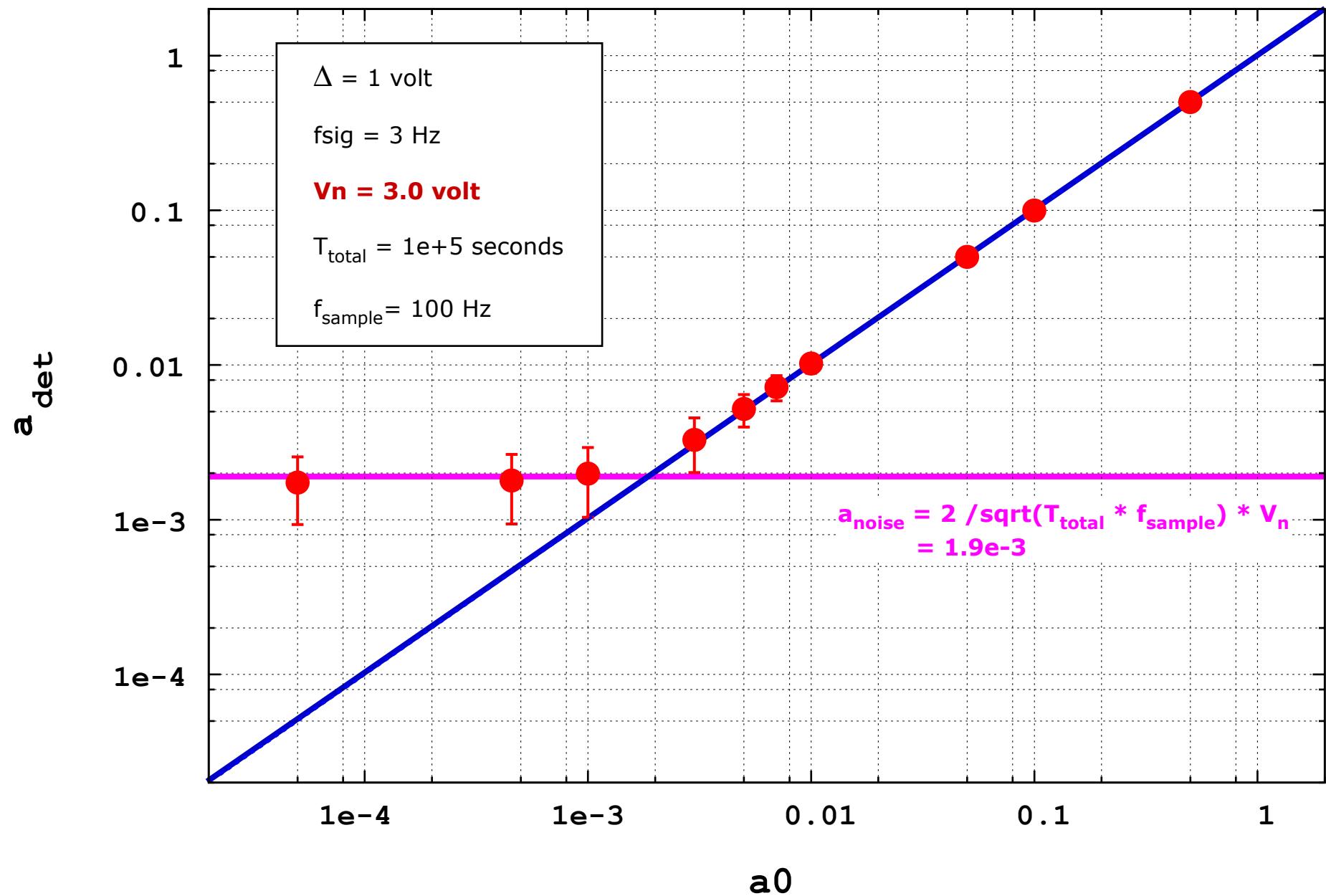
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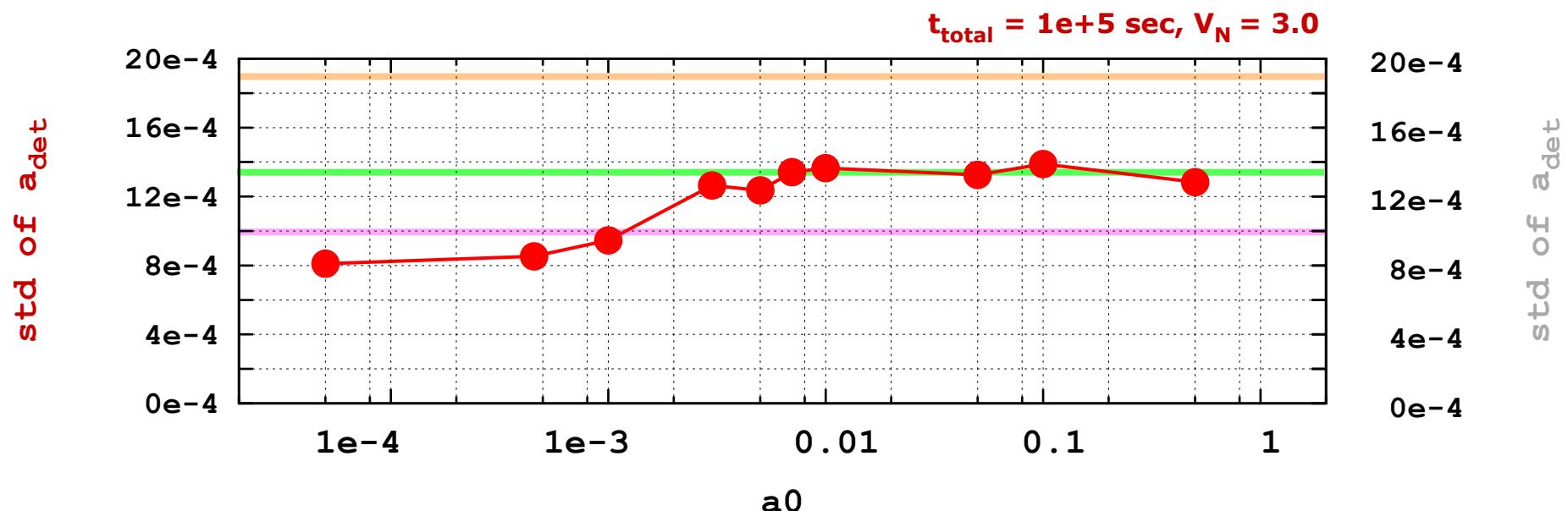
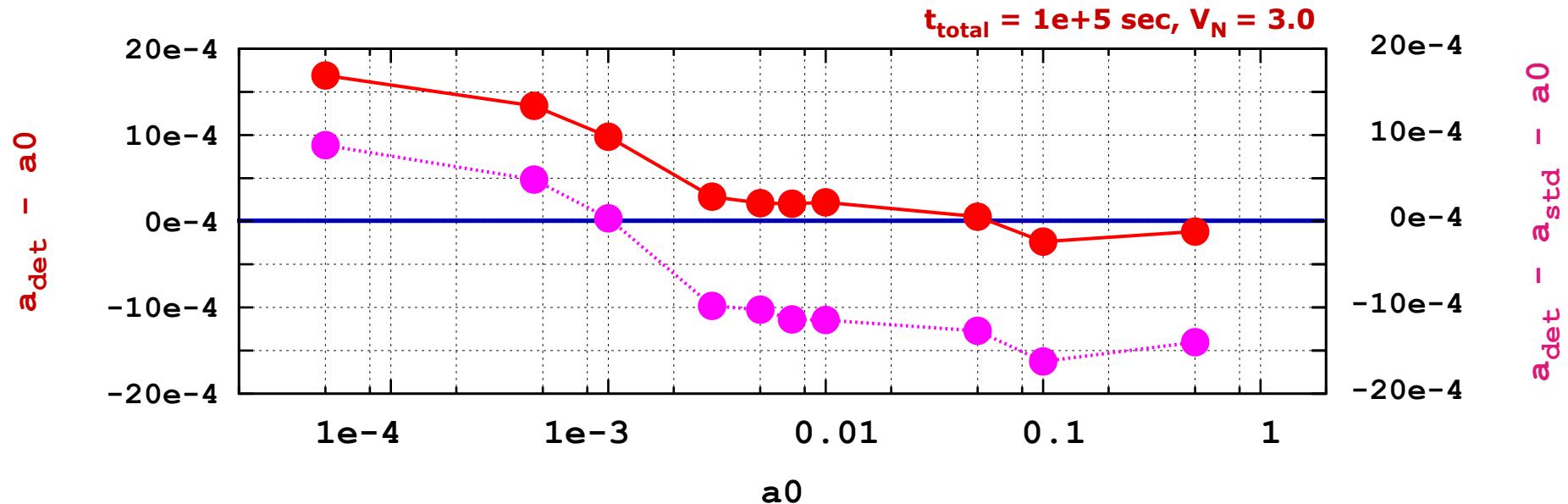
### dithering signal amplitude estimation



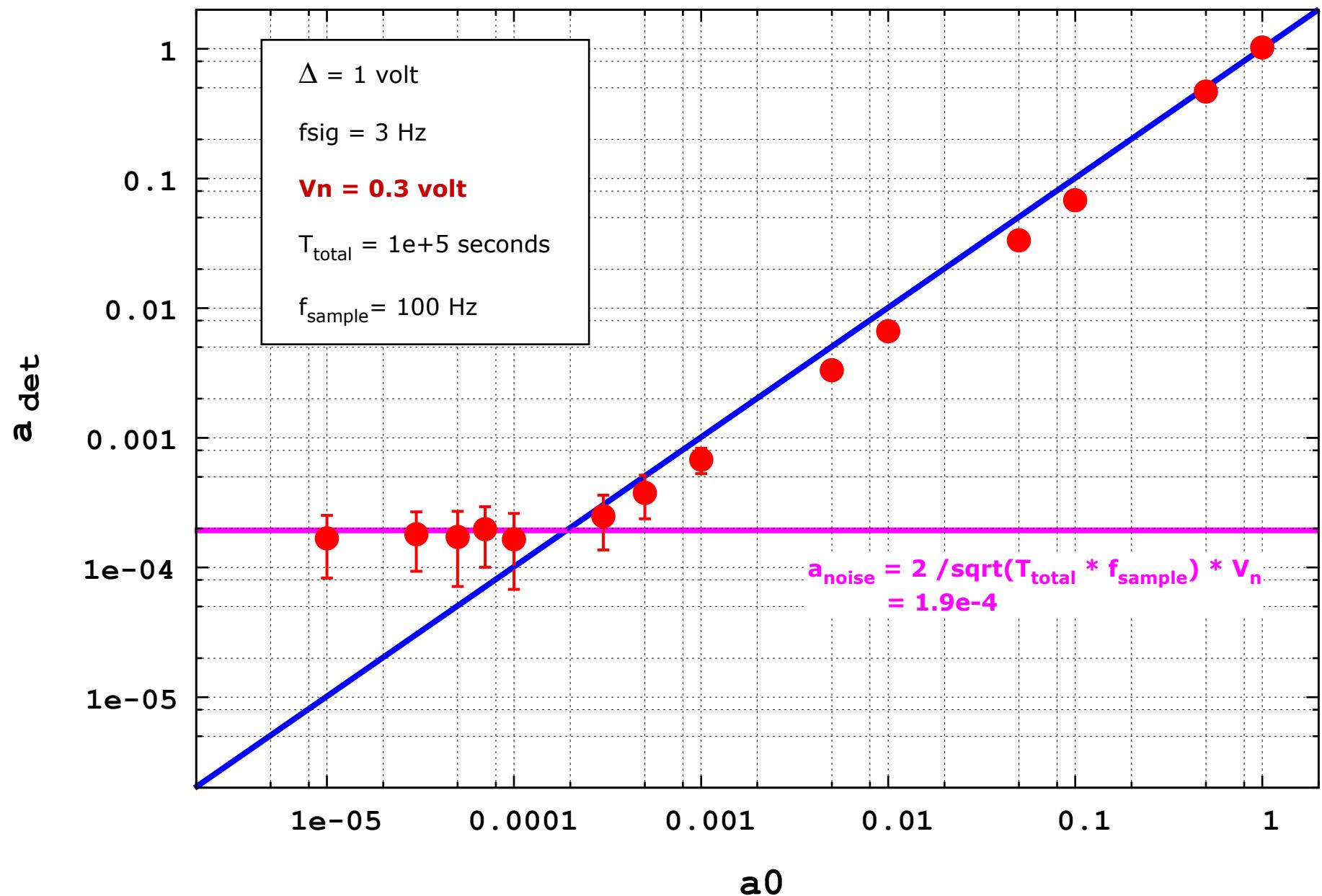
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dithering signal amplitude estimation



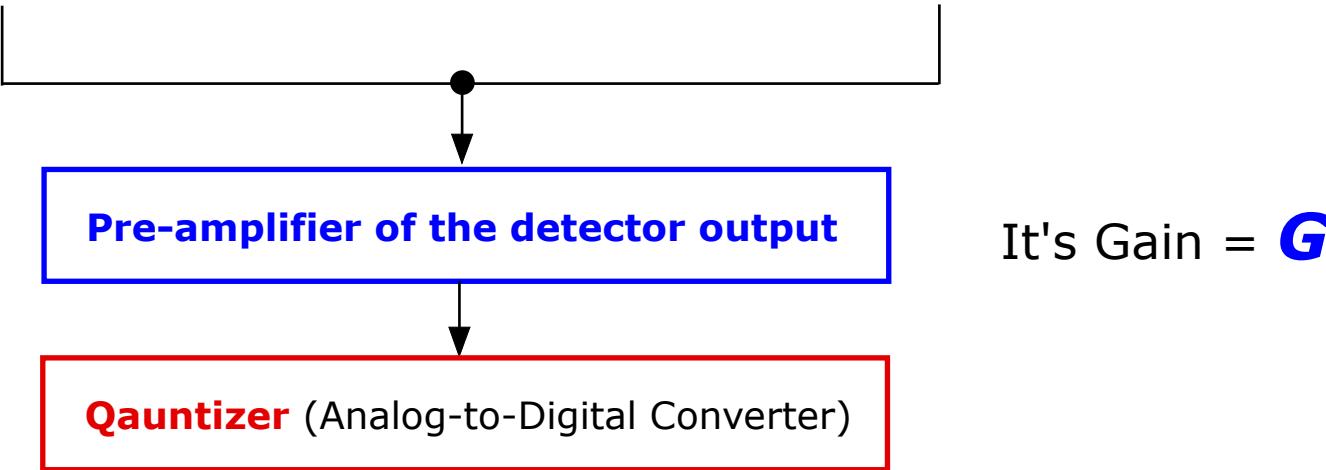
## dithering signal amplitude estimation



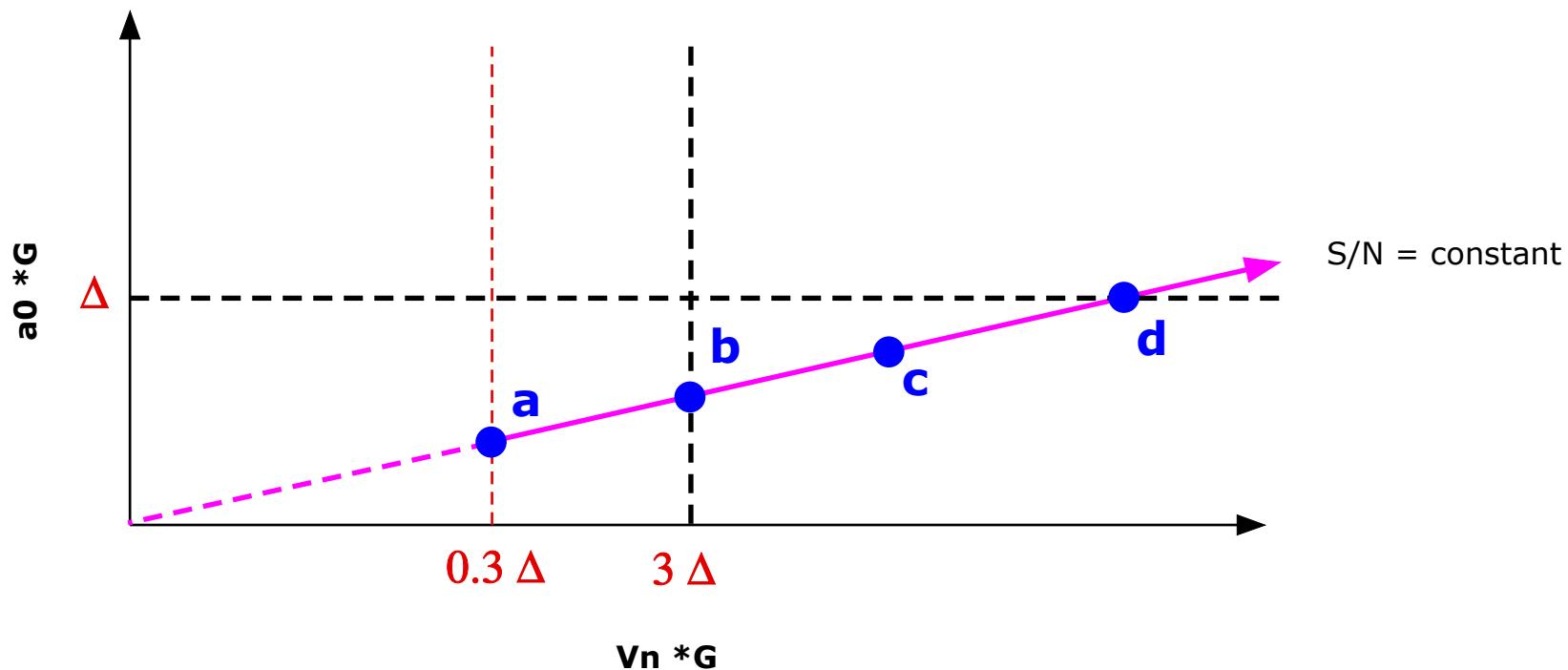
## Realistic situation for controlling dithering conditions

**a<sub>0</sub>**: continuous-wave signal of interest

**v<sub>n</sub>**: white gaussian noise due to the detector



It's Gain = **G**



## To set simulation parameters

(0)  $\Delta = 1$ ,  $T_{\text{obs}} = 1.0 \times 10^5$  sec ( $\sim 1$  days),  $f_{\text{sample}} = 100$  Hz

(1) When  $G=1$ ,  $V_n * G = V_n = 0.3 \Delta$

(2) Set " $a0$ "

$$S/N = \frac{a0}{a_{\text{noise}}} = \frac{a0 \sqrt{T_{\text{obs}} f_s}}{2 V_n}$$

$$a0 = \frac{2 V_n (S/N)}{\sqrt{T_{\text{obs}} f_s}}$$

(3) Make simulation data and obtain the analysis results as follows.

# To set simulation parameters

- (3) Make simulation data and obtain the analysis results " $a_{\text{det}}/G$ " as follows.

## 3.1 Loss of the signal

$$a' = a_{\text{det}}/G$$

$$a_{\text{measure}} = \sqrt{(a'_{\text{det}})^2 - (a'_{\text{std}})^2}$$

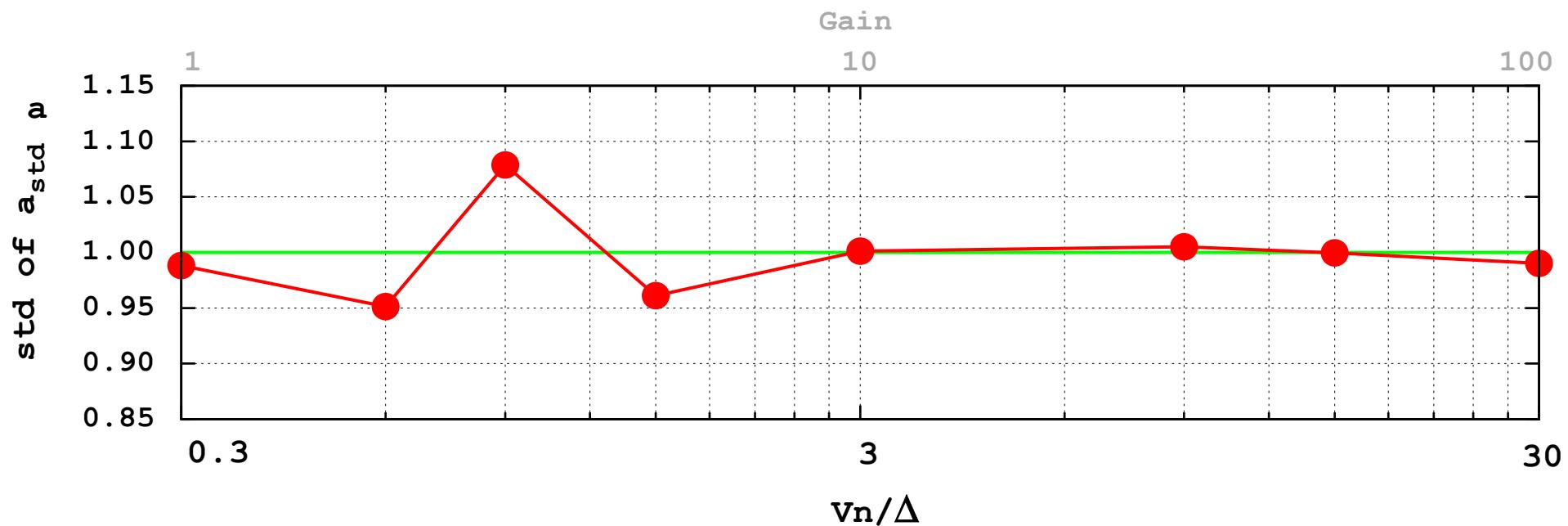
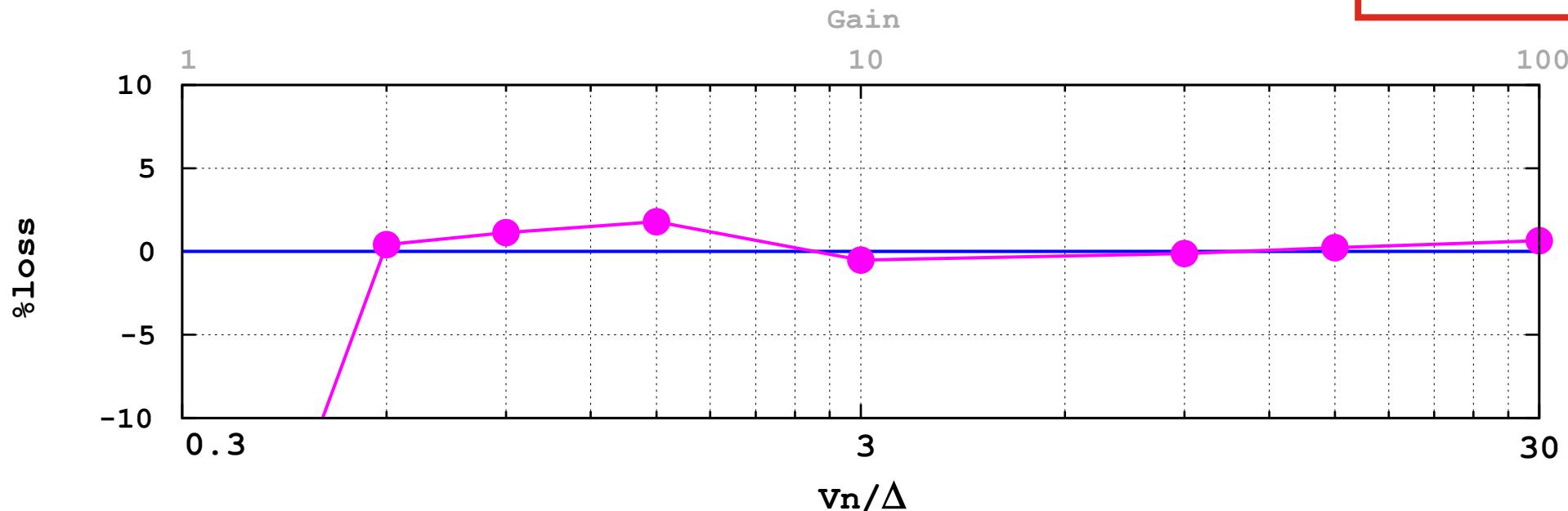
$$\%loss = \frac{a_{\text{measure}} - a_0}{a_0} \times 100$$

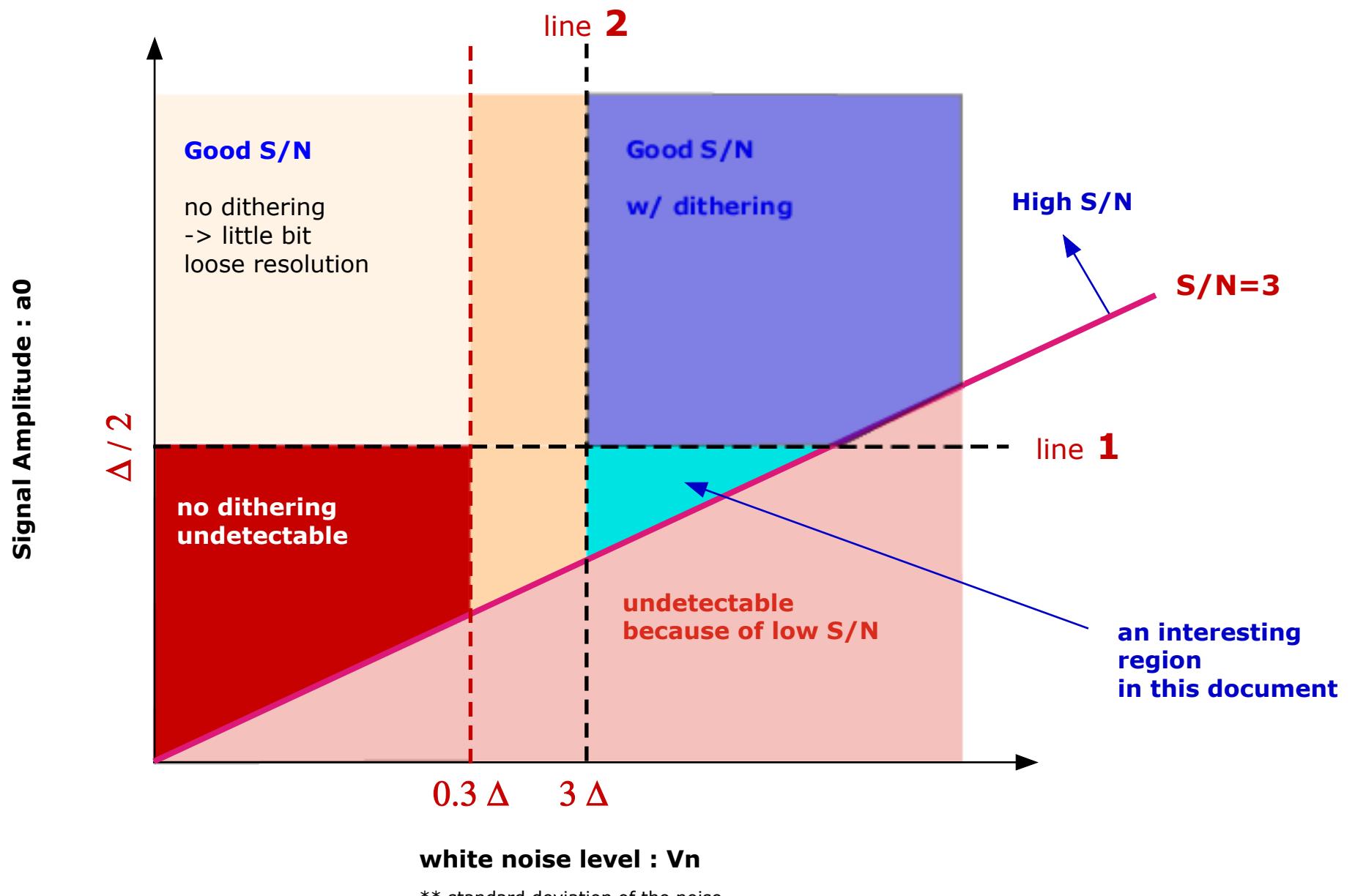
## 3.2 Standard deviation

$$(\text{expected } a'_{\text{std}}) = \sqrt{\frac{2}{T_{\text{obs}} f_s}} V_n$$

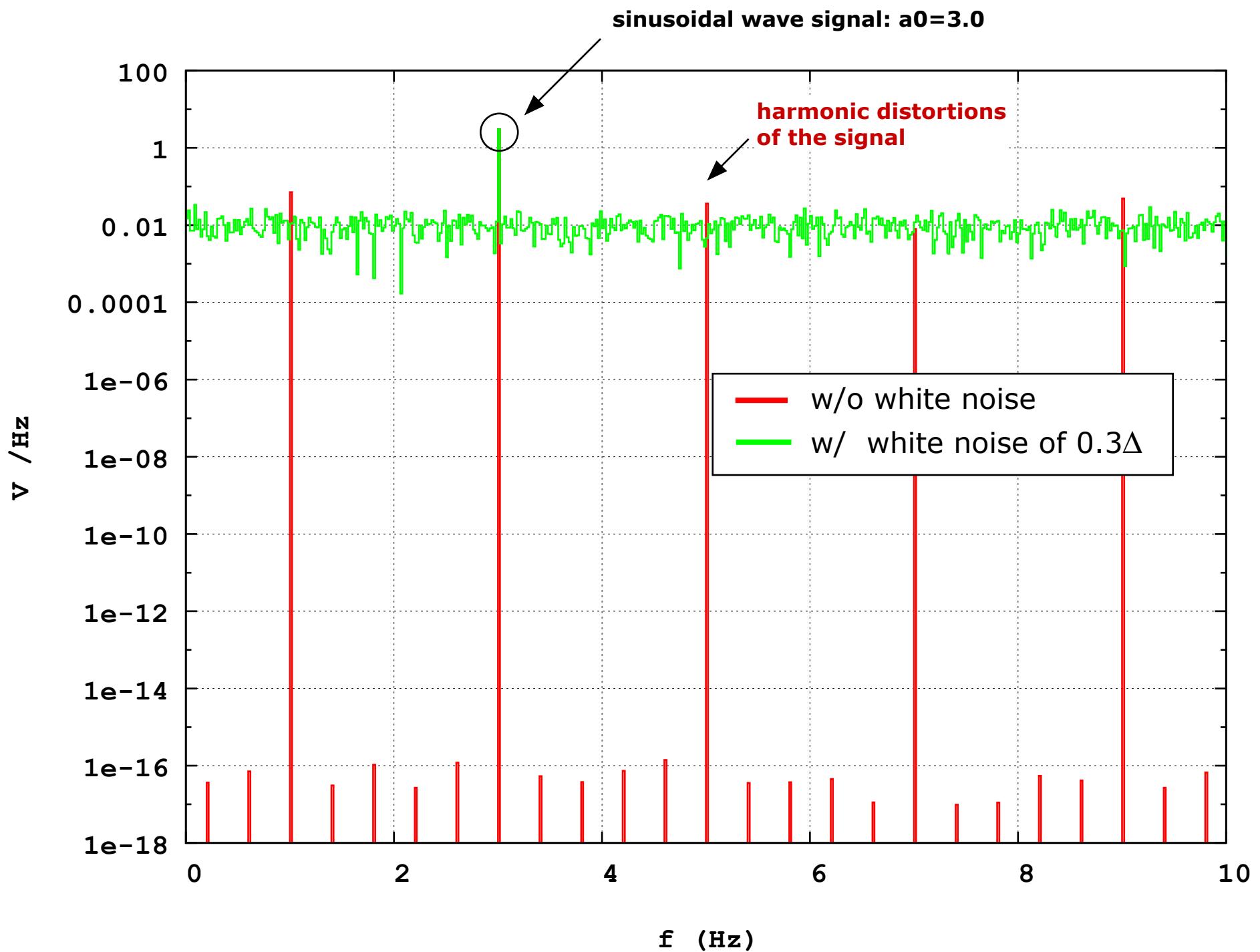
### dithering signal amplitude estimation

$S/N = a_0/a_{noise} = 3$   
 $T_{total} = 1e+5 \text{ sec}$   
 $f_{sample} = 100 \text{ Hz}$









dither simulation  
sinusoidal-wave amplitude estimation error

