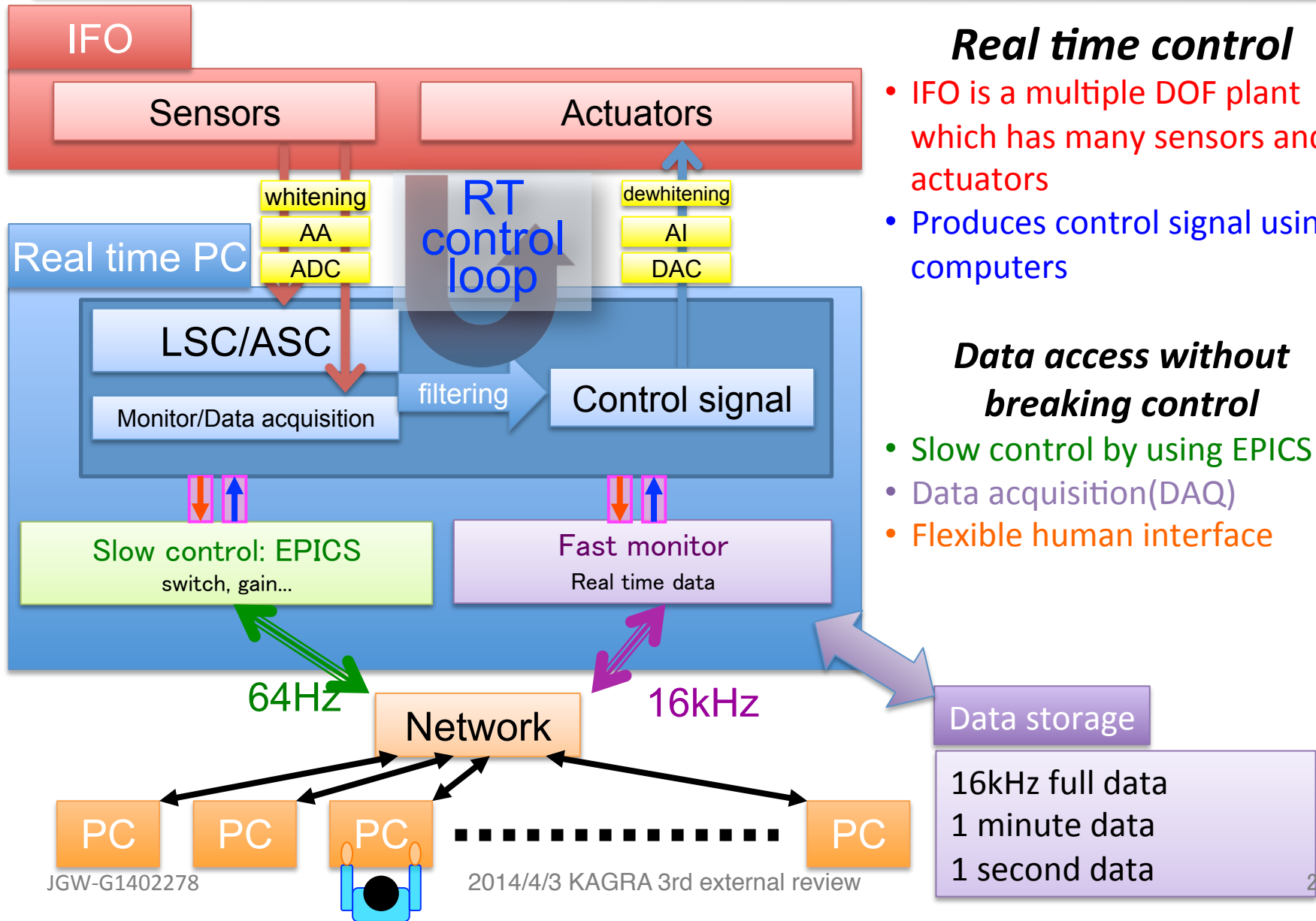


KAGRA 3rd External review for DiGital System subgroup

2014/4/3(Thu) @ICRR

Osamu Miyakawa



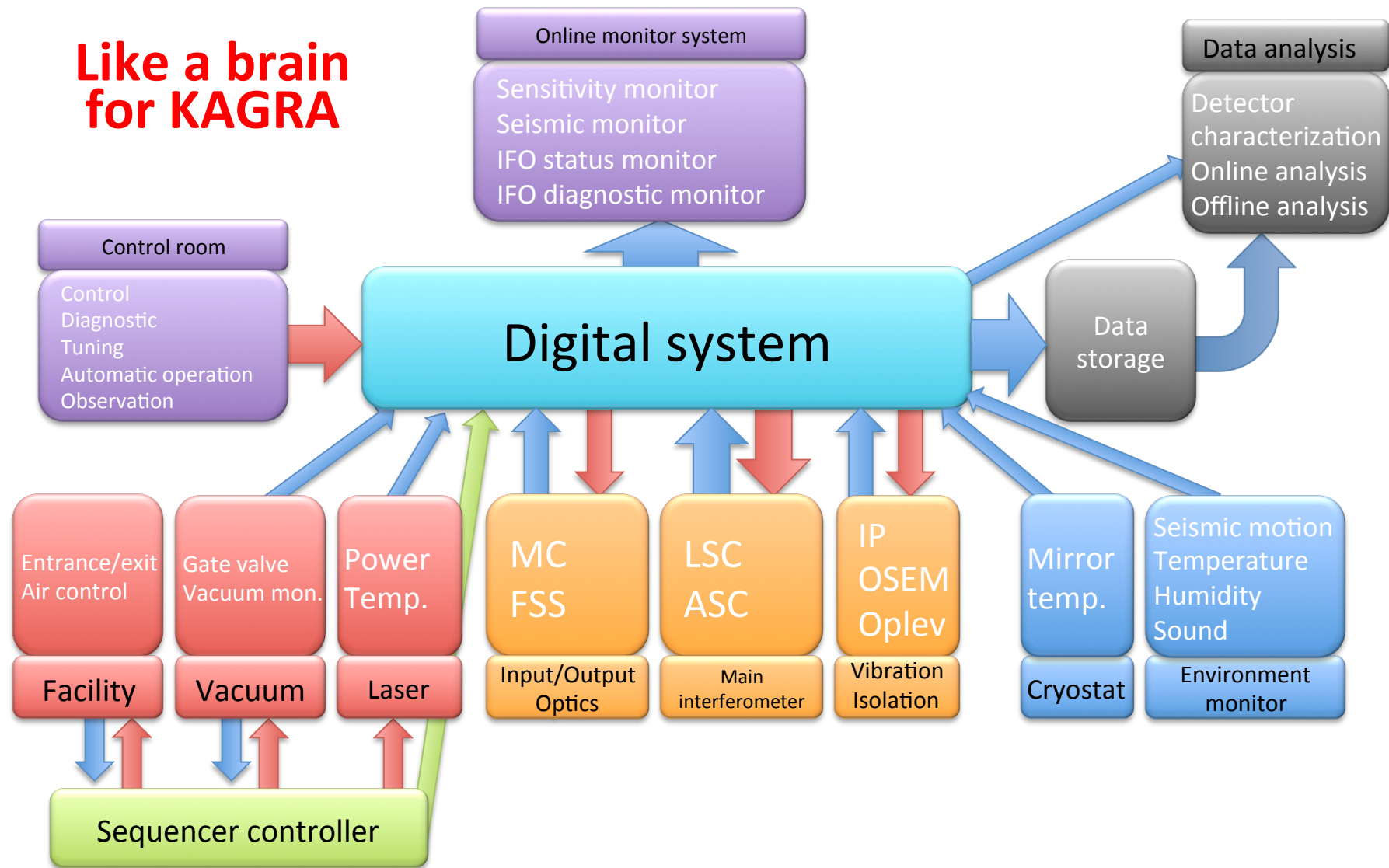
Real time control

- IFO is a multiple DOF plant which has many sensors and actuators
- Produces control signal using computers

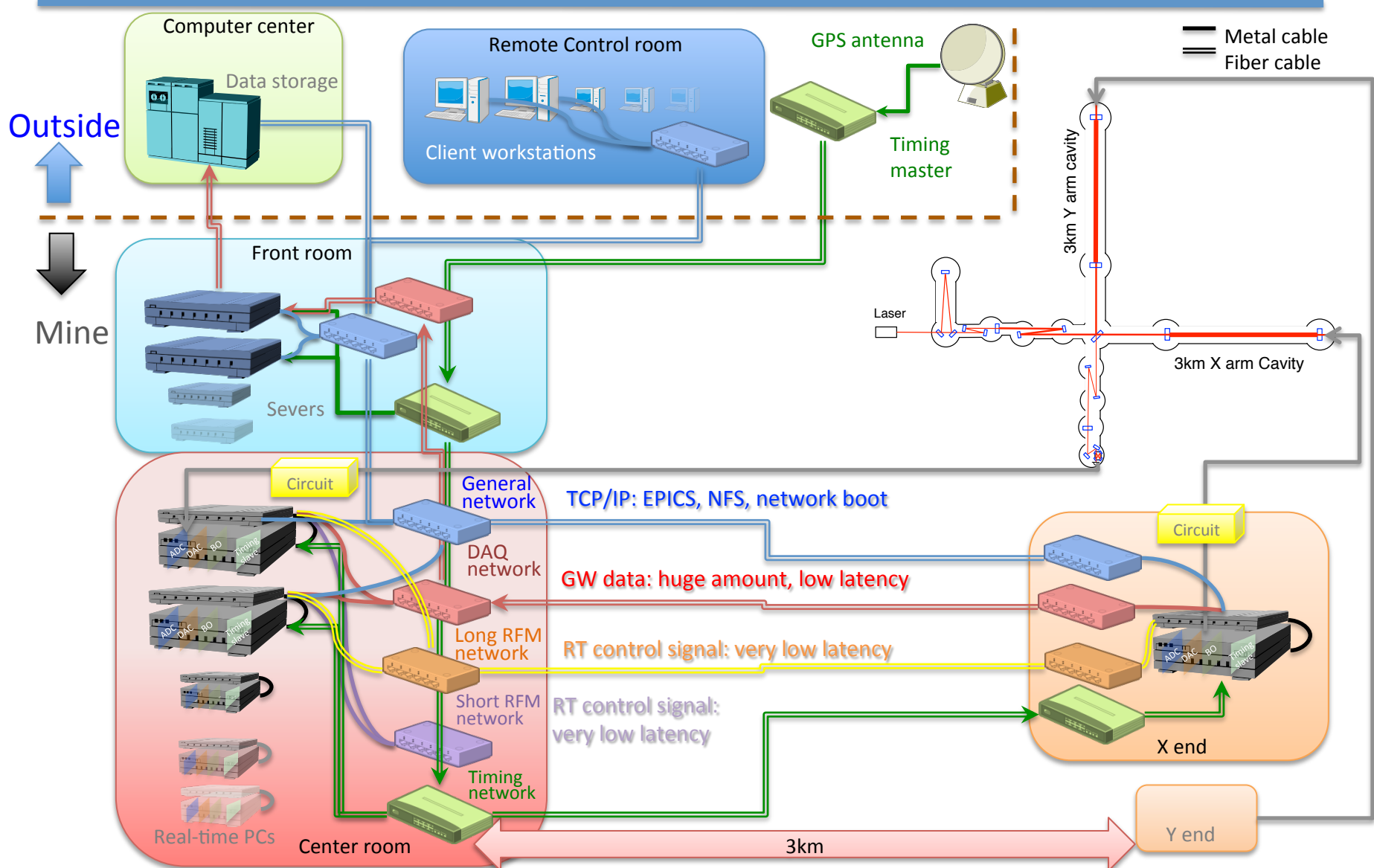
Data access without breaking control

- Slow control by using EPICS
- Data acquisition(DAQ)
- Flexible human interface

**Like a brain
for KAGRA**



1. Function as **Real time control**
 - For complicated multiple DOFs
2. Function as **Data acquisition system** for GW waves
 - Control signal = GW data
3. Function as **IFO tuning system**
 - Reducing time for improving sensitivity
4. Function as **Automatic IFO operation**
 - Stable observation
5. Function as **information collecting system** for IFO
 - Automatic channel assignment for huge number of channels

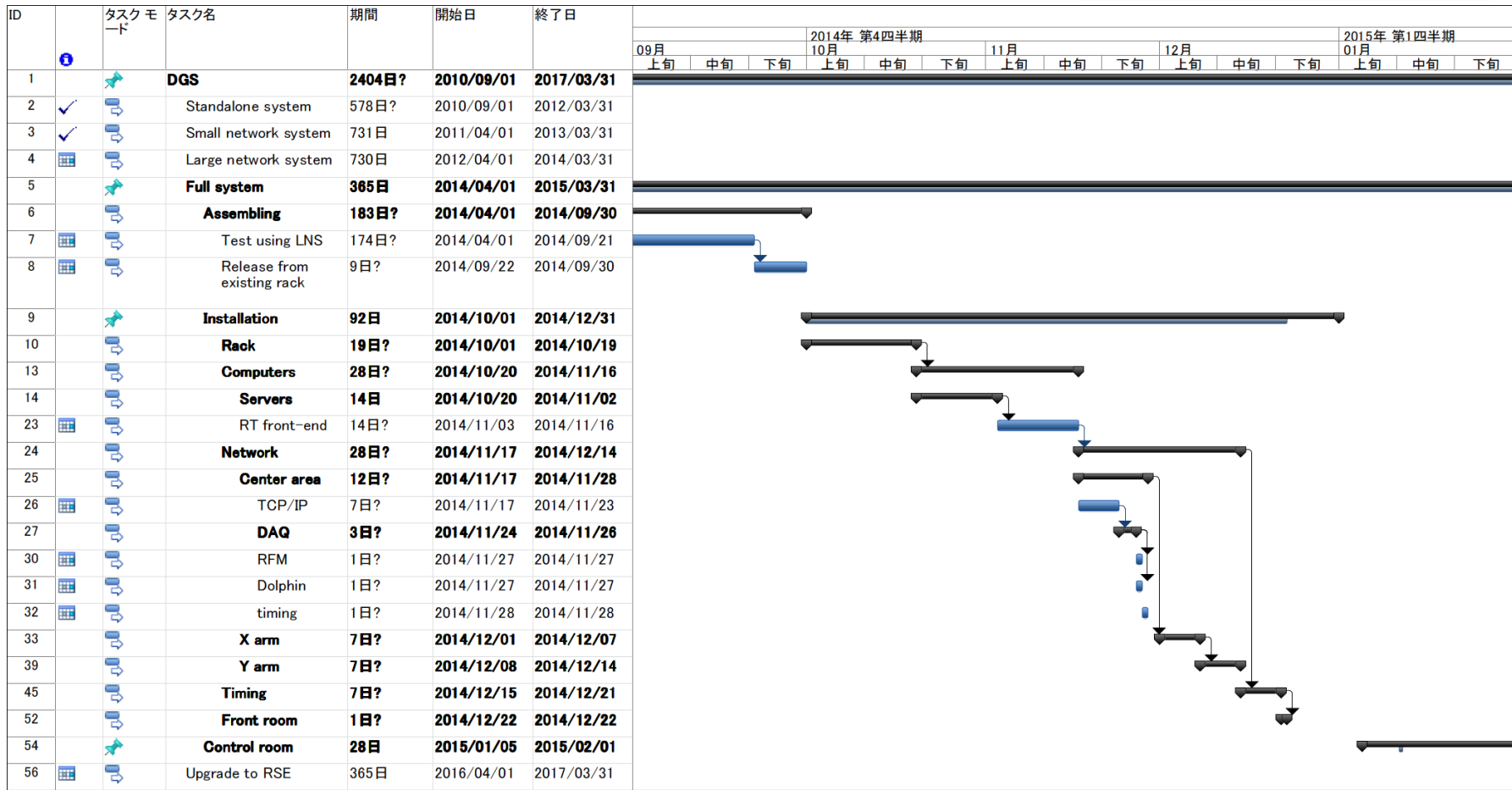


FY		2010				2011				2012				2013				2014				2015				2016							
Quarter		1Q	2Q	3Q	4Q	1Q	2Q	3Q	4Q	1Q	2Q	3Q	4Q	1Q	2Q	3Q	4Q	1Q	2Q	3Q	4Q	1Q	2Q	3Q	4Q	1Q	2Q	3Q	4Q				
Main Phase		Design								Tunnel								Vacuum				FPMI				RSE							
Prototype test	CLIO operation	█	█	█	█																												
	Data analysis test									█	█	█	█																				
Standalone system for subsystems	Hard/software setup					█	█	█	█																								
	Circuit									█	█	█	█																				
	Delivery									█	█	█	█																				
Article test	Small network									█	█	█	█																				
	Large network system													█	█	█	█																
	Circuit													█	█	█	█																
	Inspection																	█	█	█	█												
Full system	Installation																	█	█	█	█												
	Tuning																													█	█	█	█
Upgrade	RSE																																
	Cryo																																

- A. 2009-2010 prototype test @ CLIO (done)
 - Basic IFO operation and noise performance
- B. 2011~ standalone system for subsystem (done)
 - Data analysis, VIS, (IOO, CRY...)
- C. 2011 Small network test with 1 master and 2 RT PCs (done)
 - GE RFM, Dolphin RFM, DAQ, timing network
- D. 2012-2013 Full test@ Kamioka new building
 - Closer to real scale PCs and network


 Installation
 into KAGRA mine

Schedule for installation of DGS full system



- Full system installation: 2014/10-2014/12
- Connection to subsystems: 2015/1~

DGS controls and DAQ system will be installed in 2014.10 into mine.

VIS for iKAGRA

- Type-B: 1 for BS (in 2014.12)
- Type-Bp: 6 for PR2, PR3, IXA, IYA, EXA, EYA (in 2014.9)
- Type-C: 1 for MCF, MCE, IFI, IMM (in 2014.7)

for bKAGRA

- Type-A: 2 for EXV, EYV (in 2015.3)
- Type-A: 2 IXV, IYV (in 2015.9)
- Movement from IXA, IYA, EXA, EYA to PRM, SRM, SR2, SR3 (in 2015.9)

AOS: End: for BRT control (in 2016.1, or 2014.10 for test)

MIF for LSC: REFL, AS_RF, AS_DC, POP, POX, POY (around BS chamber in 2015.1)

End: TRX, TRY through RFM to LSC (in 2015.1) and ASC (in 2016.1)

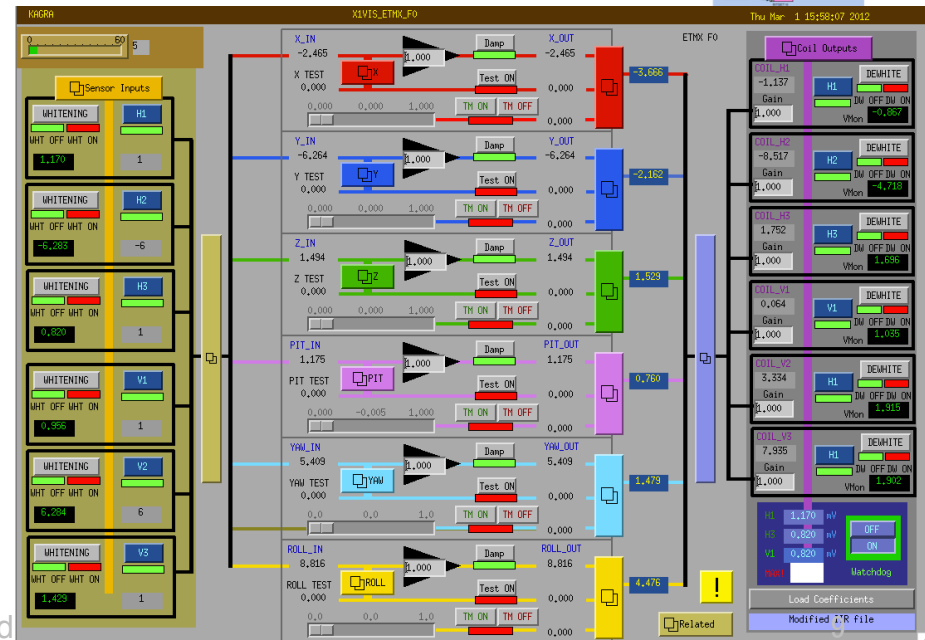
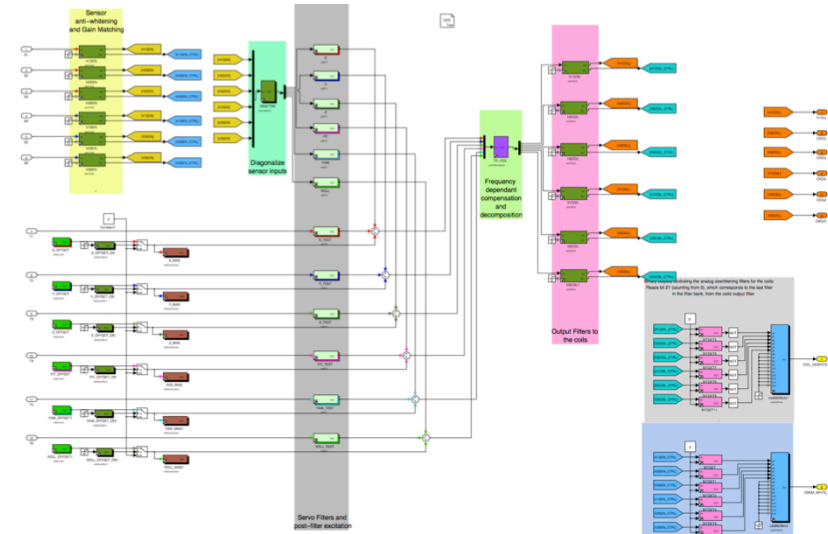
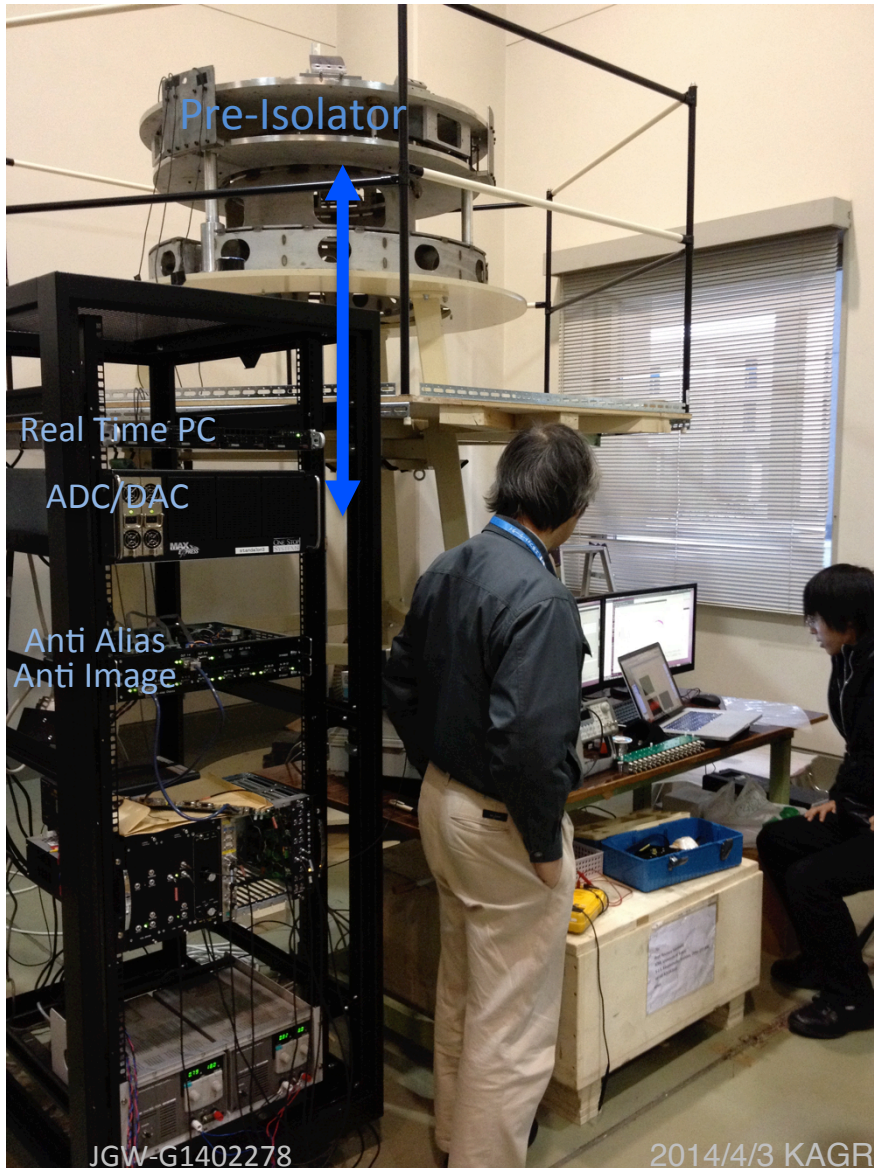
ASC: REFL, AS_RF, POP (around BS chamber in 2016.1)

AUX: Green Lock or others from POP, POS through RFM to LSC (around BS chamber in 2016.1)

IOO: FSS thermal control, MC control (around MC chamber in 2014.10)

: Prototype test: at Kashiwa (in 2014.6)

GIF: for Seismometer at center of each arm (in 2014.10)



Items for Real Time control

	Stand alone FY2010-	Small network FY2011	Large network FY2012, 2013	Full system FY2014~
Real time PC	1	2	5	~30
IO chassis	1	2	5	~30
ADC	1	2	~10	~65
DAC	1	1	~10	~45
Binary Output	1	0	~10	~85
Long distance RFM	0	1	2	3
Short distance RFM	0	1	2	2
DAQ network switch	0	1	4	4
Timing switch	0	1	3	3
Boot server	0	1	1	1
Network file system	0	0	1	1
system server	0	0	1	3
NAT	0	0	1	2
Data concentrator	0	0	1	1
NDS distributor	0	0	1	2 (redundant)
Frame writer	0	0	2 (redundant)	2 (redundant)
IRIG-B switch	0	0	1	3
Data storage	1TB (local)	1TB (local)	~20TB x2 (ext.)	~200TB (ext.)

Red: new items Green: increments



Number of PC/ADC/DAC/BO

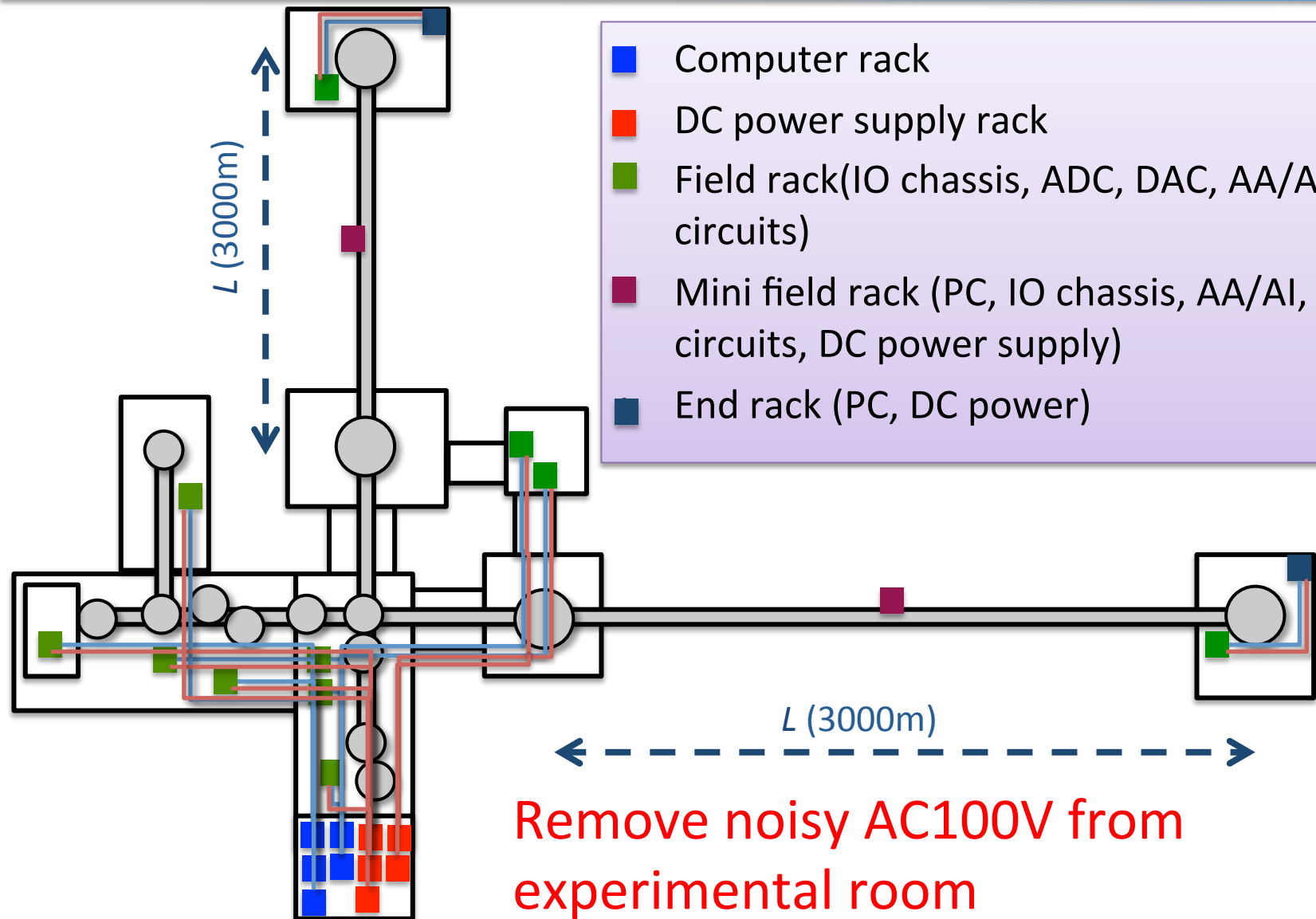
RT PC Name	RT PC room	Room No.	rack	IO chassi room	Room No.	Cable length	IO chassis DC	RFM	Dolphin	ADC	DAC	BO card	BO cards for wh.	BO cards for desk	Total cards	Items	Comments
k1io	C Control	1		FMC-Area	9	100	1		1	3	0	1	12	0	16	MCR, MCT, WFS x2, PSL(PMC, FSS, ISS)	
k1mc	C Control	1		FMC-Area	9	100	1		1	2	1	0	6	2	11	MCI, MCO, MCE	
k1mmt	C Control	1		FMC-Area	9	100	1		0	1	1	0	11	1	14	MMT1, MMT2	
k1pr	C Control	1		P-Area	7	100	2		1	2	4	0	8	3	17	PRM, PR3	
k1pr2	C Control	1		B-Area	4	75	1		1	2	2	0	4	2	10	PR2	
k1bs	C Control	1		B-Area	4	75	1		1	2	2	0	5	2	11	BS	
k1sr2	C Control	1		B-Area	4	75	1		1	2	2	0	5	2	11	SR2	
k1sr3	C Control	1		S-Area	5	50	1		1	2	2	0	5	2	11	SR3	
k1srm	C Control	1		S-Area	5	50	1		1	2	2	0	5	2	11	SRM	
k1ommt	C Control	1		S-Area	5	50	2		0	2	2	0	8	2	14	OMMT1, OMMT2, STM1, STM2	
k1omc	C Control	1		S-Area	5	50	1		1	2	1	1	4	1	9	OMC+OFI	
k1ix1	C Control	1		XFrontVI (XFrontCryoBack)	40(22)	120	2		1	2	2	0	5	2	11	ITMX	for Type A & C
k1iy1	C Control	1		YFrontVI (YFrontCryoBack)	44(32)	120	2		1	2	2	0	5	2	11	ITMY	for Type A & C
k1ex1	XEndVIPre (XEndMec)	61(54)		XEndVI (XEndCryoARsideDuct)	60(51)	50	1	1	0	3	2	0	5	2	12	ETMX	for Type A & C
k1ex2	XEndVIPre (XEndMec)	61(54)		XEndVI (XEndCryoARsideDuct)	60(51)	50	1	1	0	1	1	0	8	1	11	BRT, TRX	
k1ey1	YEndVIPre (YEndMec)	81(74)		YEndVI (YEndCryoARsideDuct)	80(71)	50	1	1	0	3	2	0	5	2	12	ETMY	for Type A & C
k1ey2	YEndVIPre (YEndMec)	81(74)		YEndVI (YEndCryoARsideDuct)	80(71)	50	1	1	0	1	1	0	8	1	11	BRT, TRY	
k1isc	C Control	1		?	?	75	1	1	1	3	0	0	13	0	16	ASRF, REFL, POX, POY, POP, POS	
k1asc1	C Control	1		?	?	75	1	1	1	3	0	0	14	0	17	WFSAS, WFSREFL, WFSPOX	
k1asc2	C Control	1		?	?	75	1	1	1	2	0	0	8	0	10	WFSAS, WFSREFL, WFSPOX	
k1aux	C Control	1		?	?	100	1		1	2	0	?	0	0	2	GRX, GRY	
k1pcx	X arm center	N/A		X arm center	?	2	3		0	1	0	0	0	0	1	PEM	
k1pcy	Y arm center	N/A		Y arm center	?	2	3		0	1	0	0	0	0	1	PEM	
Total							31	7	15	46	29	2	144	29	250		

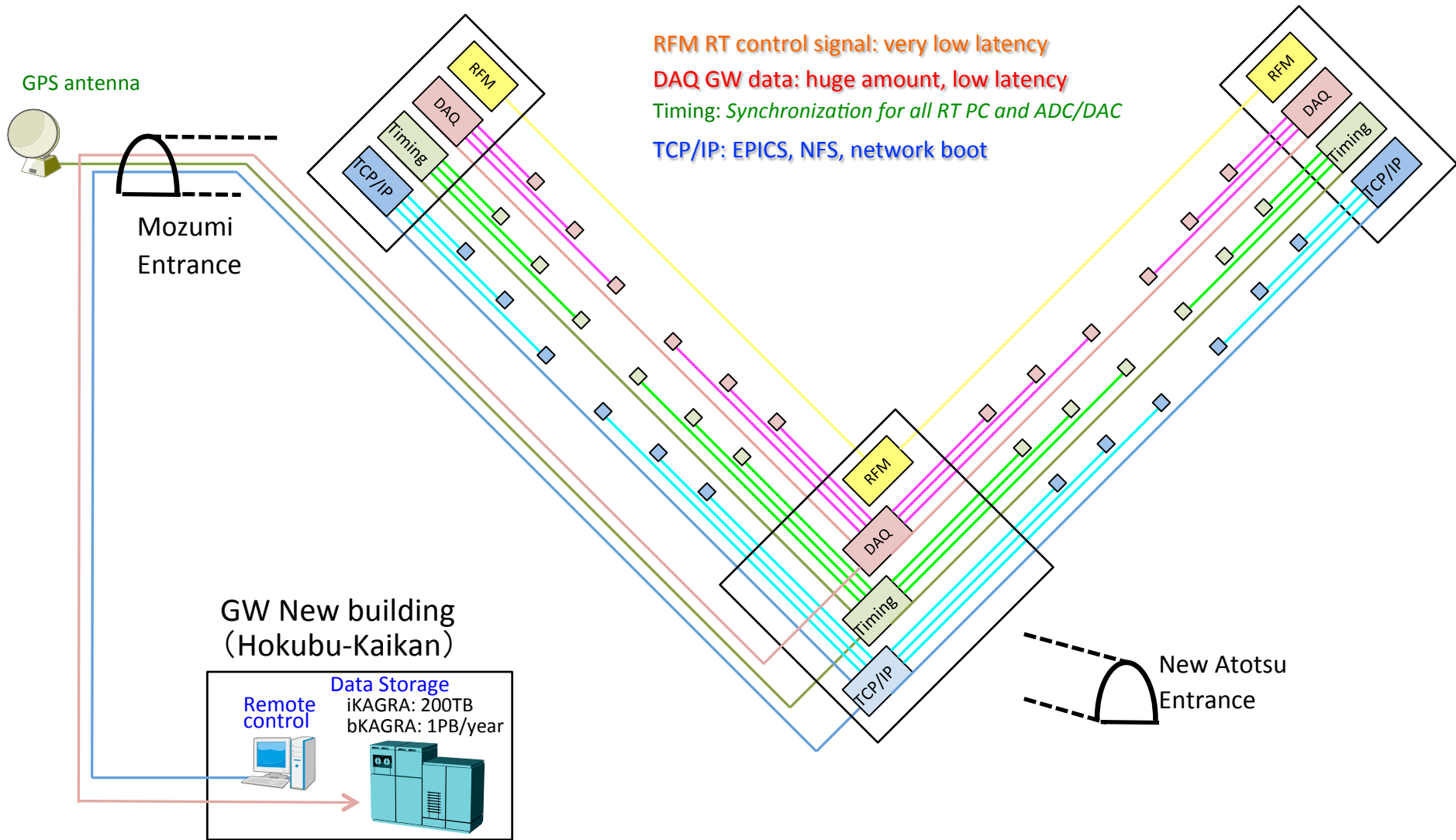
Max 18 60 40 99 17/ea.

[JGW-G1201105](#)

- 19 RT Front-End will be used in iKAGRA, and 27 in bKAGRA.
- 46 of 60 ADC and 29 of 40 DAC are assigned.
- Needs 173 Binary Out module. Only 99 we have now. Using Acromag 96ch slow BO?

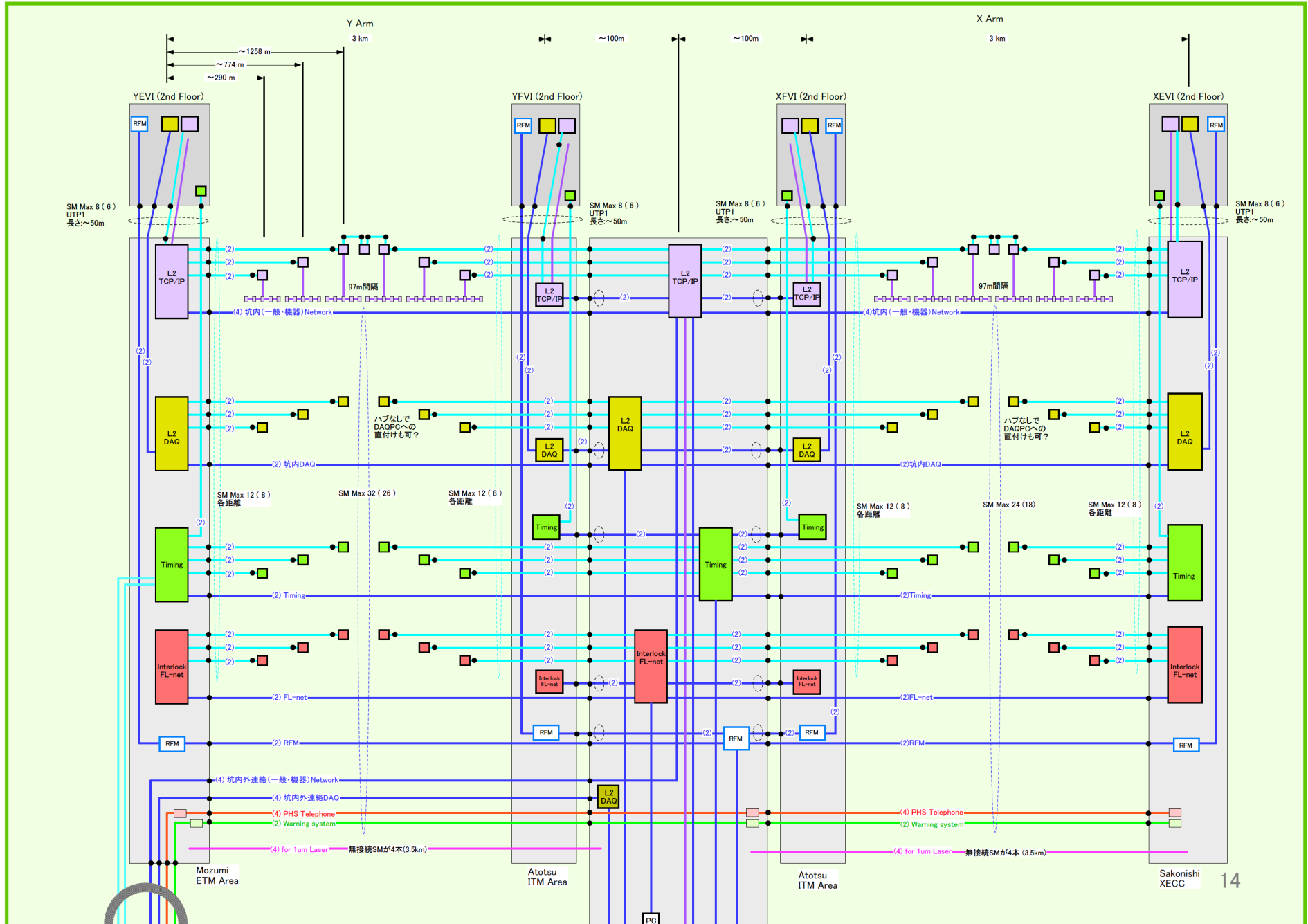
Connection to Field racks





JGW-G1201437

- SM Fiber (1G or 10G) Net
- スプライスボックス接続(予定)
- SM Fiber (1G) Net
- SM Fiber Warning System
- 1G Metal
- SM Fiber PHS System
- SM Fiber for 1um Laser
- HUB, Timing, DAQ, FL-net Instrument



- Assigned PSL, IOO, MIF, VIS (except for OMC, OMMT, BRT)
- Next task: estimation for number/length of cables (D-SUB, RF, fiber)

[JGW-T1201105](#)

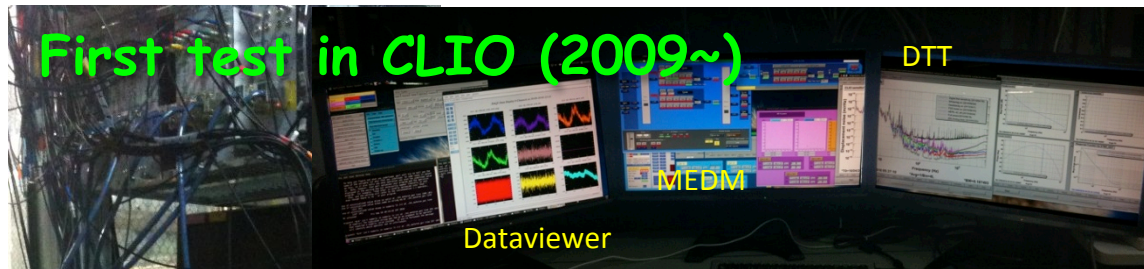
Signal channel list 2014/3/18

JGW-T1201105

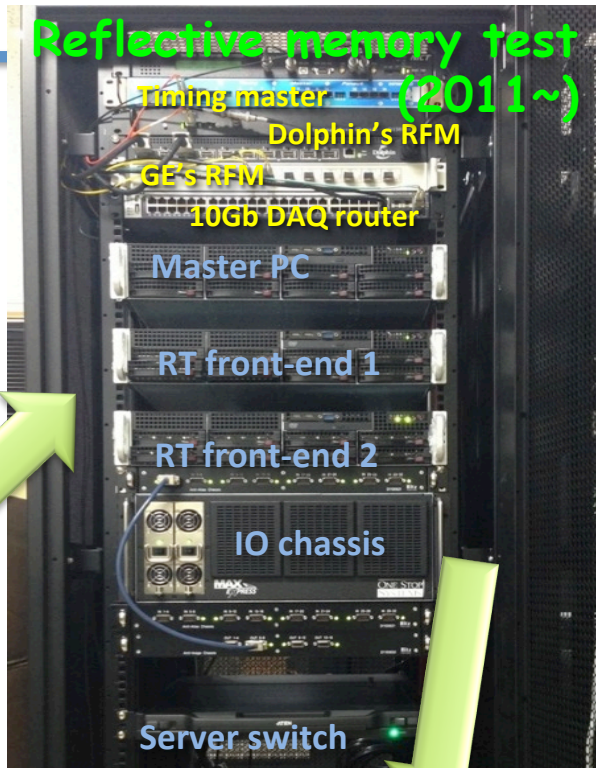
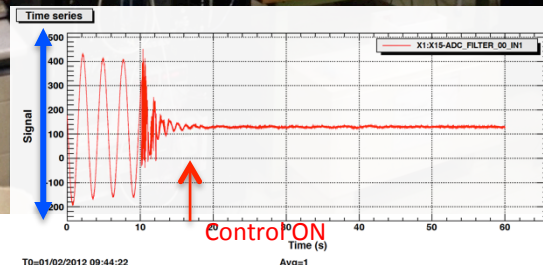
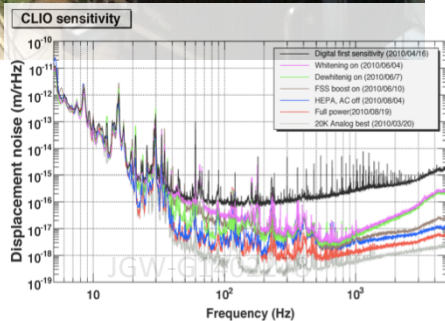
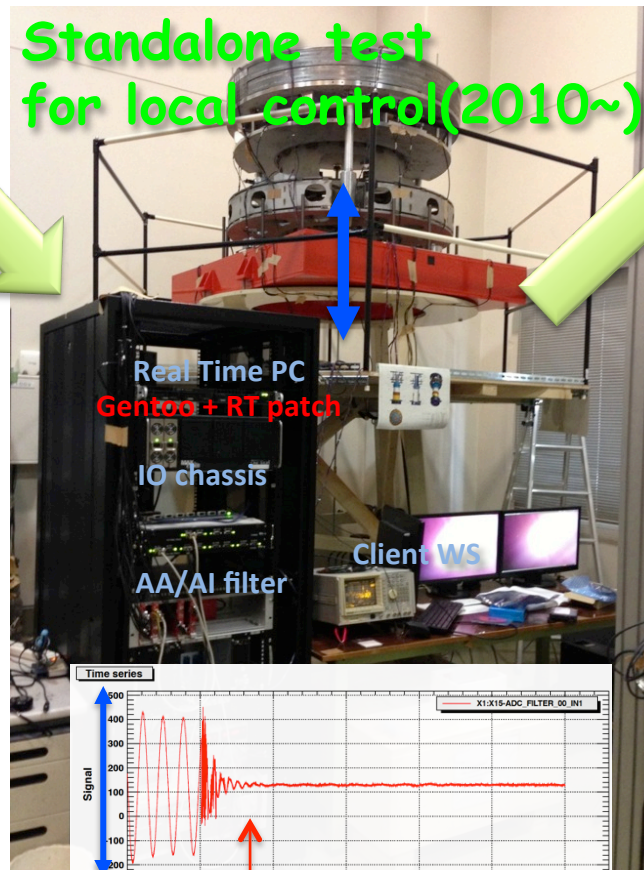
Osamu Miyakawa

Reference: [JGW-T1100689](#)

Subsystem	Location	Instrument	Signal description	Ch. Name	Card No.	Ch	Whitening	DC offset	Overrange	RT model	RT PC name
PSL	FSS	RF PD	I-phase	K1:PSL-FSS_REFL_I	ADC1	1		1		k1psl	ktio
PSL	FSS	RF PD	Q-phase	K1:PSL-FSS_REFL_Q	ADC1	2		1		k1psl	ktio
PSL	PMC	RF PD	I-phase	K1:PSL-PMC_REFL_I	ADC1	3		1		k1psl	ktio
PSL	PMC	RF PD	Q-phase	K1:PSL-PMC_REFL_Q	ADC1	4		1		k1psl	ktio
PSL	FSS	DC PD	DC	K1:PSL-FSS_REFL_DC	ADC1	5		1		k1psl	ktio
PSL	FSS	DC PD	DC	K1:PSL-FSS_TR_DC	ADC1	6		1		k1psl	ktio
PSL	PMC	DC PD	DC	K1:PSL-PMC_REFL_DC	ADC1	7		1		k1psl	ktio
PSL	PMC	DC PD	DC	K1:PSL-PMC_TR_DC	ADC1	8		1		k1psl	ktio
PSL	ISS	DC PD	DC	K1:PSL-ISS_DC	ADC1	9		1		k1psl	ktio
PSL			spare		ADC1	10		1		k1psl	ktio
PSL			spare		ADC1	11		1		k1psl	ktio
PSL			spare		ADC1	12		1		k1psl	ktio
PSL			spare		ADC1	13				k1psl	ktio
PSL			spare		ADC1	14				k1psl	ktio
PSL			spare		ADC1	15				k1psl	ktio
PSL			spare		ADC1	16				k1psl	ktio
PSL	BENCH	DC QPD	injection beam pointing monitor, quadrature 1	K1:PSL-BENCH_OUT_QPD1_Q1	ADC1	17		1		k1psl	ktio
PSL	BENCH	DC QPD	injection beam pointing monitor, quadrature 2	K1:PSL-BENCH_OUT_QPD1_Q2	ADC1	18		1		k1psl	ktio
PSL	BENCH	DC QPD	injection beam pointing monitor, quadrature 3	K1:PSL-BENCH_OUT_QPD1_Q3	ADC1	19		1		k1psl	ktio
PSL	BENCH	DC QPD	injection beam pointing monitor, quadrature 4	K1:PSL-BENCH_OUT_QPD1_Q4	ADC1	20		1		k1psl	ktio
PSL	BENCH	DC QPD	injection beam position monitor, quadrature 1	K1:PSL-BENCH_OUT_QPD2_Q1	ADC1	21		1		k1psl	ktio
PSL	BENCH	DC QPD	injection beam position monitor, quadrature 2	K1:PSL-BENCH_OUT_QPD2_Q2	ADC1	22		1		k1psl	ktio
PSL	BENCH	DC QPD	injection beam position monitor, quadrature 3	K1:PSL-BENCH_OUT_QPD2_Q3	ADC1	23		1		k1psl	ktio
PSL	BENCH	DC QPD	injection beam position monitor, quadrature 4	K1:PSL-BENCH_OUT_QPD2_Q4	ADC1	24		1		k1psl	ktio
PSL			spare		ADC1	25				k1psl	ktio
PSL			spare		ADC1	26				k1psl	ktio
PSL			spare		ADC1	27				k1psl	ktio
PSL			spare		ADC1	28				k1psl	ktio
PSL			spare		ADC1	29				k1psl	ktio
PSL			spare		ADC1	30				k1psl	ktio
PSL			spare		ADC1	31				k1psl	ktio
PSL			reserved for 1PPS		ADC1	32				k1psl	ktio
IOO	MCR	RF QPD	Gouy phase 1 Quadrature 1 I-phase	K1:IOO-MCR_QPD_G1_Q1_I	ADC2	1		1		ktio	ktio
IOO	MCR	RF QPD	Gouy phase 1 Quadrature 1 Q-phase	K1:IOO-MCR_QPD_G1_Q1_Q	ADC2	2		1		ktio	ktio
IOO	MCR	RF QPD	Gouy phase 1 Quadrature 2 I-phase	K1:IOO-MCR_QPD_G1_Q2_I	ADC2	3		1		ktio	ktio
IOO	MCR	RF QPD	Gouy phase 1 Quadrature 2 Q-phase	K1:IOO-MCR_QPD_G1_Q2_Q	ADC2	4		1		ktio	ktio
IOO	MCR	RF QPD	Gouy phase 1 Quadrature 3 I-phase	K1:IOO-MCR_QPD_G1_Q3_I	ADC2	5		1		ktio	ktio
IOO	MCR	RF QPD	Gouy phase 1 Quadrature 3 Q-phase	K1:IOO-MCR_QPD_G1_Q3_Q	ADC2	6		1		ktio	ktio
IOO	MCR	RF QPD	Gouy phase 1 Quadrature 4 I-phase	K1:IOO-MCR_QPD_G1_Q4_I	ADC2	7		1		ktio	ktio
IOO	MCR	RF QPD	Gouy phase 1 Quadrature 4 Q-phase	K1:IOO-MCR_QPD_G1_Q4_Q	ADC2	8		1		ktio	ktio
IOO	MCR	DC QPD	Gouy phase 1 Quadrature 1 DC	K1:IOO-MCR_QPD_G1_Q1_DC	ADC2	9				ktio	ktio
IOO	MCR	DC QPD	Gouy phase 1 Quadrature 2 DC	K1:IOO-MCR_QPD_G1_Q2_DC	ADC2	10				ktio	ktio
IOO	MCR	DC QPD	Gouy phase 1 Quadrature 3 DC	K1:IOO-MCR_QPD_G1_Q3_DC	ADC2	11				ktio	ktio
IOO	MCR	DC QPD	Gouy phase 1 Quadrature 4 DC	K1:IOO-MCR_QPD_G1_Q4_DC	ADC2	12				ktio	ktio
IOO			spare		ADC2	13				ktio	ktio
IOO			spare		ADC2	14				ktio	ktio
IOO			spare		ADC2	15				ktio	ktio
IOO			spare		ADC2	16				ktio	ktio
IOO	MCR	RF QPD	Gouy phase 2 Quadrature 1 I-phase	K1:IOO-MCR_QPD_G2_Q1_I	ADC2	17		1		ktio	ktio
IOO	MCR	RF QPD	Gouy phase 2 Quadrature 1 Q-phase	K1:IOO-MCR_QPD_G2_Q1_Q	ADC2	18		1		ktio	ktio



Standalone test for local control(2010~)

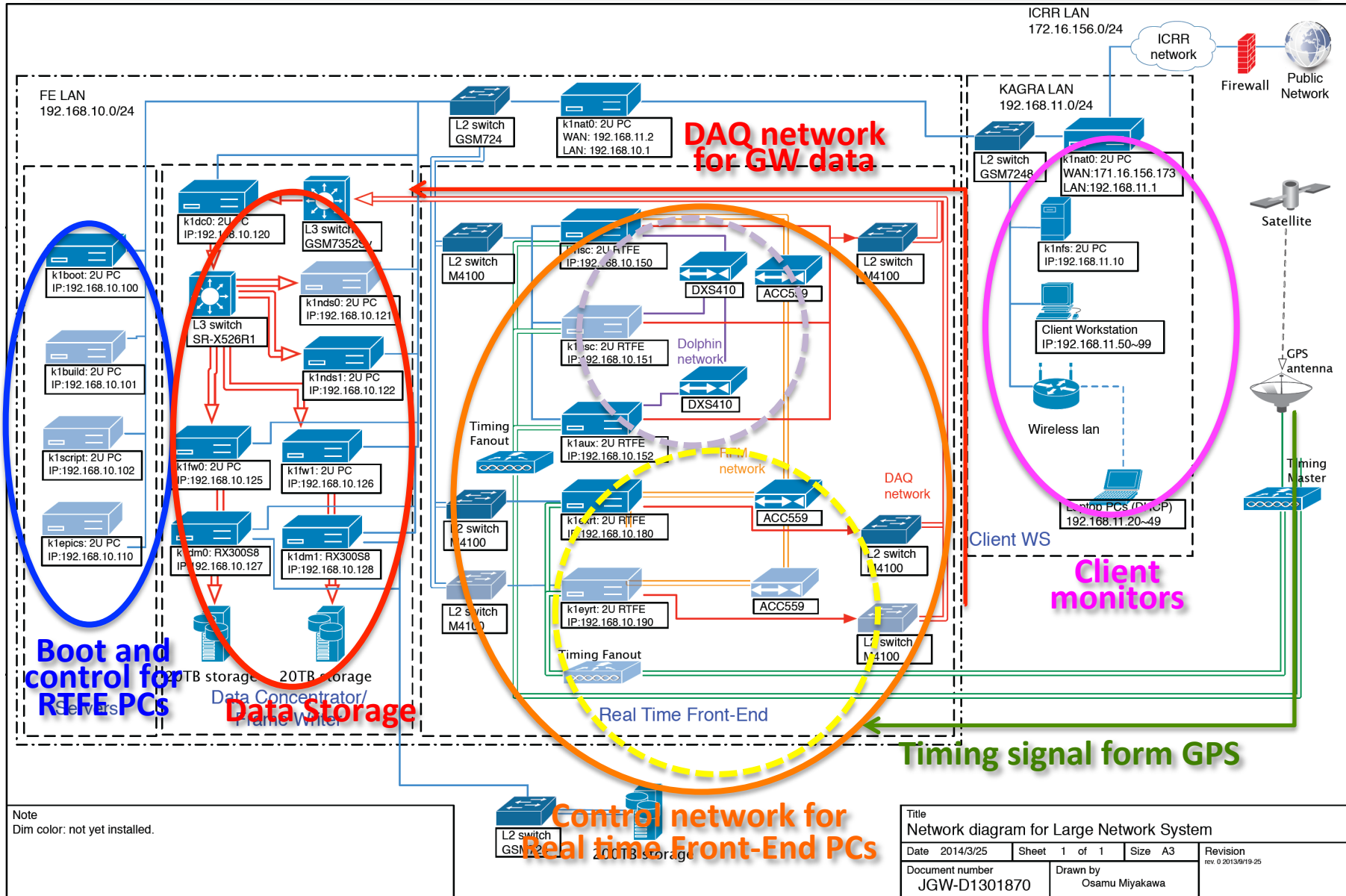


Large scale setup for KAGRA(2012~)



1. Very close system as real KAGRA control system, and easy installation into mine.
 2. Operation test with multiple computers.
 - Real Time Front-End computers
 - Servers (boot, model building, scripting, NFS)
 3. Data acquisition test.
 - Huge amount of data, latency
 4. Stable operation.
 - Long term operation test
 - Preparations for power shutdown and power recovery
 5. Redundancy.
 - Dual path for DAQ network
 - Dual power supply for servers being equipped with hard drives
- What we cannot test at LNS.
 - Network connection through 3km arms
 - Full scale Real Time network with ~30 RT computers

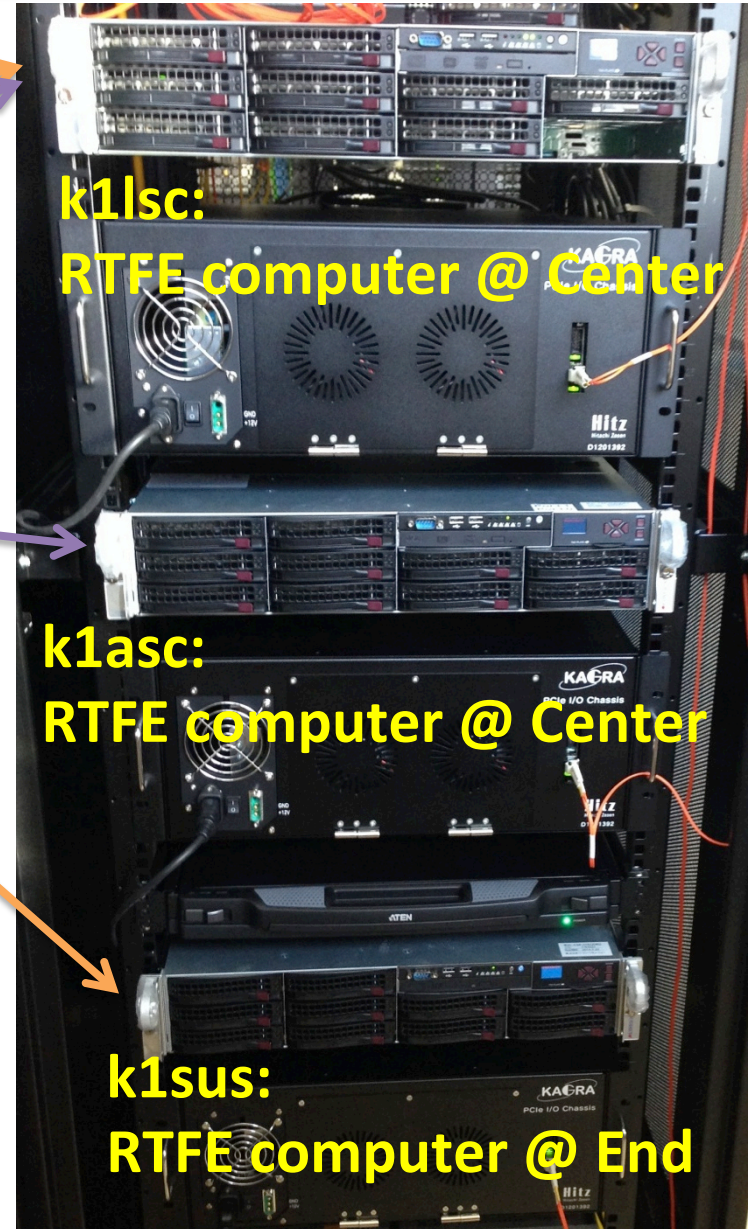
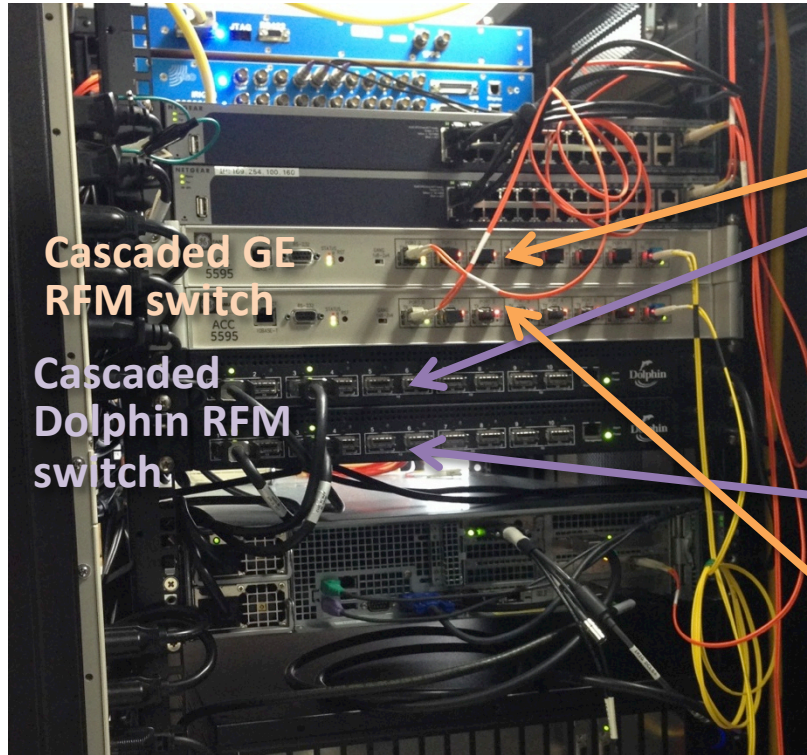
Diagram of Large Network System



Title Network diagram for Large Network System			
Date 2014/3/25	Sheet 1 of 1	Size A3	Revision rev. 0 2013/9/19-25
Document number JGW-D1301870	Drawn by Osamu Miyakawa		



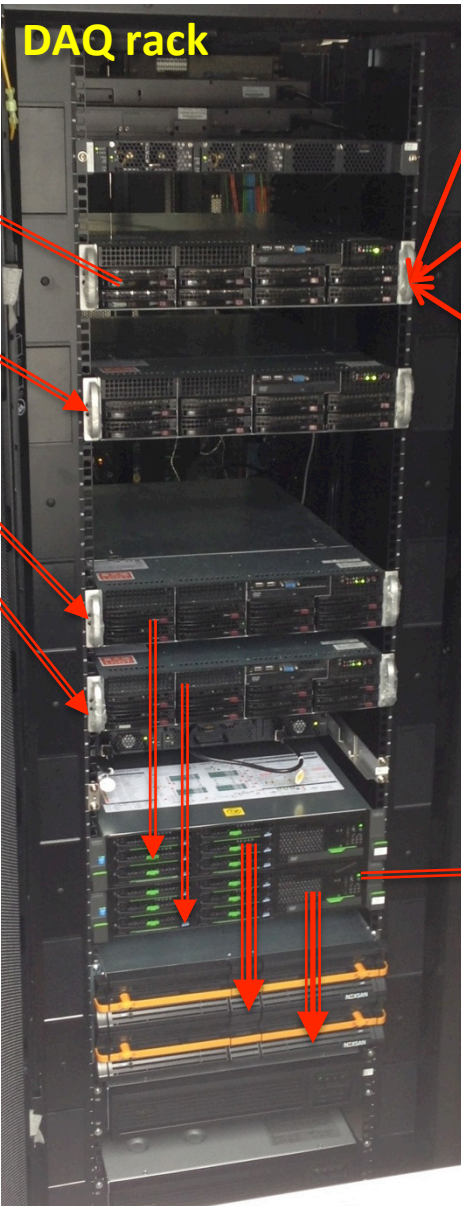
Control signal network for Real Time Front-end using ReFlective Memory technology



GE RFM:
long distance
real time signal
~3km



**Fujitsu: SR-X526R1
10GB low latency
switch**



DAQ rack

k1dc0

k1nds0

k1fw0

k1fw1

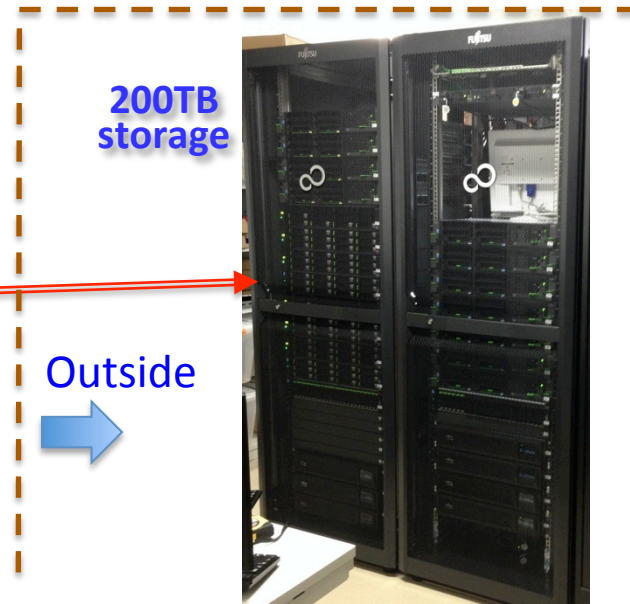
**k1dm0
k1dm1**

**20TB storage
20TB storage**

UPS



**Real Time Front-End
computers**



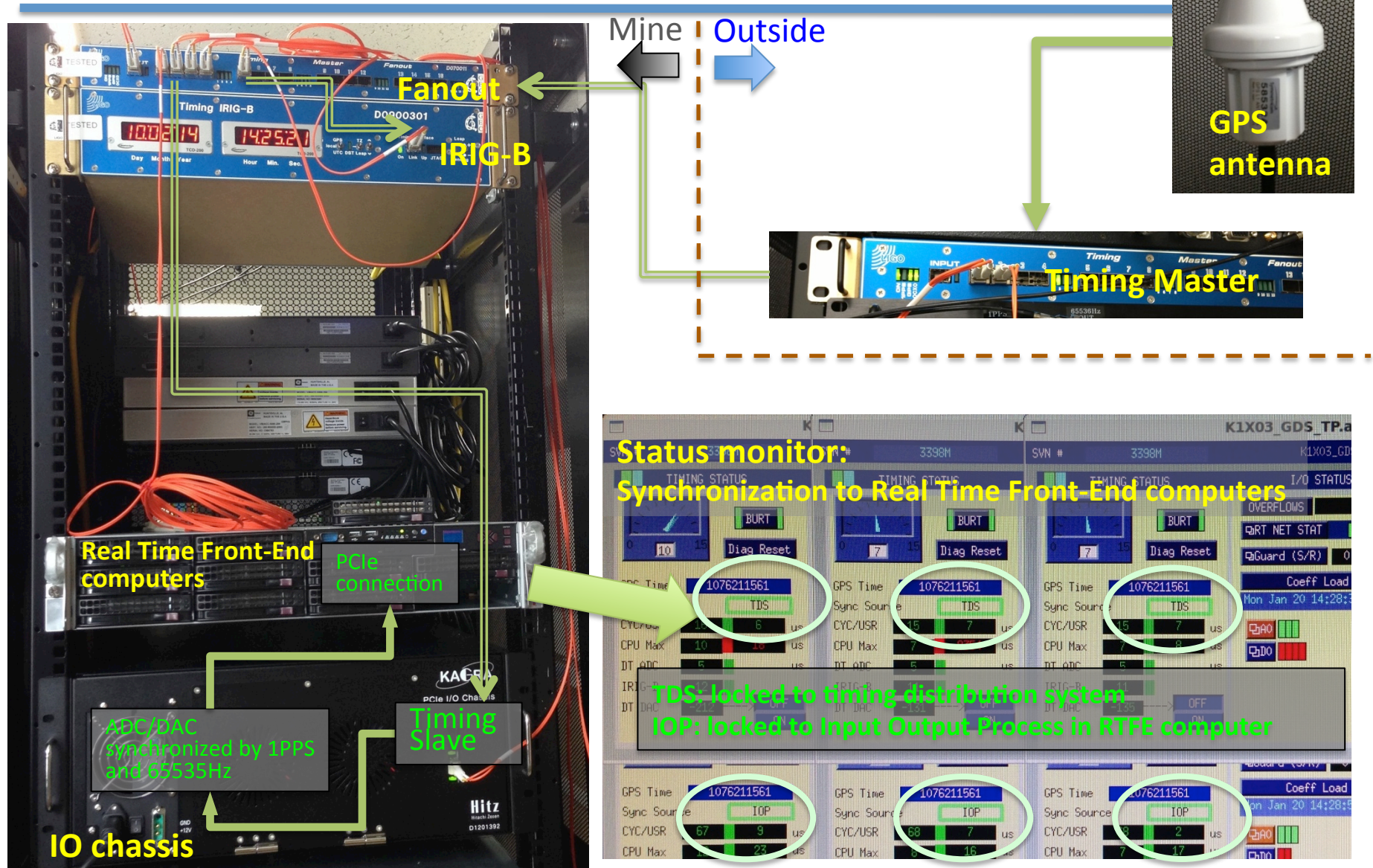
**200TB
storage**

Mine

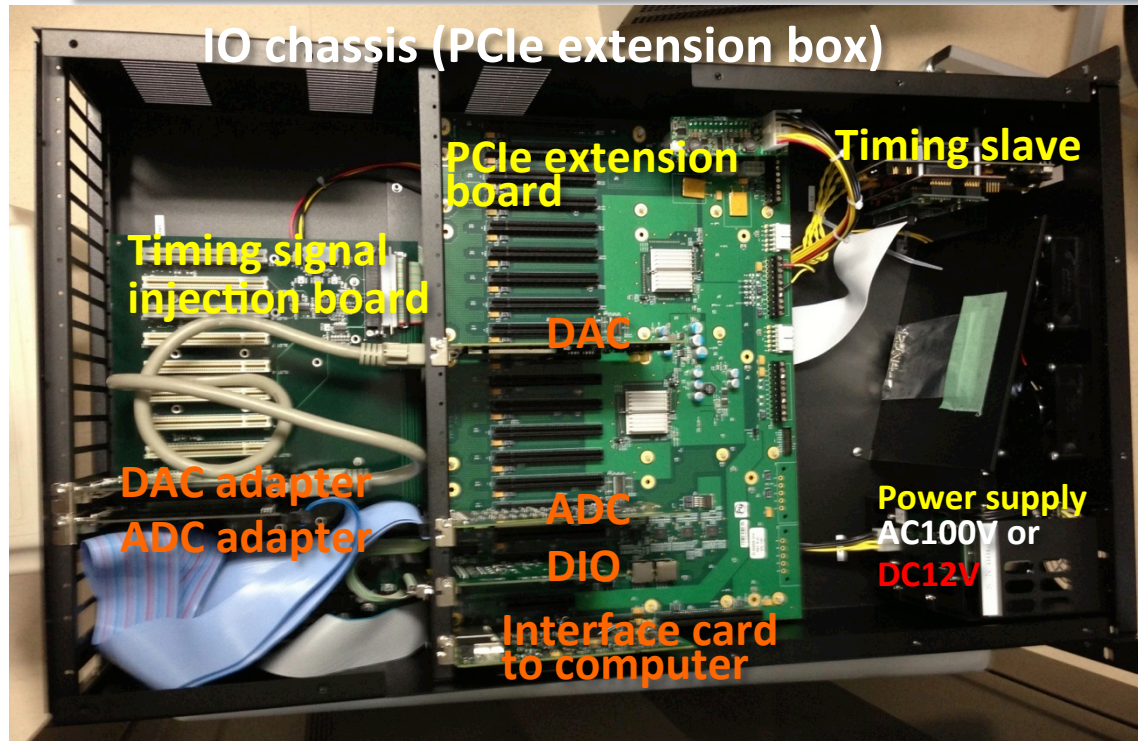
Outside



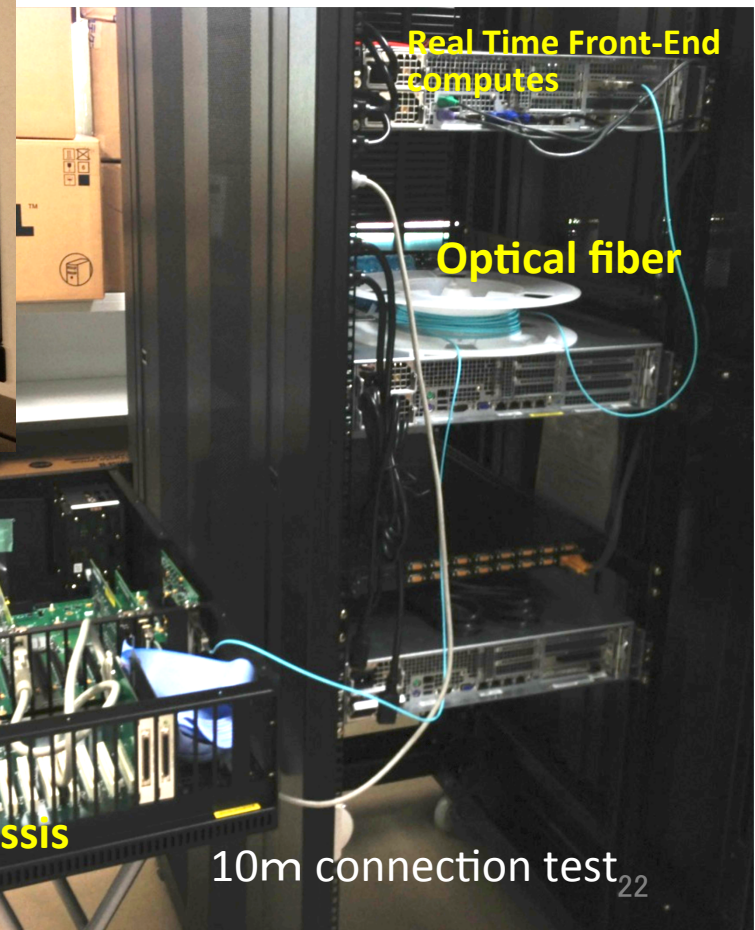
How to synchronize ADC/DAC and PC



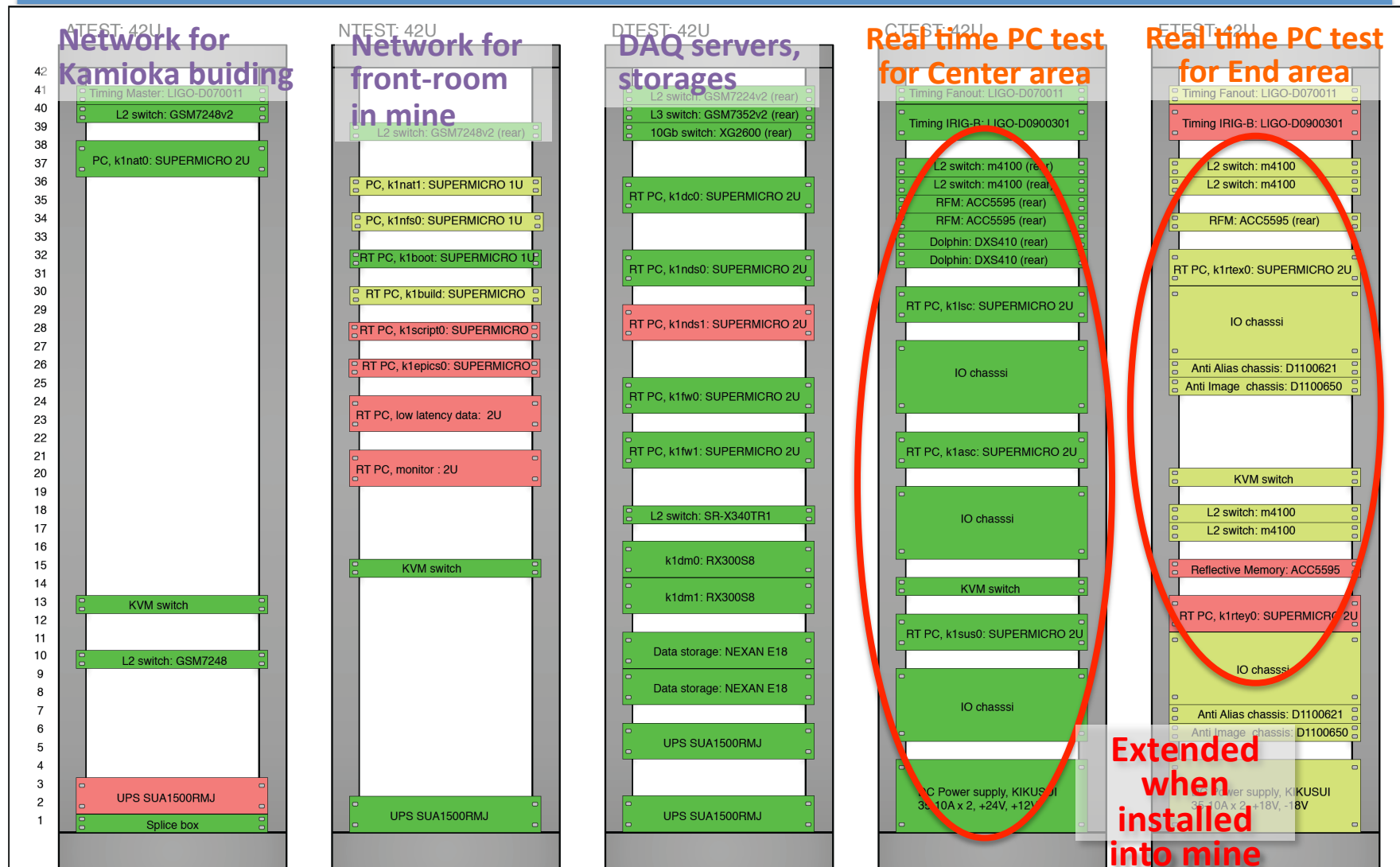
Connection between RTFE computer and PCIe extension chassis



Total 31 chassis manufactured for bKAGRA



- Remote connection up to 100m using optical fiber will be tested soon.



Extended when installed into mine

Note: Status as of 12 February 2014
Location: Kamioka branch

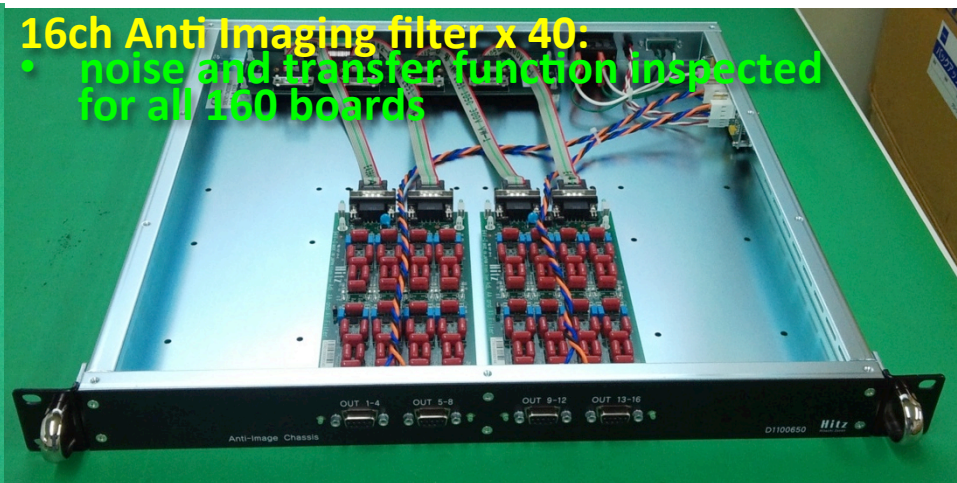
Color Key			
	Installed		Mounted but not being used
	Ready for installation		Waiting for mount

Title					
Rack Layout for Large Network System					
Date	2012/3/14	Sheet	1 of 2	Size	A3
Document number	JGW-D1301569	Drawn by	Osamu Miyakawa		rev. 0 2012/3/14

KAGRA DAQ items

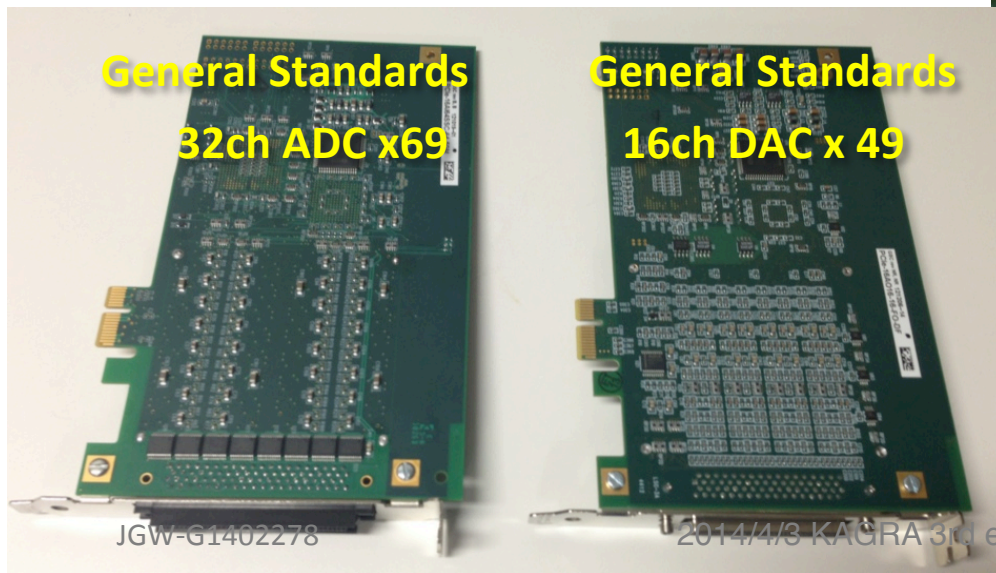


32ch Anti Alias filter x60 :
• noise and transfer function inspected for all 240 boards



16ch Anti Imaging filter x 40:
• noise and transfer function inspected for all 160 boards

All AA/AI manufactured for bKAGRA



**General Standards
32ch ADC x69**

**General Standards
16ch DAC x 49**



Objective

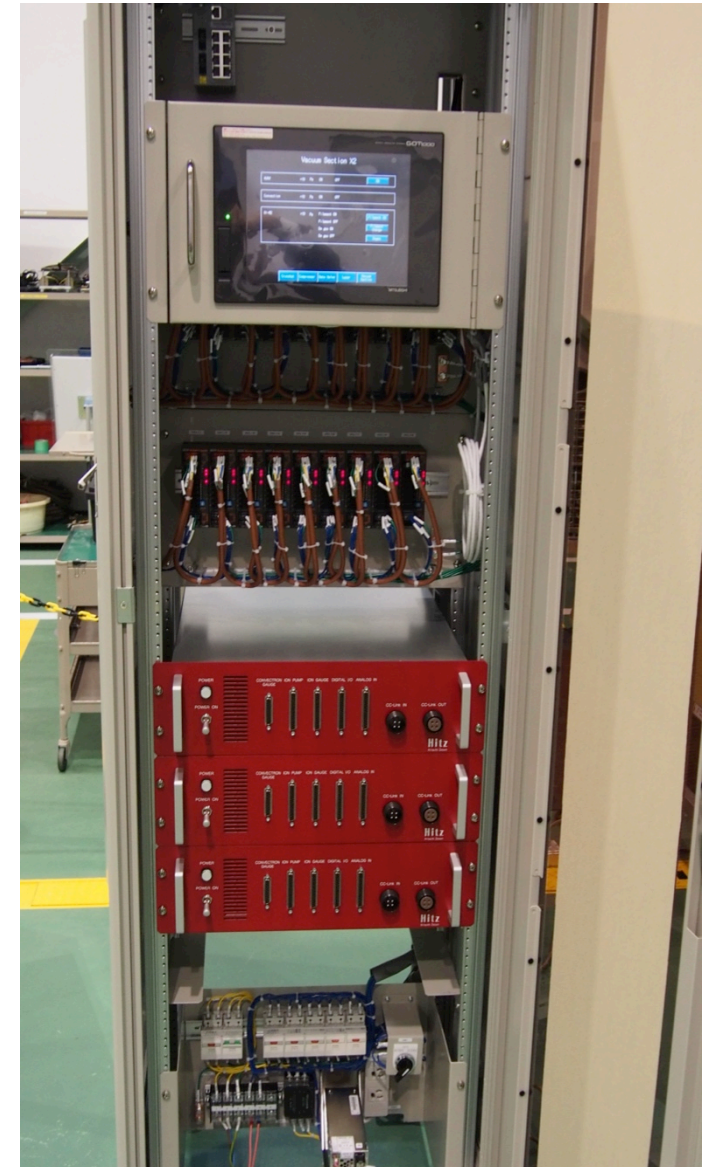
- Monitor the status of various instruments throughout the KAGRA site including environmental monitors.
- Remotely manipulate some instruments.
- Automatically shut the gate valves and the laser in case of an accident.

Implementation

- Industrial PLC for robust operation
- Three core modules (center, X-end, Y-end)
- 30 I/O modules along each arm
- EPICS translator to interface for user interface

Status

- Central area core module: **Delivered**
- X-end, Y-end core modules: **Delivered**
- 6 I/O modules: **Delivered**
- 54 I/O modules: **To be purchased**



Client workstation in control room

- 3 heads client workstations in the control room
- Direct access to 2weeks past frame data in 20TB storage.
- Control software:
 - MEDM (EPICS GUI)
 - StripTool (long term EPICS ch viewer)
 - Dataviewer (oscilloscope)
 - DTT (spectrum analyzer)
 - Foton (digital filter composer)
 - TDS commands (script)



KAGRA Storage in the current/new building at Kamioka

AA: 1U x 66

AI: 1U x 46

IO chassis: 4U x 31

RT PC: 2U x 28

Server PC: 1U x 11

DC power supply: 4U x 75

Total ~600U = 42U x **15** racks



Total number of racks in the mine will be ~**30**.

Analog electronics chassis will be continuously made and stored in the racks until installation.

- Connection between RTFE and IO chassis through 100m fiber since Trenton backplane does not support GEN2 connection.
 - One Stop System answered they will patch GEN1 mode to their GEN2 interface cards.
- Inspection of ADC/DAC
 - Some excess noise channels seen on ADC
- Timing injection to data concentrator (k1dc0)
 - Synchronization error on DTT
- Fixing mapper on Myrinet
 - No DAQ stream
- Slow start of Myrinet cards on frame writers causes no connection to frame data when booted.
- Build, script, epics, NFS and NAT servers

- Almost of core technologies for real time control have been implemented with LIGO CDS support.
- Some remaining items and some minor issues to be fixed.