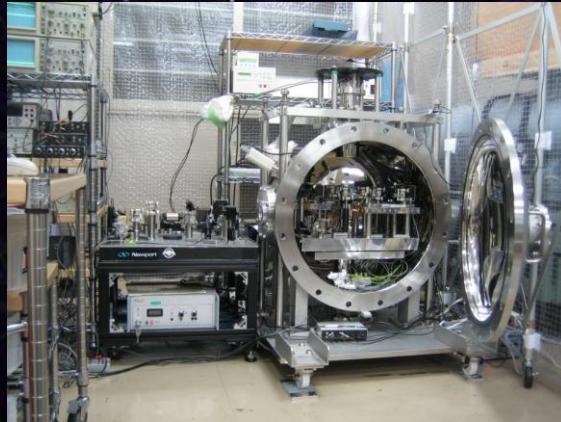


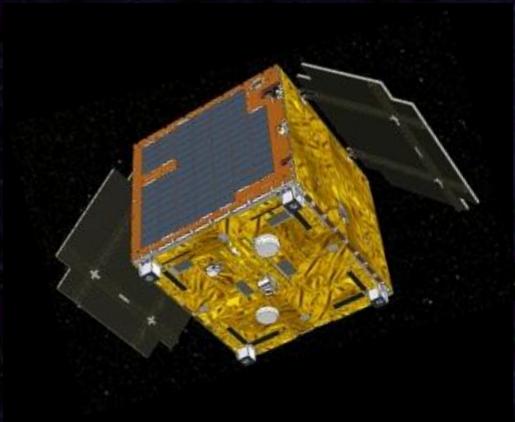
TOBA: Torsion-Bar Antenna



Small-scale TOBA at Tokyo



Small-scale TOBA at Kyoto



SWIM on SDS-1 satellite

Masaki Ando (Kyoto University)

Ayaka Shoda (University of Tokyo)

K. Ishidoshiro, K. Okada, W. Kokuyama, K. Yagi, K. Yamamoto,
H. Takahashi, N. Kanda, Y. Aso, N. Matsumoto, K. Tsubono, A. Takamori

Special thanks to the MANGO members

Motivation

Low-freq. GW observation → New sciences

- Large amplitude and/or stationary GWs radiated by sources with large masses and long time-scales.
- Difficult with ground-based detectors because of fundamental limitation and seismic disturbances.
- Space-borne detector requires large resources.



Novel approach : TOBA (Torsion-Bar Antenna)

- Low-freq. GW obs. even with ground-based config.
- Unexplored band observation with space detector.

Introduction Prototype results

- **Ground-based TOBA (A. Shoda)**
- **Rotating TOBA in space**

Next steps

Reference:

- M.Ando, et. al, Phys. Rev. Lett. 105, 161101 (2010)
- K.Ishidoshiro, et. al, Phys. Rev. Lett. 106, 161101 (2011)
- A. Shoda, presentation at GWPAW2011
- W.Kokuyama, in preparation

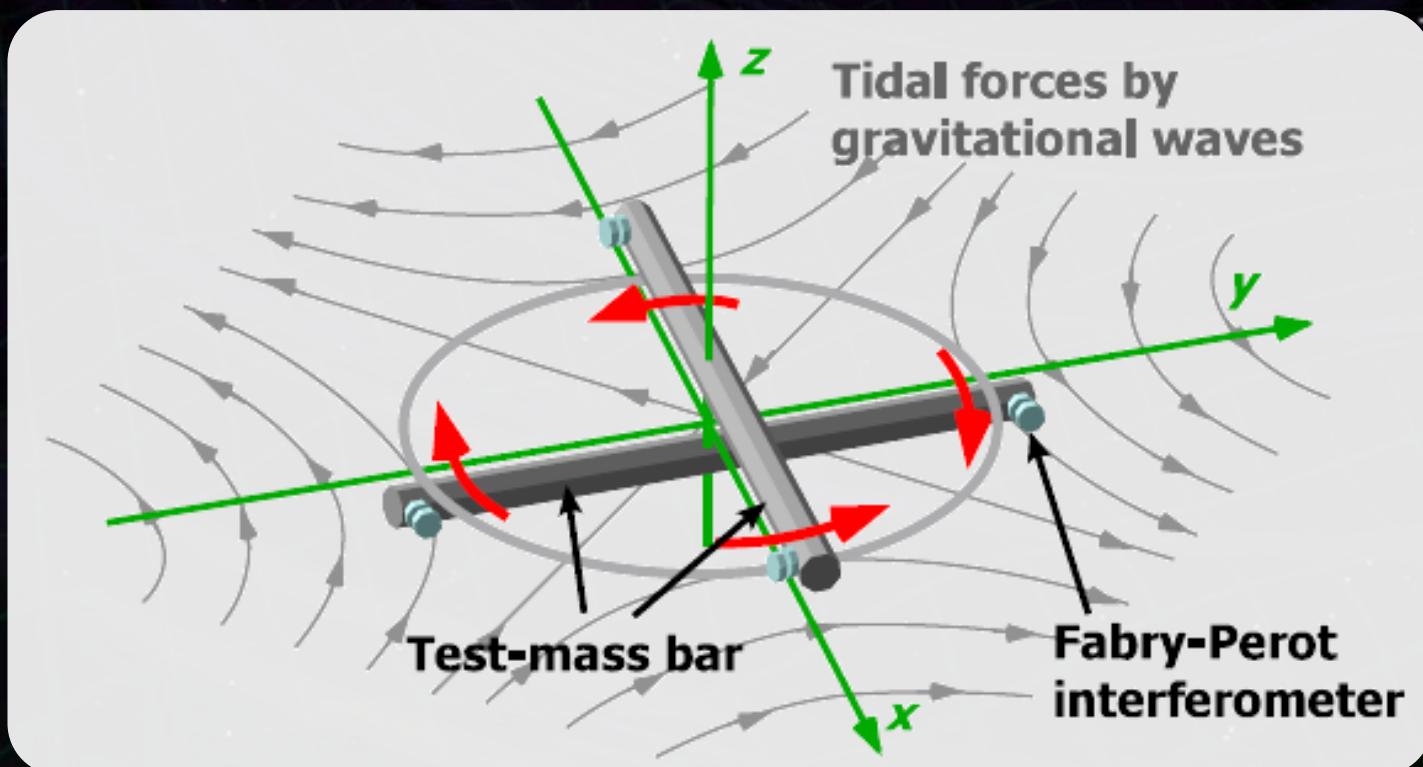
TOBA Introduction

Reference: MA+, Phys. Rev. Lett. 105, 161101 (2010)

TOBA

TOBA : Torsion-Bar Antenna

Monitors tidal-force fluctuation caused by GWs.

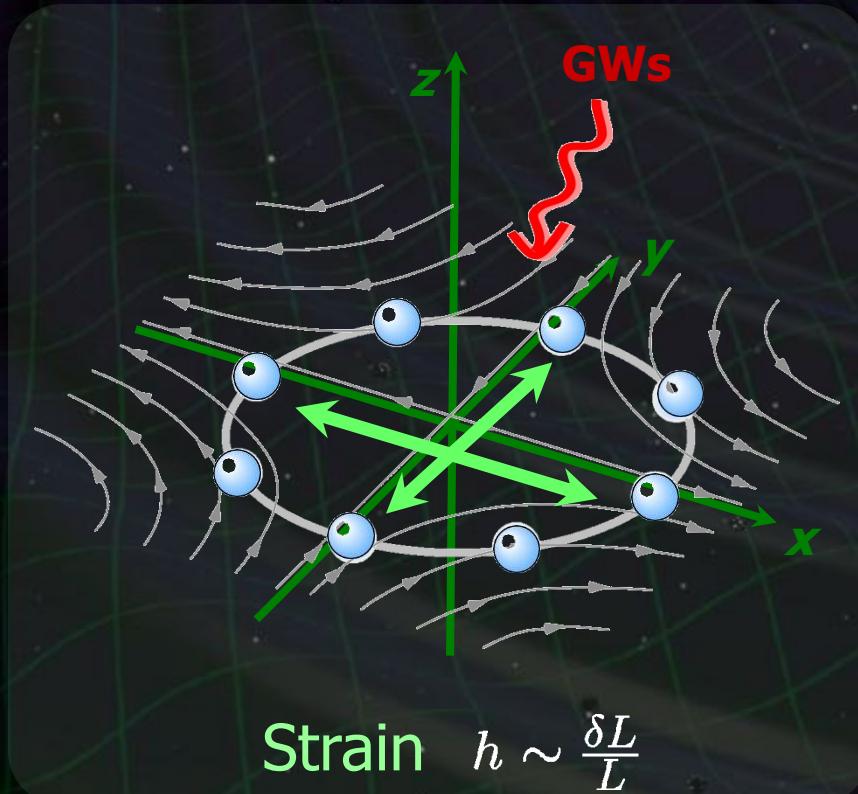


MA+, Phys. Rev. Lett. 105, 161101 (2010)

Detection principle

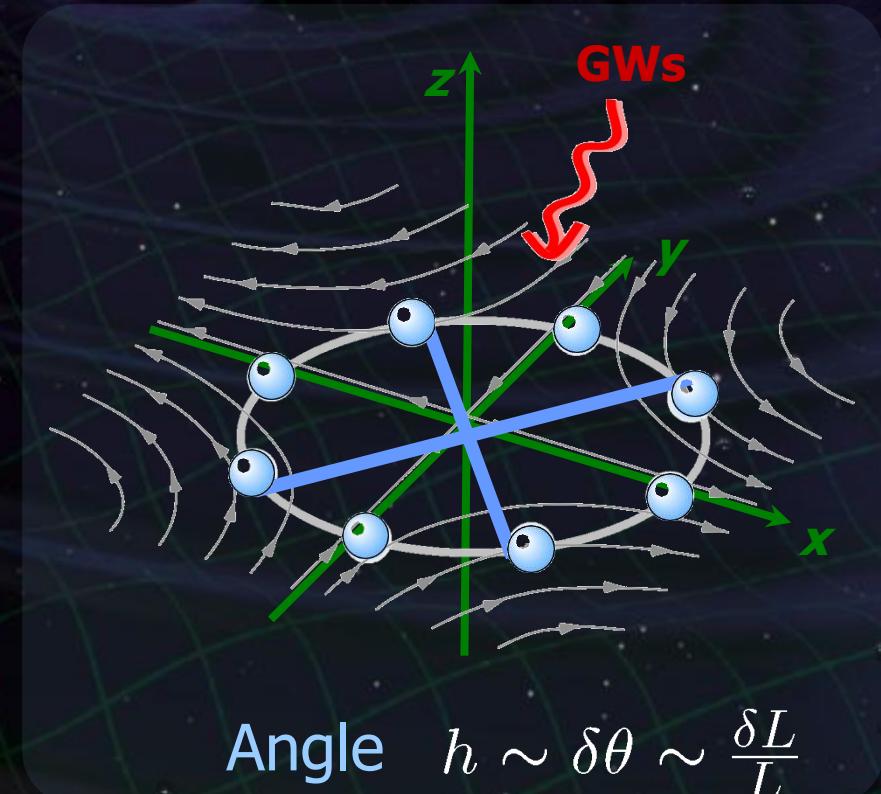
Conventional IFO antenna

Detect differential length change



Torsion-bar antenna

Detect differential rotation

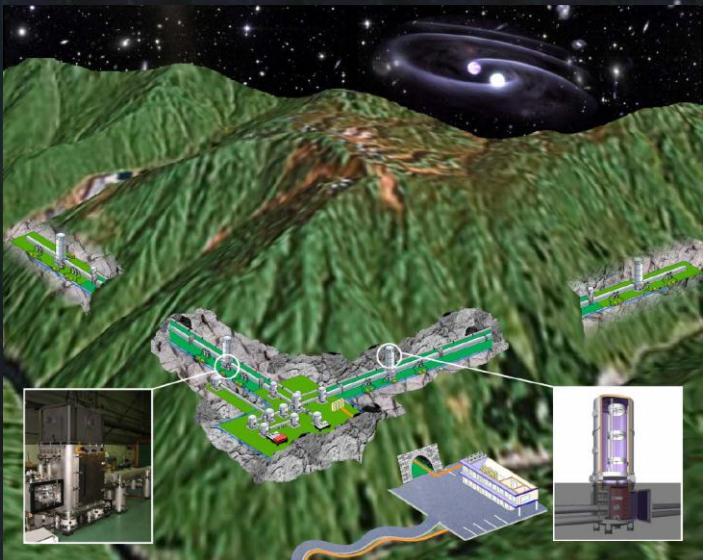


Changes in tidal forces using free test masses

Comparison

Conventional IFO

Obs. band 10Hz-1kHz

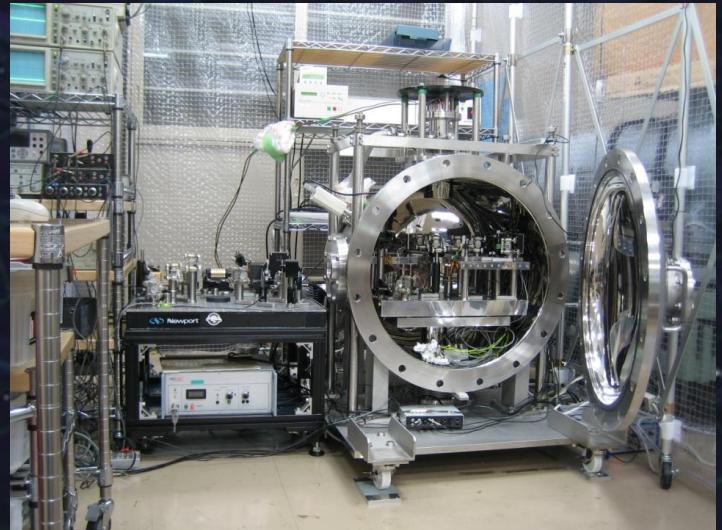


Suspended as pendulum
(Res. Freq. ~1Hz)

Long baseline
→ High sensitivity
 $SQL \propto 1/(M \cdot L^2)^{1/2}$

TOBA

Obs. band 10mHz-1Hz

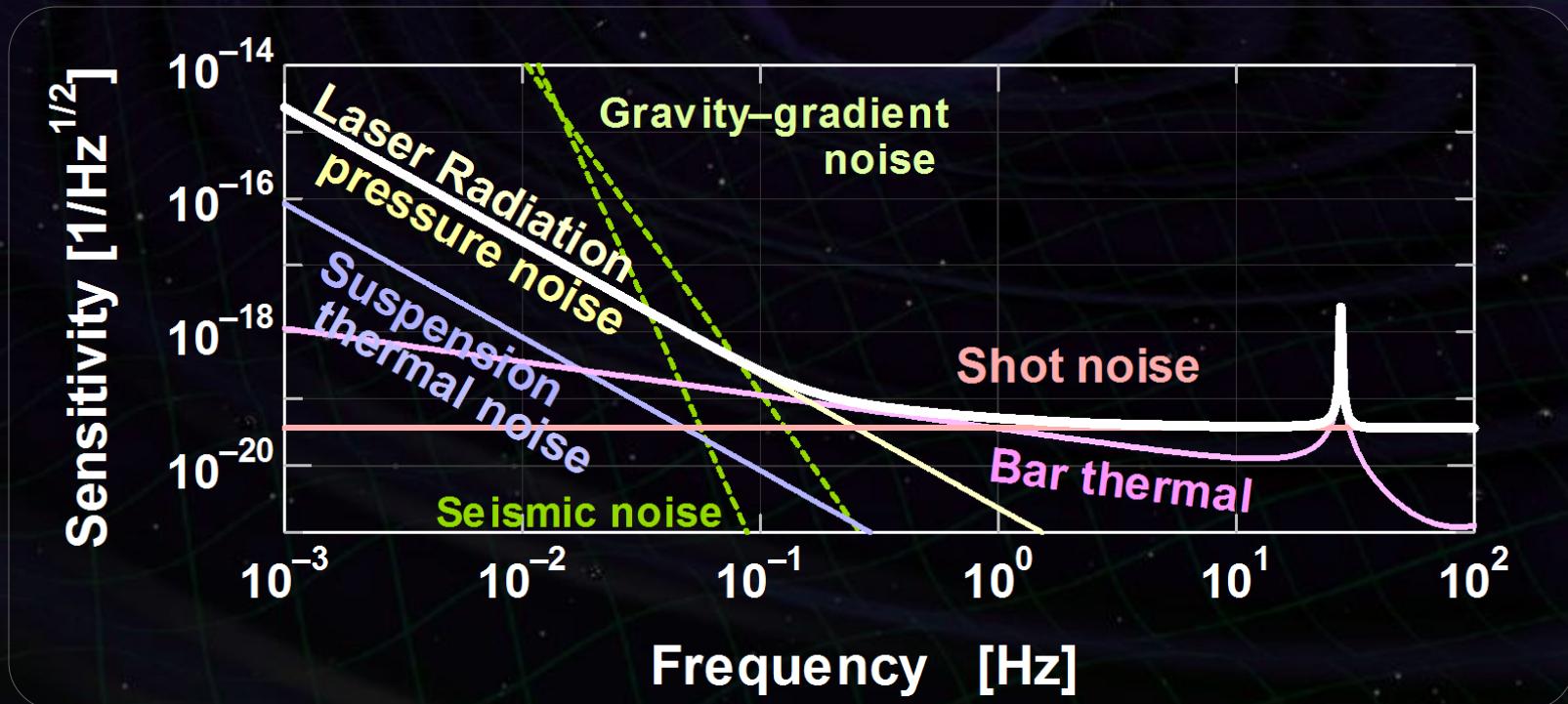


Torsion pendulum
(Res. freq ~1mHz)

Shorter length
→ Simple config.
Common-mode rejection

Fundamental noise level of TOBA

Practical parameters $\Rightarrow \tilde{h} \simeq 3 \times 10^{-19} \text{ [Hz}^{-1/2}\text{]} \text{ (at 0.1 Hz)}$



Bar length : 10m, Mass : 7600kg

Laser source : 1064nm, 10W

Cavity length : 1cm, Finesse : 100

Bar Q-value : 10⁵, Temp: 4K

Support Loss : 10⁻¹⁰

Laser Freq. noise < 10Hz/Hz^{1/2},

Freq. Noise CMRR>100

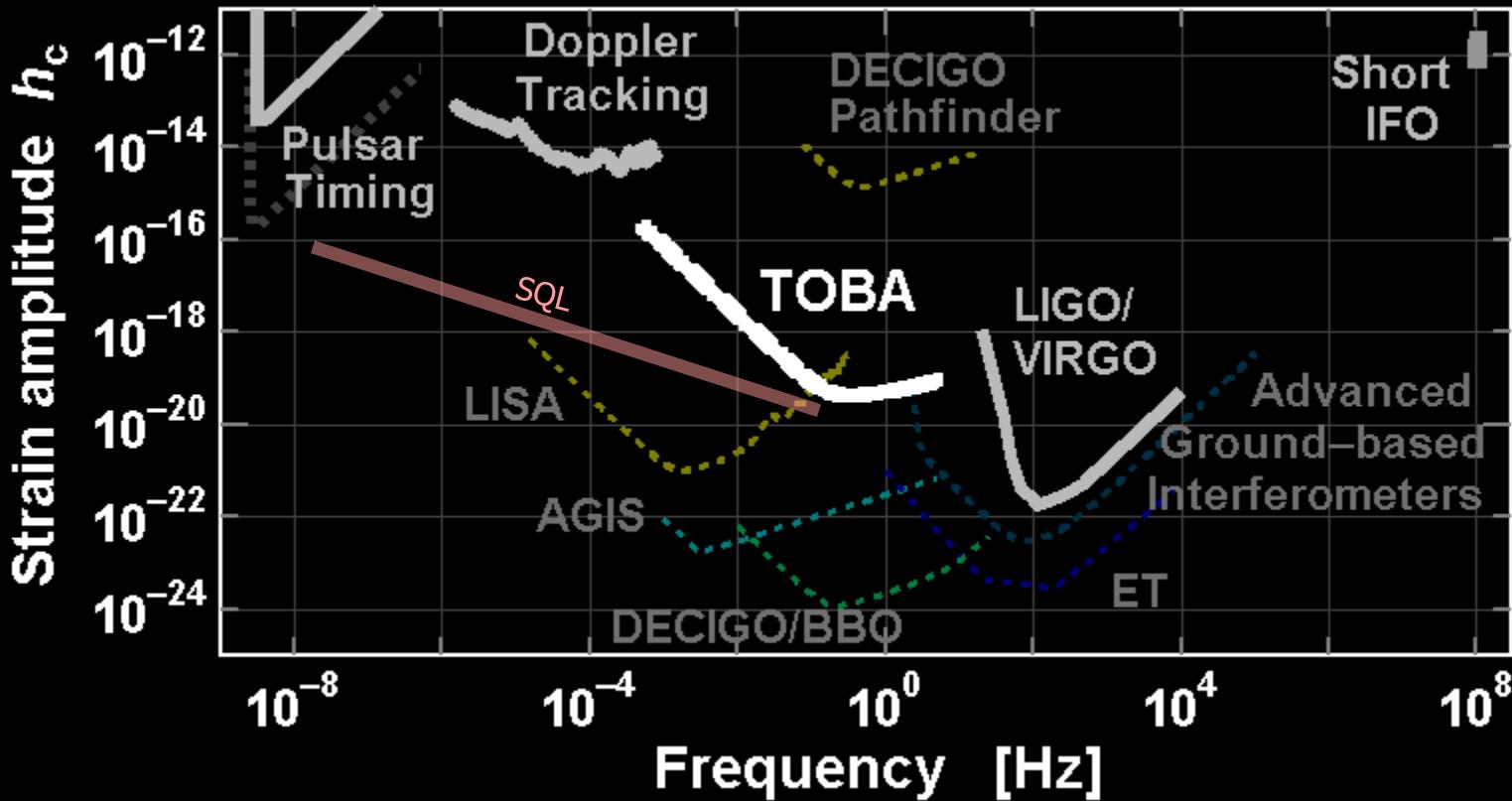
Intensity noise < 10⁻⁷/Hz^{1/2},

Bar residual RMS motion < 10⁻¹² m

TOBA Sensitivity

Comparison with the other detectors

DECIGO/BBO band: Between ground-based detectors and LISA bands

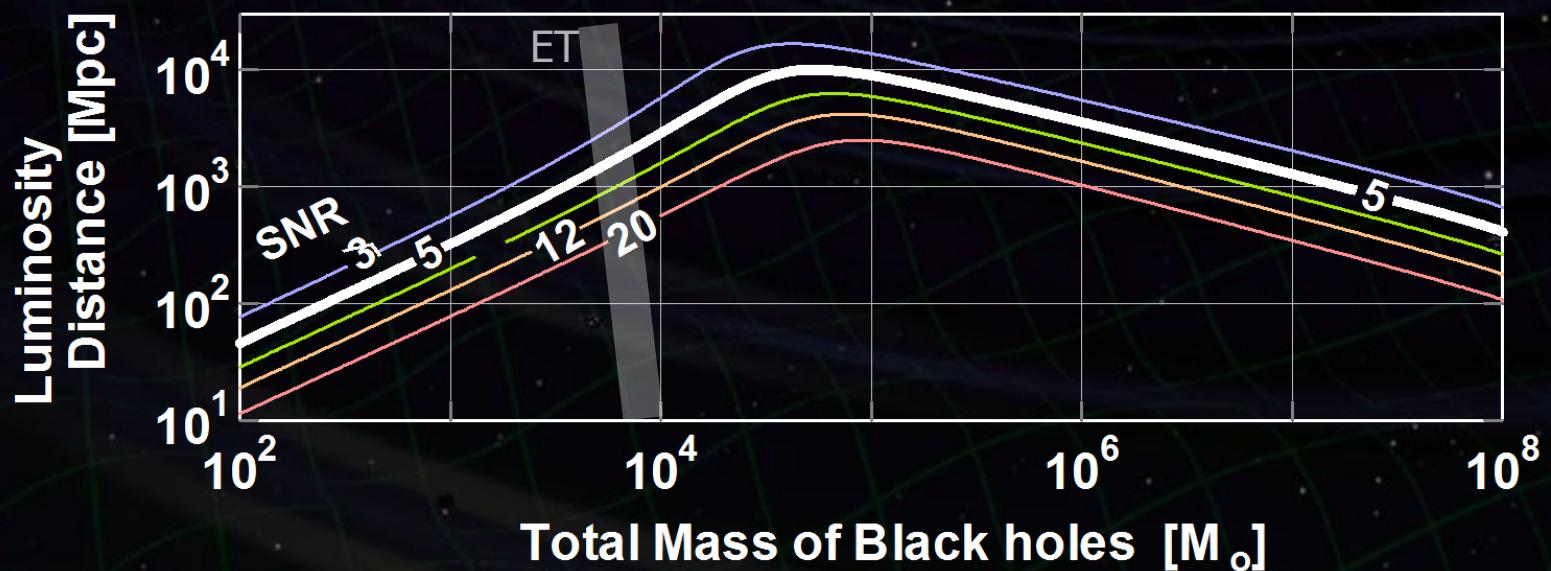


$$\text{Characteristic amplitude : } h_c = \tilde{h} \times \sqrt{f_{\text{center}}} \quad (\text{Dimensionless strain})$$

Observable range

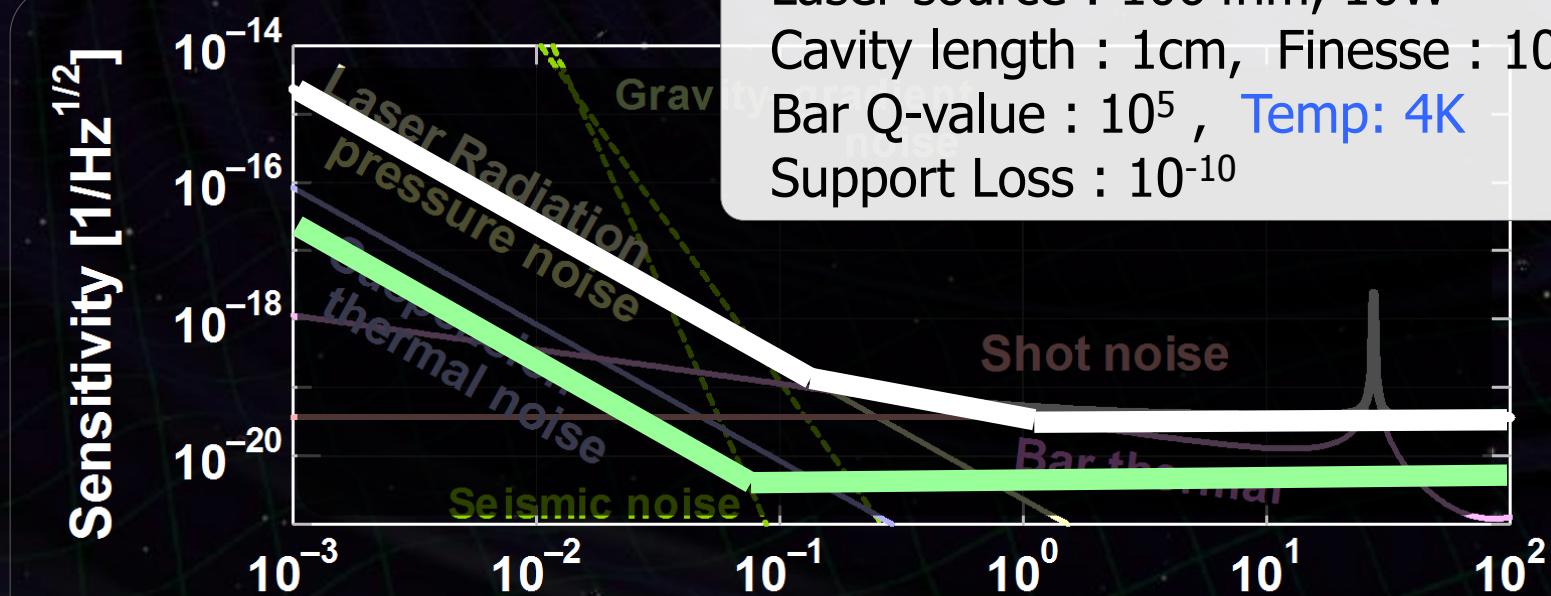
GWs from binary BH mergers

⇒ Obs. Range $\sim 10\text{Gpc}$ ($\sim 10^5 M_\odot$, SNR = 5)



Calculation by K.Yagi : BH merger hybrid waveform, spin 0.5/0.5

And more...



Si bar, Length : 25m, Mass : 90 ton

Laser source : 1550nm, 10W

Squeezing 10dB, Finesse : 100

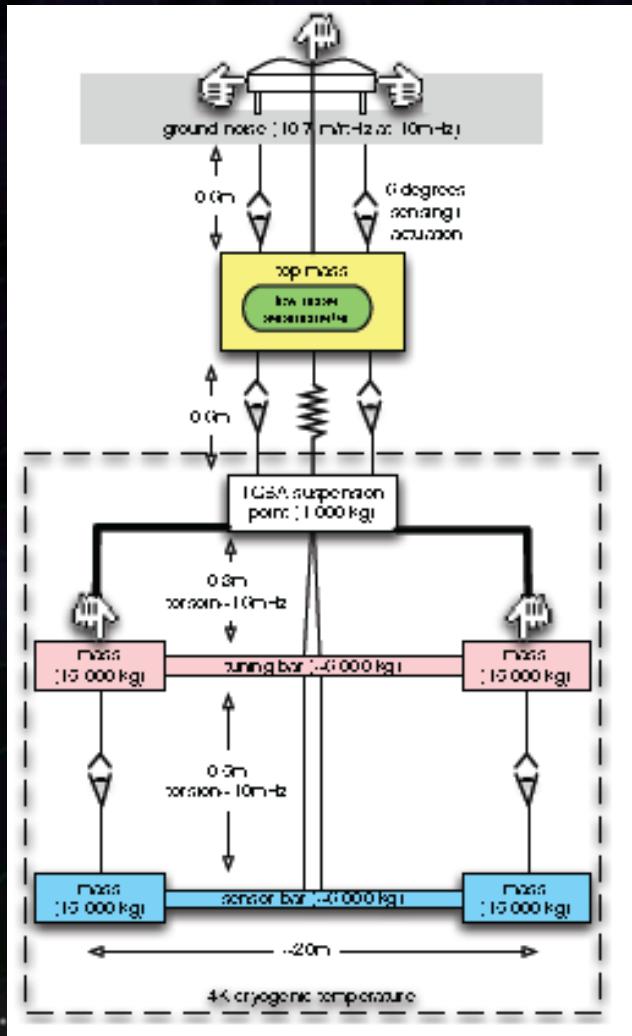
Bar Q-value : 10⁹, Temp: 4K

Support Loss : 10⁻⁹

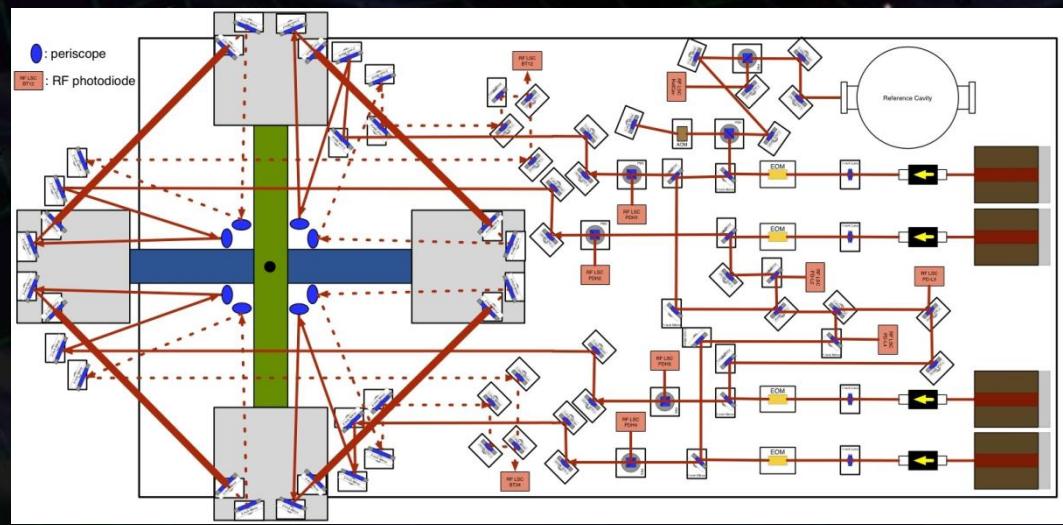
>10 times better!

Schematic design

- Example of extreme design (By Bram Slagmolen)



Si bar, Length : 10m, Mass : 11 ton
Laser source : 1550nm, 100mW
Squeezing 10dB, Finesse : 300
Bar Q-value : 10^9 , Temp: 4K
Support Loss : 10^{-9}



Rotating TOBA

Rotate the detector along its axis

- Up-conversion of low-freq. GWs

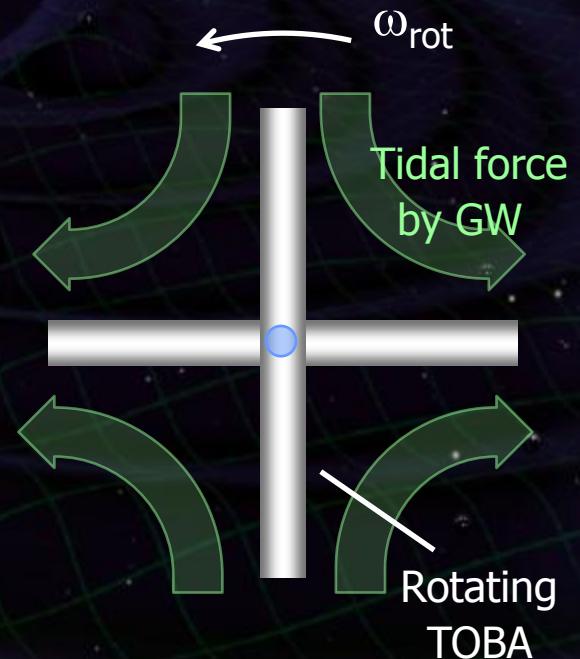
Low-freq. GW appears at $2 \omega_{\text{rot}}$

- Avoid low-freq. noises

Observer rotates with the detector

Noises at ω_{rot} : not important

- Two independent polarization of GW.
- Allow intermittent observation.



Rotating TOBA

Equation of Motion of a test-mass bar

$$I \left(\ddot{\theta} + \frac{\omega_0}{Q} \dot{\theta} + \omega_0^2 \theta \right) = \frac{1}{4} q^{ij} \cdot \ddot{h}_{ij}(t) \quad \begin{cases} I : \text{Moment of Inertia} \\ q^{ij} : \text{Dynamic quadrupole moment} \end{cases}$$

Rotation $\Rightarrow \theta_{\text{diff}} \simeq \alpha \left(\frac{\omega_g}{2\omega_{\text{rot}}} \right)^2 [h_x \cos(2\omega_{\text{rot}}t) + h_+ \sin(2\omega_{\text{rot}}t)]$,

GW with very-low freq. (ω_g) appears
as high freq. ($2\omega_{\text{rot}}$) signal by up-conversion.

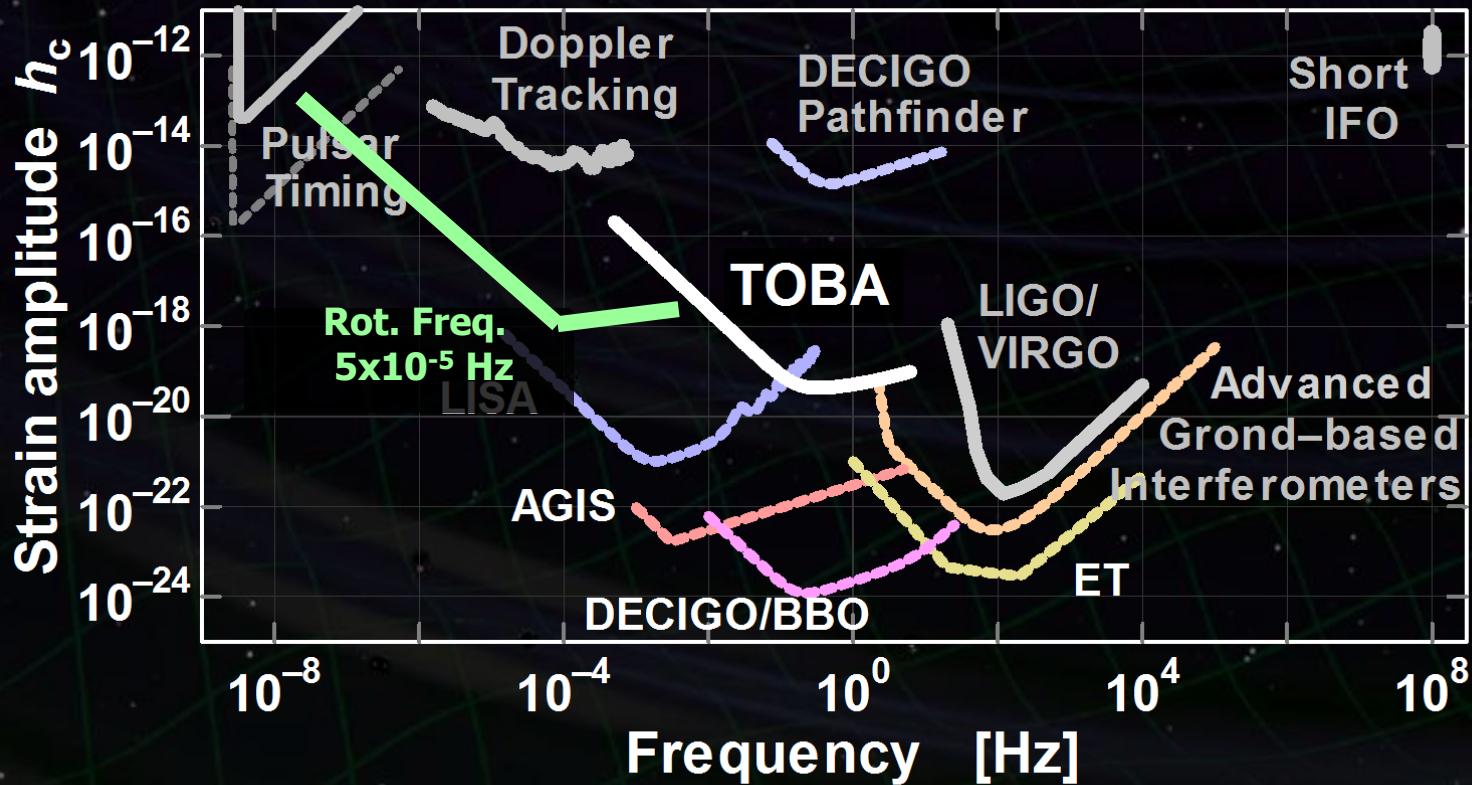
Sensitivity by R-TOBA

Sensitivity example

(Rotation freq. 5×10^{-5} Hz, Laser power 1mW)

⇒ Bridge the Pulsar-timing and LISA

Bar length : 10m, Mass : 7600kg
Laser source : 1064nm, 1mW
Cavity length : 1cm, Finesse : 1
Bar Q-value : 10^5 , Temp: 4K
Support Loss : 10^{-10}



Results from Prototypes

→ A.Shoda's file

Reference:

- K.Ishidohiro+, Phys. Rev. Lett. 106, 161101 (2011)
- A. Shoda, presentation at GWPAW2011

Rotating TOBA prototype

(SWIM on SDS-1 satellite)

Reference: W. Kokuyama, Ph.D thesis

Rotating TOBA : SWIM μ v

Small Module SWIM μ v on SDS-1

Launched Jan. 2009, Terminated Sept. 2010

Photo:
JAXA

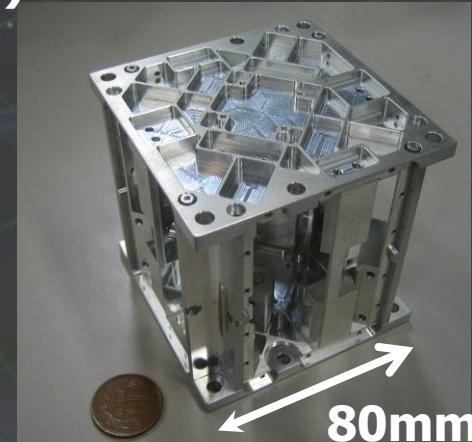
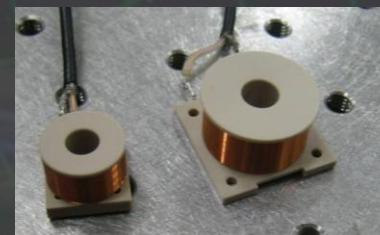
TAM: Torsion Antenna Module with free-falling test mass
(Size : 80mm cube, Weight : ~500g)

Test mass

~47g Aluminum, Surface polished
Small magnets for position control

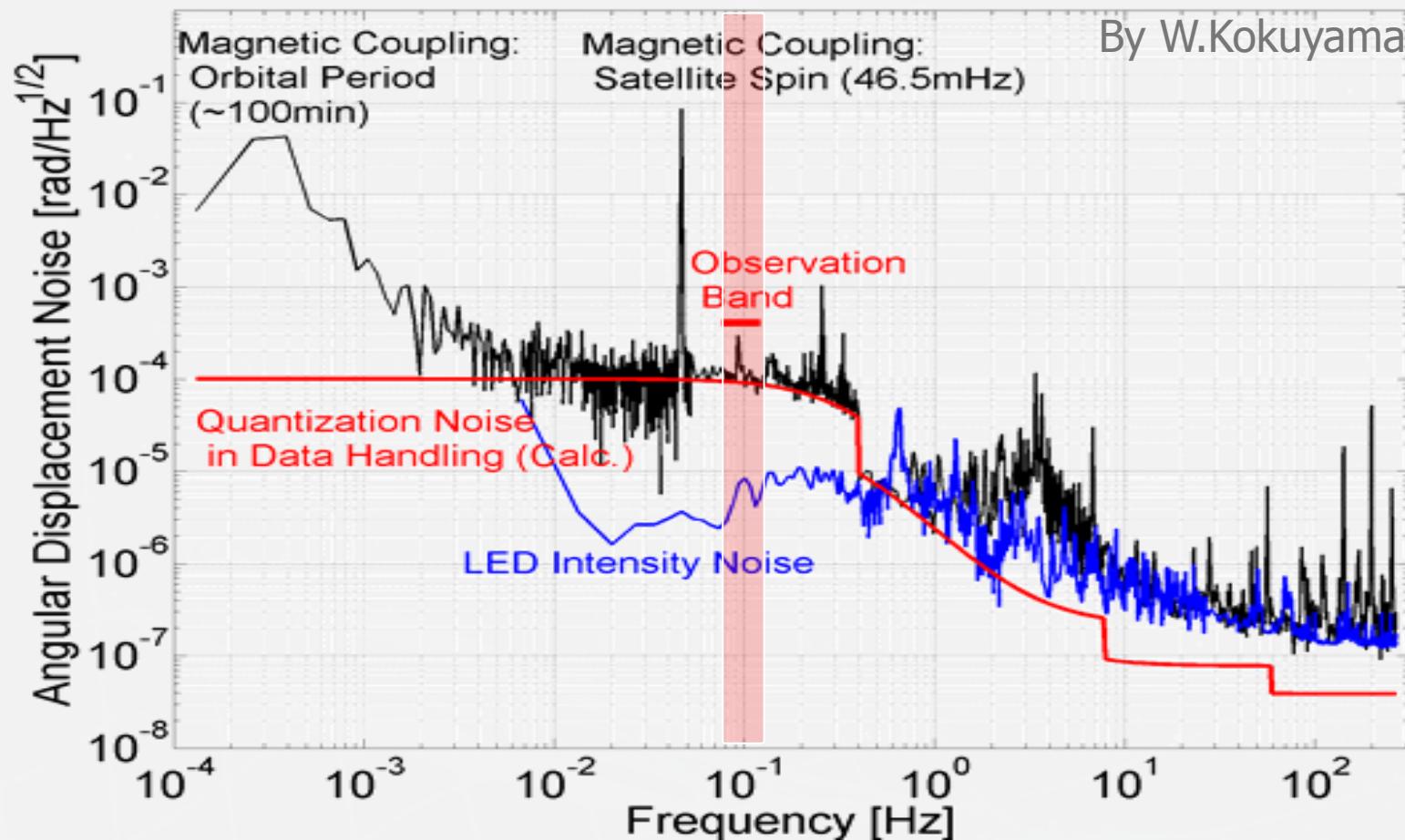


Photo sensor
Reflective-type optical
displacement sensor
Separation to mass ~1mm
Sensitivity ~ 10^{-9} m/Hz $^{1/2}$
6 PSs to monitor mass motion



Sensitivity

Though limited by non-fundamental noises,
best as a space-borne GW detector.

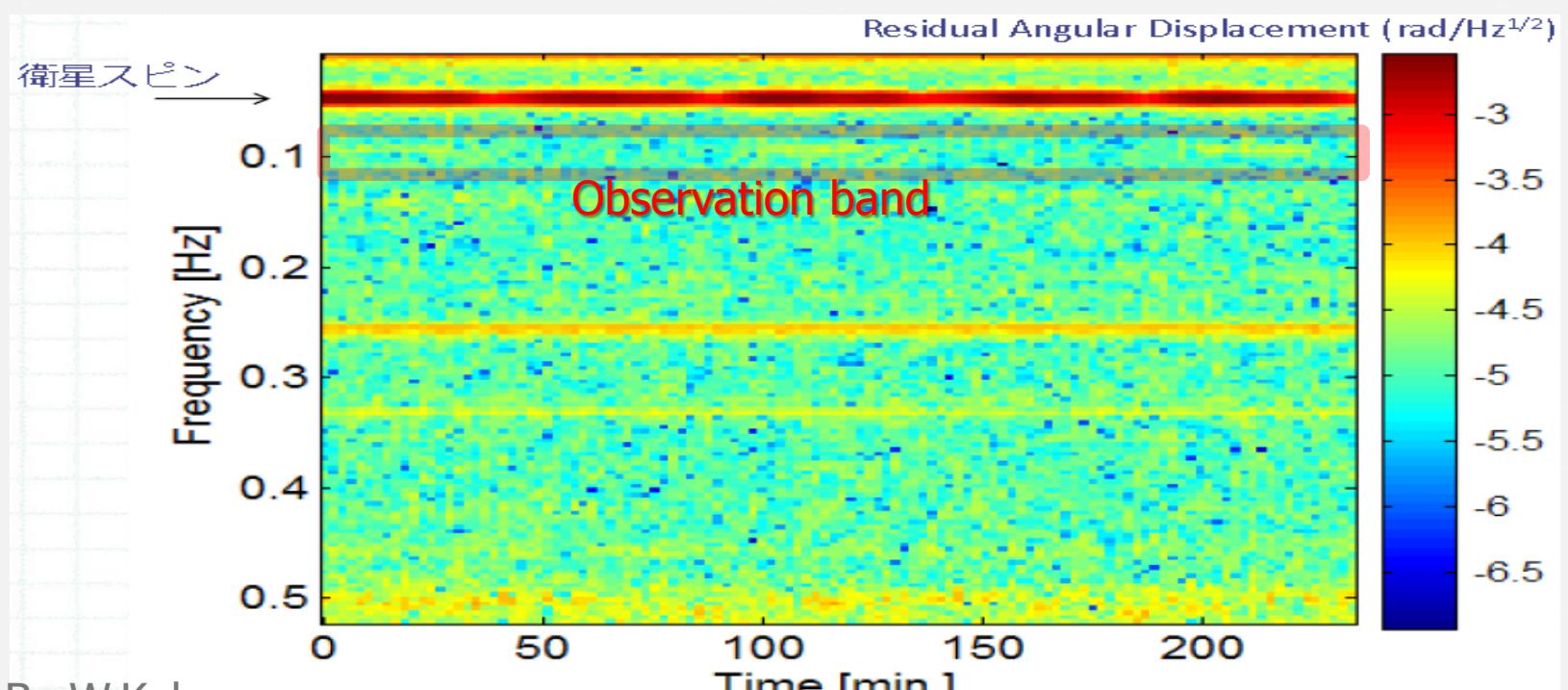


Observation by SWIM

Continuous data taking

Jun 17, 2010 ~120 min.

July 15, 2010 ~240 min.



By W.Kokuyama

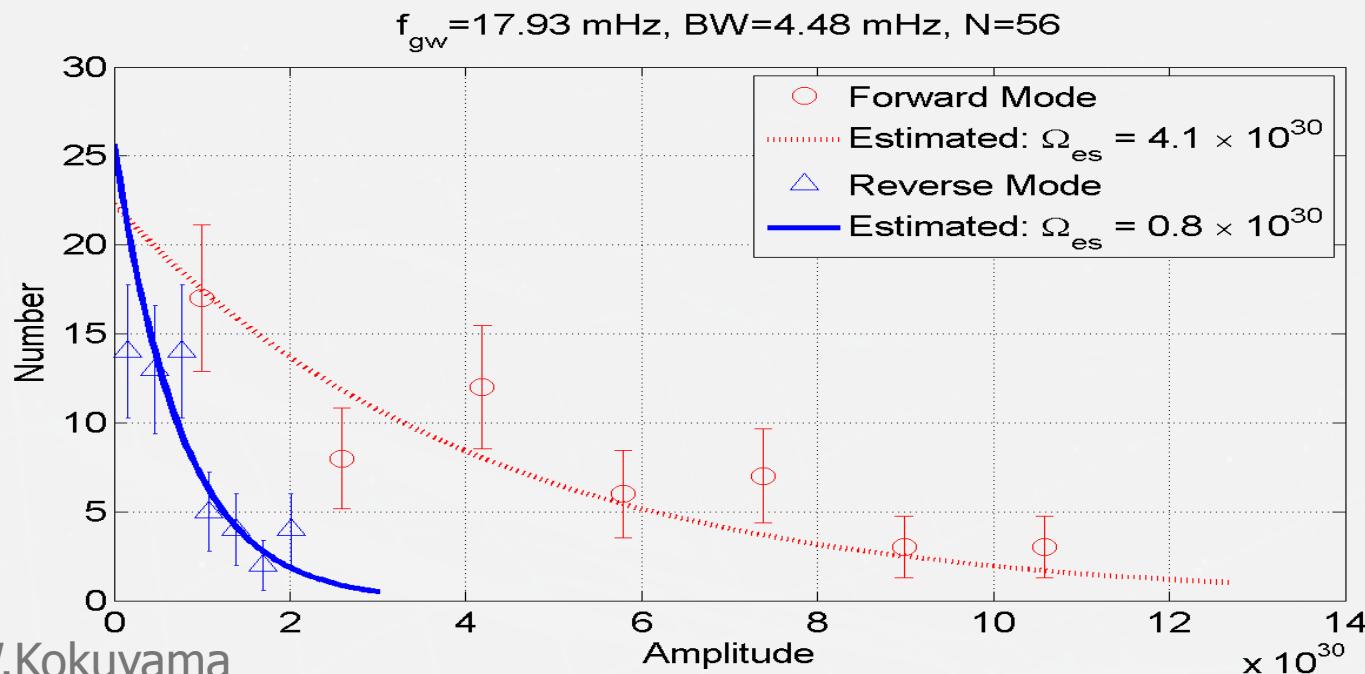
Upper Limit on GWB

Upper Limit at two frequencies (two polarizations)

'Forward' mode $\Omega_{\text{gw}}^{\text{FW}} = 1.7 \times 10^{31}$

'Reverse' mode $\Omega_{\text{gw}}^{\text{RE}} = 3.1 \times 10^{30}$

(C.L. 95%, f0 18mHz, BW 4mHz)

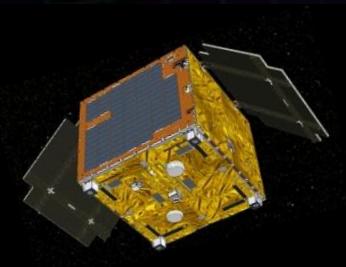
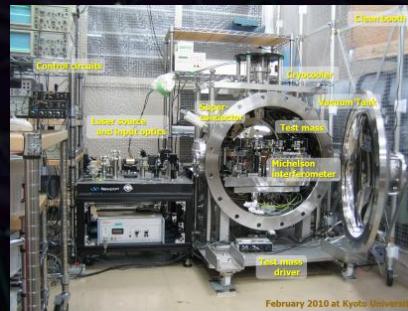
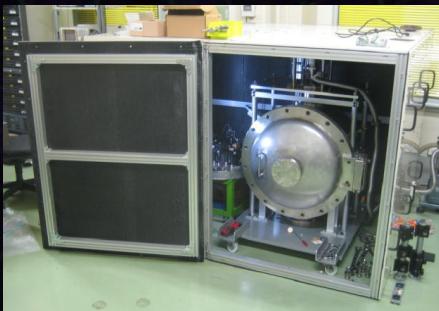


By W.Kokuyama

Next Prototype plan

TOBA next plan

- Results from two small-scale TOBAs at Tokyo and Kyoto, and rotating TOBA in space.



⇒ One more prototype step
before the 10-m scale TOBA.

Concepts

- Design concepts

- Should be intermediate step for the 10-m scale TOBA.
- Scientific outcomes.
- Common techniques with KAGRA, ET, ...
- Realistic both in technology and the budget.



Medium-scale TOBA for Newtonian noise observation.

- NN monitor sensor
- Take the most advantages of R&Ds
for the next generation detectors.

Gravity gradient noise

- Newtonian noise by ground motion.
 - Coherent plane wave with long wavelength

Velocity 5km/s, Frequency 0.1Hz
→ wavelength ~ 50km

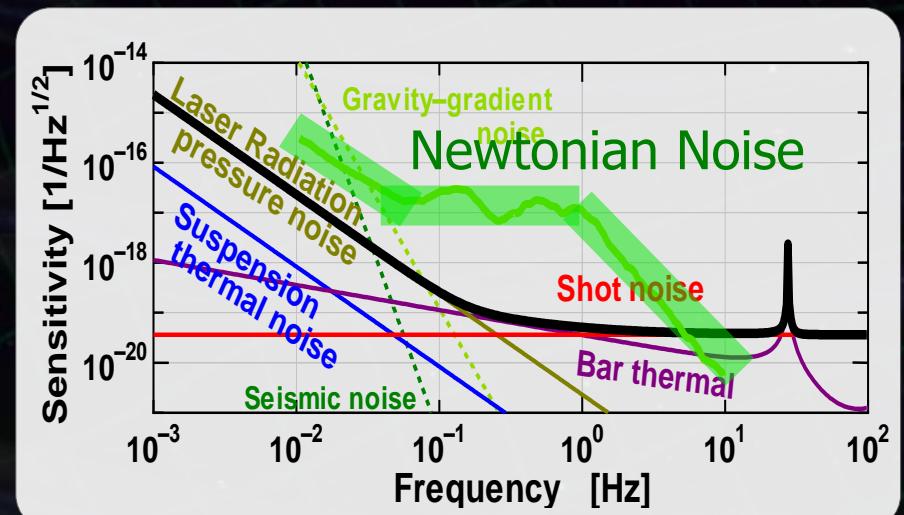
⇒ Same effect as km-scale interferometer



- NN estimation (by Jan Harms)

$$h_{\text{gw}} \sim 10^{-17} \text{ Hz}^{-1/2}$$

Assumption:
Infinite plane wave
Homestake mine seismic level



Atmospheric NN may be larger; should be considered.

Medium-scale TOBA candidates

- Sensitivity estimation (only with fundamental noises)
 - Silicon test mass, room-temp. or cryogenic
 - Laser 1550nm for two orthogonal bars.
 - Readout by interferometers.
 - Isolation system : KAGRA technology.

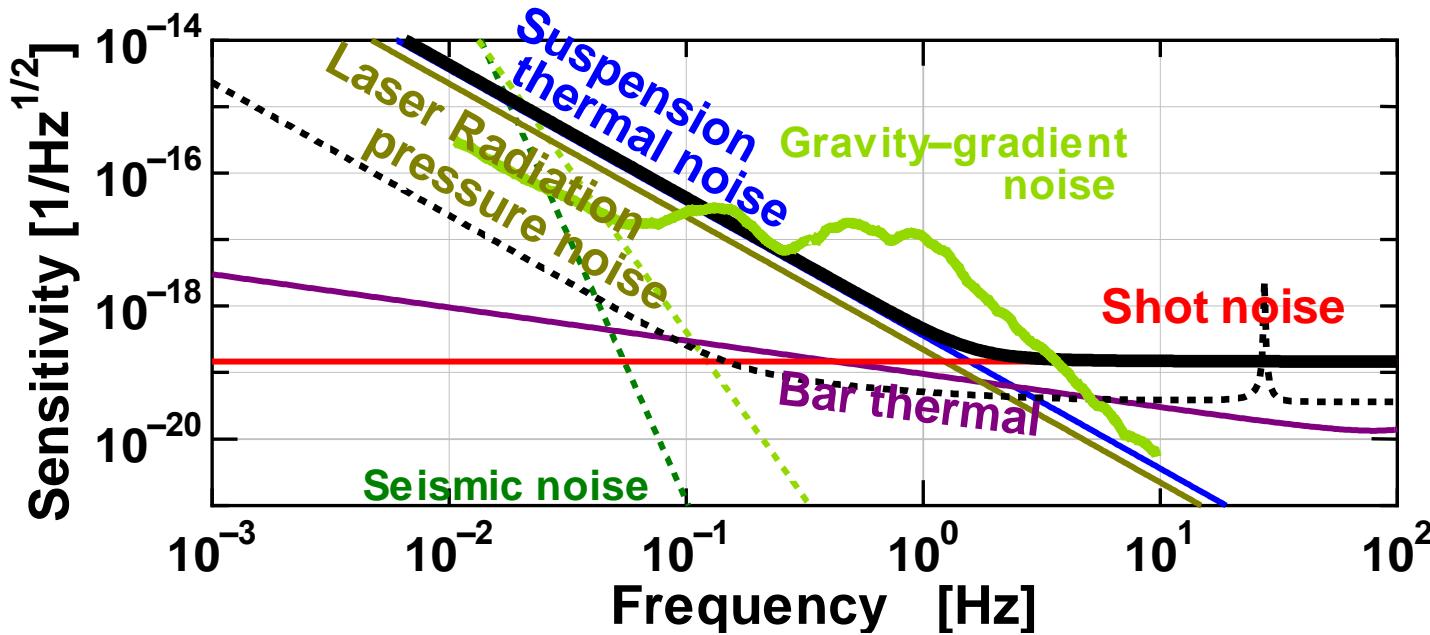
	Length	Diameter	Mass	MoI	Sensitivity	Max IR
Room temp. (300K)	10	0.3	1646	1.37×10^4	3×10^{-18}	800
	3	0.2	219	164	3×10^{-17}	150
	1	0.15	41	3.4	3×10^{-16}	20
Cryogenic (4K)	10	0.3	1646	1.37×10^4	4×10^{-19}	3500
	3	0.2	219	164	6×10^{-18}	350
	1	0.15	41	3.4	3×10^{-17}	50
	[m]	[m]	[kg]	[kg·m ²]	[1/Hz ^{1/2} @0.1Hz]	[Mpc]

※ Gravity-gradient noise : $\sim 10^{-17}$ [1/Hz^{1/2}] at 0.1Hz

Sensitivity estimation

Bar length : 3m, Mass : 219kg
Laser source : 1550nm, 10W
Cavity length : 1cm, Finesse : 100

Silicon bar, Q-value : 10^9 , Temp: 300K
Pendulum Q-value : 10^{10}
Pendulum resonance 0.1mHz



Medium-scale TOBA design

- Under discussion, but may be ... Cryo. with 1-m scale
 - Same direction as KAGRA, ET, ...
→ Effective use of resources and technologies.
(Cryo-system, Suspension, Isolators, Materials)

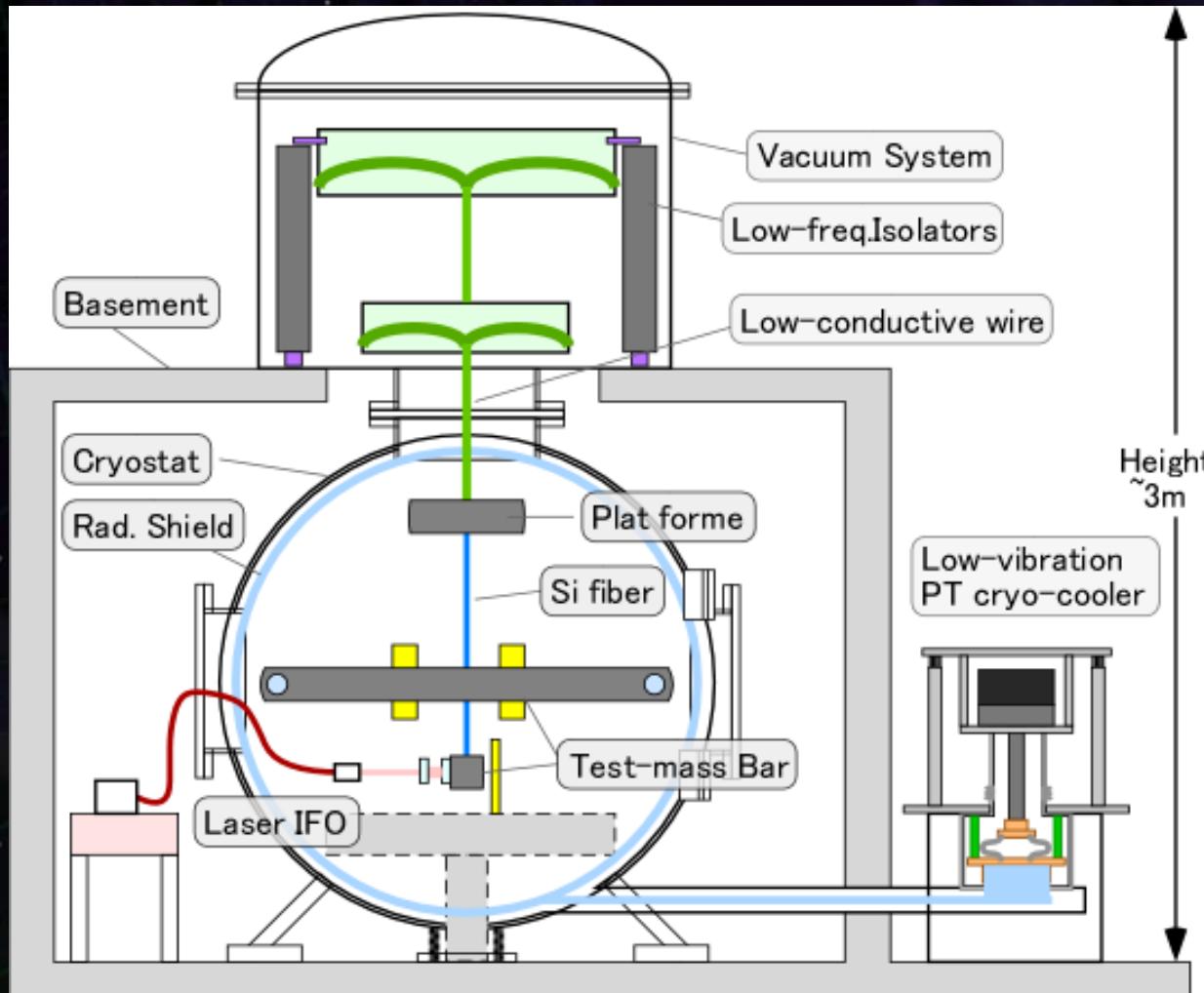
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	3	0.2	219	164	6×10^{-18}	350
	1	0.15	41	3.4	3×10^{-17}	50
	[m]	[m]	[kg]	[kg·m ²]	[1/Hz ^{1/2} @ 0.1Hz]	[Mpc]



※ Gravity-gradient noise : $\sim 10^{-17}$ [1/Hz^{1/2}] at 0.1Hz

Medium-scale TOBA design

- Under discussion, but probably ... Cryo. with 1-m scale



Summary

Summary (1/2)

- Novel type GW detector : TOBA
 - Low-freq. observation ($\sim 10^{-8} - 1$ Hz) .
 - Observable Range > 10 Gpc for BH inspirals.
 - Rotating TOBA for lower freq. (< 1 mHz) GWs.
- First prototypes
 - Small-scale TOBAs at Tokyo and Kyoto
 - First upper limits on GWB at 0.1-0.2Hz band.
 - SWIM as a space-borne rotating TOBA
 - Upper limit on GWB at 18mHz.

Summary (2/2)

- Next prototype plan
 - Medium-scale TOBA with length \sim 1m.
 - Low-freq. GW detector and also a NN sensor.
 - Common techniques with KAGRA, ET, ...
- Another plan by Australian group
 - Medium-scale TOBA at room temp.
 - Please ask Bram Slagmolen!

Any suggestions are welcome!



End

Backups

Detector response

Equation of Motion of a test-mass bar

$$I \left(\ddot{\theta} + \frac{\omega_0}{Q} \dot{\theta} + \omega_0^2 \theta \right) = \frac{1}{4} q^{ij} \cdot \ddot{h}_{ij}(t)$$

I : Moment of Inertia
 q^{ij} : Dynamic quadrupole moment



$$\tilde{\theta}(\omega) = \frac{1}{2} \alpha \tilde{h}_x(\omega) \quad (\omega \gg \omega_0)$$

α : shape factor, between 0 to 1

Dumbbell or thin bar $\rightarrow \alpha = 1$

Dimension less,
Independent of matter density



Bar shape

- Design of bar shape

- Detector response to GW $\tilde{\theta}(\omega) = \frac{1}{2}\alpha\tilde{h}_X(\omega)$

Shape factor $\alpha = \frac{\int (x^2 - y^2) dV}{\int (x^2 + y^2) dV} \Rightarrow$ Thin bar or dumb-bell along x-axis $\rightarrow \alpha=1$

- Standard quantum limit $h_{SQL} \propto 1/\sqrt{I} \propto 1/L$

Moment of Inertia $I = \int \rho(x^2 + y^2) dV \Rightarrow$

Cylindrical bar $I = M \cdot L^2/12$

Dumb-bell $I = M \cdot L^2/4$

- Bar thermal noise

When mass is kept, $h_{bar} \propto L^2 \Rightarrow$ Shorter is better.

- Suspension thermal noise

When mass is kept, $h_{bar} \propto 1/I \propto 1/L^2 \Rightarrow$ Longer is better.

Bar material

- Selection of bar material
 - Bar thermal noise
 - Electro-magnetic properties
 - Availability (production, cost)

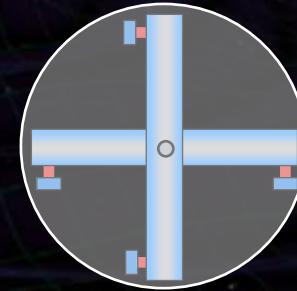
⇒ Silicon is promising.

	Q-factor	Young's modulus	Density	Availability	Thermal noise
Aluminum	$<10^7$	72 GPa	2700 kg/m ³	○	$8 \times 10^{-20} \text{ Hz}^{-1/2}$
Sapphire	10^8	335 GPa	3970 kg/m ³	△	$1 \times 10^{-20} \text{ Hz}^{-1/2}$
Silicon	10^9	185GPa	2329 kg/m ³	○	$5 \times 10^{-21} \text{ Hz}^{-1/2}$ (L=10m, $\phi=0.3\text{m}$)

Interferometer configuration

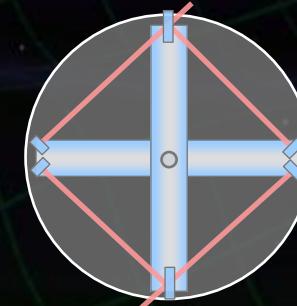
- Readout from reference plate

- Readout by short FP cavities at the bar edge.
- Reference mirrors fixed to isolated base plate.
- Independent measurement
→ Linear combination for GW signals.
- Require a seismic-isolated reference plate.



- MI fixed at bar edges

- Form Michelson interferometer at the bar edge.
- Direct angular measurement
- Do not need reference mirrors.
- Coupling from bar displacements.
→ Room for improvements

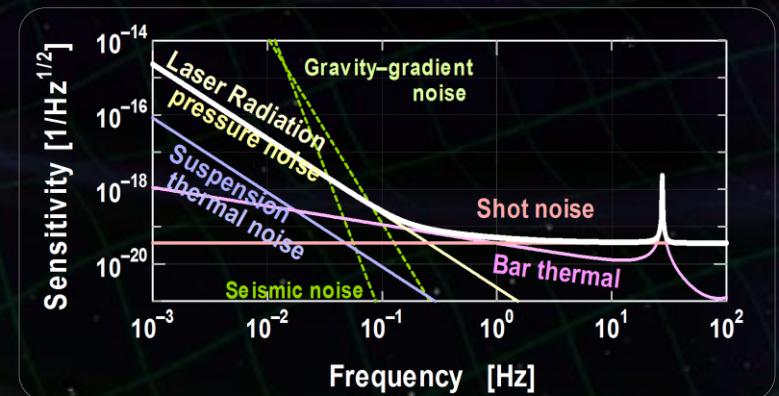
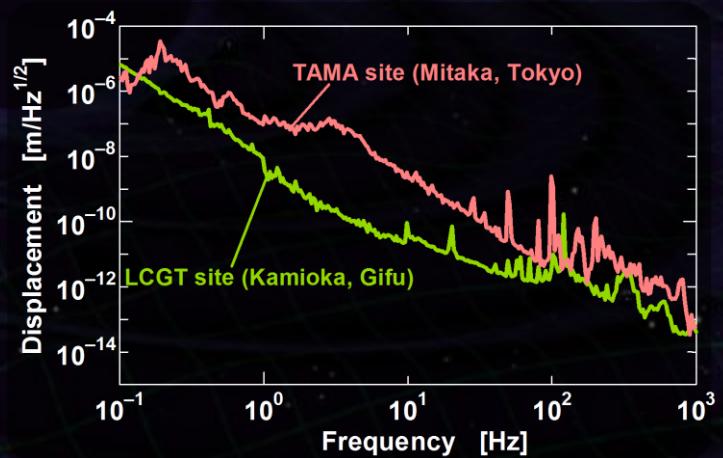


Seismic noise

- Rotational ground motion
- Coupling from displacement DoF

Coupling 10^{-3} or CMRR 10^{-3}
→ $<10^{-9}$ isolation is required
at 0.1Hz freq. band.

Horizontal : IP (10mHz) x 5 stages
Vertical : GASF ???



Bar thermal noise

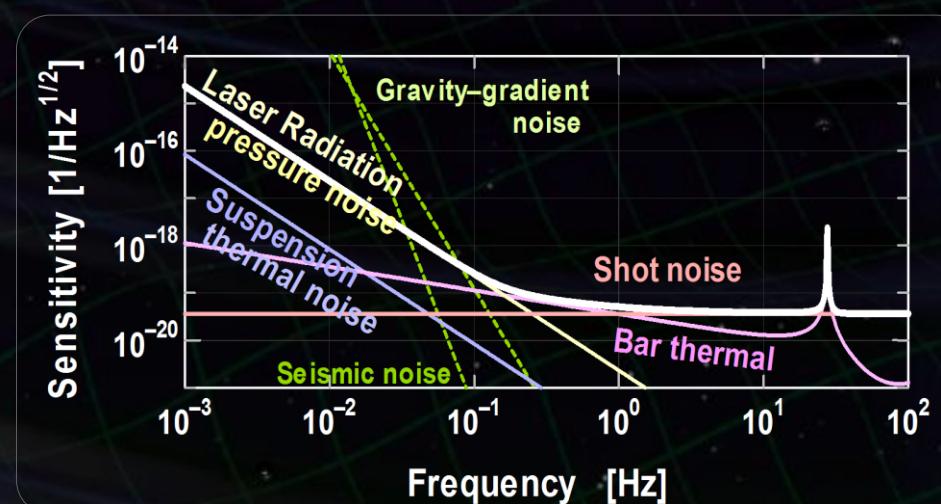
- Thermal noise of bar mode

Differential readout at the edges
→ Contribution of odd modes

Aluminum bar (7.6 ton)
length 10 m, ϕ 0.3 m
Temp. 4K, Q 10^7

⇒ $8 \times 10^{-20} \text{ } 1/\text{Hz}^{1/2}$ at 0.1Hz

By keeping the total mass,
- High Q and low T is better
- Shorter is better
- High Young's modulus is better



Suspension thermal noise

- Thermal noise of suspension system

- Torque by dissipation (one bar)

$$T_{\text{ther}} = \sqrt{4\gamma k_B T} = \sqrt{4(I\omega_0/Q)k_B T}$$

$$\Rightarrow h_{\text{ther}} = \frac{4}{\alpha\omega^2} \cdot \sqrt{\frac{k_B T \omega_0}{IQ}}$$

Detector response

$$I\ddot{\theta} + \gamma\dot{\theta} + \kappa\theta = \frac{1}{4}q^{ij} \cdot \ddot{h}_{ij}(t)$$
$$(\omega_0 = \sqrt{\kappa/I}, \quad Q = I\omega_0/\gamma)$$

- Mechanical loss in suspension fiber

Steel wire

Tungsten wire

Silica fiber

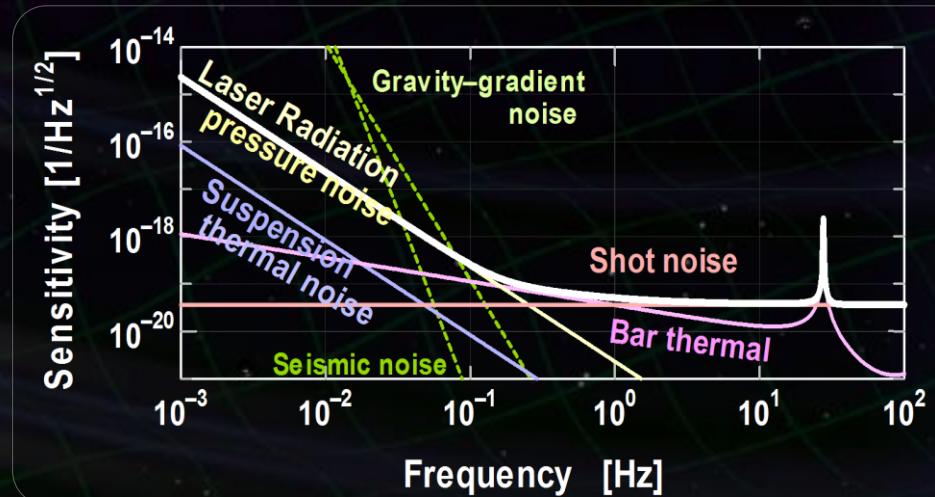
Cryogenic sus.

Superconductor sus.

- Momentum of inertia

$$h_{\text{bar}} \propto 1/I \propto 1/(M \cdot L^2)$$

Cryogenic suspension, Temp. 4K, $\gamma 10^{-10}$



Gravity gradient noise

- Newtonian noise by point-like source.

- Assume a dumb-bell mass and a point-like source mass

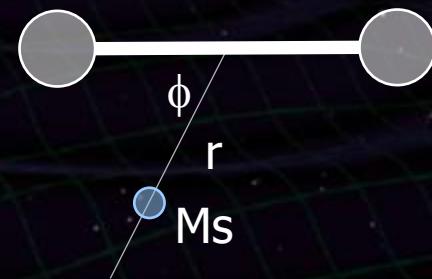
$$\Rightarrow \text{DC torque} \quad T_{\text{tidal}} \simeq \frac{2GM_s I}{r^3} \sin(2\phi)$$

$$\text{Equivalent noise} \quad \delta h_{\text{tidal}} \simeq \frac{12GaM_s}{r^4\omega^2}$$

(Radial motion, Max. direction, a: amplitude, a, L << r)

(Ex.) Human activity

$$M_s = 100 \text{ kg}, r = 10 \text{ m}, \\ \phi = \pi/2, f = 0.1 \text{ Hz}, a = 0.1 \text{ m} \Rightarrow \delta h \sim 2 \times 10^{-12}$$



Open questions...

- Readout scheme

- Better setup to reduce couplings from the other DoF?
- Non-optical readout, such as SQUID?

- Gravity gradient noise

- What happens at an underground site?
- Propagation of seismic waves?
(Cancelation, Scattering, Diffraction)



- Seismic noise

- Design of isolation system.
- Active controls.

- Other fancy ideas....

- Detector configuration.
- QND measurement.

TOBA prototype example (2)

- Space TOBA

- Silicon test mass, tune at 1mHz.
- Differential measurement using two orthogonal bars.

	Length	diameter	mass	MoI	Sensitivity	Max IR
Room temp. (300K)	10	0.3	1646	1.37×10^4	2×10^{-17}	70
	3	0.2	219	164	2×10^{-16}	7
	1	0.15	41	3.4	1×10^{-15}	1
	[m]	[m]	[kg]	[kg·m ²]	[1/Hz ^{1/2} @ 1mHz]	[Gpc]

※ Acceleration noise is not included.

Discussions

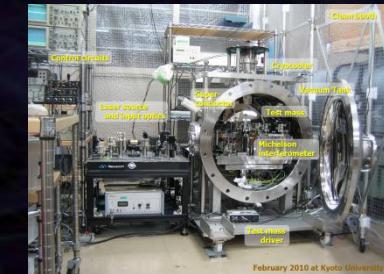
New motivations for GW research field...

- Optical readout noise
- Low freq. seismic isolation and reduction of Newtonian noise.
- Material, bar shape, and thermal noise
- Cryogenic system
- New possibility as a space mission
- GW sources at different freq. band
 - Between pulsar timing and LISA
 - Between LISA and ground-based detectors
- Data analysis schemes
 - Rotating TOBA configuration
 - Distributed multiple detectors

TOBA prototype plan

- We have two small-scale TOBAs at Tokyo and Kyoto.

- Aluminum test mass, length \sim 20cm, mass \sim 300g.
- Room temperature, poor seismic isolation.
- Magnetic levitation using superconductor bulk.



- Next plan concepts

(A) Medium-scale TOBA at room temperature.

- Silicon test mass, length \sim 1m, mass \sim 100kg.
- Differential measurement using two orthogonal bars.
- Better isolation system.

(B) Medium/small-scale TOBA at cryogenic temperature.

- Similar configuration to (A), but with a cryogenic system.
- Resonant detector configuration???

(C) Medium-scale TOBA development for a space mission.

- Low-freq. observation by a rotation configuration.
- Several options:
Resonant?, Cryogenic?, Orbit?

TOBA prototype example (1)

- Medium-scale TOBA

- Realistic configuration with current technology.
- Also works as a gravity-gradient noise monitor,
or a test bench for quantum noise investigation.

※ Gravity-gradient noise : $\sim 10^{-17}$ [1/Hz $^{1/2}$] at 0.1Hz

- ⇒ - Silicon test mass,
- Differential measurement using two orthogonal bars.
- Isolation system : LCGT type-B SUS, placed at an under ground site.

	Length	diameter	mass	MoI	Sensitivity	Max IR
Room temp. (300K)	10	0.3	1646	1.37×10^4	3×10^{-18}	800
	3	0.2	219	164	3×10^{-17}	150
	1	0.15	41	3.4	3×10^{-16}	20
Cryogenic (4K)	10	0.3	1646	1.37×10^4	4×10^{-19}	3500
	3	0.2	219	164	6×10^{-18}	350
	1	0.15	41	3.4	3×10^{-17}	50
	[m]	[m]	[kg]	[kg·m 2]	[1/Hz $^{1/2}$ @0.1Hz]	[Mpc]

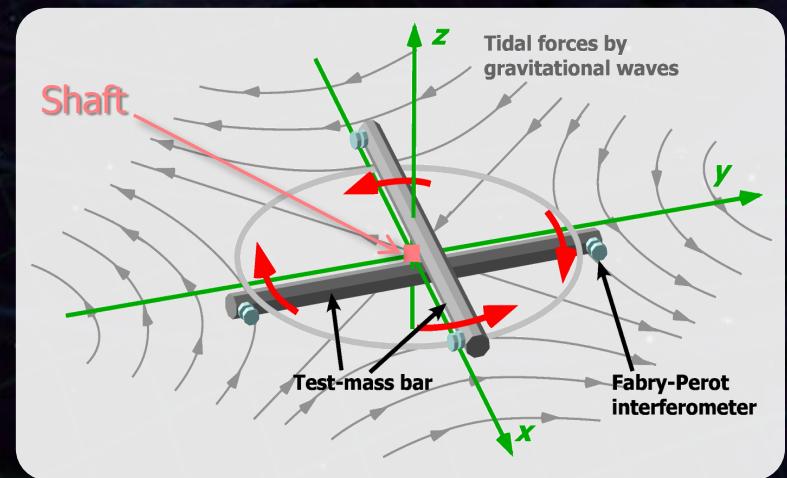
Resonant detector

- Connect two bars by a shaft
→ resonant torsion detector
 - GW signal is enhanced at resonant frequency by Q .
 - Requirements for readout and bar-thermal noise are relaxed.
 - Detector noise is mainly limited by thermal noise of the shaft.

- Thermal noise level

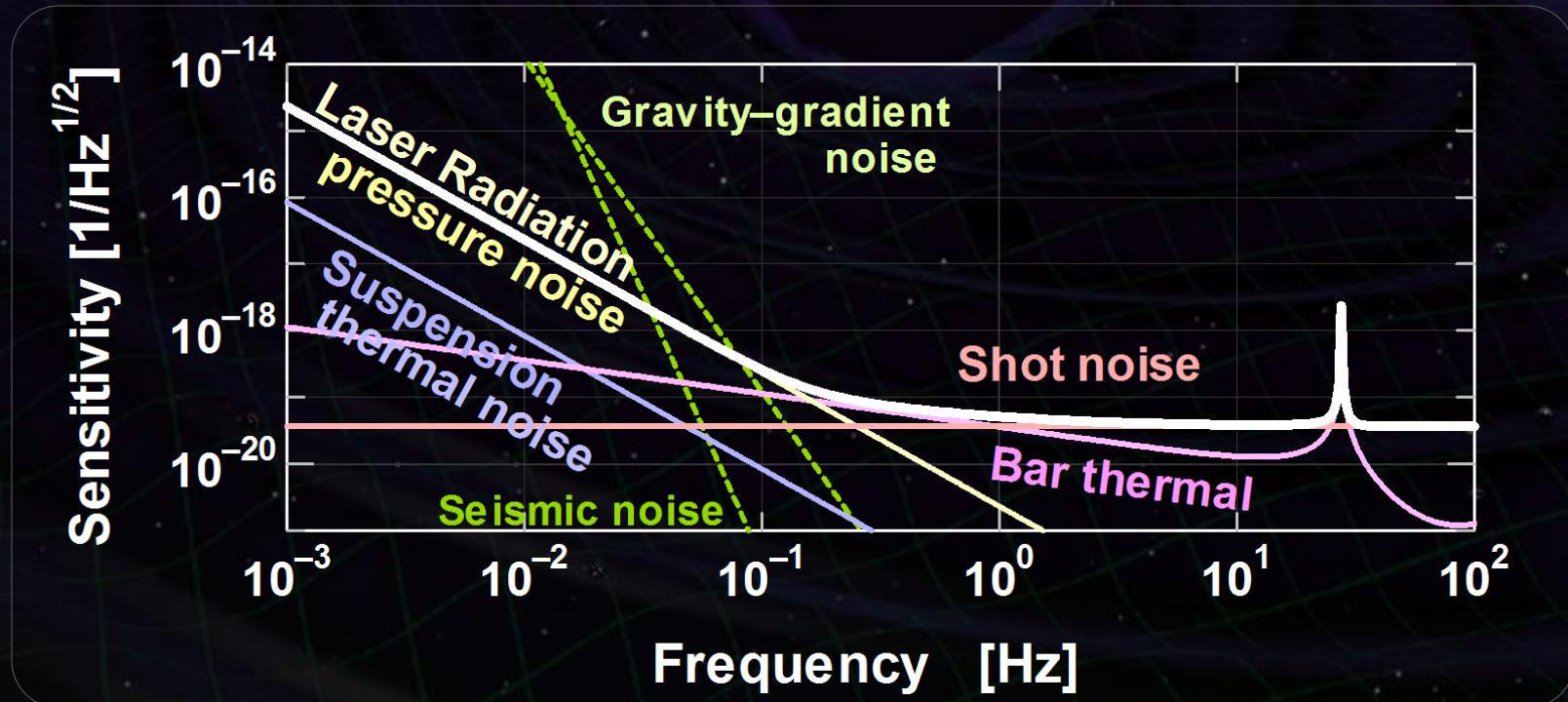
$$\text{At resonant freq. } h_{\text{ther}} = \frac{4}{\alpha} \cdot \sqrt{\frac{k_B T}{I \omega_0^3 Q}}$$

$$f_0 = 0.1 \text{Hz}, Q = 10^9, T = 4 \text{K}, \quad \Rightarrow \quad 7.5 \times 10^{-18} [1/\text{Hz}^{1/2}] \\ M = 7600 \text{kg}, L = 10 \text{m}$$



Fundamental noise level of TOBA

Practical parameters $\Rightarrow \tilde{h} \simeq 3 \times 10^{-19}$ [Hz $^{-1/2}$] (at 0.1 Hz)



Bar length : 10m, Mass : 7600kg

Laser source : 1064nm, 10W

Cavity length : 1cm, Finesse : 100

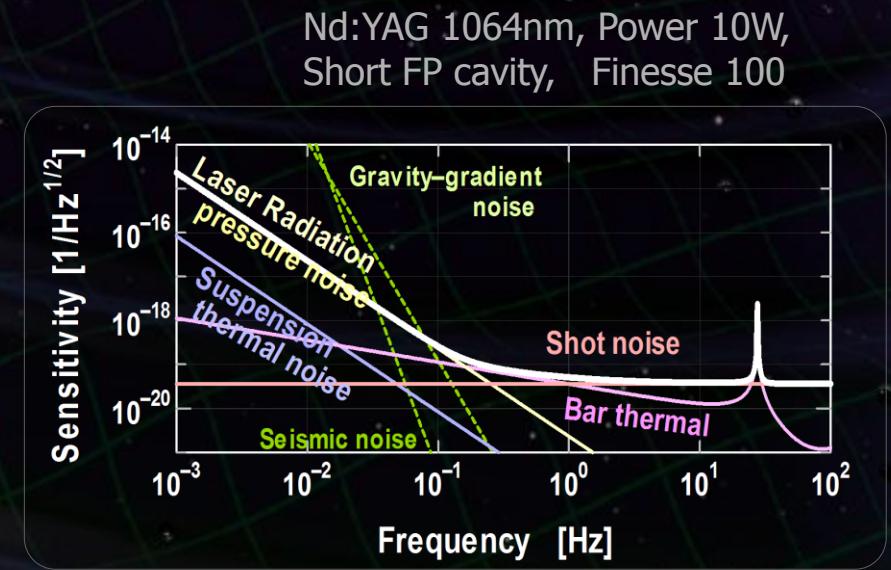
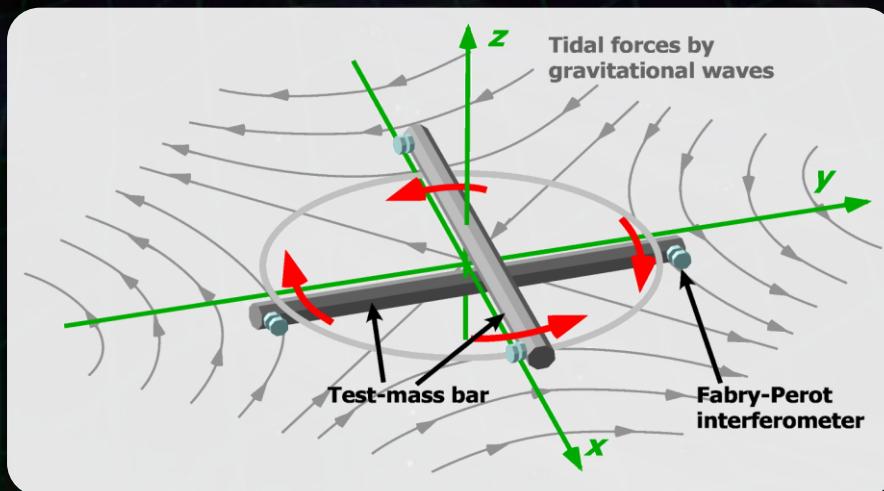
Bar Q-value : 10^5 , Temp: 4K

Support Loss : 10^{-10}

Laser Freq. noise < 10Hz/Hz $^{1/2}$,
Freq. Noise CMRR>100
Intensity noise < 10^{-7} /Hz $^{1/2}$,
Bar residual RMS motion < 10^{-12} m

Optical readout noise

- Optical readout noise
 - Readout by short FP cavities at the bar edge.
 - Reference mirrors fixed to isolated base plate.
- ⇒ Shot noise + Rad. Pressure noise

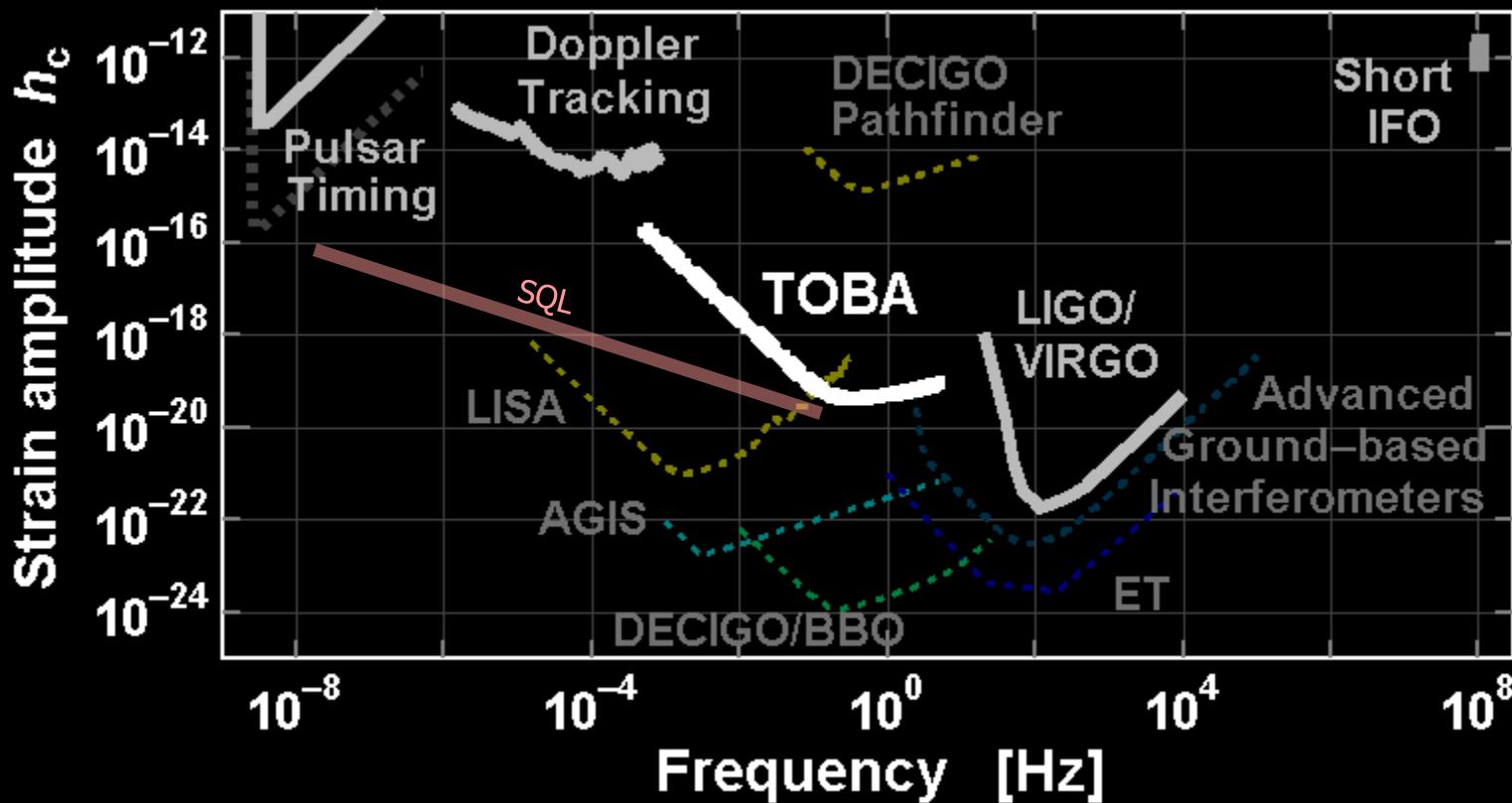


TOBA Sensitivity

Comparison with the other detectors

DECIGO/BBO band:

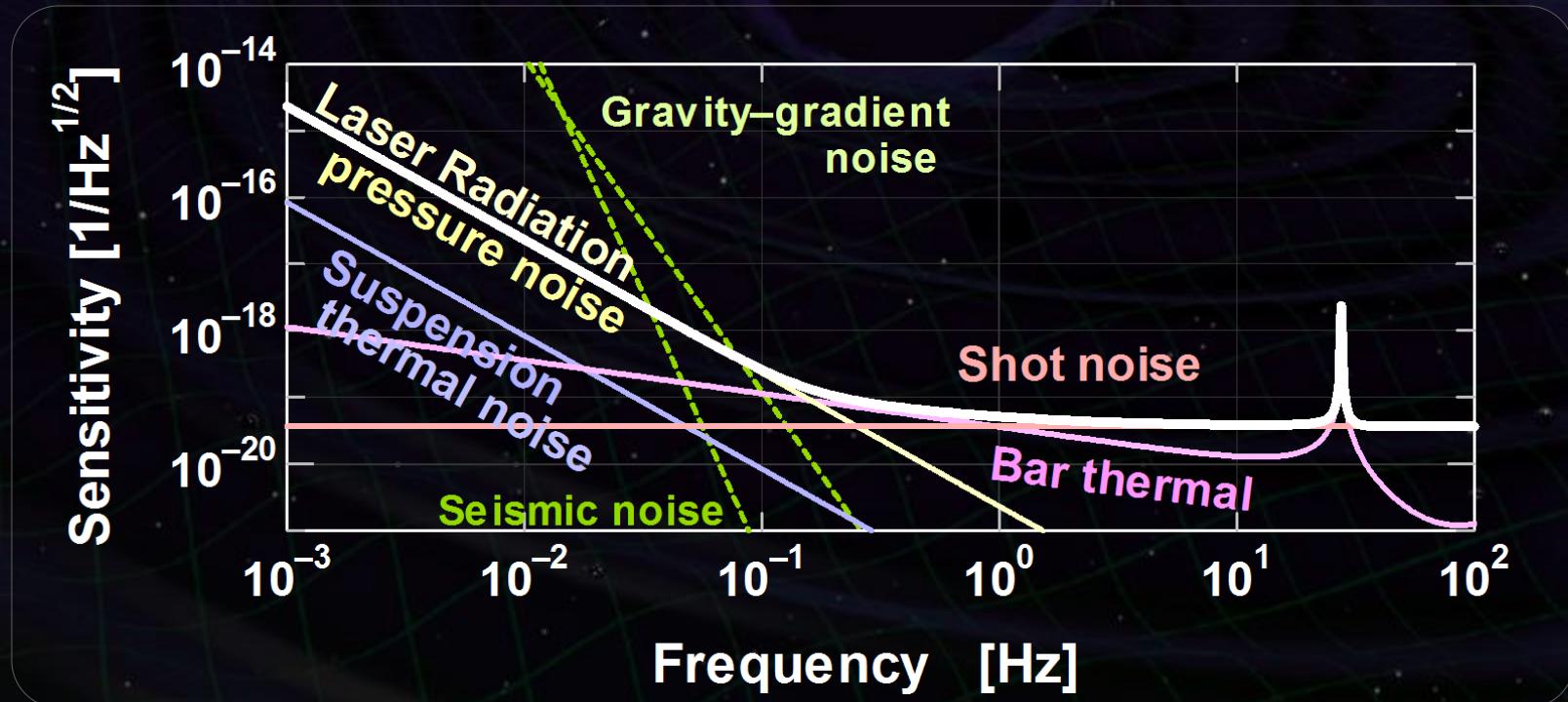
Between ground-based detectors and LISA bands



Characteristic amplitude : $h_c = \tilde{h} \times \sqrt{f_{\text{center}}}$ (Dimensionless strain)

Fundamental noise level of TOBA

Practical parameters $\Rightarrow \tilde{h} \simeq 3 \times 10^{-19}$ [Hz $^{-1/2}$] (at 0.1 Hz)



Bar length : 10m, Mass : 7600kg

Laser source : 1064nm, 10W

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Bar Q-value : 10^5 , Temp: 4K

Support Loss : 10^{-10}

Laser Freq. noise < 10Hz/Hz $^{1/2}$,
Freq. Noise CMRR>100
Intensity noise < 10^{-7} /Hz $^{1/2}$,
Bar residual RMS motion < 10^{-12} m

Chirp waveform

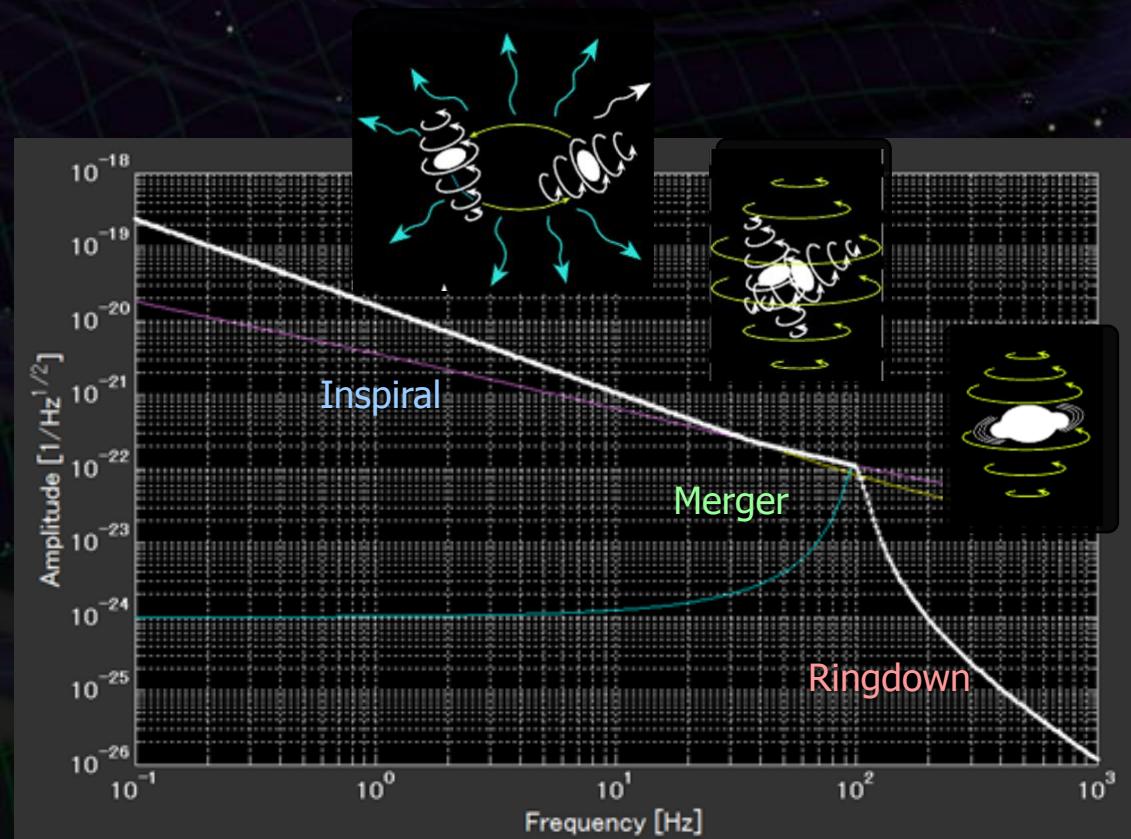
- Phenomenological waveform by numerical simulation

(Ajith+ arXiv 0909.2867)

- For BH inspiral (no tidal deformation).
- Include chirp, merger, and ring-down.
- Include spin effect.

GW from BH merger

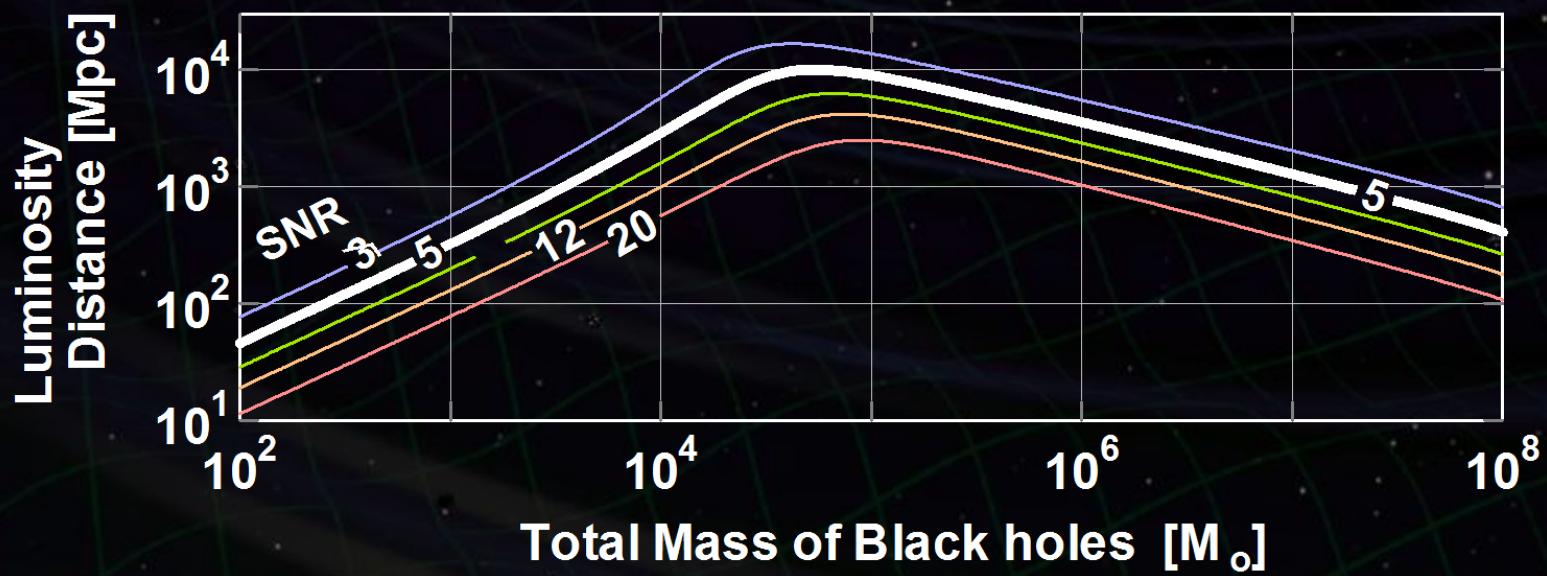
- 100 Msolar equal mass
- Spin parameter 0.5
- Distance 100 Mpc



Observable range

GWs from binary BH mergers

→ Obs. Range $\sim 10\text{Gpc}$ ($\sim 10^5 M_\odot$, SNR = 5)



Calculation by K.Yagi

Background GWs

**Observable GW
energy density ratio**

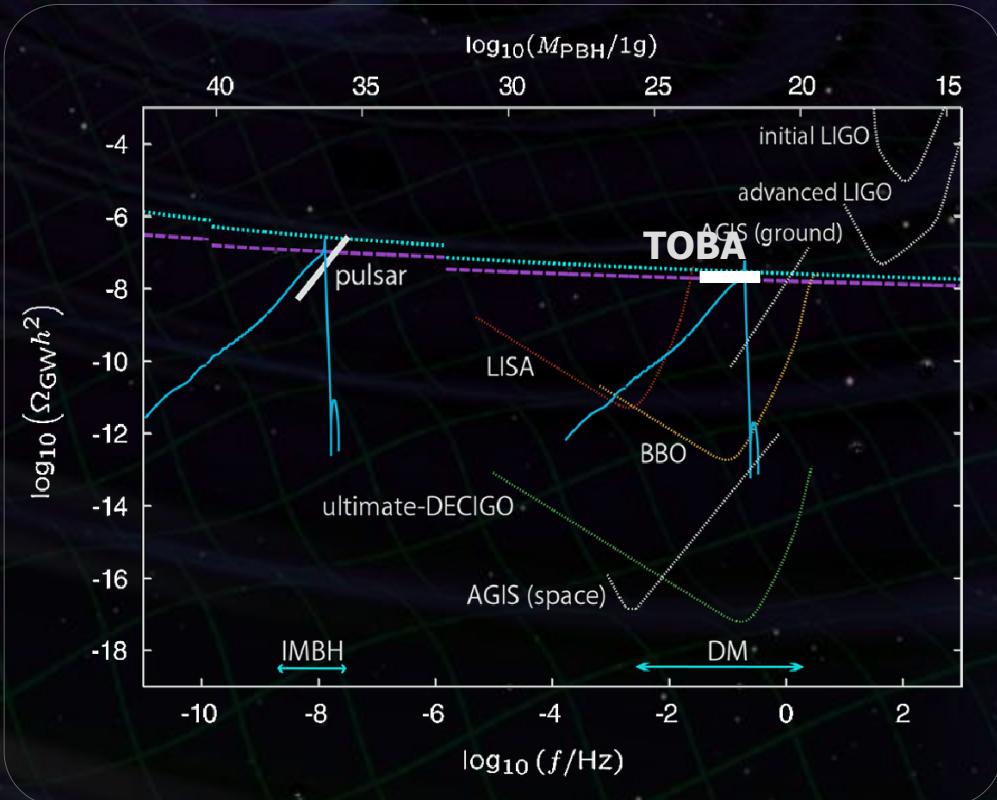
$$\Omega_{\text{gw}} \sim 10^{-7}$$

(1-yr obs. by 2 TOBAs)



Beat BBN upper limit
**GW by primordial
tensor perturbation**

R.Saito and J.Yokoyama,
PRL 102, 161101 (2009)



Sensitivity by R-TOBA

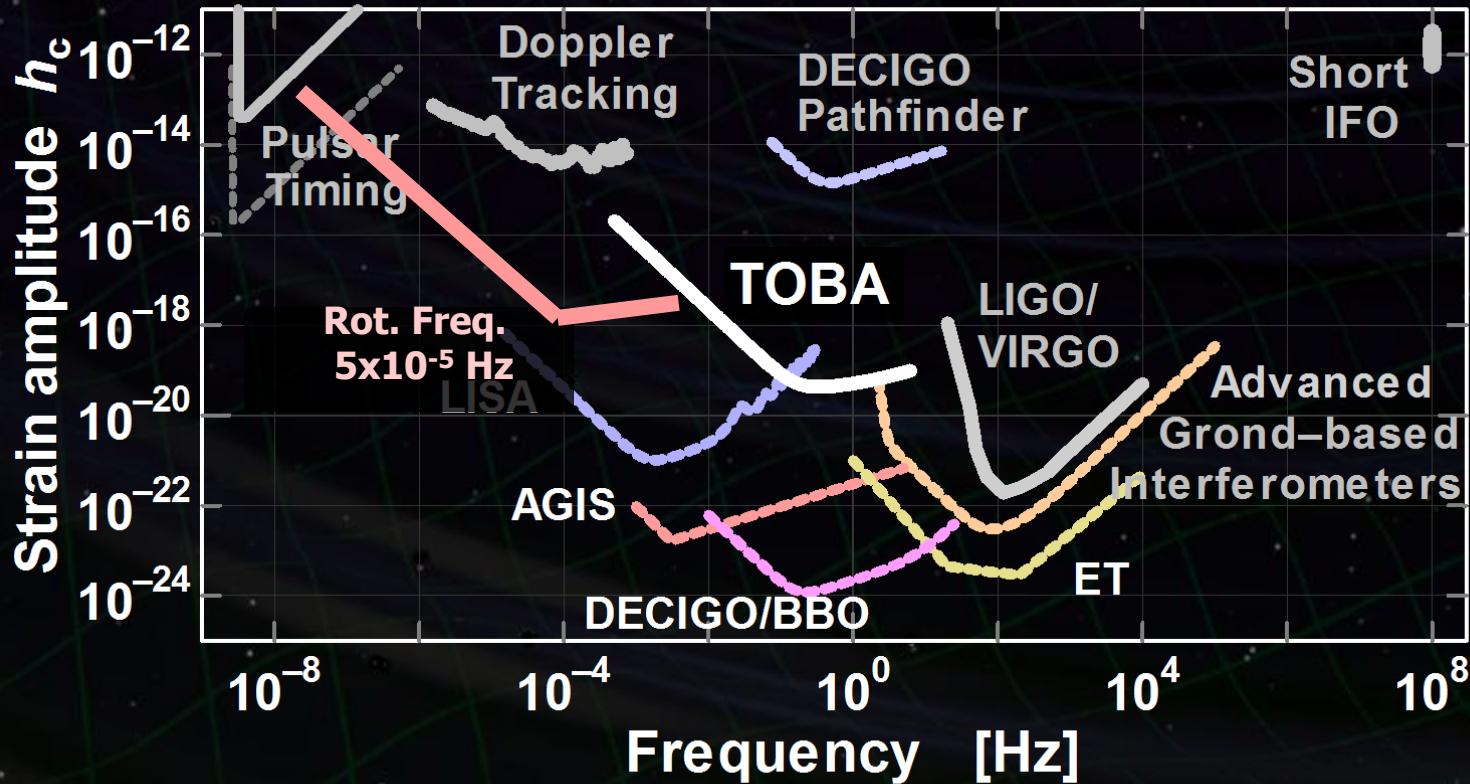
Sensitivity example

Rotation freq. 5×10^{-5} Hz

Laser power 1mW

↗ Bridge the Pulsar-timing and LISA bands

Bar length : 10m, Mass : 7600kg
Laser source : 1064nm, 1mW
Cavity length : 1cm, Finesse : 1
Bar Q-value : 10^5 , Temp: 4K
Support Loss : 10^{-10}



Small-scale TOBA

- Optical readout

Mirrors at both edges of the test-mass bar
→ Form Michelson interferometer
Sensitive angular sensor

Nd:YAG laser source

Wavelength 1064nm

Power 50mW

- Test-mass bar

Length ~200mm, Weight 160g

Made of Aluminum

Room temperature

- Suspension

Magnetic levitation by pinning effect of type-II superconductor
Superconductor bulk

$Gd_1Ba_2Cu_3O_{6.9}$: 70.9%

$Gd_2Ba_1Cu_1O_7$: 19.2%

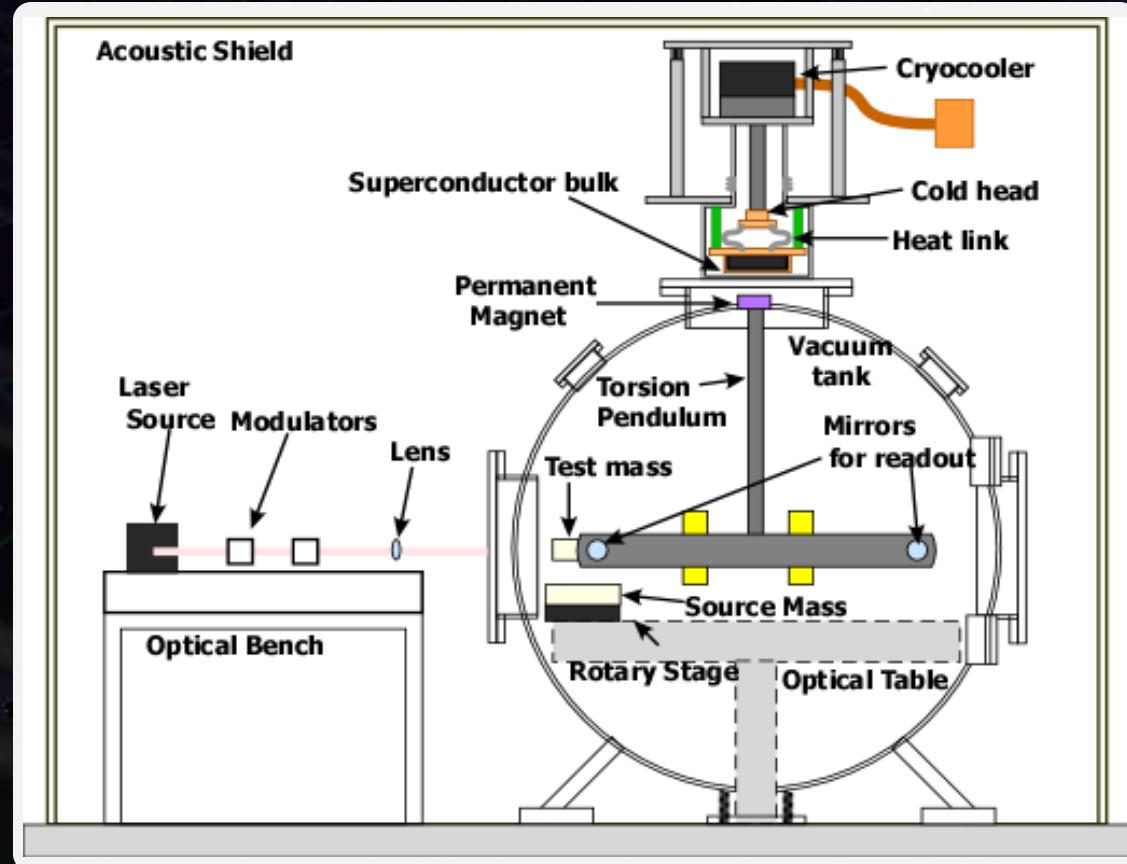
$\phi 600\text{mm}$, t 20mm, $T_c \sim 92\text{K}$

Low-vibration cryo-cooler

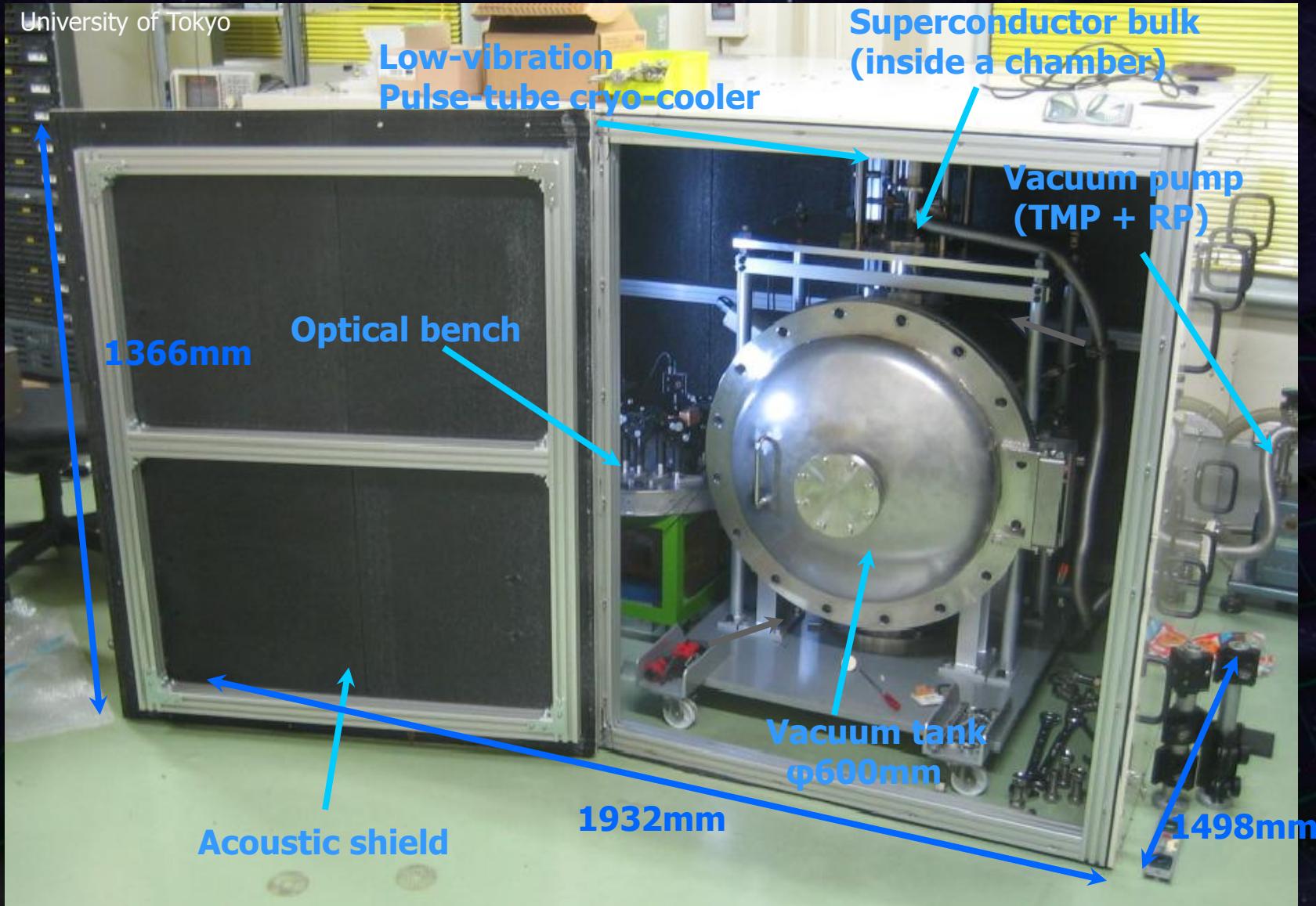
Operation temp. ~65K

- Vacuum system

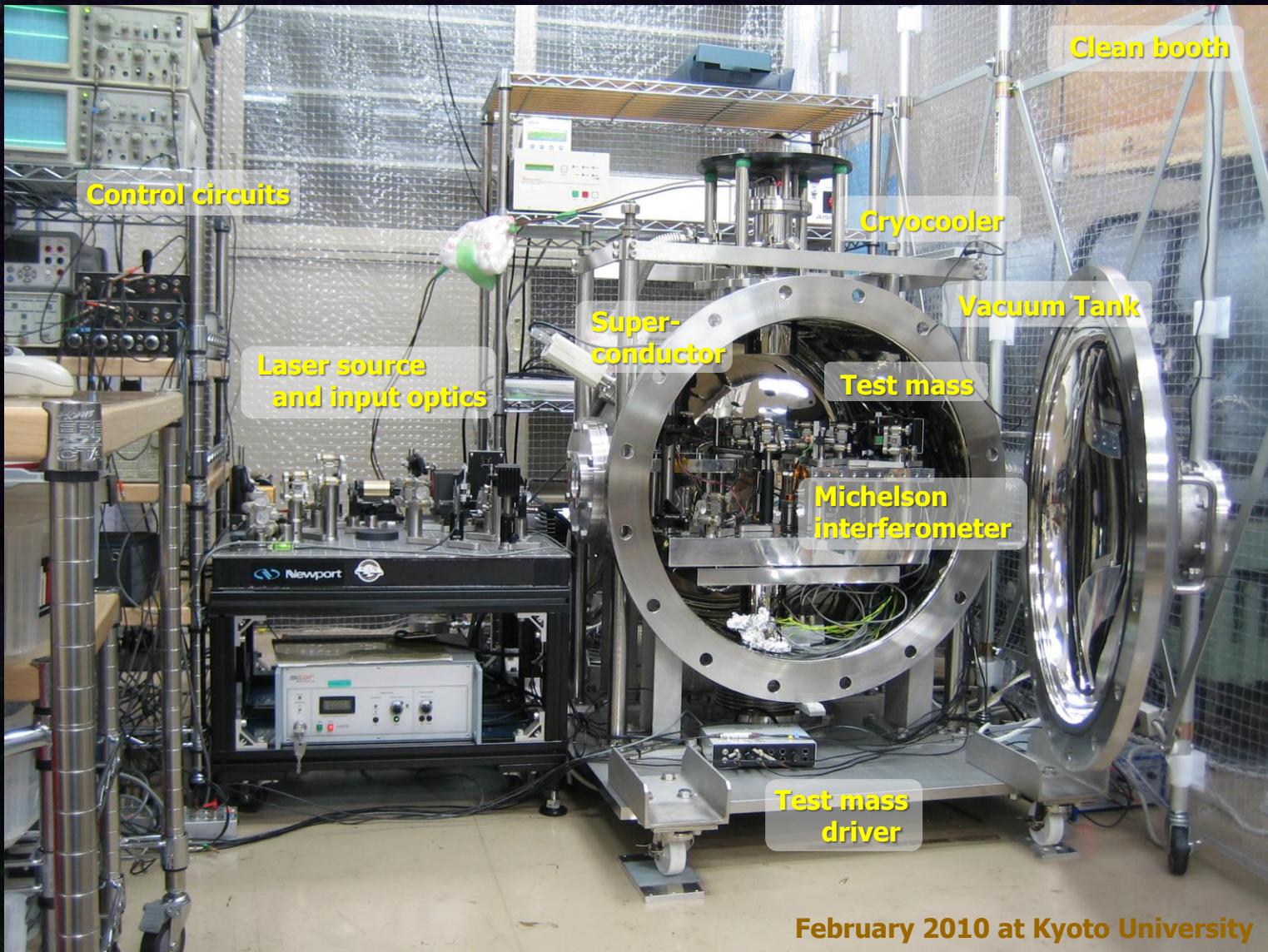
Pressure 10^{-5} Pa by TMP+RP
Acoustic shield enclosure



Small-scale TOBA at Tokyo



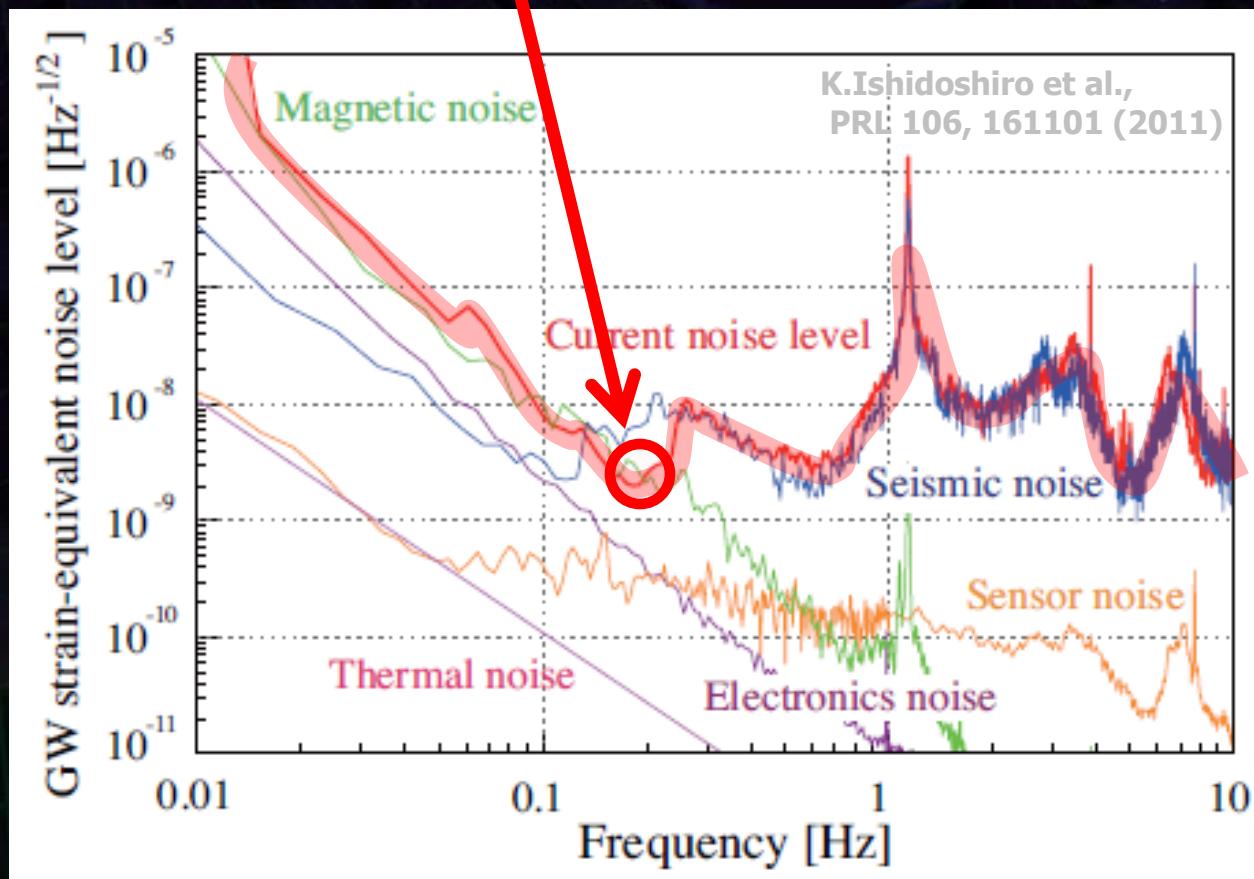
Small-scale TOBA at Kyoto



Sensitivity of small TOBA

Small-scale TOBA at University of Tokyo

Sensitivity $\tilde{h} \simeq 2 \times 10^{-9}$ [Hz $^{-1/2}$] at 0.2Hz



Limited by magnetic disturbances and seismic coupling

GWB observation by small TOBA

- Observation run by small-scale TOBA at the University of Tokyo
One-night observation → 7.5 hours' data
Use stable 3.5 hours' data



- Data analysis for stochastic background GW
Assume isotropic, unpolarized GWB

GWB energy density ratio

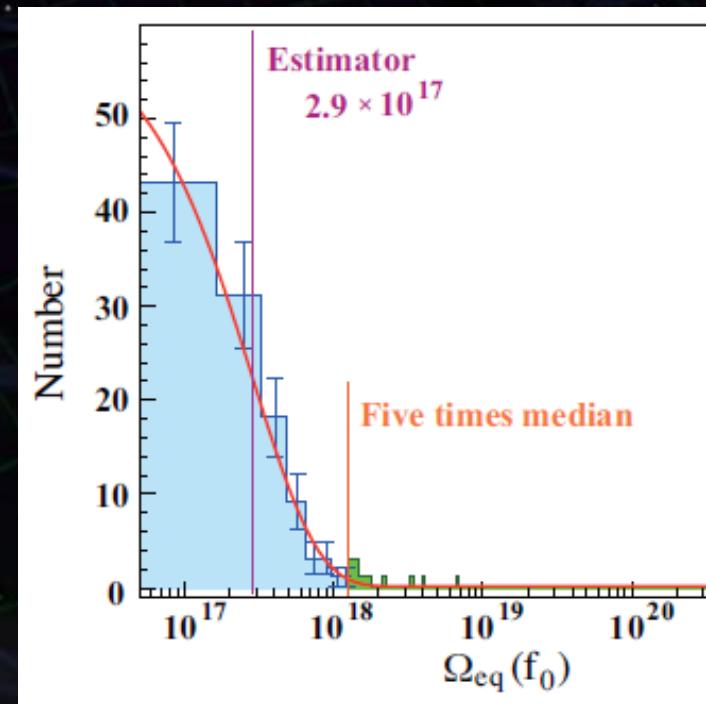
$$\Omega_{\text{eq}}(f_0) = \frac{10\pi^2}{3H_0^2} f_0^3 \tilde{h}^2(f_0)$$

Hubble constant $H_0 = 70$ [km/s/Mpc]

Divide obs. data into 120 segments

→ Average and distribution

$$f_0 = 0.2 \text{ [Hz]}, \quad f_{\text{BW}} = 0.01 \text{ [Hz]}$$



Upper limit on GWB

- Distribution → Averaged power at 0.2Hz

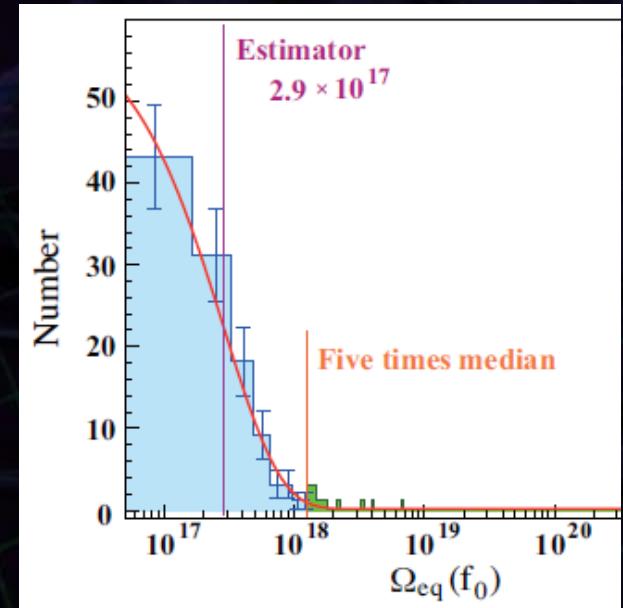
$$\overline{\Omega_{\text{eq}}} = 2.9 \times 10^{17}$$



Upper limit on Ω_{gw}

$$\Omega_{\text{gw}}^{\text{UL}} = 4.3 \times 10^{17} \quad (\text{C.L. 95\%})$$

Conservative upper limit including calibration error ($\delta h/h \sim 10\%$) and the other systematic errors.



Some details...

Probability to have larger result than $\overline{\Omega_{\text{eq}}}$

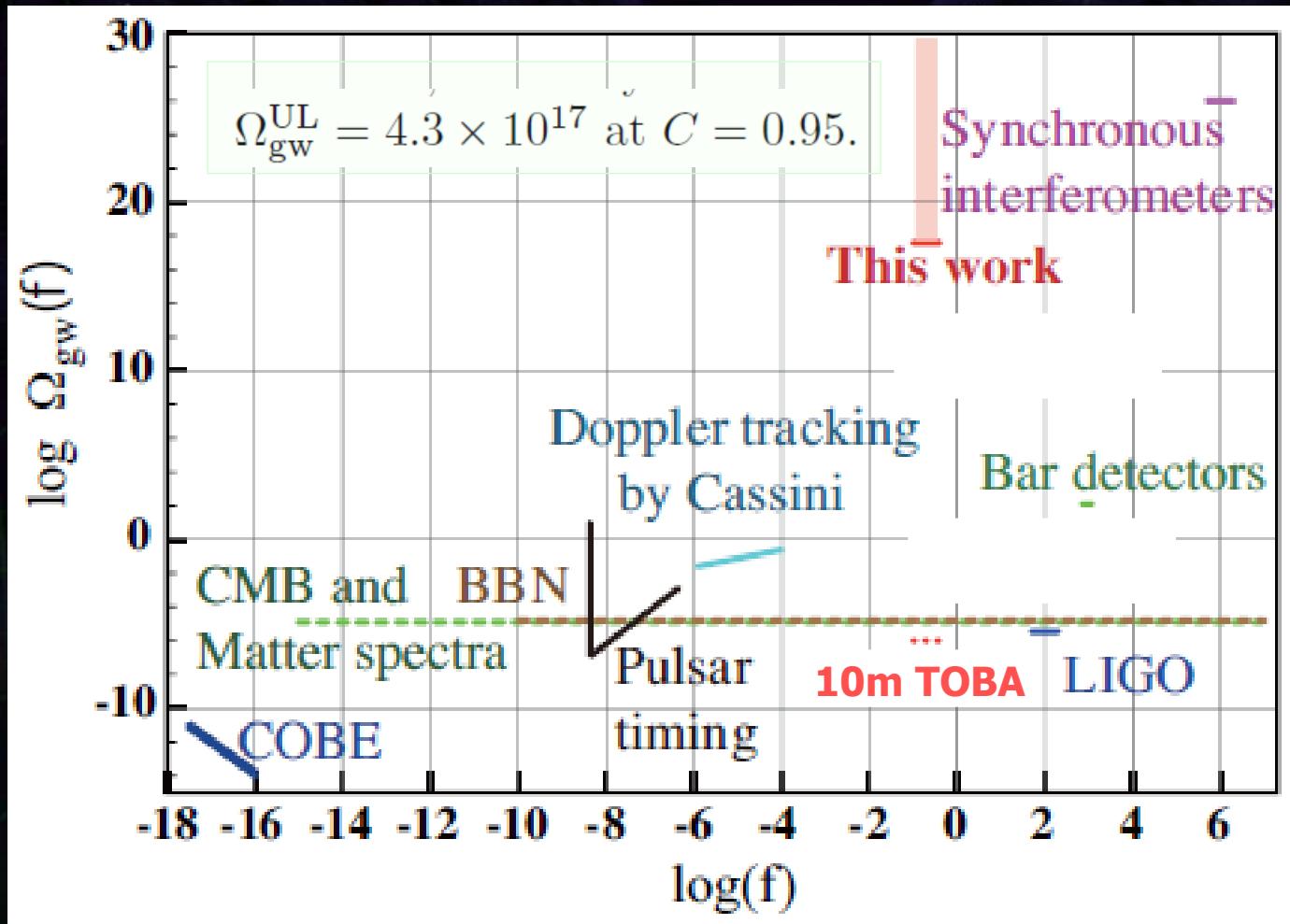
$$C = \int_{\Omega_{\text{eq}}}^{\infty} P(\Omega_{\text{es}}|\Omega_{\text{gw}}) d\Omega_{\text{es}}$$

Distribution with Ω_{gw} assuming Gaussian dist.

$$P(\Omega_{\text{es}}|\Omega_{\text{gw}}) \propto \exp \left[-\frac{(\Omega_{\text{es}} - \Omega_{\text{gw}})^2}{2\Omega_{\text{gw}}^2/N} \right]$$

Comparison with previous results

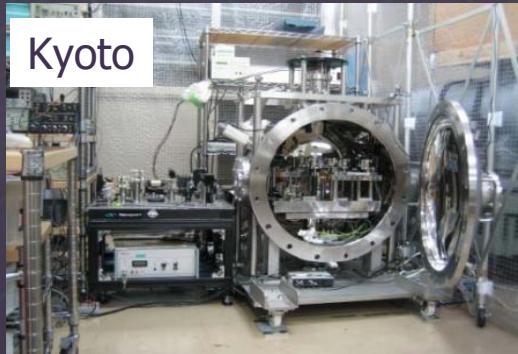
New upper limit at unexplored frequency band of 0.2Hz



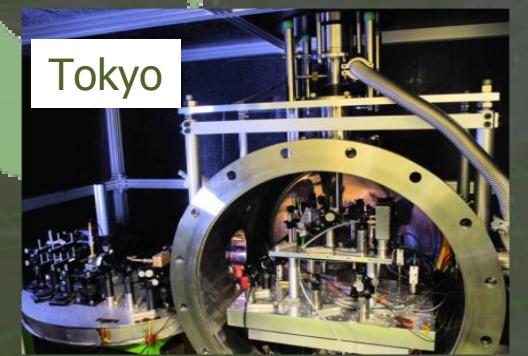
Observation with two detectors

Observation with two detectors places at Tokyo and Kyoto, Japan.
Comparable sensitivity, Separation : 370km

- Better upper limit on GWB
Possible detection



On-line calibration
(for monitoring the gain):
8.7 Hz signal
Monitored GPS signal:
1pps and serial signal
Temperature: ~40K



On-line calibration
(for monitoring the gain):
10 Hz signal
Monitored GPS signal:
1pps signal
Temperature: ~70K

DATE: 0:00 – 5:00, July 20, 2010
Sampling frequency: 1kHz
Direction of Test-mass bar: north-south

Original fig. by
A.Shoda
(GWPW 2011)

Observation with two detectors

1台の観測では、背景重力波の検出は極めて困難。

検出器の雑音と背景重力波を区別できない。

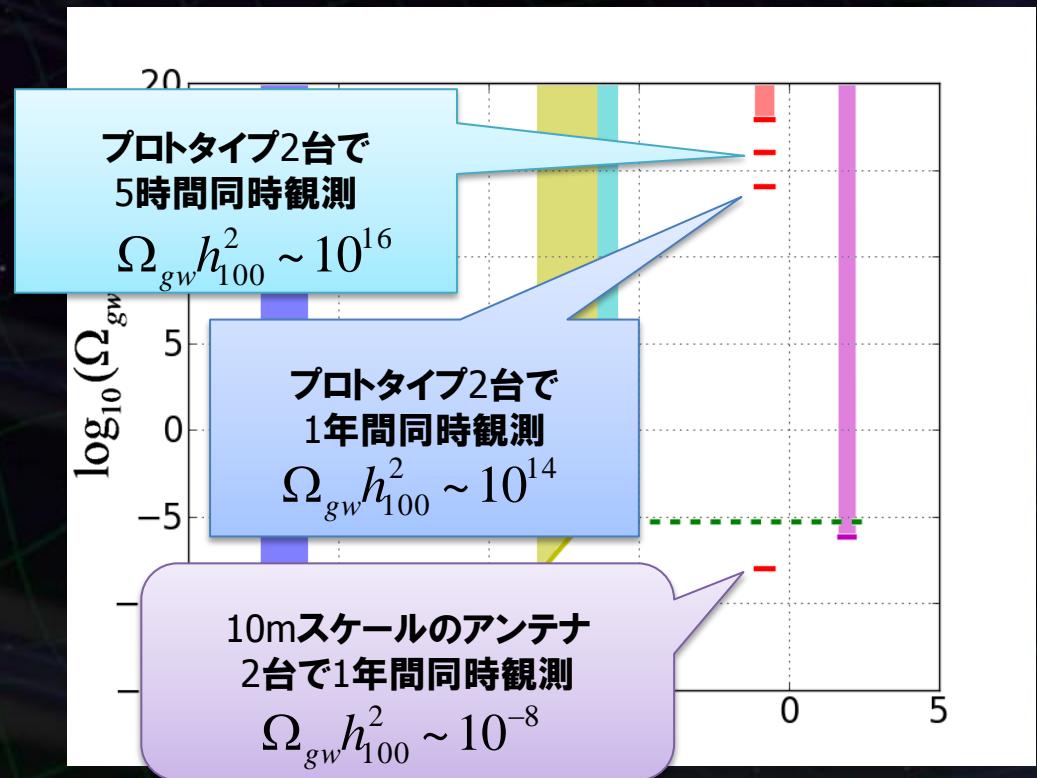
Fig. By A.Shoda



複数台での
同時観測、相関解析を行う。
信号と雑音を区別できる。
感度を向上できる。

$$\sqrt{T_{\text{obs}} \Delta f_{\text{obs}}}$$

程度の向上。



Sensitivities

One-night observation runs x three times

Data analysis underway $\rightarrow \Omega_{gw}^{UL} < 9 \times 10^{15}$ is expected

(1/50 better upper limit than that by one detector)

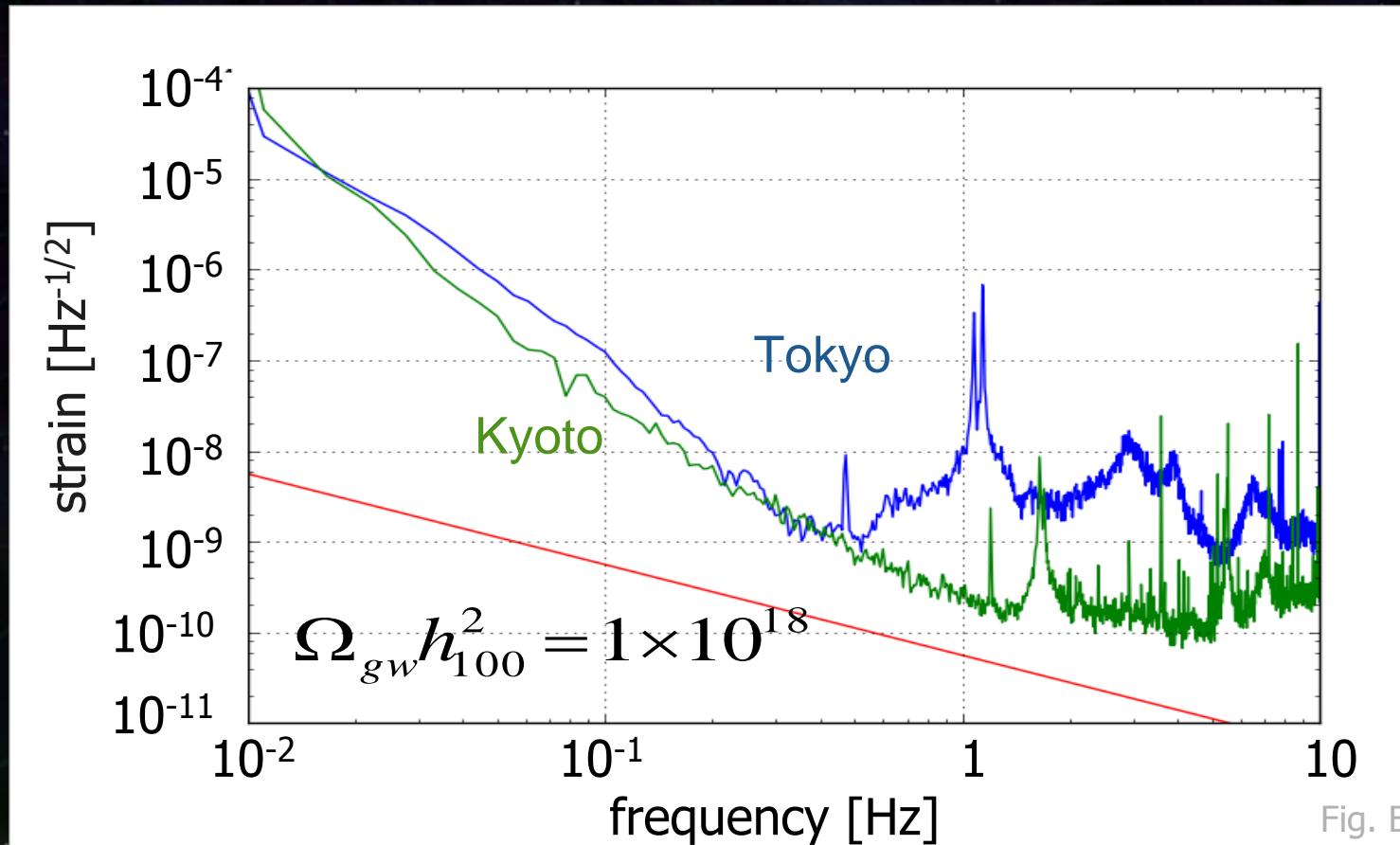
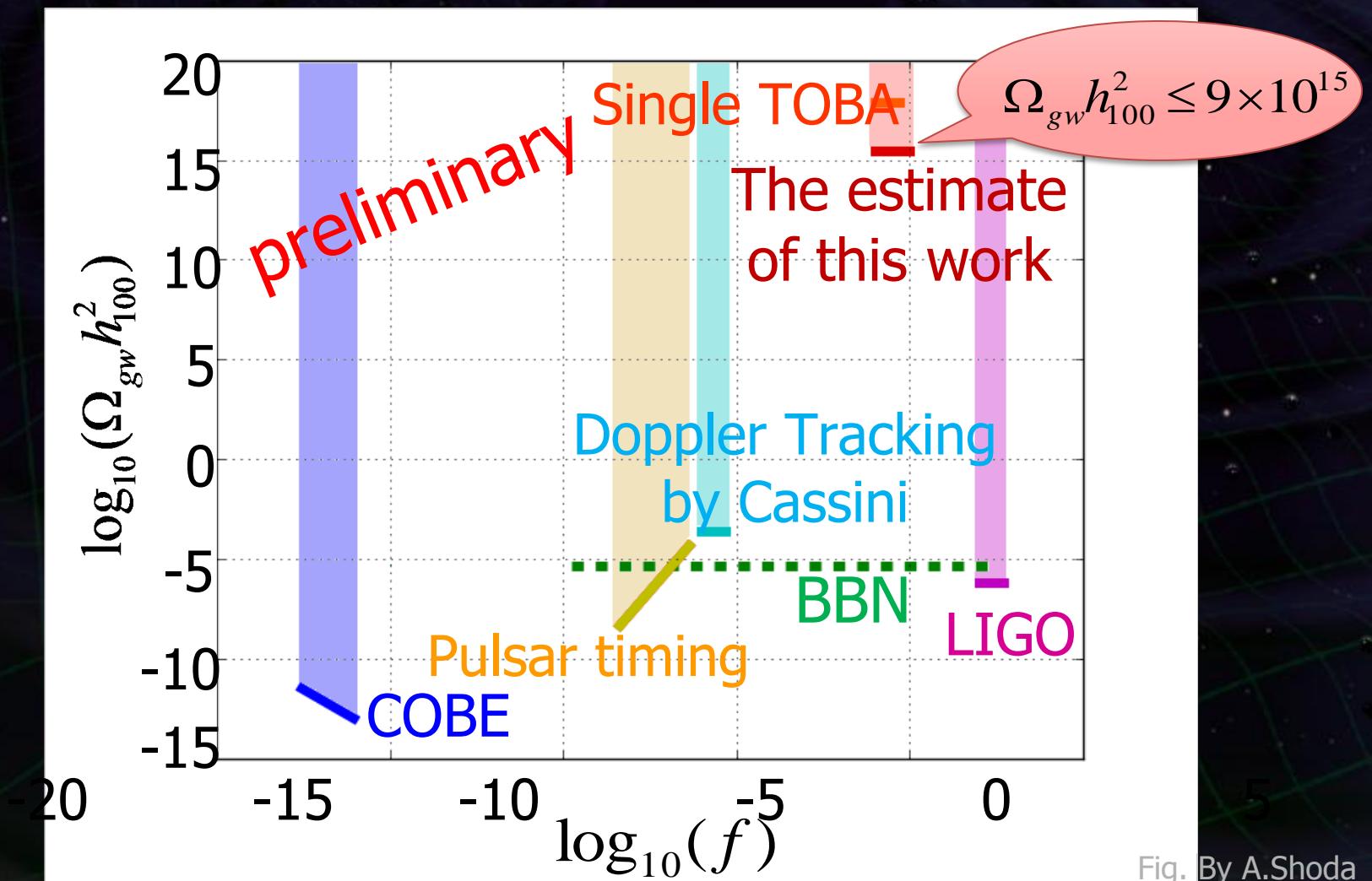


Fig. By A.Shoda

結果の見通し

観測データ(2010年7月)解析の暫定結果.

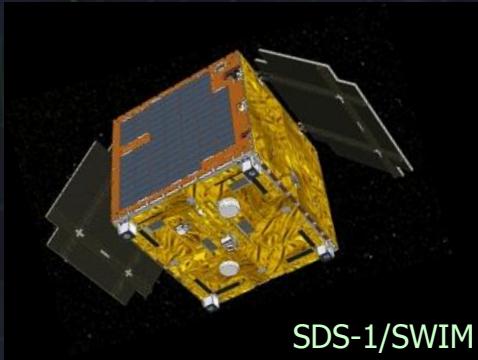


プロトタイプ

2つの地上装置, 1つの衛星搭載モジュール

ねじれ型重力波検出器A

(地球周回軌道, 2009年-)



試験マス

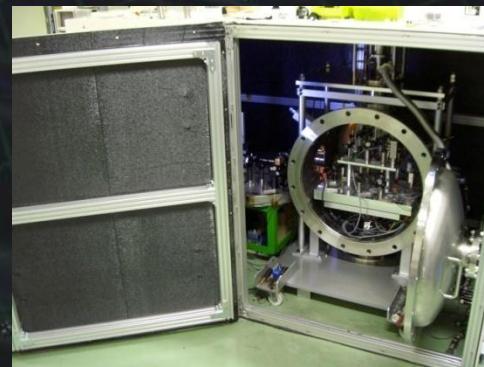
変動検出

位置・姿勢

質量 50g, 長さ 5cm
無重力浮上 + 制御
反射型フォトセンサ
スピニ + 軌道運動

ねじれ型重力波検出器B

(東京大学, 2008年-)



質量 150g, 長さ 20cm
超電導磁気浮上 + 制御
レーザー干渉計
地上静置観測

ねじれ型重力波検出器C

(京都大学, 2010年-)

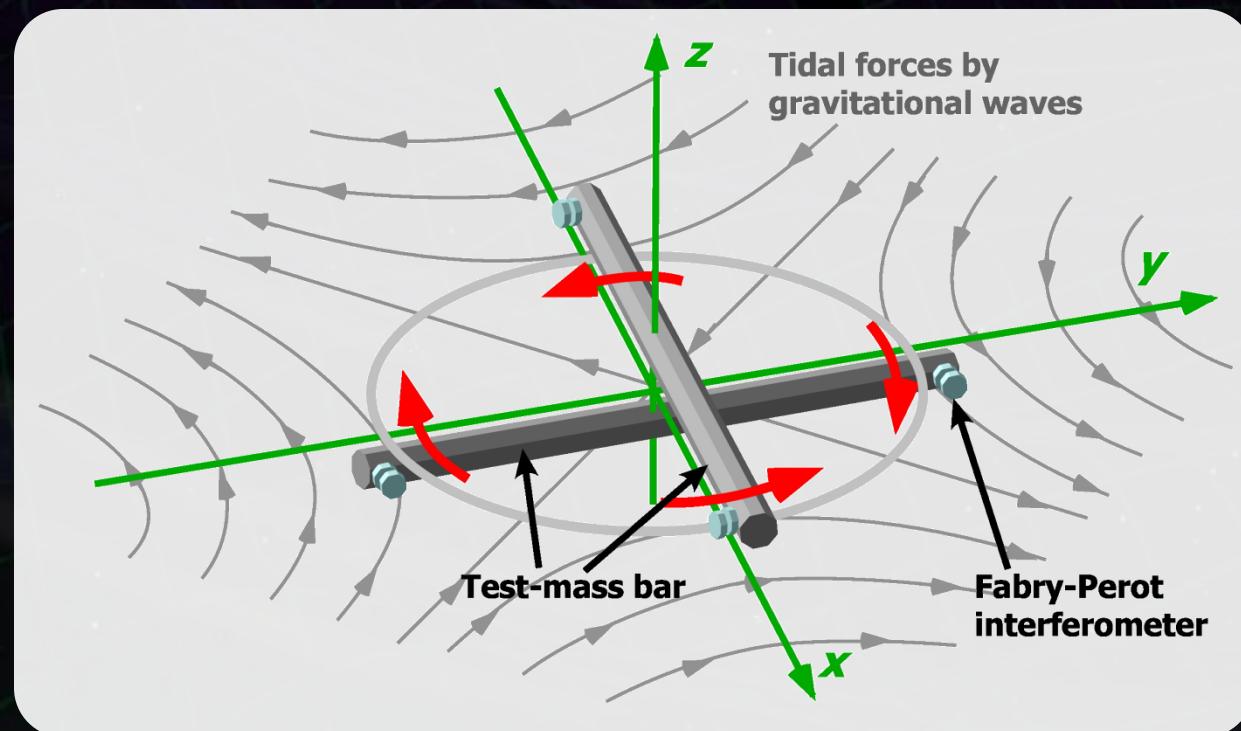


質量 340g, 長さ 25cm
超電導磁気浮上 + 制御
レーザー干渉計
地上静置観測

Rotating TOBA

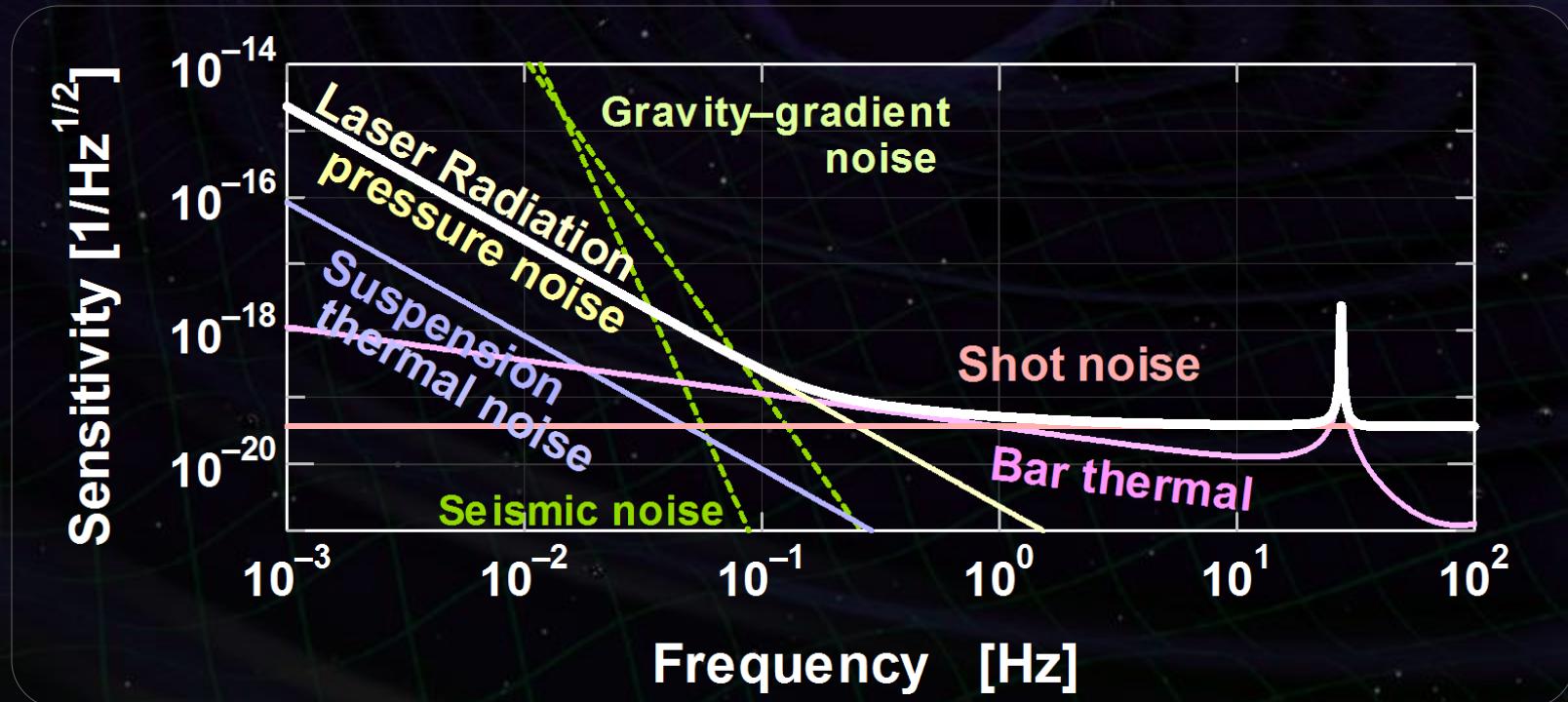
Rotate the detector along its axis

- Very low-freq. GW signal ($\sim 10^{-8} - 10^{-4}$ Hz) is up-converted to 2 x (Rotation freq.)



Fundamental noise level of TOBA

Practical parameters $\Rightarrow \tilde{h} \simeq 3 \times 10^{-19}$ [Hz $^{-1/2}$] (at 0.1 Hz)



Bar length : 10m, Mass : 7600kg

Laser source : 1064nm, 10W

Cavity length : 1cm, Finesse : 100

Bar Q-value : 10^5 , Temp: 4K

Support Loss : 10^{-10}

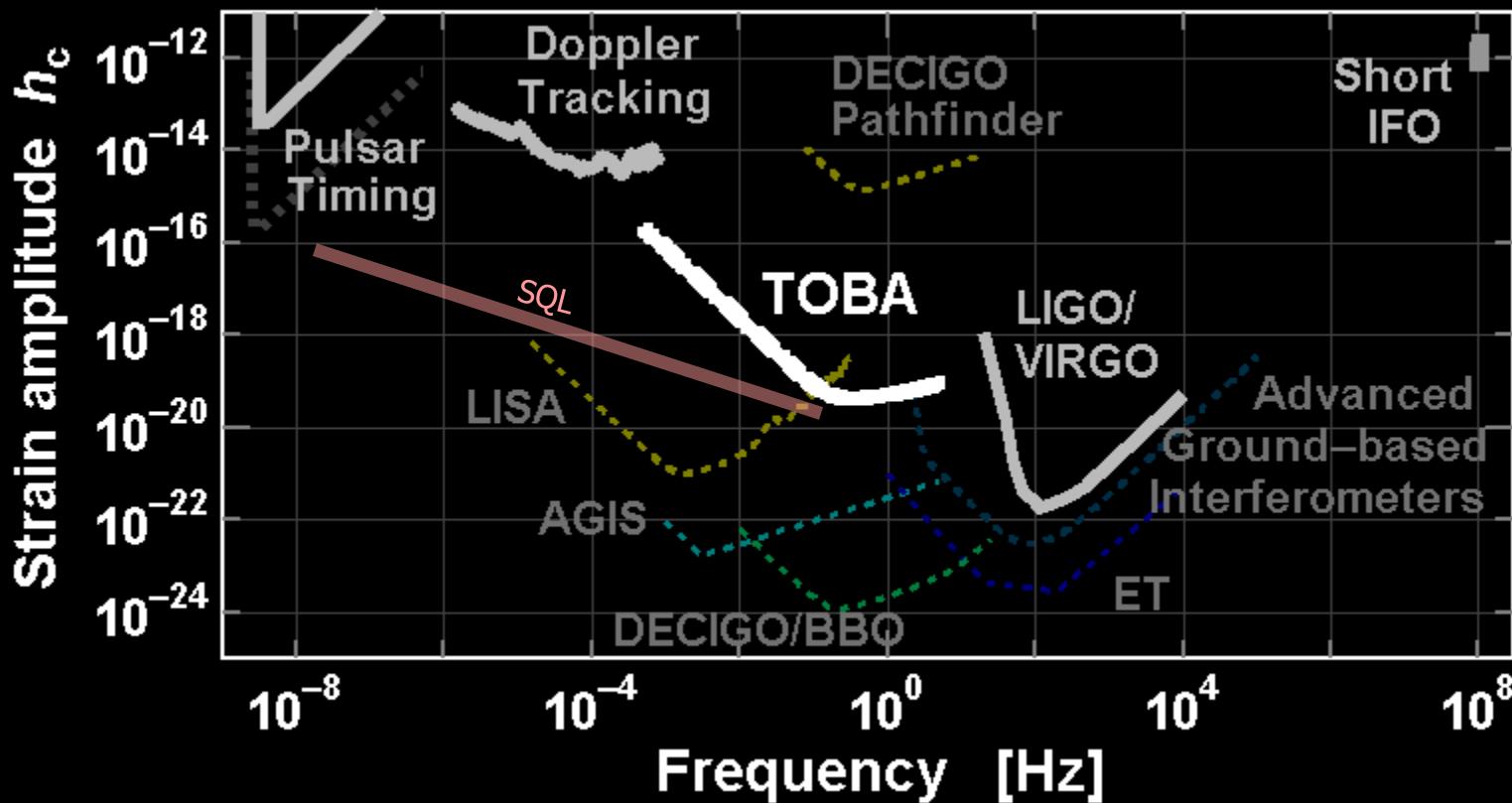
Laser Freq. noise < 10Hz/Hz $^{1/2}$,
Freq. Noise CMRR>100
Intensity noise < 10^{-7} /Hz $^{1/2}$,
Bar residual RMS motion < 10^{-12} m

TOBA Sensitivity

Comparison with the other detectors

DECIGO/BBO band:

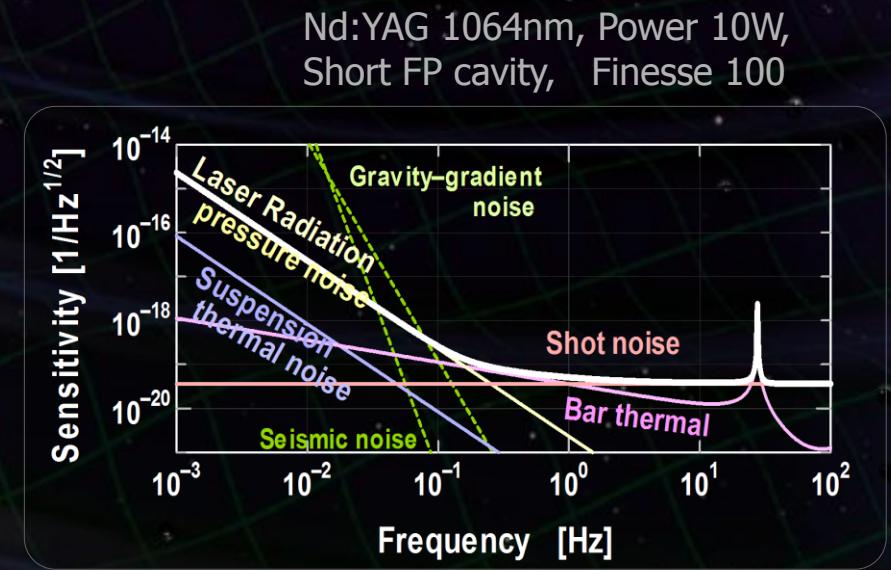
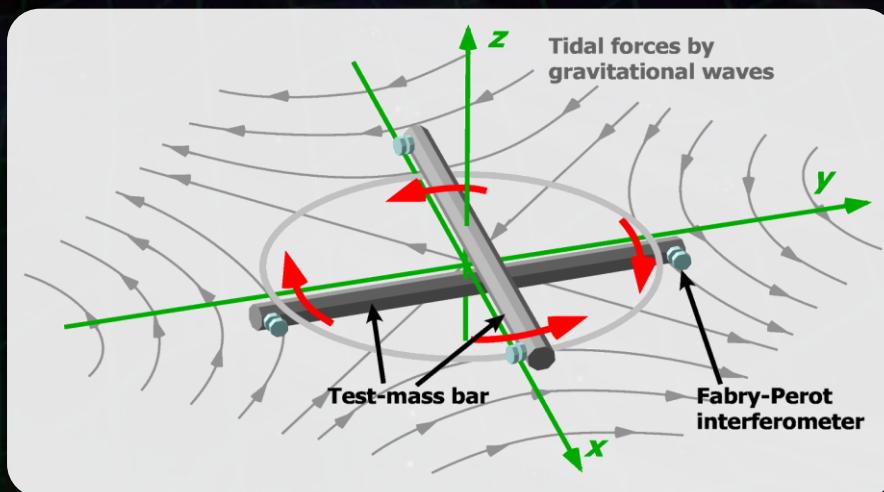
Between ground-based detectors and LISA bands



$$\text{Characteristic amplitude : } h_c = \bar{h} \times \sqrt{f_{\text{center}}} \quad (\text{Dimensionless strain})$$

Optical readout noise

- Optical readout noise
 - Readout by short FP cavities at the bar edge.
 - Reference mirrors fixed to isolated base plate.
- ⇒ Shot noise + Rad. Pressure noise



Bar thermal noise

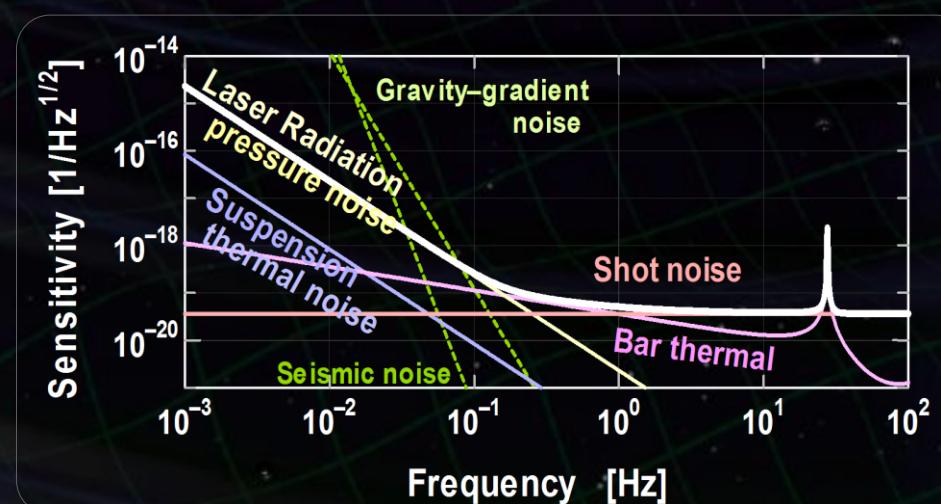
- Thermal noise of bar mode

Differential readout at the edges
→ Contribution of odd modes

Aluminum bar (7.6 ton)
length 10 m, ϕ 0.3 m
Temp. 4K, Q 10^7

⇒ $8 \times 10^{-20} \text{ } 1/\text{Hz}^{1/2}$ at 0.1Hz

By keeping the total mass,
- High Q and low T is better
- Shorter is better
- High Young's modulus is better



Chirp waveform

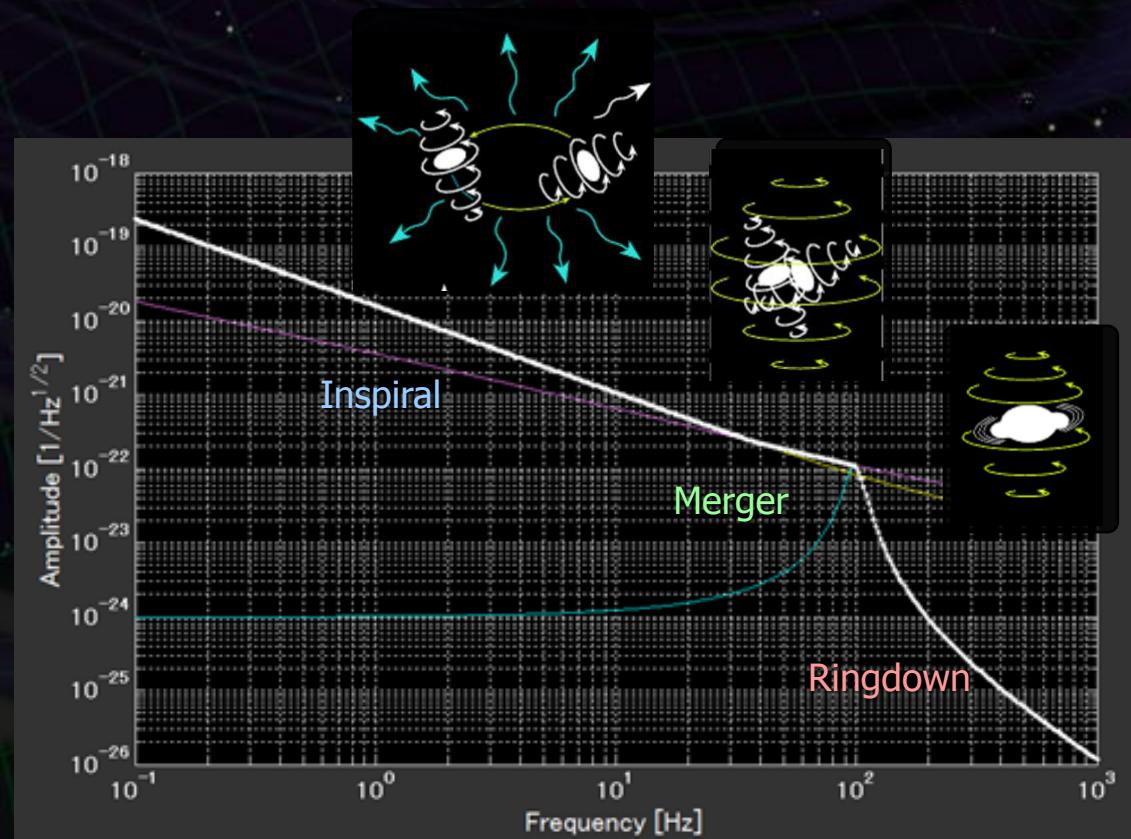
- Phenomenological waveform by numerical simulation

(Ajith+ arXiv 0909.2867)

- For BH inspiral (no tidal deformation).
- Include chirp, merger, and ring-down.
- Include spin effect.

GW from BH merger

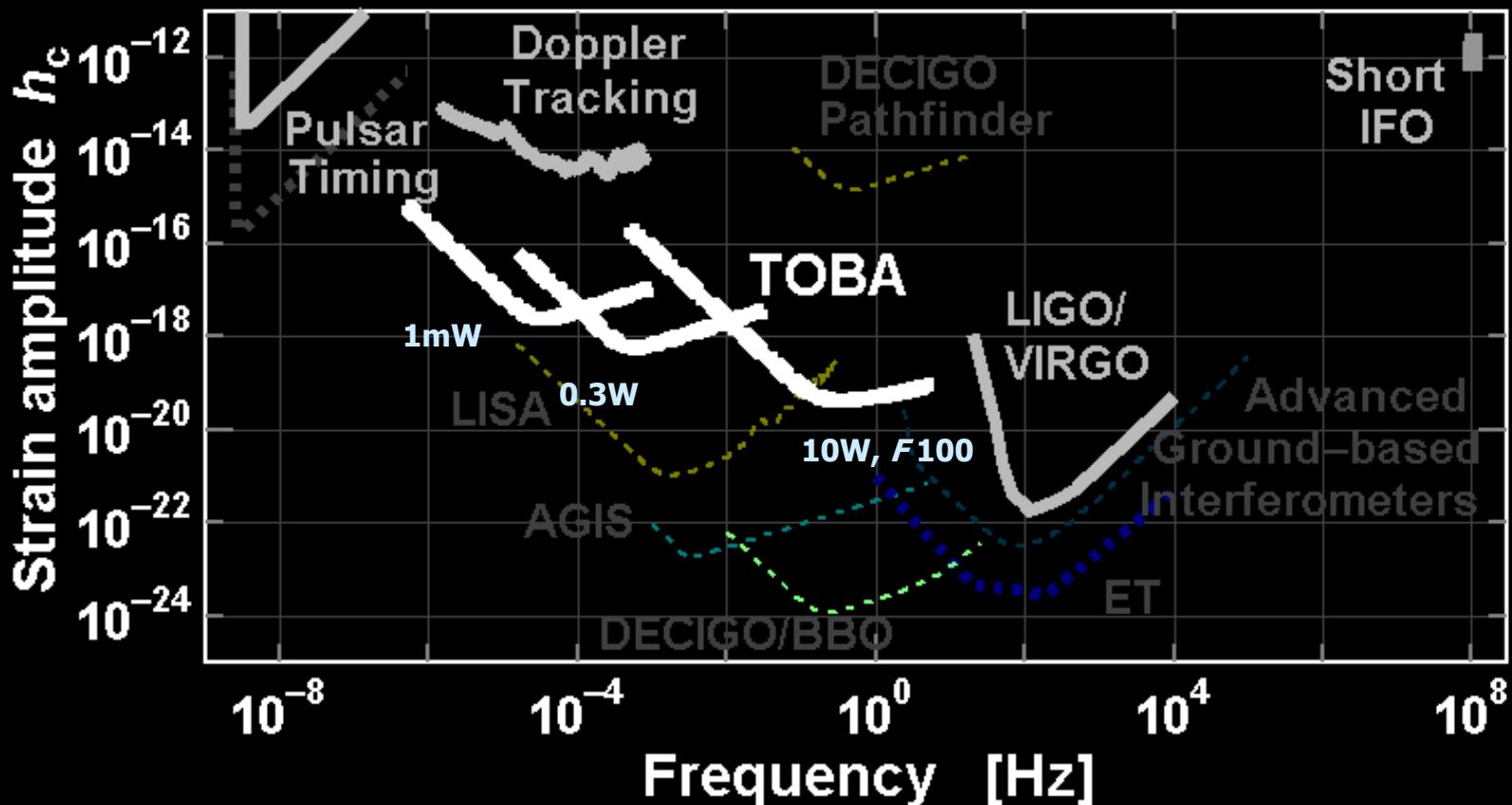
- 100 Msolar equal mass
- Spin parameter 0.5
- Distance 100 Mpc



TOBA Sensitivity

Sensitivity example

Bar length : 10m, Mass : 7600kg
Laser source : 1064nm
Bar Q-value : 10^5 , Temp: 4K
Support Loss : 10^{-10}



Topic

Homodyne detection

Ideas of :

Bar rotation by tidal acceleration by GW

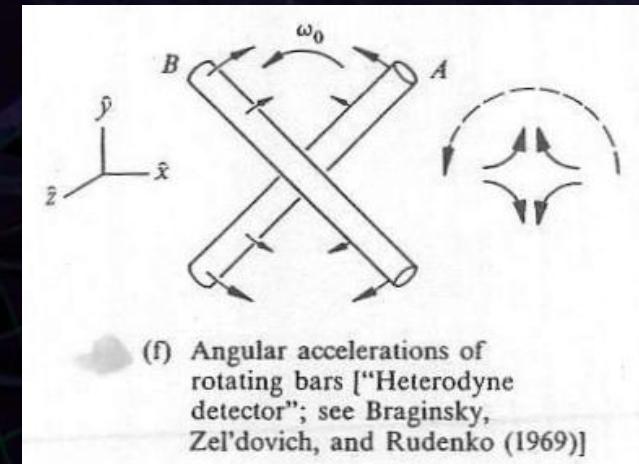
Detection of Circularly polarized GWs

Heterodyne detection method

V.B.Braginsky, Ya.B.Zel'dovich, and V.N.Rudenko
Sov. Phys.- JETP Lett. 10 (1969) 280.

Being introduced in:

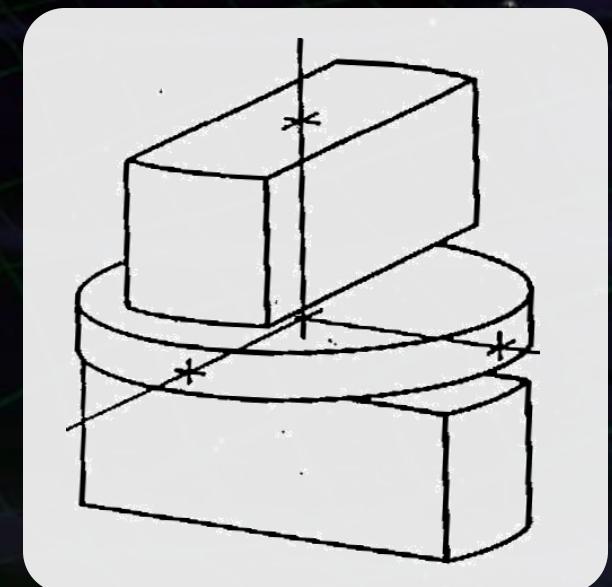
C.W.Misner, K.S.Thorne, J.A.Wheeler,
'Gravitation' W.H.Freedman (1973) pp.1016.



Observation with torsion antenna :

Cryogenic torsion antenna to observe continuous GWs from Grab pulsar

S.Owa, et al.,
'Cryogenic Detector for Gravitational Radiation from the Crab Pulsar'
Proceedings of the fourth Mercel Grossmann Meeting on General Relativity (1986).



SDS-1衛星での実証

SDS-1 (Small Demonstration Satellite - 1)

JAXA開発による100kg級の技術実証衛星

Size : 70x70x60cm, Weight : 100kg

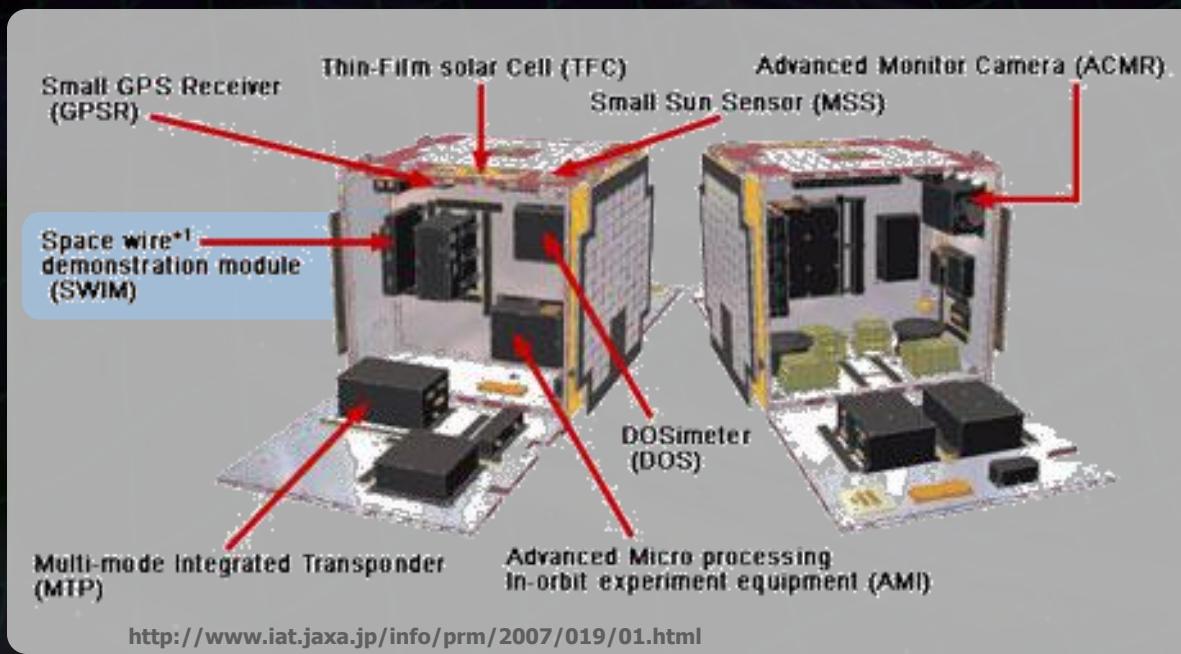
Power : >100W, Downlink : ~5kbps

Orbit : SSO (~660km)

Spin stabilization and 3-axis attitude control

Mission Lifetime : ~Half year (nominal)

SDS-1 and GOSAT
(Press Release, November 4, 2008)
Photo from Mainich Newspaper Web



SDS-1/SWIM

SDS-1/SWIM

2005年 検討・開発開始.

2009年 1月23日打上げ.

2011年 9月 運用停止.

全ての機器で

full success以上を達成.

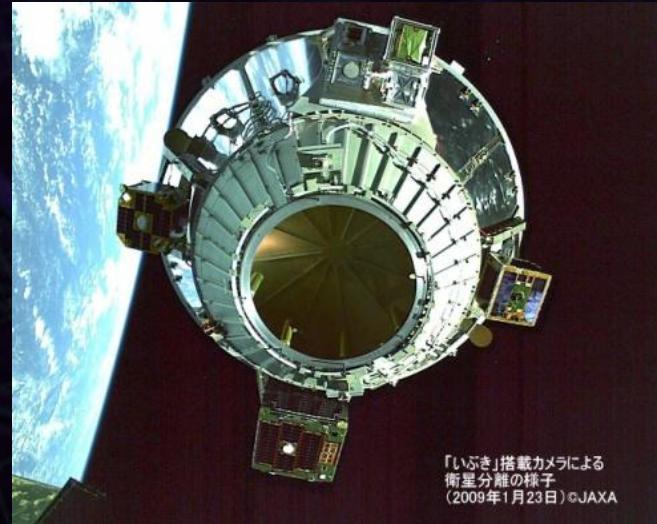


写真:
JAXA

SpaceCube2: Space-qualified Computer

CPU: HR5000
(64bit, 33MHz)

System Memory:
2MB Flash Memory
4MB Burst SRAM

4MB Asynch. SRAM

Data Recorder:
1GB SDRAM
1GB Flash Memory

SpW: 3ch

Size: 71 x 221 x 171

Weight: 1.9 kg

Power: 7W



Photo by JAXA

SWIM μ v : User Module

Processor test board
GW+Acc. sensor
FPGA board
DAC 16bit x 8 ch
ADC 16bit x 4 ch
→ 32 ch by MPX

Torsion Antenna x2
~47g test mass

Data Rate : 380kbps
Size: 124 x 224 x 174
Weight: 3.5 kg
Power: ~7W

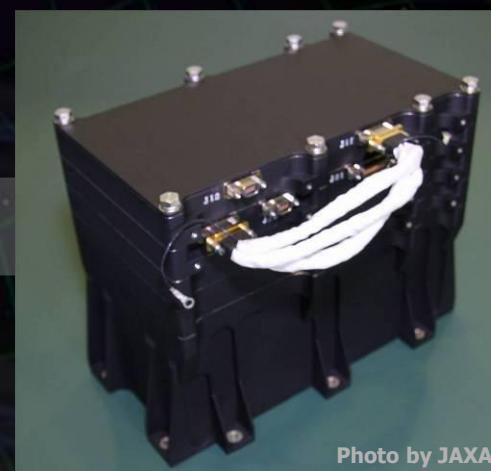


Photo by JAXA

SWIM μ v GW sensor

Tiny GW sensor : Test-mass length \sim 50mm

Launch in Jan. 2009, Decommission in Sept. 2010

Successful operation and data-taking

TAM: Torsion Antenna Module with free-falling test mass
(Size : 80mm cube, Weight : \sim 500g)

Test mass

\sim 47g Aluminum, Surface polished
Small magnets for position control

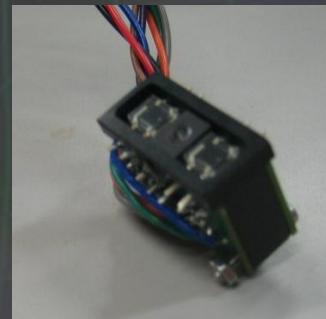
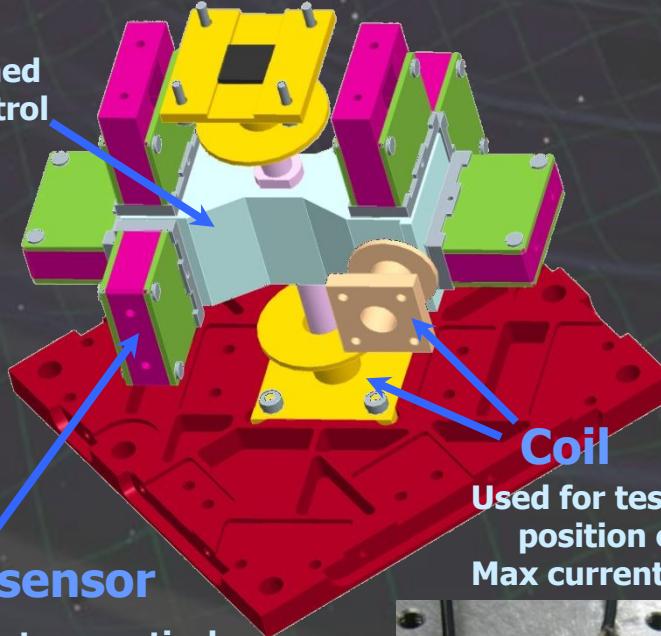
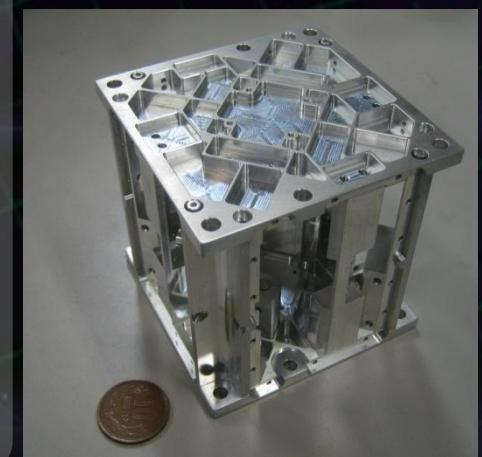
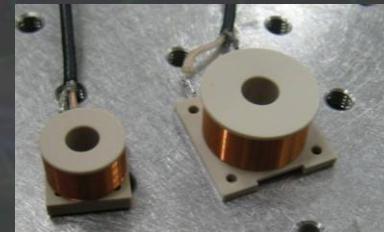


Photo sensor

Reflective-type optical displacement sensor
Separation to mass \sim 1mm
Sensitivity $\sim 10^{-9}$ m/Hz $^{1/2}$
6 PSs to monitor mass motion



SWIM μ v 軌道上実証

SWIM

In-orbit operation

Test mass controlled

Error signal → zero

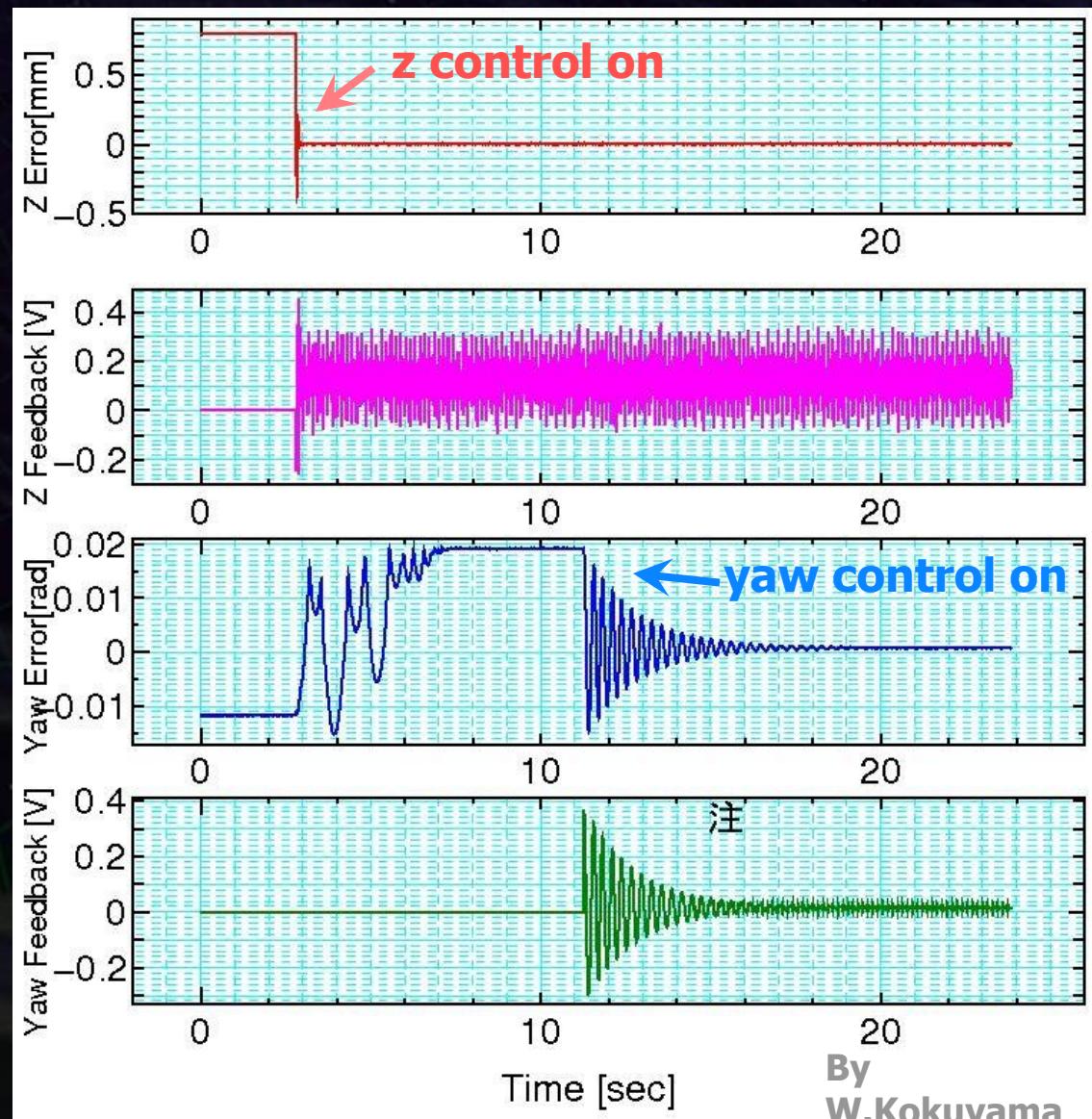
Damped oscillation
(in pitch DoF)

Free oscillation
in x and y DoF

Signal injection
→ OL trans. Fn.

Operation: May 12, 2009

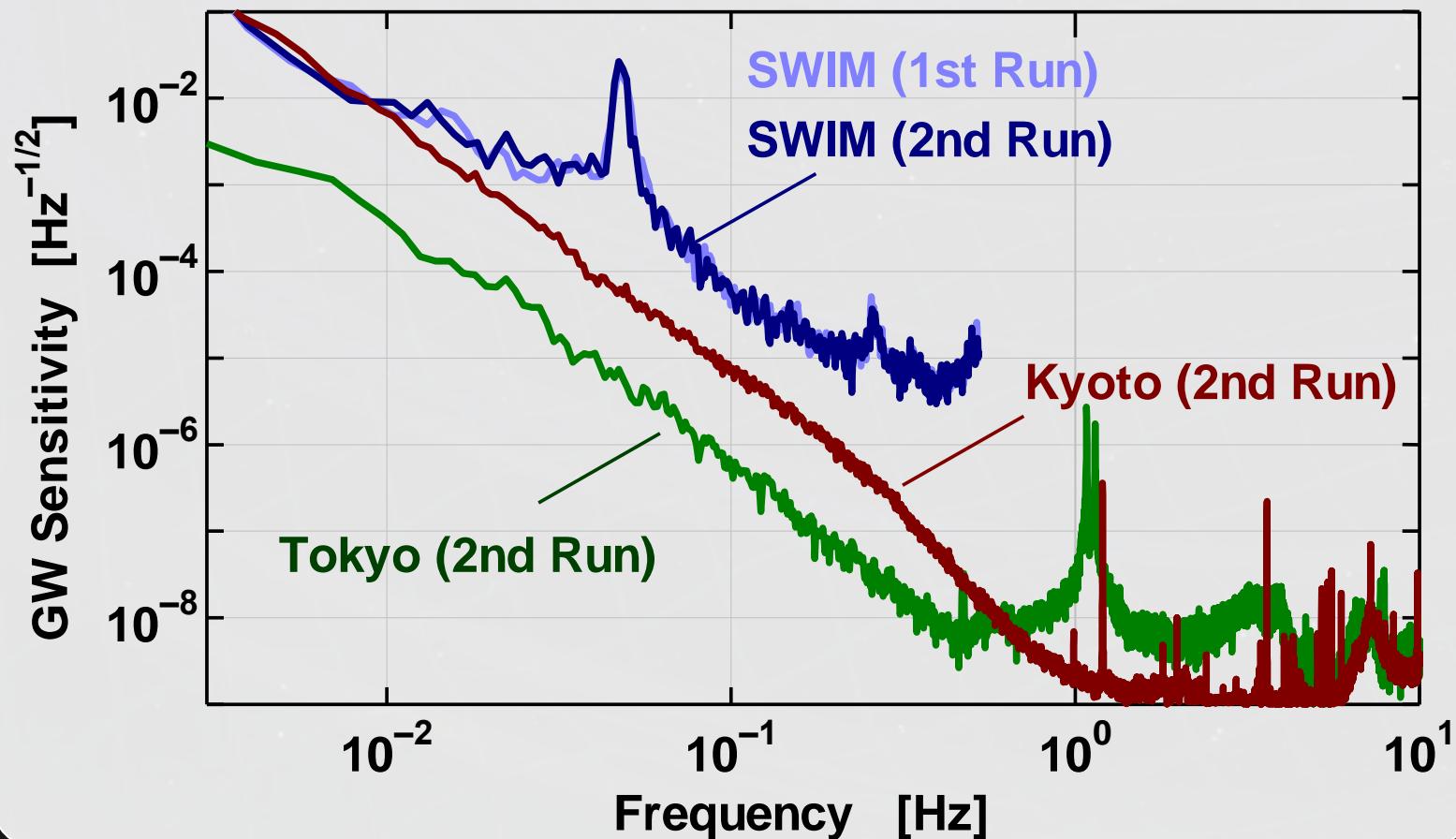
Downlink: ~ a week



By
W.Kokuyama

Sensitivity

Observation by SWIM and ground-based detectors
1st run June 17 2010, 2nd run July 15 2010



Dynamic Quadrupole moment

Dynamic quadrupole moment

$$q^{ij} \equiv \int \rho \left(x^i w^j + w^i x^j - \frac{2}{3} \delta^{ij} x_k w^k \right) dV$$

$\vec{w}(x)$: Mode pattern function

In case of bar rotation... $\vec{w}(x) = (-y, x, 0)$

$$q^{11} = \int \rho(-2xy) dV$$

$$q^{22} = \int \rho(2xy) dV$$

$$q^{12} = \int \rho(x^2 - y^2) dV$$

$$q^{21} = \int \rho(y^2 - x^2) dV$$