

# Internal Review of Main Interferometer Subsystem

2012/1/27

Yoichi Aso

## Overview: Definition and scope of the subsystem

MIF includes: Arm cavities, Recycling cavities, Michelson part

### Assigned tasks

- Parameter selection of the MIF
  - Length, ROC, etc
  - Optical layout
- Design of the control scheme
  - LSC, ASC
- Lock acquisition scheme
- Commissioning

For some reason, detector characterization is a part of MIF  
Maybe the Instrument Control will be too

# Interface with other subsystems

- Mirror
  - Reflectivity, ROC, Loss, other specs.
- Suspension
  - Isolation requirements
  - Actuator design
  - Installation procedure
- Suspension+AOS
  - Local sensors
- Laser
  - Power
- IOO
  - Intensity Noise
  - Frequency Stabilization Path
  - Input/Output mode matching
  - Detection ports
  - OMC
  - Green lock
- AOS
  - Scattered light
- Digital System
  - Servo model
- Analog electronics
  - PD, QPD, I-Q demodulator, servo filters, etc
- Vacuum
  - Layout

# Design Status

IFO params	semi-final	LSC principle	final
ASC principle	preliminary	Servo modeling	TBD
Green Lock Design	preliminary	Optical Layout	final
Frequency Servo	preliminary	Commissioning Plan	TBD
OMC	early stage	Analog Circuits	TBD

# iLCGT Design

## Target Specs

- Stably operate Fabry-Perot Michelson Interferometer
- No sensitivity requirement

## Final(?) Design

Based on bLCGT design

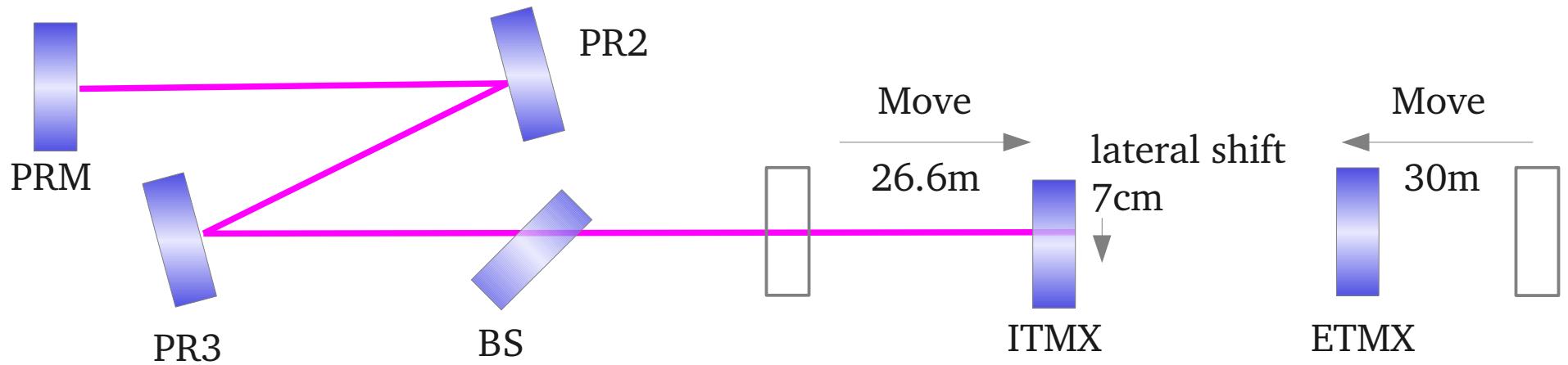
- Use Silica TMs
- ROCs are the same as bLCGT
- Locations of TMs are shifted by 26.6m/30m from bLCGT
  - ITMs laterally shifted by 7cm
  - Arm GV is shifted accordingly
- No folding part optimization
- PRM will not be installed (PR2, PR3 will be)
- Tweak the Input MMT to get a reasonable mode matching
- SRC is isolated vacuum wise.
- Pick-off the AS beam before the GV
- Green lock may be tested with X-arm

# (Virtual) Layout Change in iLCGT

**Location of ITMs:** Shifted by 26.6m from the bLCGT position

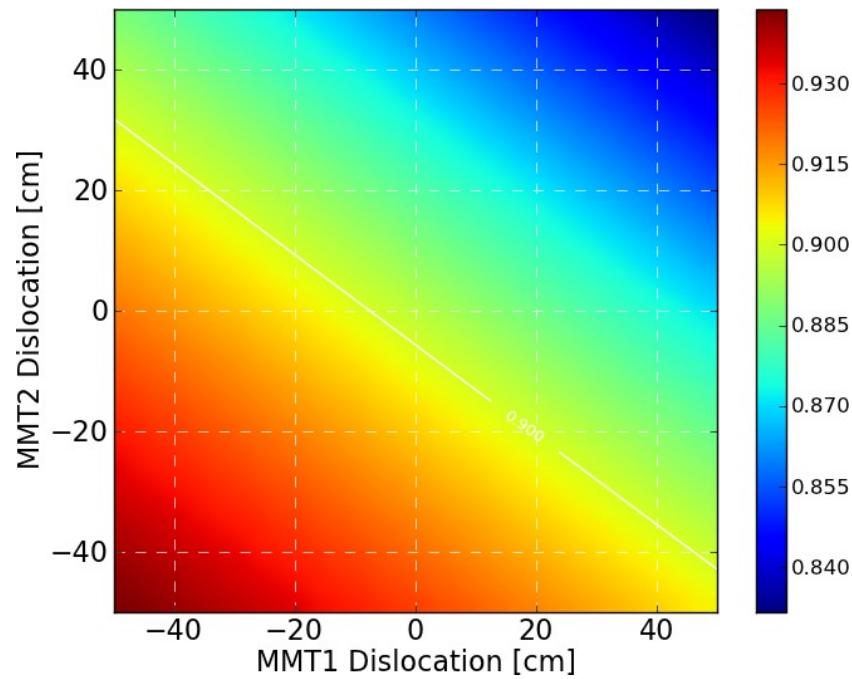
**Location of ETMs:** Shifted by 30m from the bLCGT position

**ITM lateral shift:** 7cm

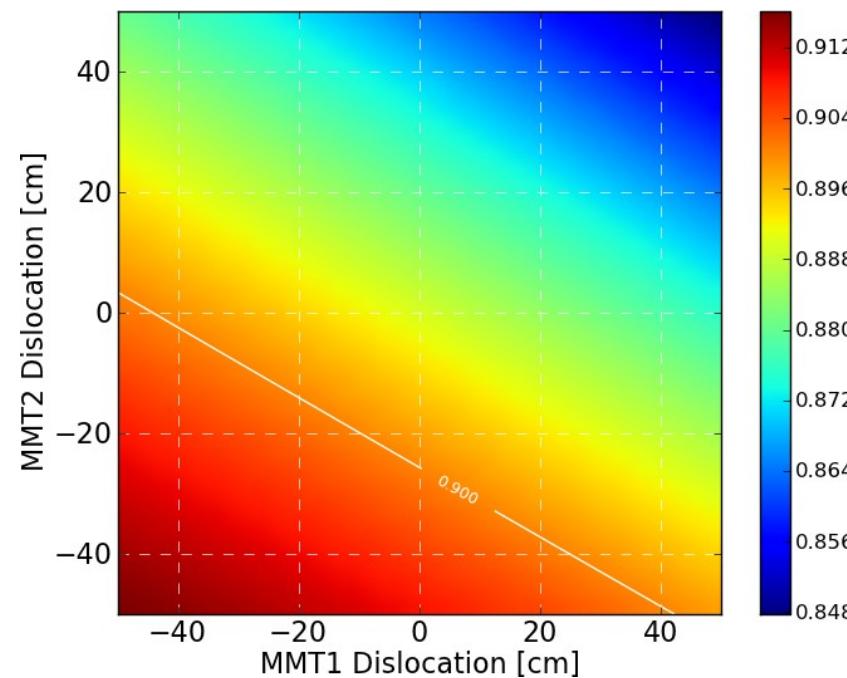
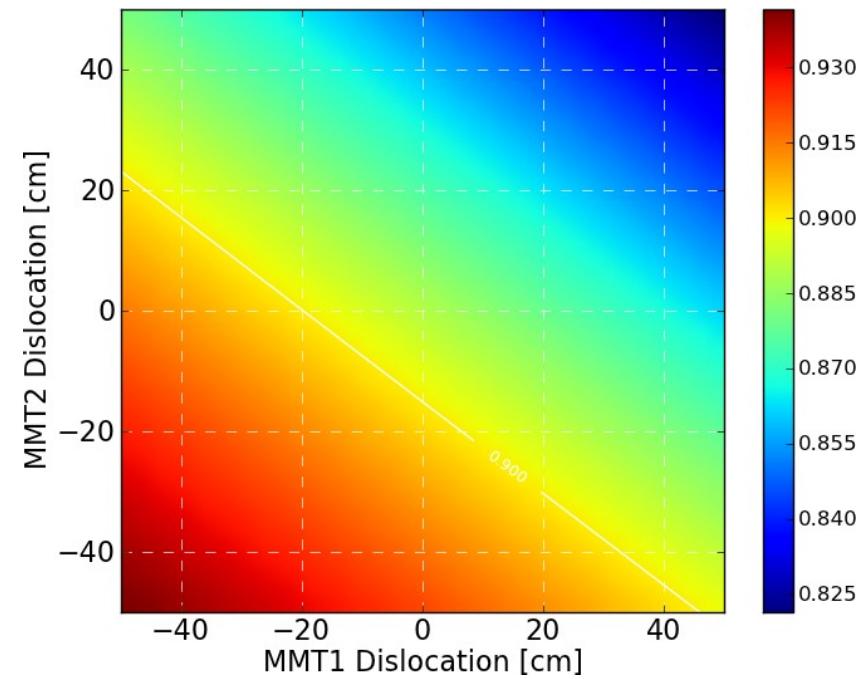


# Mode Matching (iLCGT-Ab2)

With PRM



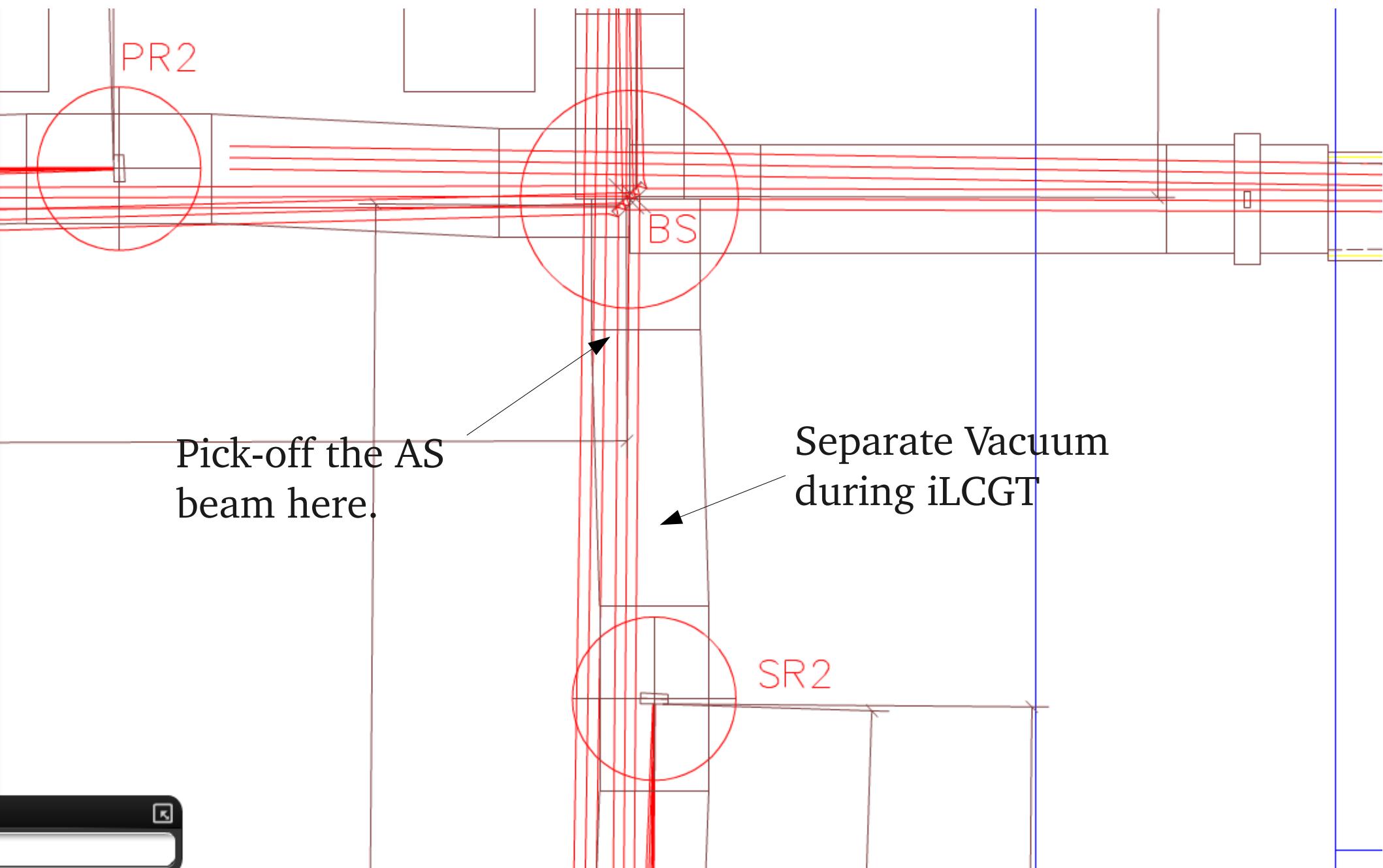
Without PRM



DRMI

JGW-G1200763-v1

# Vacuum Isolation of SRC



# Schedule

## Task list during tunnel excavation (to be finished by March 2014)

- Intensity noise, frequency noise requirements
- LSC/ASC Servo model including hierarchical actuation
- Frequency servo topology
- Servo model noise analysis
- Servo model implementation on RTS
- Green lock design
- Green injection system assembly
- Commissioning planning,
- Suspension positioning method
- Optical bench layout (with IOO)
- Analog electronics list up/Design

# Installation & Commissioning Scenario

ID	タスク名	期間	2014年				2015年			
			Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4
40	Suspension Installation for iLCGT	394日					Suspension Installation for iLCGT			
41	MC Suspension	1月			MC Suspension					
42	ETMX (StackB)	1月			ETMX (StackB)					
43	ITMX (StackB)	1月				ITMX (StackB)				
44	PRC, BS (StackB)	4月				PRC, BS (StackB)				
45	ITMY (StackB)	1月				ITMY (StackB)				
46	ETMY (StackB)	1月					ETMY (StackB)			
47	Type A Commissioning	435日					Type A Commissioning			
55	SRC SAS Installation	4.5月						SRC SAS Installation		
56	iLCGT IFO Commissioning	543日					iLCGT IFO Commissioning			
57	MC Lock	2月			MC Lock					
58	X-arm	3月				X-arm				
59	Michelson	2月				Michelson				
60	Y-arm	2月				Y-arm				
61	FPMI	2月					FPMI			
62	iLCGT Observation	1月						iLCGT Observation		

## Quality assurance

- Each component will be tested by corresponding subsystem (e.g. mirrors, laser, etc)
- The quality of MIF is the noise level of the interferometer
  - It is guaranteed that the quality will not meet the requirement at first
  - Thorough and careful planning for the commission is the best quality assurance

# Risk Management

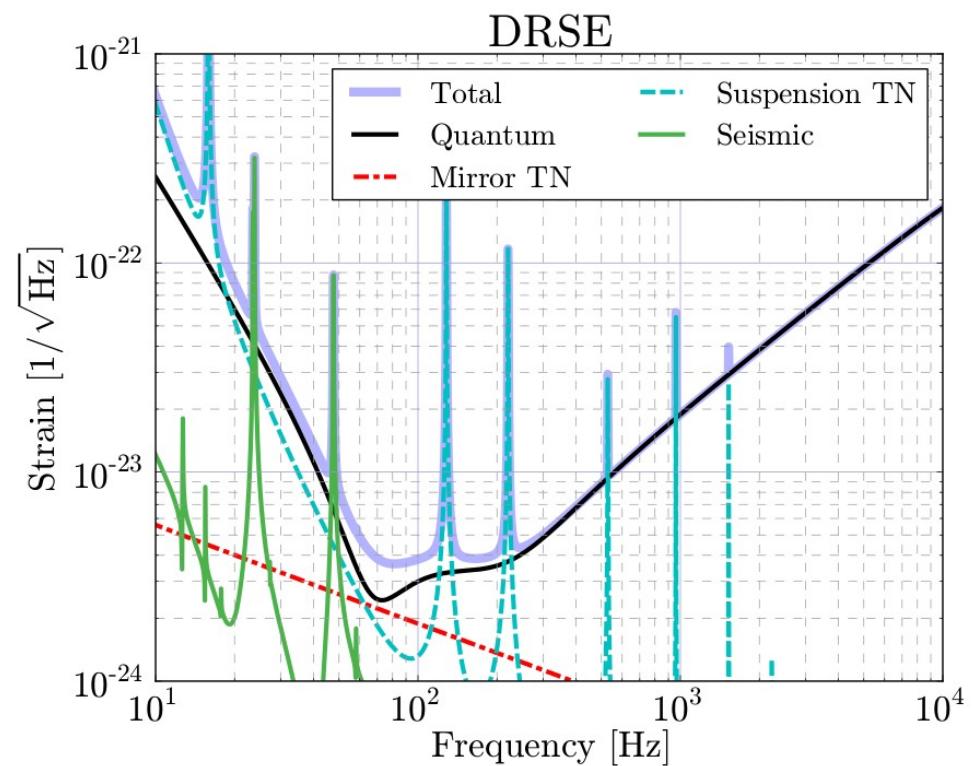
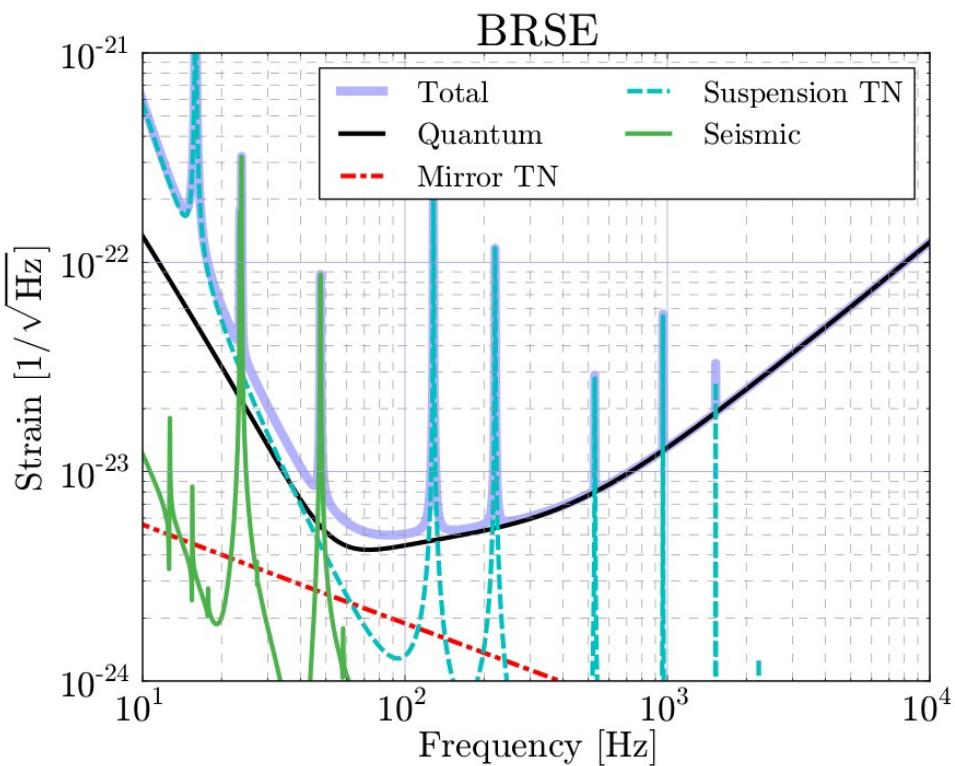
## Risk factors

- StackB is too noisy
  - => Strong damping, strong actuators at the expense of noise
- Laser frequency noise is too large
  - => Spend more time on the frequency stabilization servo
- Mirror quality is poor
  - => ....
- Commissioning takes too long (very likely to happen)
  - => Work harder folks !

bLCGT

# Requirements

Operate the interferometer with the following noise level  
Duty cycle > 90% (?)



# Preliminary Design

## Interferometer Parameter

Arm Finesse	1550	Arm Length	3km	PRG	10
SRM Reflectivity	85%	Input Laser Power	51W	PRC Length	66.6m
SRC Detuning	$3.5^\circ$	SRC Length	66.6m	MICH Asym.	3.33m
g1	-0.786	g2	-0.602	$g_1 \cdot g_2$	0.473
R1	1.68km	R2	1.87km		

For details:

<http://gwwiki.icrr.u-tokyo.ac.jp/JGWwiki/LCGT/subgroup/ifo/MIF/OptParam>

# **g-factor selection**

## **Beam Size**

**ITM: 3.5cm, ETM:4.0cm**

- 4.0cm is the maximum spot size for 22cm mirror.
- 3.5cm beam at the central part is easier to handle.
- Since ITMs have less coating layers, the thermal noise is not compromised by 3.5cm beam size on ITMs.

**Decided:**  $g_1 \cdot g_2 = 0.473$

## Candidates

- $g_1 = 0.786, g_2 = 0.602$  ( $R_1 = 14\text{km}, R_2 = 7.5\text{km}$ )
- $g_1 = -0.786, g_2 = -0.602$  ( $R_1 = 1.68\text{km}, R_2 = 1.87\text{km}$ )

# Arm Cavity HOM Resonances

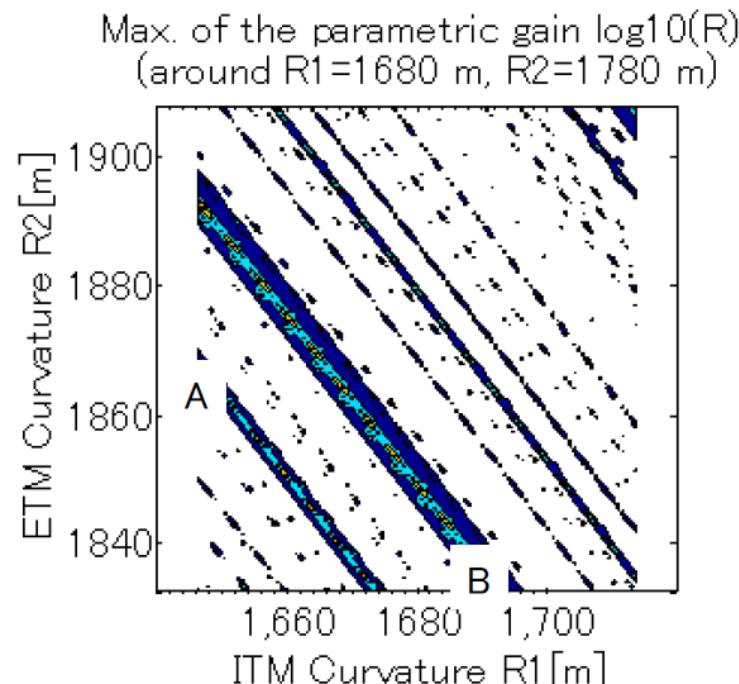
No significant difference between Positive and Negative

See JGW-G1200789

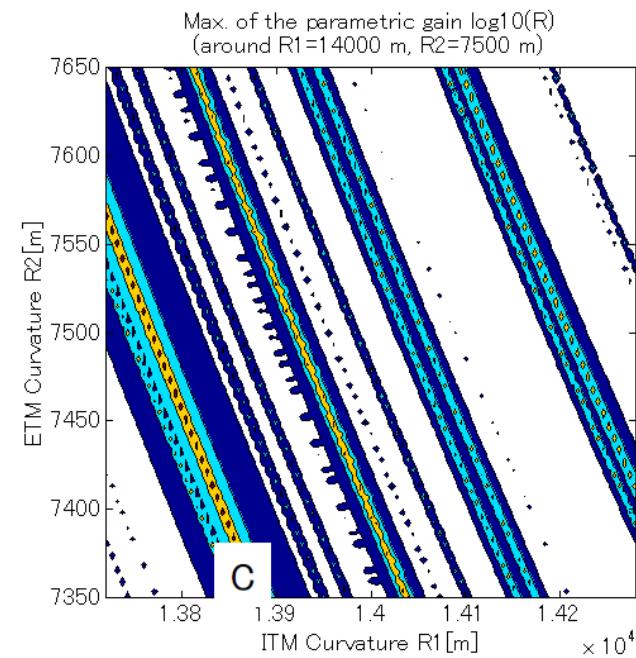
## Parametric Instability

Colored area = Unstable mode exists

Negative g



Positive g



See JGW-T1200787

## Sidles-Sigg Instability (ASC)

- WFS UFG for Pitch has to be lower than 1Hz
- For arm power > 330kW, Pitch instability frequency > 1Hz for positive g-factor
- Negative g-factor never makes Pitch unstable
- Current arm power (compromised to deal with high sapphire absorption) = 250kW --> even positive g-factor is OK
- Original (desirable) arm power = 376kW  
--> positive g-factor is not an option

### Conclusion

Negative g-factor is better

Positive g-factor limits us to operate only with low power

# Sideband Resonant Conditions for Signal Extraction

## Signal Ports

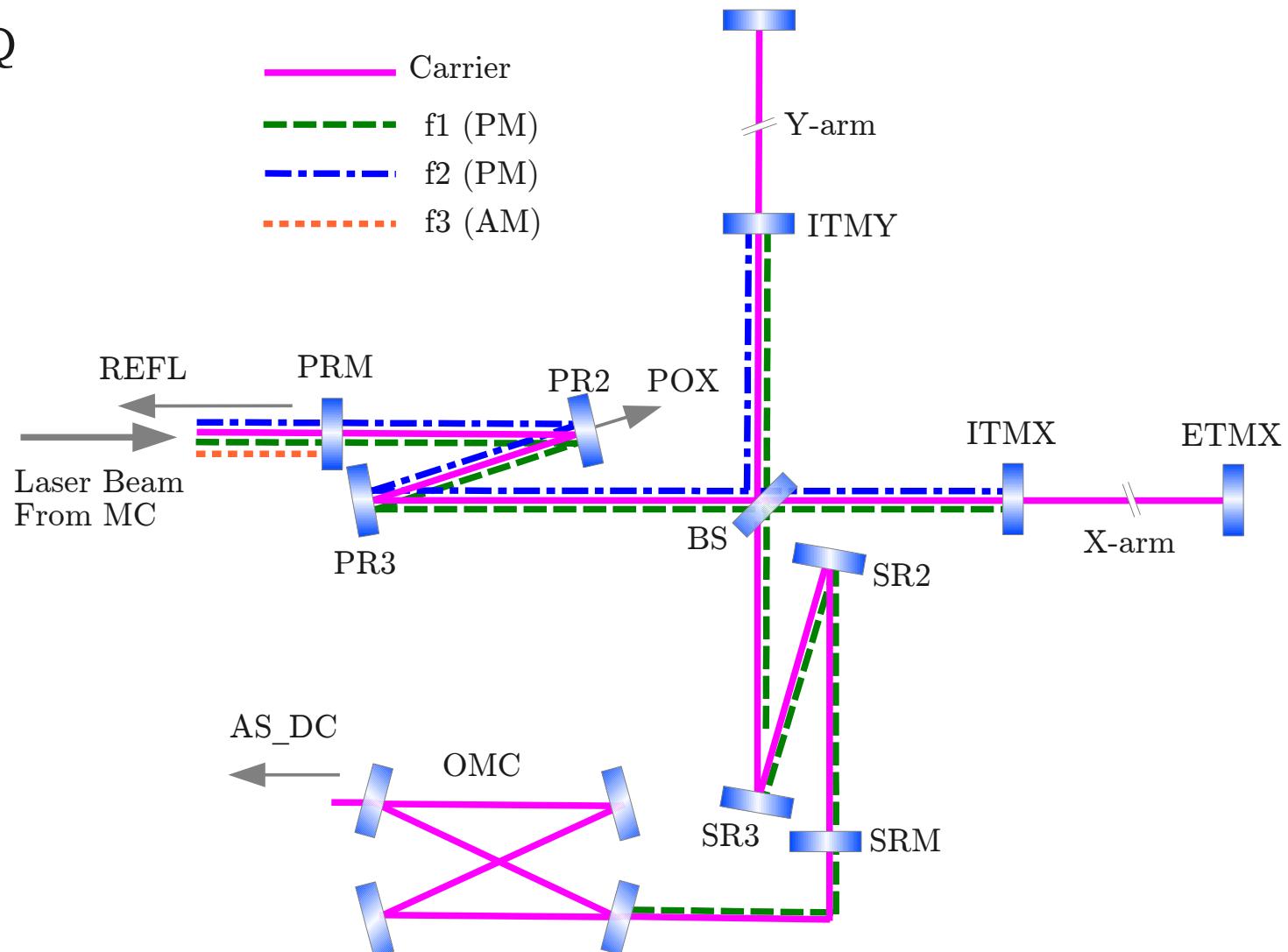
DARM: AS\_DC

CARM: REFL\_1I

MICH: REFL\_1Q

PRCL: POP\_2I

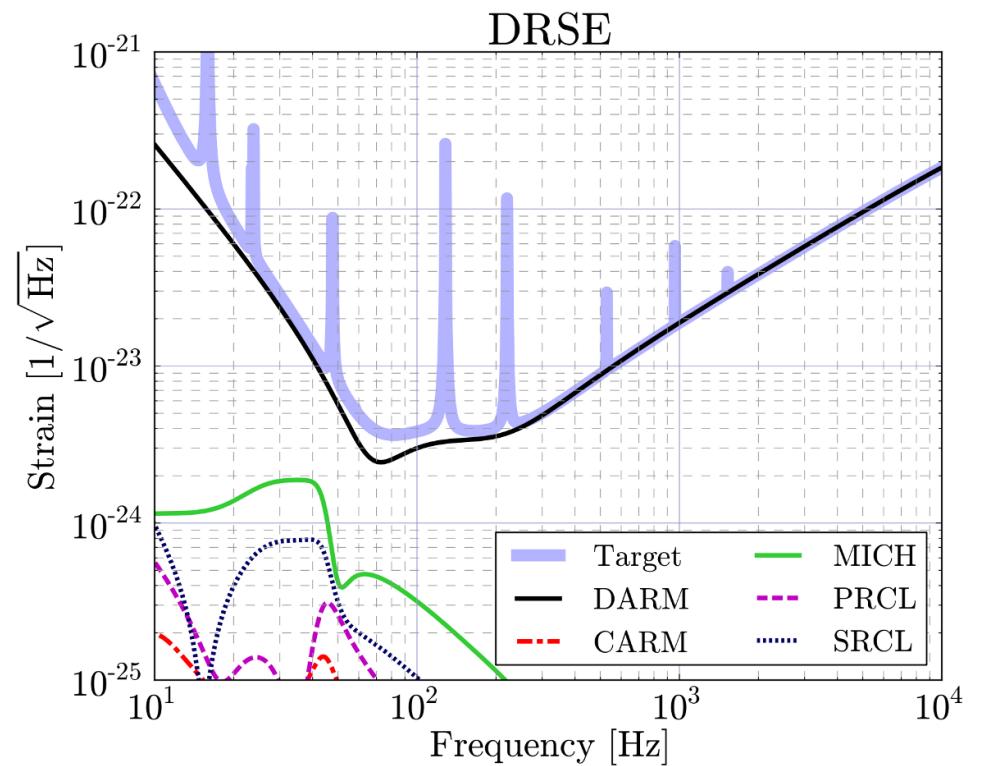
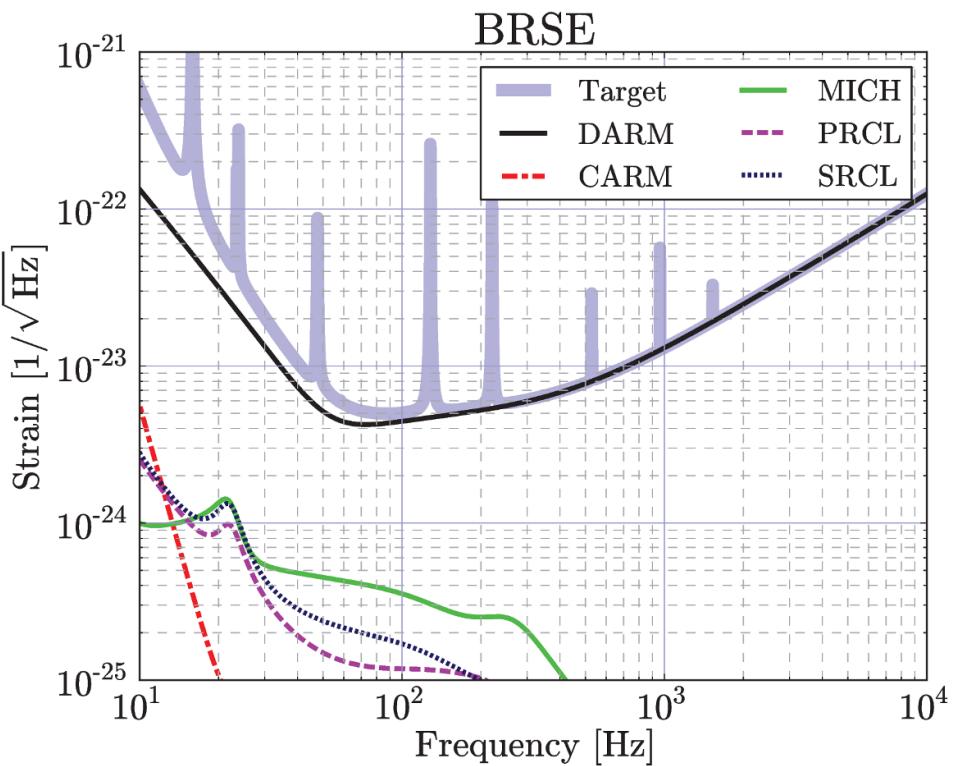
SRCL: POP\_1I



# LSC Loop Noise Couplings

UGF DARM: 200Hz, CARM: 10kHz, Others: 50Hz

Feed Forward Gain: 100



# ASC

## WFS+OpLev

WFS Sensing Matrix [W/mrad/sqrt(2/pi)]

(Gouy phases at POP A:80.8, POP B:42.2 REFL A:80.6, REFL B:-0.9, AS A:89.0, AS B:-1.0, TR A:-67.8 deg)

だいたい  
対角化できてる ← 制御  
自由度

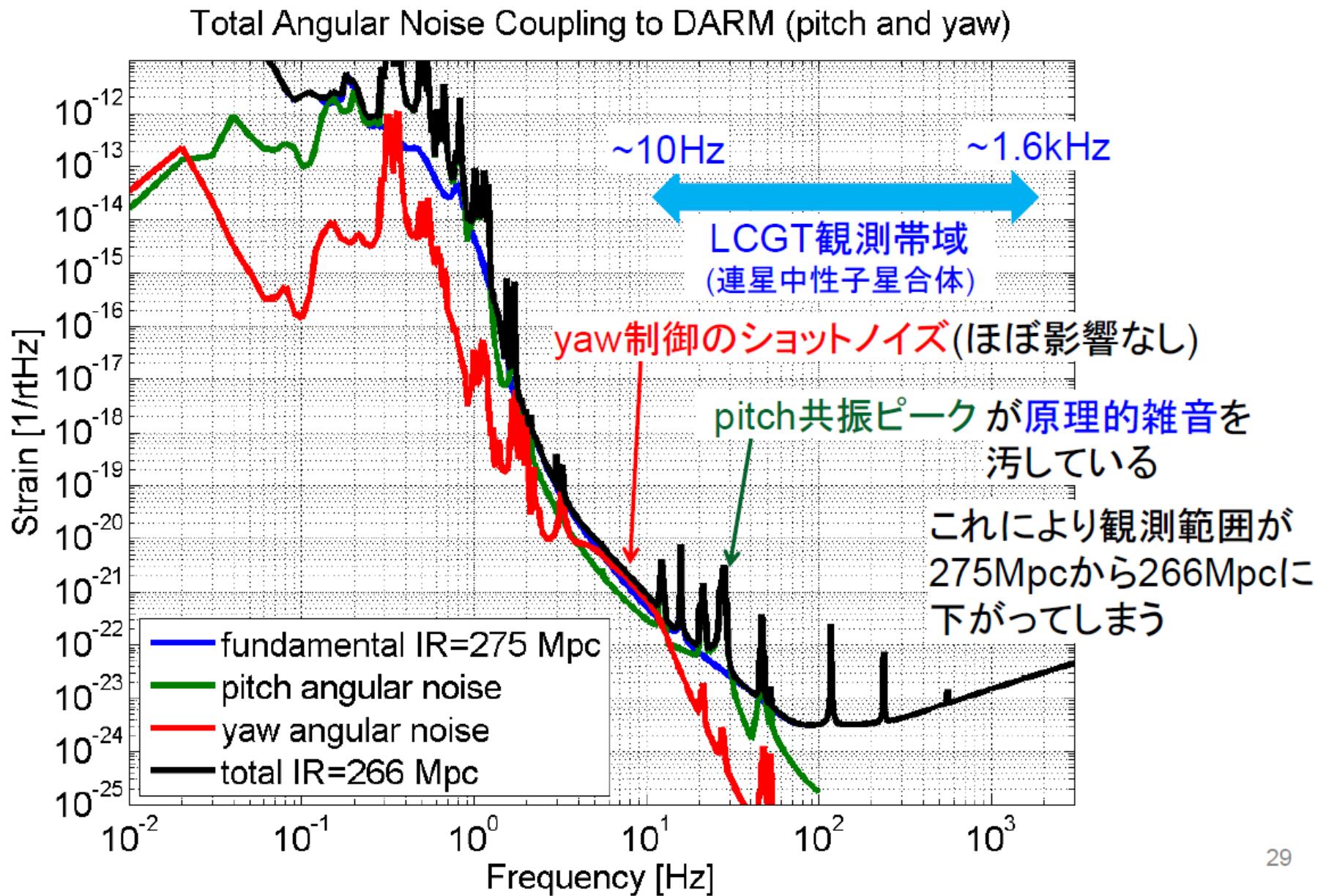
	CS	CH	DS	DH	BS	PR3	PR2	PRM	SR3	SR2	SRM
TRX_ADC	-12.89	-2.36	-12.89	-2.36	0.00	-0.01	-0.00	-0.00	0.00	0.00	0.00
REFL_A1I	-29.45	-156.82	-0.00	-0.01	0.13	0.85	0.45	3.96	-0.04	-0.00	-0.00
TRY_ADC	-12.89	-2.36	12.89	2.36	-0.01	-0.01	-0.00	-0.00	-0.00	-0.00	-0.00
AS_A1Q	0.00	0.00	0.28	1.49	0.00	-0.00	-0.00	-0.00	0.00	0.00	0.00
AS_B1Q	0.00	0.00	-0.02	-0.00	-0.01	0.00	0.00	0.00	0.00	0.00	-0.00
POP_A2I	-6.83	2.65	0.02	-0.01	3.95	11.31	1.47	1.30	-0.00	-0.00	-0.00
POP_ADC	-0.09	0.08	-0.00	0.00	0.07	0.16	-2.72	-2.35	0.00	0.00	0.00
REFL_B1I	2.08	0.30	0.00	-0.00	-0.94	-2.84	-0.37	12.12	-0.29	-0.04	-0.03
POP_B1I	0.07	0.01	0.00	-0.00	0.02	-0.03	-0.00	-0.01	-0.07	-0.01	-0.01
AS_ADC	1.07	-0.93	0.29	-0.10	0.13	-1.01	-0.13	0.87	-0.91	-0.12	0.80

数字の色は  
信号の強さ  
 $\times 10^{-3}$

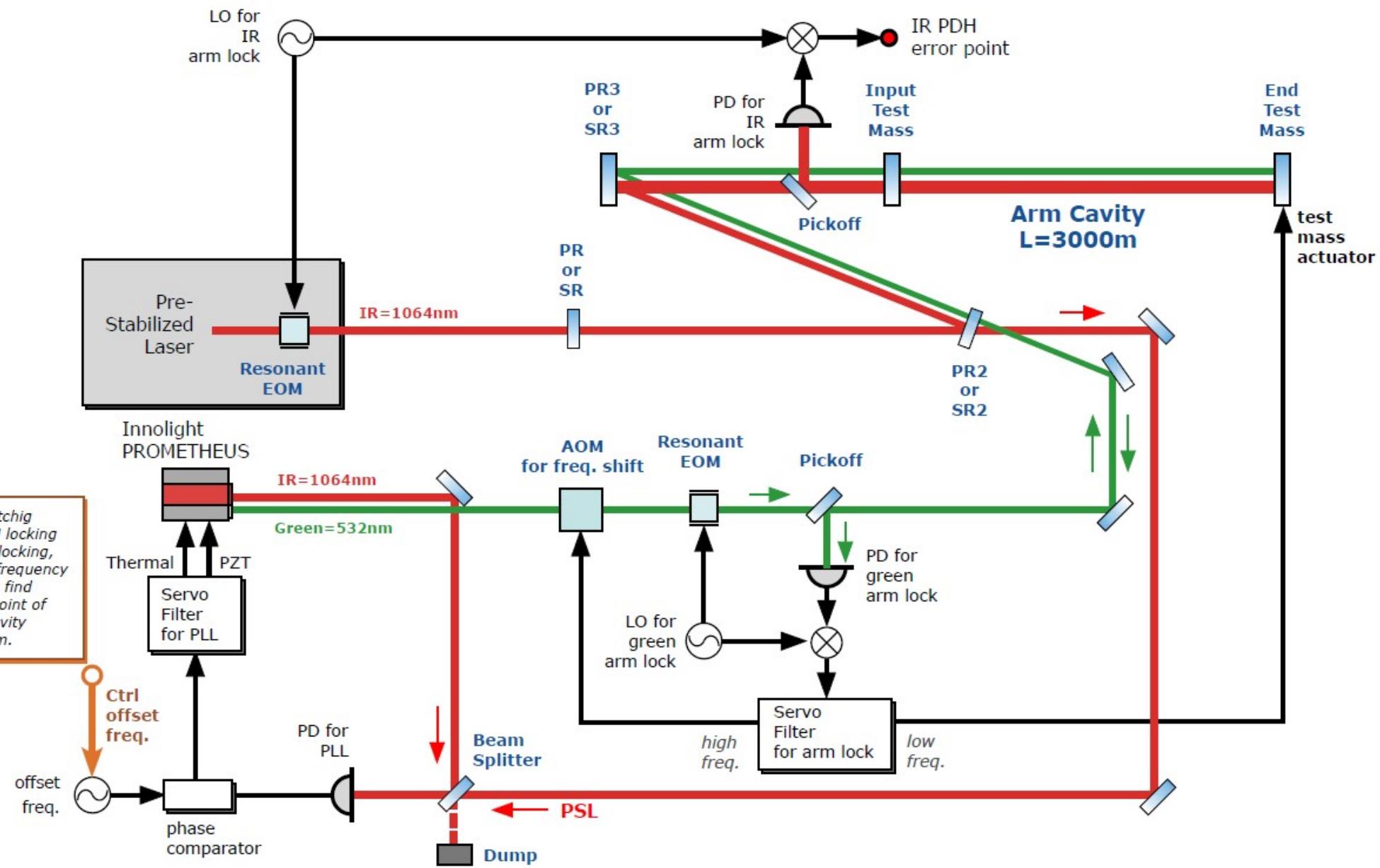
↑ 選択した信号取得ポート

信号が出にくいためSR2は  
WFSでは制御しない

# Total Angular Noise Couplings to DARM

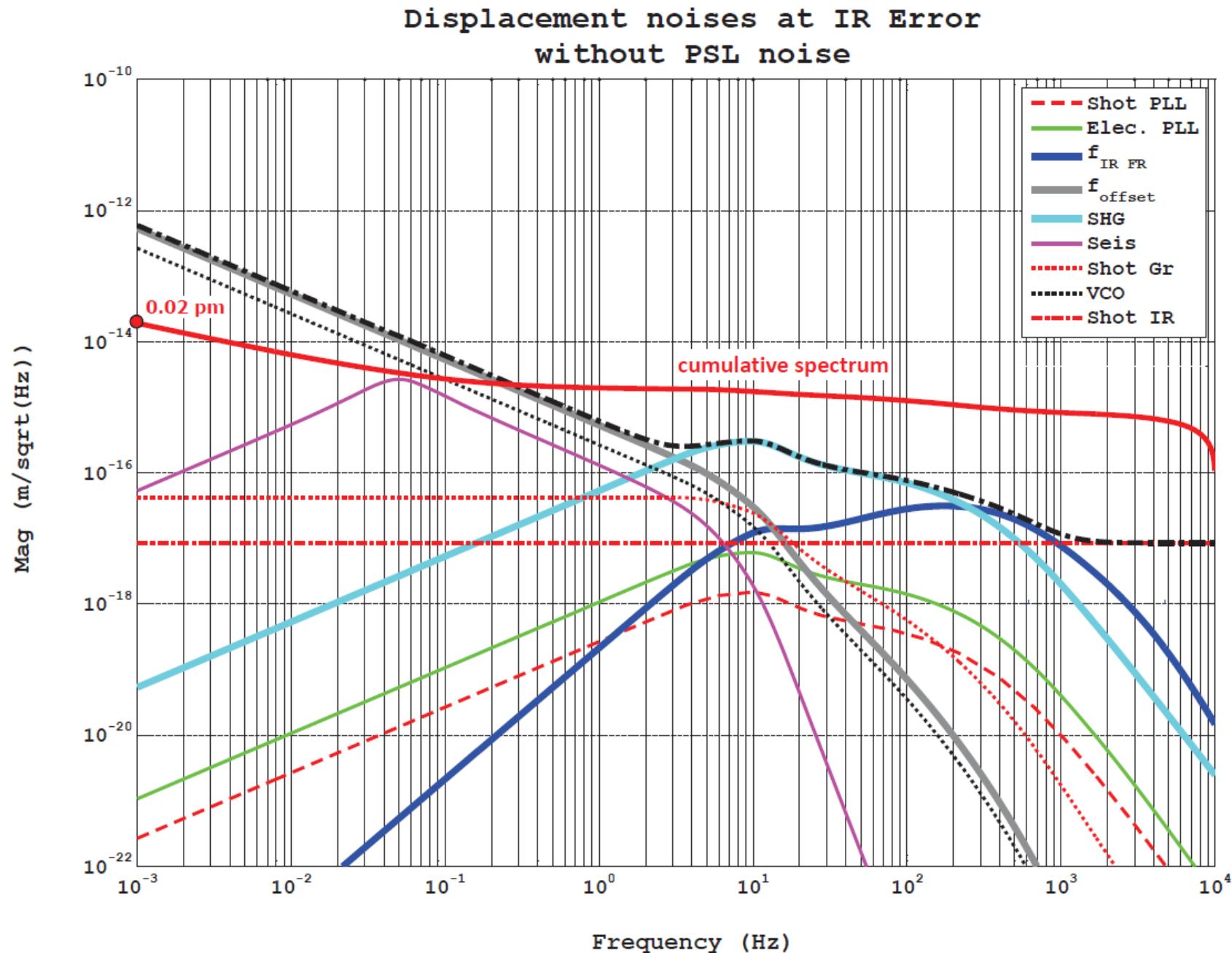


# Green Lock Setup



# Arm Cavity Stability after Green Lock

Requirement: 0.3pm RMS



## Relevant documents

MIF design procedure: JGW-G1100604

LSC design: arXiv:1111.7147

ASC: JGW-G1100608, JGW-G1100533

g-factor selection: JGW-G1200789, JGW-T1200787, JGW-G1200808

Input Mode Matching: JGW-G1200763

Parametric Instability: JGW-T1200787

Recycling Cavity Adjustment: JGW-T1100512

Wedge Angle Error Tolerance: JGW-T1100489

Green Lock: JGW-T1200788

# Schedule & Installation Scenario

ID	タスク名	期間	期間											
			2016年			2017年			2018年			2019年		
			Q4	Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4	Q1	Q2	Q3
64	Change Suspensions	376日			Change Suspensions									
65	ETM	3月			ETM									
66	ITM	3月				ITM								
67	Aux. Mirrors	4.5月	Aux. Mirrors			Room Temp. RSE								
68	Room Temp. RSE	481日					Room Temp. RSE							
69	Silica DR Interferometer	4月			Silica DR Interferometer									
70	PRMI	1月				PRMI								
71	DRMI	1月					DRMI							
72	RSE	6月					RSE							
73	Cryogenic RSE	6月						Cryogenic RSE						
74	First Science Run	1月					First Science Run							
75	IFO Tuning	5月						IFO Tuning						
76	Observation	365日						Observation						

## Prototype Test

- ISC simulation using virtual interferometer on RTS
- Green injection table will be tested beforehand  
(Kashiwa ? NAOJ ?)

## Quality Assurance

Commissioning is QA for MIF

# Risk Management

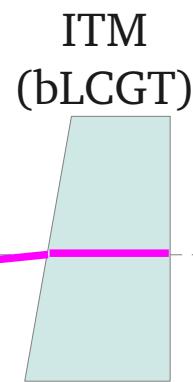
## Risk factors

- Arm cavity loss is too large: PRC under-coupled  
=> Prepare a spare PRM with lower reflectivity
- Arm cavity reflectivities are so matched that the homodyne phase cannot be set to around  $45^\circ$   
=> Forget about BAE
- Mirror quality is poor  
=> ....
- Commissioning takes too long (very likely to happen)  
=> Work even harder folks !
- Lack of man power  
=> Get money to hire people

# Appendix

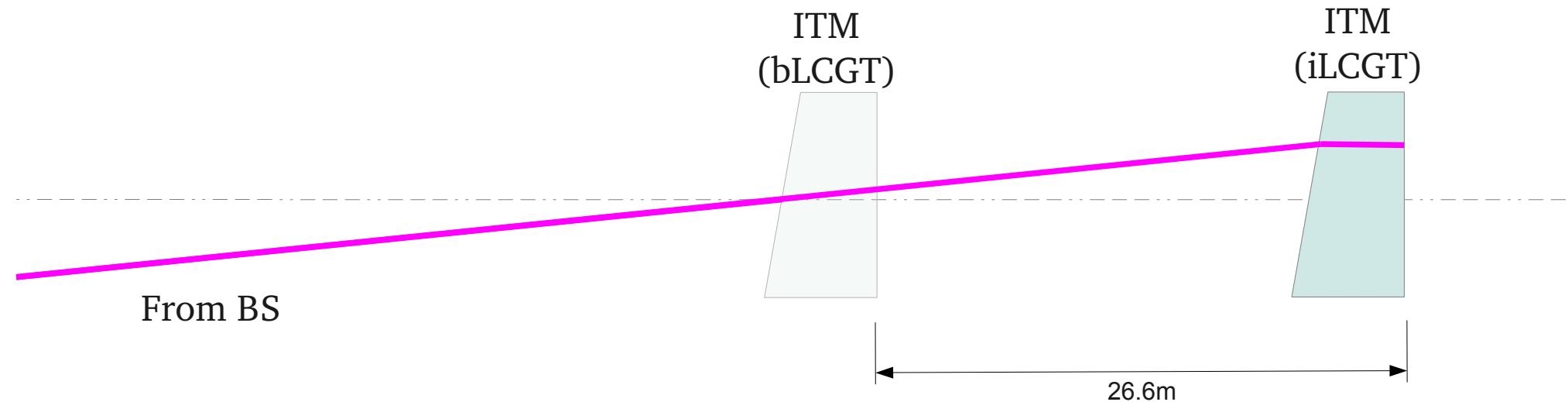
ITMにWedgeが付いているので  
斜めから入射する

From BS



腕共振器光軸

そのまま26.6m先にITMを動かすと、中心にビームが当たらない

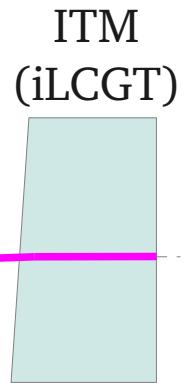
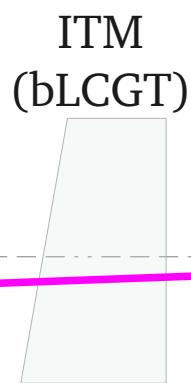


# 調整方法1

- BS, PR3を動かす
- 最大移動量2cm
- SRCも調整

PR3とBSの位置と向きを調節  
入射ビームの位置と角度を変える

From BS



Wedge角も変える

## 調整方法2

- ITMを横に動かす
- 他のミラーには触れない
- GVの窓を通らない

