# Status of seismic attenuation and suspension design and construction

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JGW-G1100524-v0

## Prototyping strategy

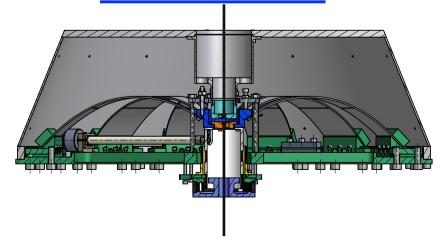
Seismic attenuation design is modular

 Every relevant part of the system is prototyped

Prototypes are tested before production

#### Standard filter

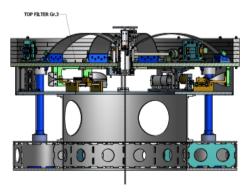
- Prototyped
- Tested in NIKHEF
- More tests ongoing
- Ordered (19 units)
- T1100450-v7 Gr.2
- T1100386-v1





## Top filter – Inverted Pendulum

- Prototyped
- Starting tests
- T1100452-v1
- T1100450-v7 Gr.1-3-5-6-8

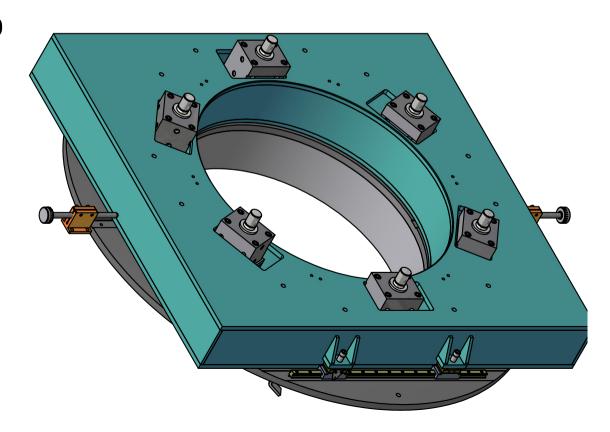


Please visit us downstairs

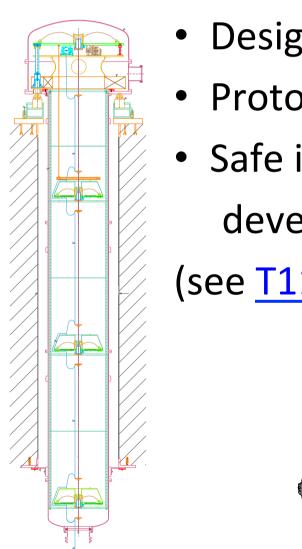


#### IP basement

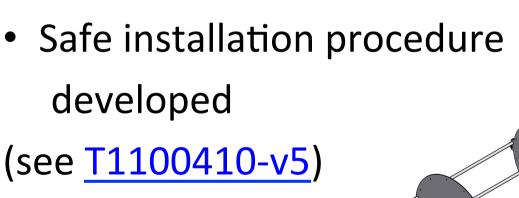
- Designed
- Prototype in construction
- T1100450-v7 Gr.0



#### Safety-Installation structure/procedure



- Designed
- Prototype in construction

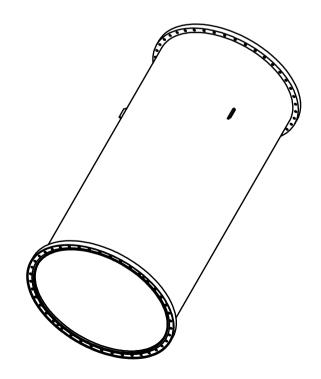


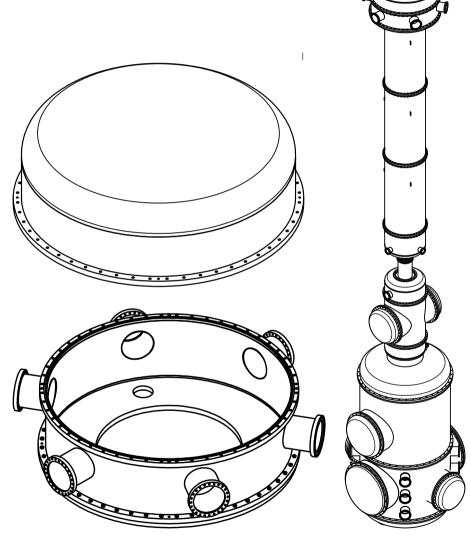
## Design

- Ongoing design work involves
- Cabling
- Vacuum
- Type-B seismic chains
  - Recycler mirrors
  - Beam Splitter

### Vacuum tanks

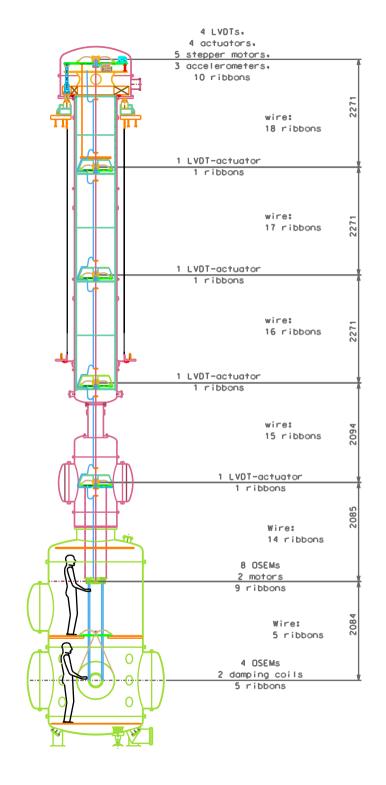
- Being designed
- T1100418-v3





# UHV cabling and connectoring

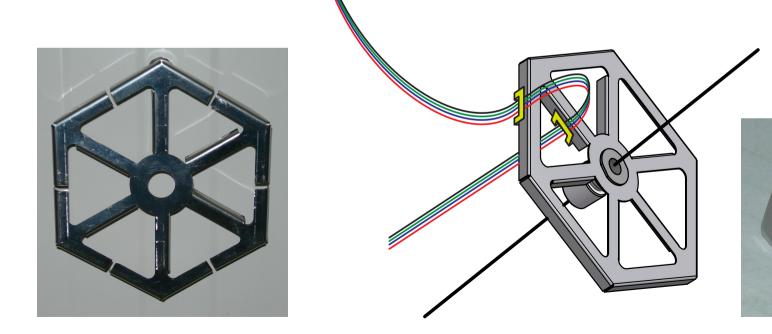
- Suspended chain
  - 18 ribbons
  - 144 conductors
  - 15 m extension
- Pre-isolator
  - 10 ribbons
  - 80 conductors
- Low electrical and mechanical noise required



## UHV cabling and connectoring

 Routing scheme being designed (see <u>T1100499-v3</u>)

• Sample prototype components in construction



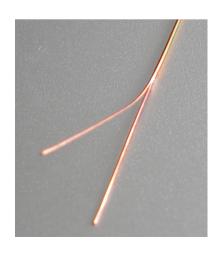
## UHV cabling and connectoring

- Cable type identified
- Connector strategy provisionally chosen (see <u>T1100499-v3</u>), designing connector housings
- Samples being procured







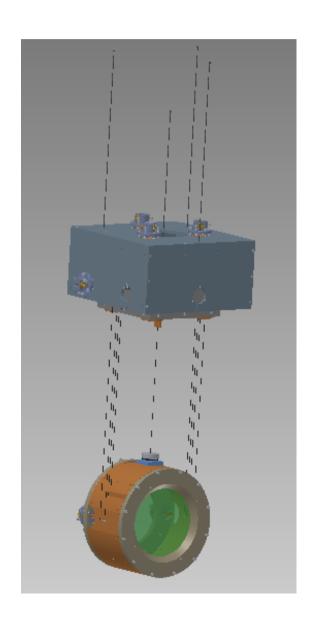


## Type-B payload

 Being Designed according to simulations (see Takanori's presentation)

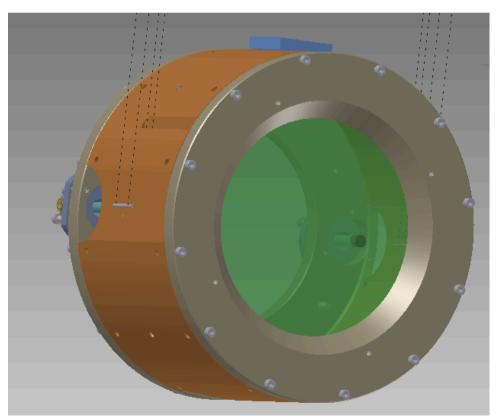
D1100470-v6

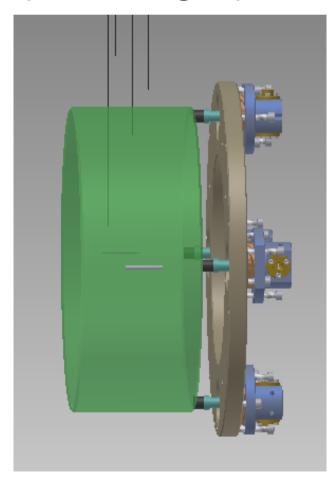
 Decided for a concentric design, despite geometric difficulties
 D1100542-v1



## Recycler mirror controls

- Four wire suspension
- Thin wall concentric recoil mass (Titanium gr.5)
- OSEM sensor actuators



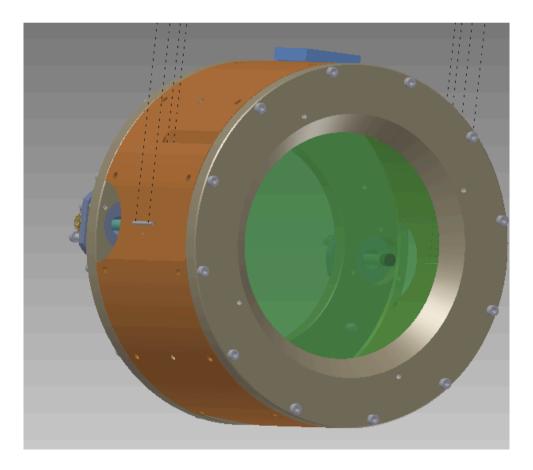


#### Recoil mass controls

• Eddy current mitigation:

Titanium recoil masswith Scalloping

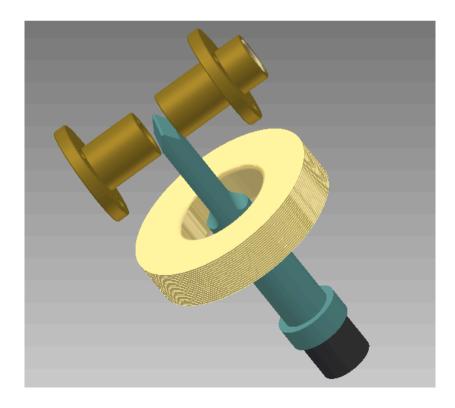
OSEM support plate
 and OSEM coil support
 out of C-loaded PEEK



## OSEM working principle

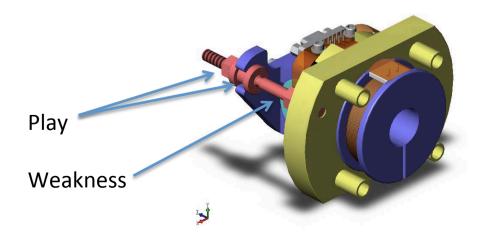
- Position sensor: LED-photodiode pair reads shadow of mirror's flag
- Actuator: Coil apply force on magnet at base of flag

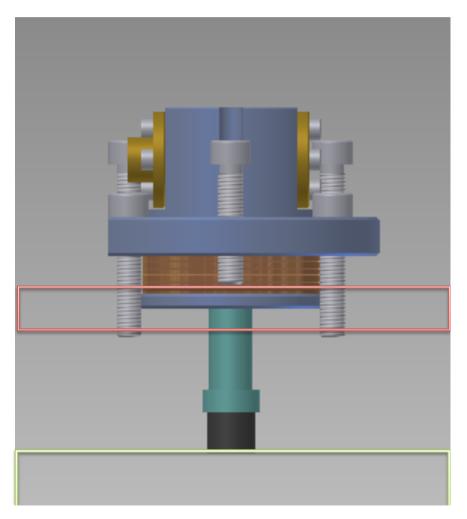




#### OSEM mechanical structure

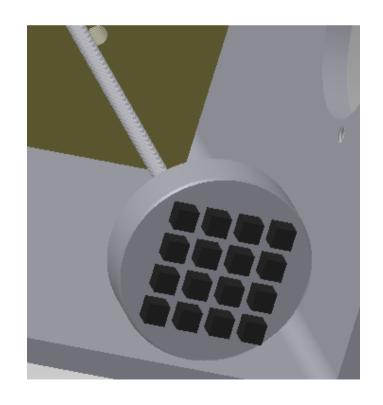
- Three pulling screws
- Three pushing screw
- Allows zero-settings
- While guaranteeing mechanical stability (screw play elimination)

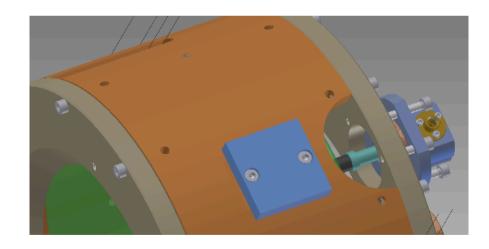




## Modal damping

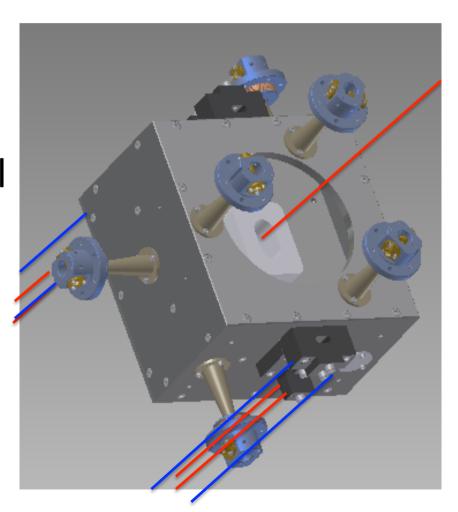
 Whip from intermediate mass, with magnets, causes Eddy current damping on pad on mirror recoil mass





#### Intermediate mass structure and controls

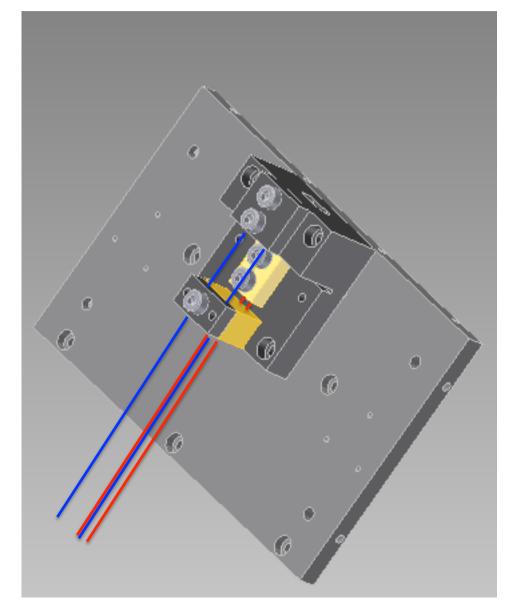
- Suspends mirror and its recoil mass
- Suspended from a central wire from a small GAS filter
- Controlled from a recoil mass suspended from the body of the GAS filter above



## Wire clamping structure

Double clamping

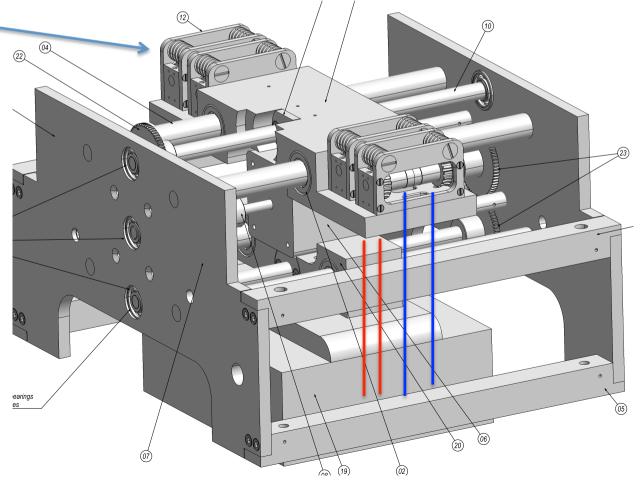
- UPPER For weight support
- LOWER For flexure point definition



## NIKHEF suspension wiring tooling

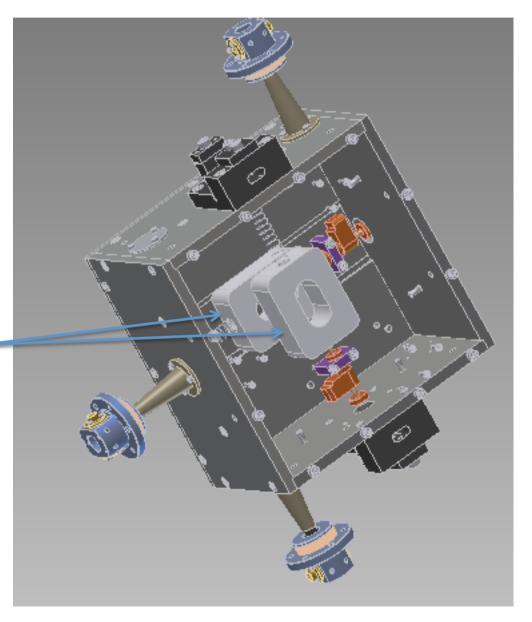
• The eight capstans will be used to pre-tension the four mirror and recoil mass wires before clamping

Jo Van Den Brand Eric Hennes Alessandro Bertolini From NIKHEF are joining the seismic group



#### Static attitude controls

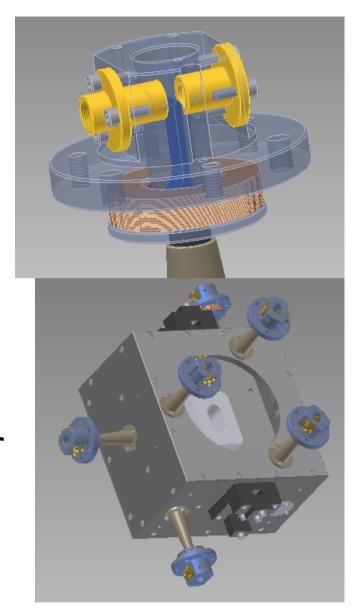
- Tuneable suspension point height for pitch-roll frequency reduction
- Longitudinal moving mass for pitch and roll



## Dynamic controls

 Shadow-meter/Voice-coil control units in all degrees of freedom

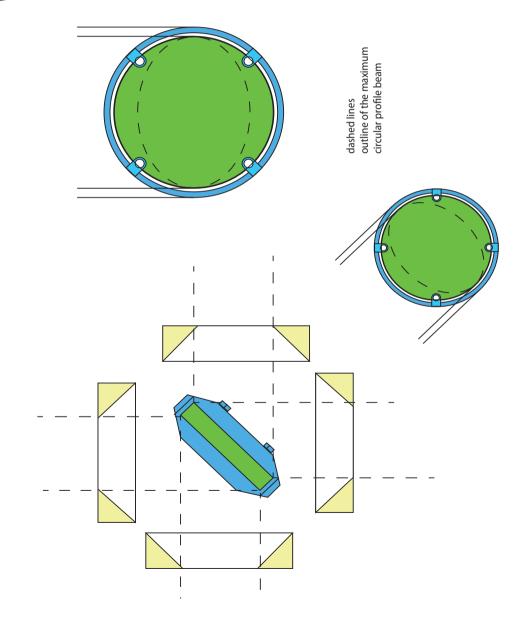
 Positioning of control units for diagonal or block control matrix



Support from Ludovico Carbone andreas Freise Birmingham Nick Lockerbie Strathclyde

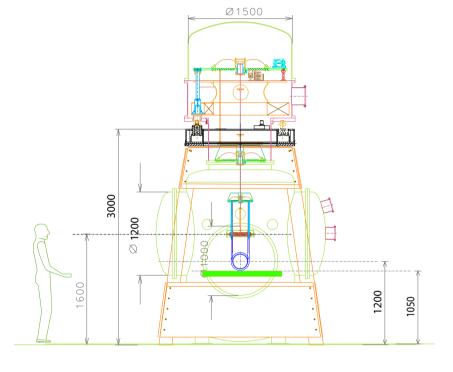
## Design ahead

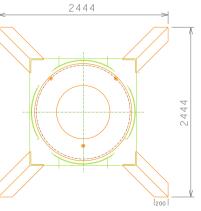
- Beam splitter suspensions
- Need to start its design <u>before</u> finalizing recycler suspensions



## Design ahead

- Type-B support structure
- Starting Design
- D1100470-v6





# Seismic and suspensions Conclusions

Production On track

Prototyping On track

Design On track

 As everybody else, swamped with work!

