LCGT Main Interferometer Subsystem

**Type B Review** 

2011/3/1@ICRR

Y. Aso on behalf of the LCGT MIF Working Group

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### Definition of the Subsystem

Main Interferometer

FP arms, PRC, SRC, Michelson, (OMC)

Length Control, Alignment Control, Lock Acquisition

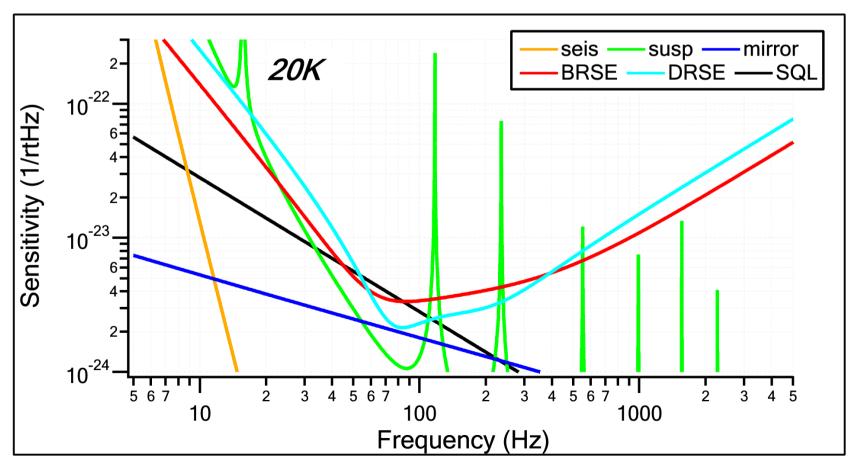
Commissioning

- No Hardware Manufacturing
- Design and Commissioning

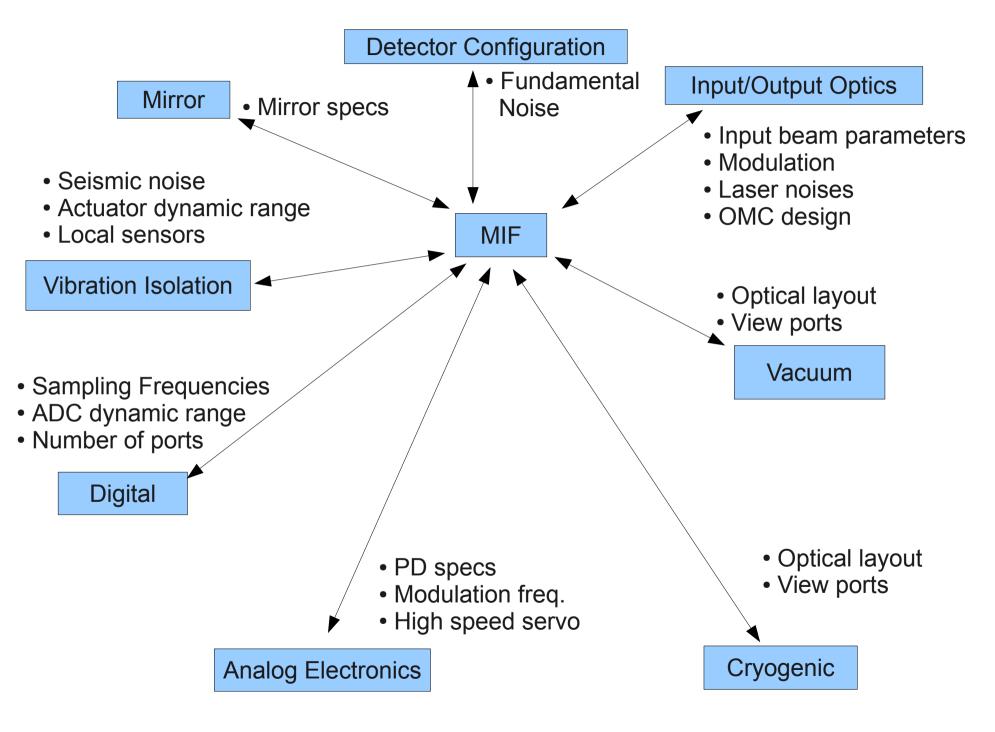
#### Requirements

- Design an interferometer which can achieve the target sensitivity of bLCGT
- Switchable between BRSE and DRSE
- Robust operation
- Efficient commissioning

#### **bLCGT** Target Sensitivity



## Interfaces with Other Subsystems



# Contents

- Design of bLCGT Main Interferometer
- iLCGT design
- Activity plan during the tunnel excavation period
- Commissioning Schedule
- Risk Assessment

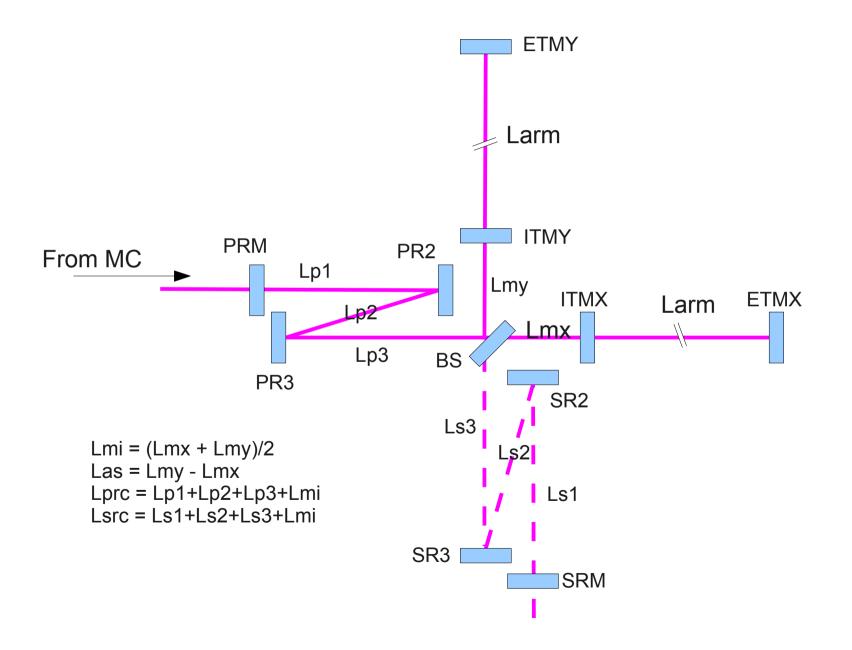
### Main Interferometer Design

#### Arm Cavity Design

- Angular Instability
- Parametric Instability
- Higher Order Spatial Modes
- Recycling Cavities
  - Modulation Frequencies
    - Length Sensing Schemes
  - Folding
    - Alignment Sensing
- Lock Acquisition Strategy
  - Green laser pre-lock
  - 3<sup>rd</sup> Harmonics Demodulation
  - Non-Resonant Sideband
- Optical Layout

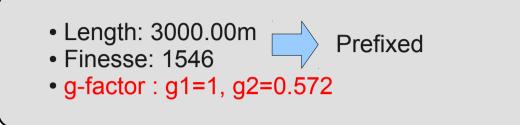
#### Overview

Dual Recycled Fabry-Perot Michelson Interferometer in RSE mode.



# Arm Cavity Design

#### Parameters



Arm Cavity g-factor

- Spatial Mode Stability
- Beam Spot Size => Thermal Noise
- Angular Radiation Pressure Instability (Sidles-Sigg effect)
- Parametric Instability

#### Beam Spot Size

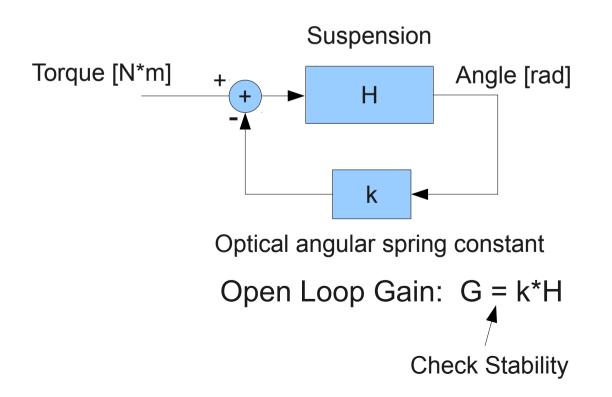
- Larger is Better for Thermal Noise
- 4.53cm@ETM => 0.6ppm diffraction loss
- 3.43cm@ITM
  - ITM coating is thinner than ETM
  - No problem for Thermal Noise

# Angular Instability

Sidles-Sigg Stiffness Matrix

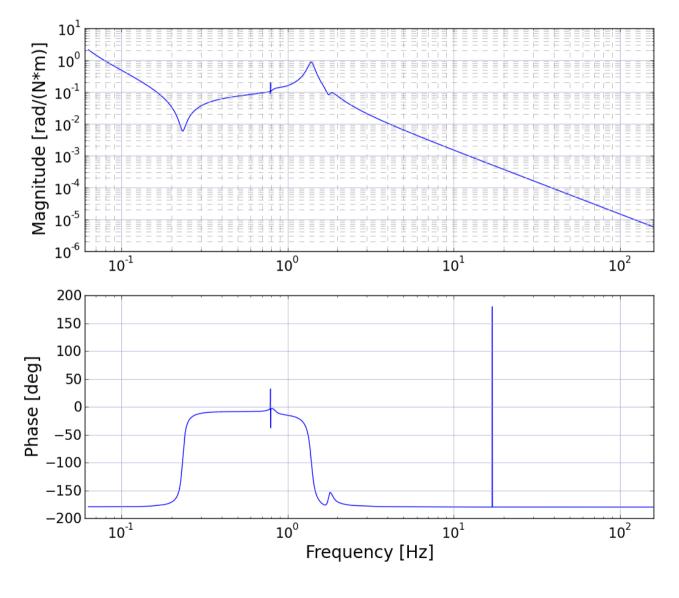
Angular Optical Spring Constant k [N\*m/rad]

Large Beam (ITM=3.5cm, ETM=4.5 or 4.2cm) 4.4, -33.8 (g1 = 1, g2 = 0.572) -4.6, 29.2 (g1 = -0.87, g2 = -0.6) Small Beam (ITM=ETM=3.5cm) 5.0, -19.3 (g1 = g2 = 0.586) -5.0, 19.3 (g1 = g2 = - 0.586)



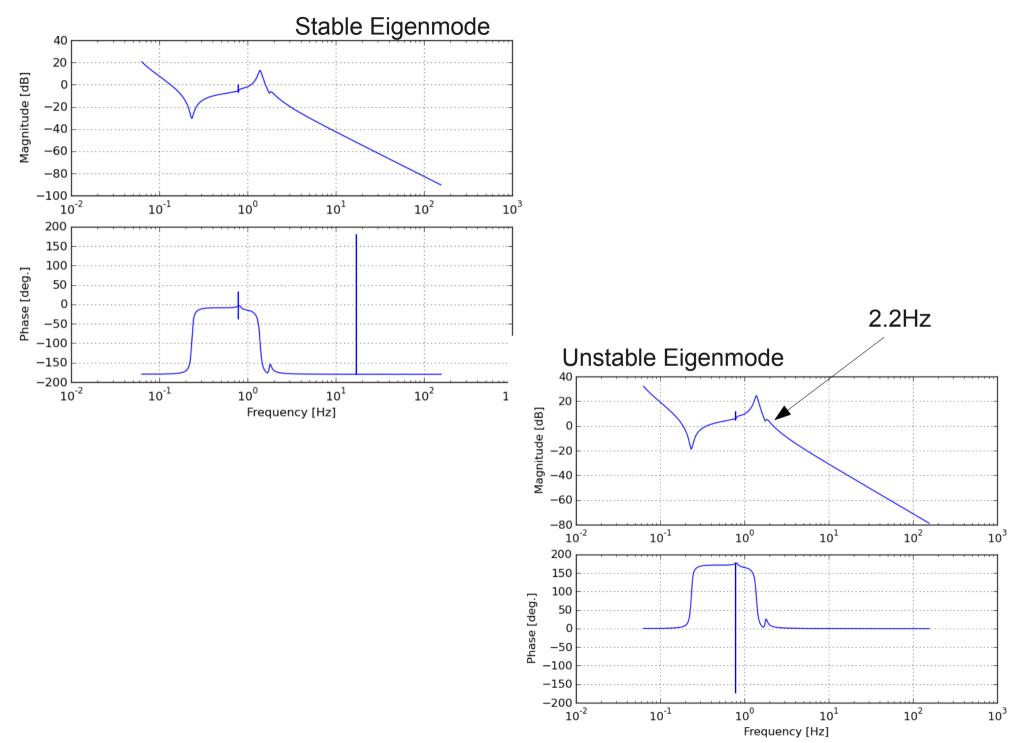
#### Suspension TF

Yaw Torque -> Yaw Angle

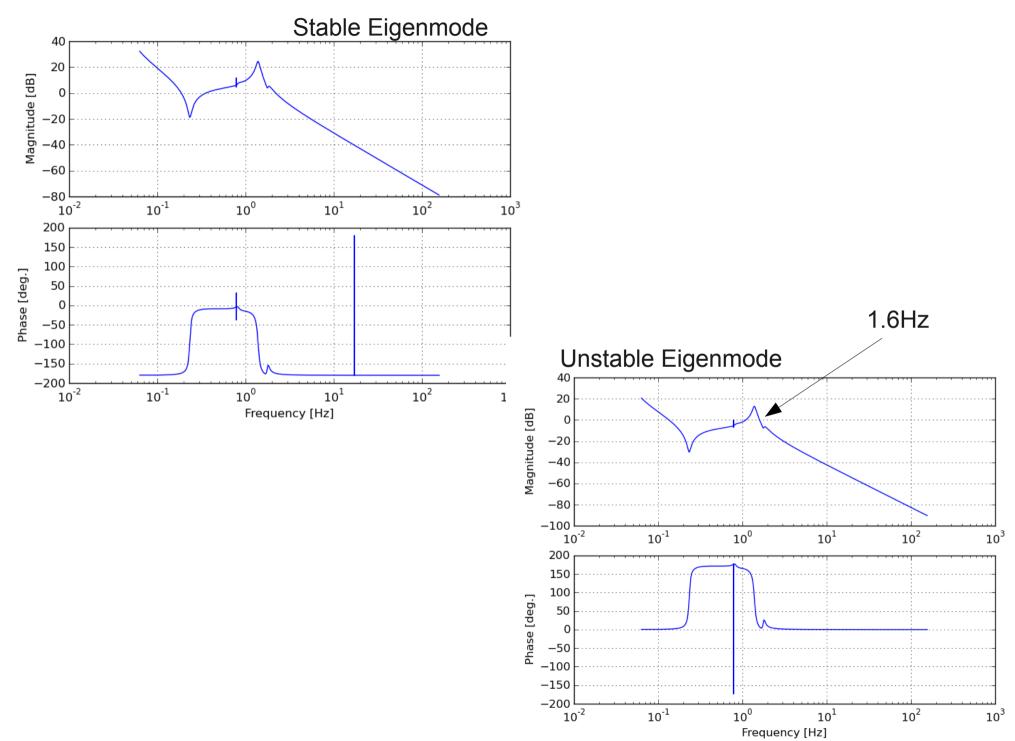


This is H

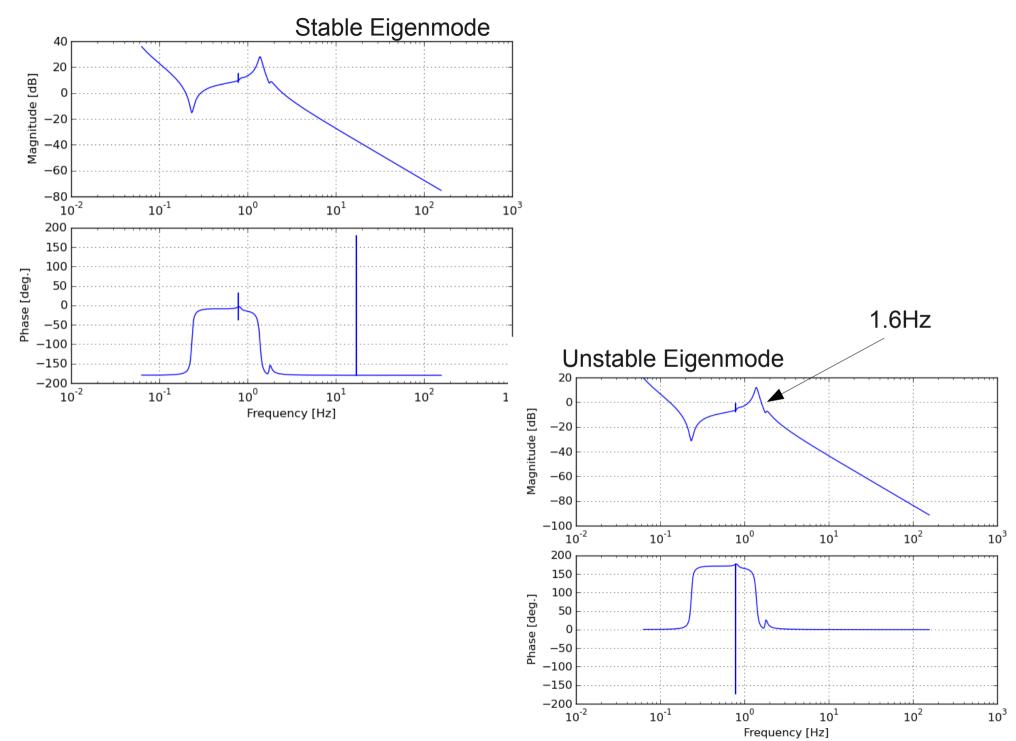
### Small beam, positive (g1=g2=0.586)



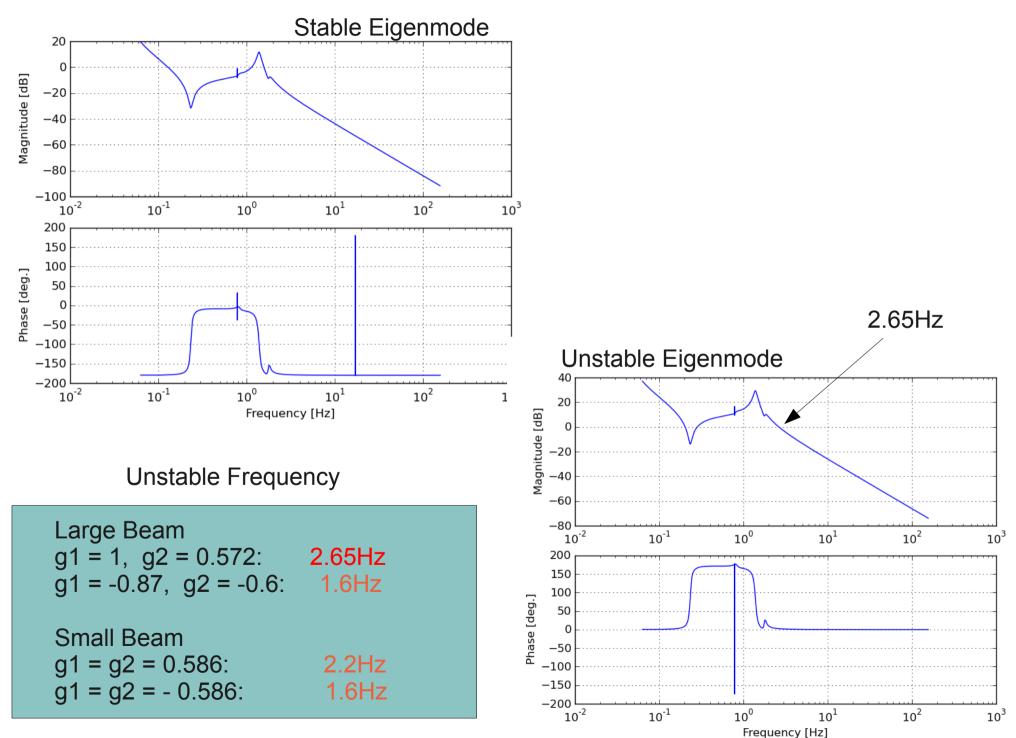
### Small beam, negative (g1=g2=-0.586)



Large beam, negative (g1=-0.87,g2=-0.6)

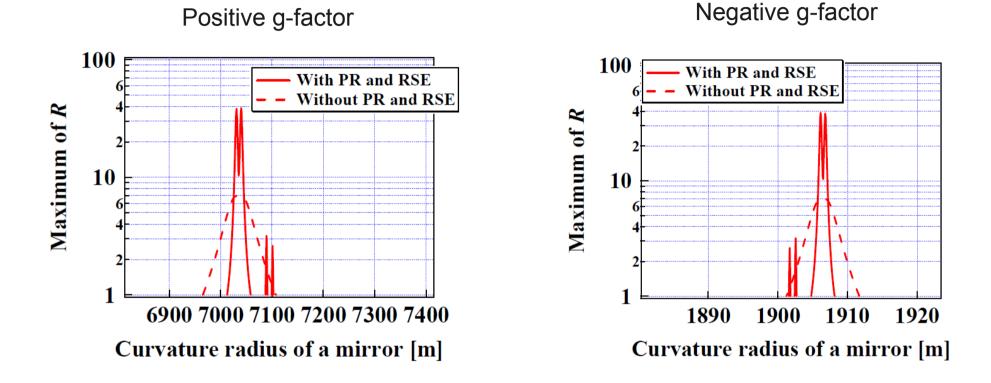


#### Large beam, positive (g1=1,g2=0.572)



#### **Parametric Instability**

There are dangerous regions to avoid in the g-factor space



The error requirement on the mirror ROC is stricter for the negative g-factor. by  $(R_{\rm p}/R_{\rm n})$ 

Negative g-factor: R ~ 1.9km<br/>Positive g-factor: R > 7kmNegative g-factor is about 3.7 times more<br/>severe to ROC error in terms of PI10m ROC error for 1.9km mirror -> 0.5% error<br/>100m ROC error for 7km mirror -> 1.5% error

# g-factor Comparison

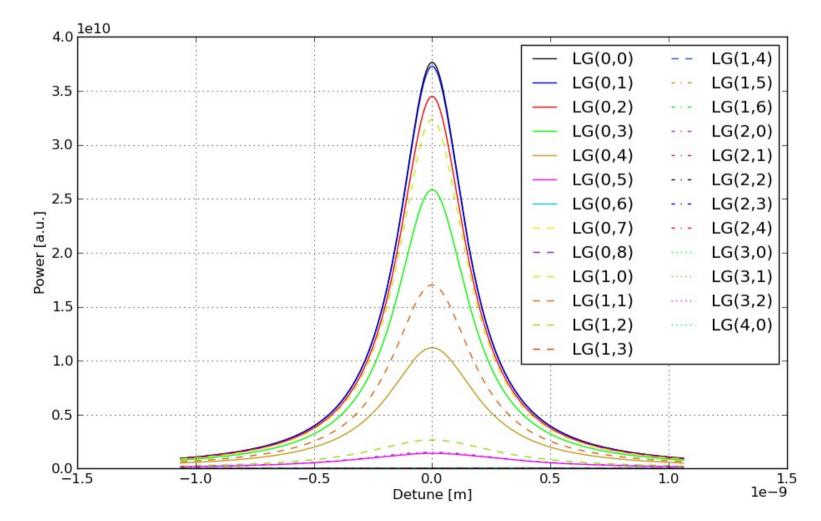
		Thermal Noise (IR) DRSE/BRSE [Mpc]	Optical Spring Unstable Freq.	PI	ROC
(a)	g1=1 g2=0.572	275/246	2.6Hz	Easy	ITM: >100km ETM: 7000m
(b)	g1=-0.87 g2=-0.6	273/245	1.6Hz	Severe	ITM: 1604m ETM: 1875m
(C)	g1=0.586 g2=0.586	266/241	2.2Hz	Easy	ITM: 7246m ETM: 7246m
(d)	g1=-0.586 g2=-0.586	266/241	1.6Hz	Severe	ITM: 1892m ETM: 1892m

#### **Arm Cavity Parameters**

Length	3000.00m	ETM ROC	7000m
ITM Reflectivity	99.6%	ETM Beam Size	4.53cm
ITM ROC	flat	g-factor	0.572
ITM Beam Size	3.43cm	Round Trip Loss	<100ppm
ETM Reflectivity	>99.9945%	Finesse	1546

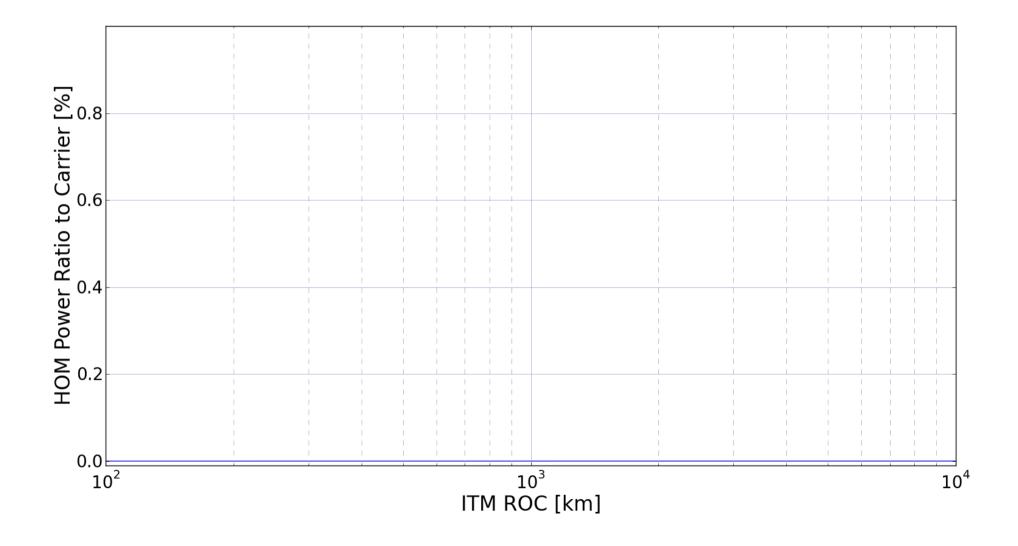
#### Higher Order Modes

- TEM00 resonance has to be isolated from higher order modes
- Higher order modes are large => Diffraction loss

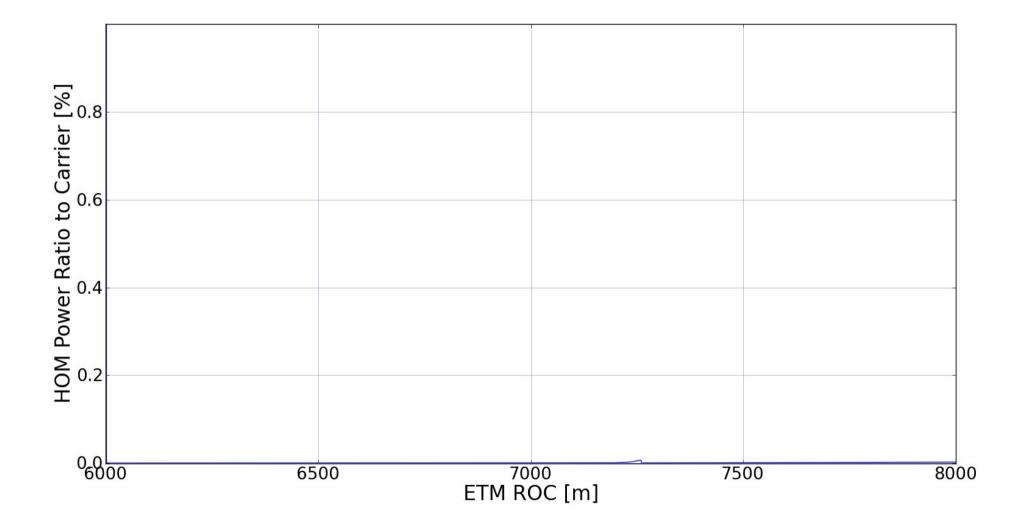


#### Resonant curves of LG(I,m) modes

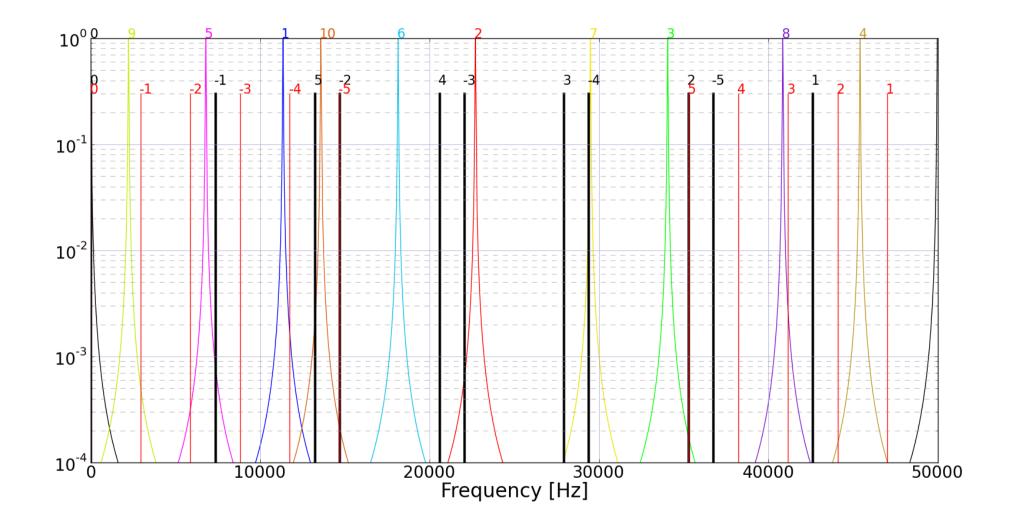
#### Maximum HOM Power, ITM ROC error



#### Maximum HOM Power, ETM ROC error



### HOM RF Sideband Overlap

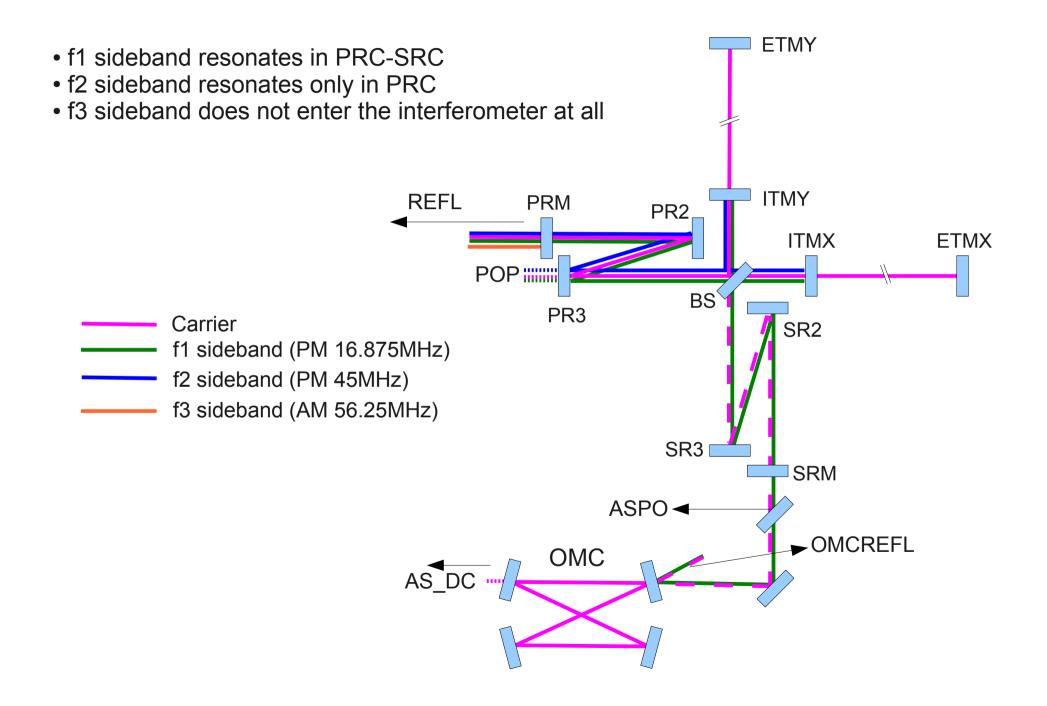


# Recycling Cavity Lengths and Modulation Frequencies

### **Constraints**

- Resonate RF sidebands in desired parts of the interferometer
  - f1 sees both PRC and SRC
  - f2 is only resonant in PRC
- MC length must not be too long (< 30m)
- Modulation frequencies should not be too high
  - PD and QPD response
- Modulation frequencies should not be too low
  - RF laser noise, CARM UGF
- Michelson Average Length ~ 25m
  - Cryogenic radiation shield = 20m (BS <-> ITM)
  - Schnupp asymmetry
- Not too large asymmetry
- Room for Folding

### **RF Sideband Resonant Conditions**



# **RC Length Parameter Scan**

There are many candidates of Lprc, Lsrc, Las which satisfy the resonant conditions

Parameter selection procedure

- Fix f2 to be 45MHz
  - Not too high, not too low
- Choose Las
  - MICH reflectivity for f2 = 100%
  - Las = 3.3m or 6.6m
- Choose Lprc
  - Resonate f2
  - 65m< Lprc <85m
- Choose f1
  - Integral (or half integral) multiple of the FSR of PRC
  - MC length must not be too long (GCD of f1 and f2 is large enough)
- Choose Lsrc
  - f1 is resonant in SRC <= anti-resonant in PRC</li>
  - f1 is anti-resonant in SRC <= resonant in PRC</li>
  - 65m < Lsrc < 85m

#### Still there are many candidates

- Finesse of PRC-SRC for f1 varies depending on the MICH reflectivity to f1
- Choose one with wide enough resonance to allow detuning of SRC by offset

#### Parameter Candidates

#### It is basically a matter of choosing f1 frequency

			-				· · · · · · · · · · · · · · · · · · ·	
f1/f2	PRC/SRC	f1(MHz)	MC(m)	Lp(m)	Ls(m)	ls (BRSE)	ls (DRSE)	linearity (DRSE)
5/6	anti/reso	37.5	20	70	70	0.00140	0.00061	-0.63183
2/7	anti/reso	~12.9	23	70	70	0.00403	0.00182	-0.59047
3/7	anti/reso	~19.3	23	70	70	0,00839	0.00416	-0.49474
2/8	anti/reso	11,25	27*	79.9	79.9	0.00312	0.00139	-0.60448
3/8	anti/reso	16.875	27	79.9	79.9	0.00670	0.00319	-0.53623
7/8	anti/reso	39,375	27	66,6	66,6	0.00079	0.00034	-0.64081
2/9	anti/reso	10	30	89.9	89.9	0.00248	0.00109	-0.61486
4/9	anti/reso	20	30	89.9	89.9	0.00887	0.00447	-0.48042
2/10	anti/reso	9	17	83,3	83,3	0.00202	0.00088	-0.62215
3/10	anti/reso	13,5	33	66.6	66.6	0.00444	0.00202	-0.58195
4/10	anti/reso	18	17	66.6	66.6	0.00741	0.00357	-0.52424
9/10	anti/reso	40.5	33	83,3	83,3	0.00051	0.00022	-0.64465
5/6	reso/anti	37.5	20	60	60	0.00370	0.00360	-0.01577
6/7	reso/anti	~38.6	23	70	70	0.00279	0.00275	-0.00785
2/8	reso/anti	11,25	27*	73,3	73,3	0.00739	0.00644	-0.07847
3/8	reso/anti	16.875	27	66,6	66,6	0.01143	0.00757	-0.25657
7/8	reso/anti	39,375	27	79.9	79.9	0.00216	0.00215	-0.00386
8/9	reso/anti	40	30	60	60	0.00173	0.00173	-0,00172
3/10	reso/anti	13,5	33	83,3	83,3	0,00950	0.00744	-0,14314
9/10	reso/anti	40.5	33	66.6	66.6	0.00141	0.00141	-0.00046
5/6	reso/reso	37.5	20	60	70	0,00133	0.00133	-0.00017
7/8	reso/reso	39,375	27	79.9	66.6	0,00233	0.00231	-0.00479
9/10	reso/reso	40,5	33	66.6	83.3	0.00350	0.00342	-0.01388

# Figure of Merit

Nonlinearity=2次の係数/1次の係数

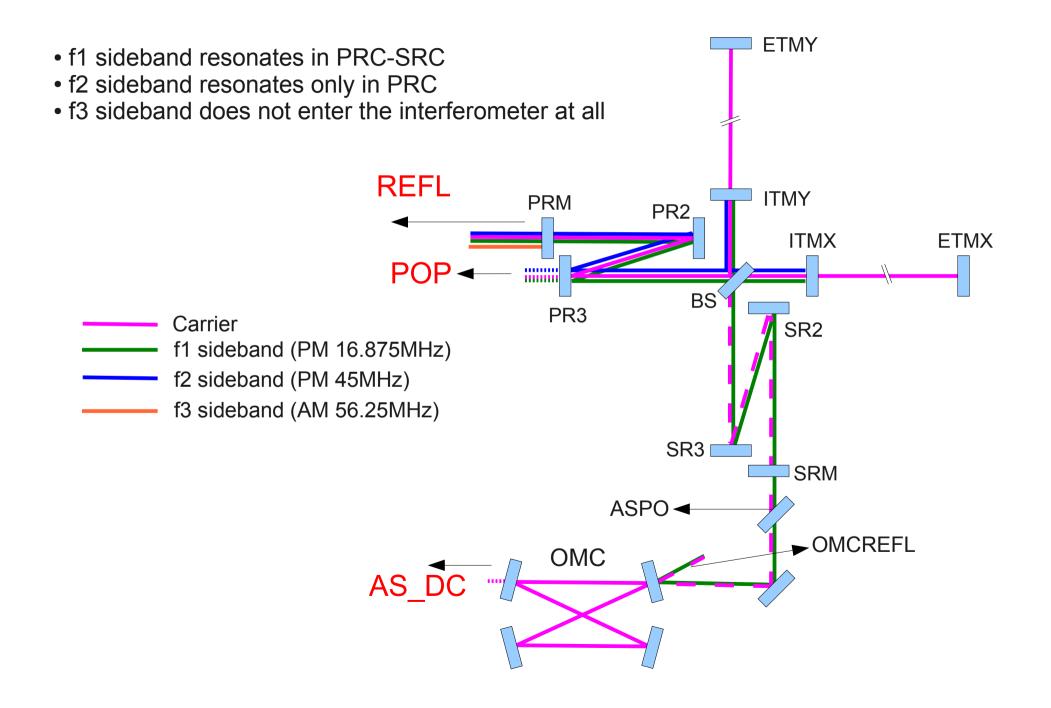
# **Final Candidates**

	9MHz	11.25MHz	16.875MHz
Lprc	74.95m	73.28m	66.62m
Lsrc	74.95m	73.28m	66.62m
Las	6.66m	3.33m	3.33m
Lmc	33.3m	26.65m	26.65m
f3	13.5MHz(f2*3/10)	61.9MHz(f2*11/8)	56.3MHz (f2*10/8)
DDM freq.	22.5MHz, 31.5MHz	16.9MHz, 50.6MHz	11.25MHz, 39.4MHz

#### Pros and Cons

- Loop noise 11.25MHz < 16.875MHz < 9MHz (worse < better)
- 9MHz needs a bit longer MC (33m not 27m)
- 9MHz has a longer asymmetry (6.6m compared to 3.3m)
- 11.25MHz is incompatible with 3<sup>rd</sup> harmonics demodulation
- 9MHz and 16.875MHz have larger SRCL non-linearity

#### Signal Extraction Ports



# **Modulation Types**

#### PM or AM ?

- AM wastes laser power
  - Low loss method exist [N. Ohmae, Opt. Lett.]
     ---> complicated
- Mach-Zhender may introduce extra noise.

Conventional Scheme f1:PM, f2:PM

• No MZ

• No AM

Conventional Scheme + NRS f1:PM, f2:PM, f3:AM

- May need MZ
- Need AM
- AM can be weak if used only for lock acquisition

AM-PM Scheme f1: AM, f2:PM

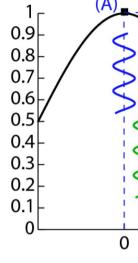
- Need MZ
- Need AM
- May have a problem with WFS at AS

Default: Conventional Scheme + (NRS)

 $\pi/4$ 

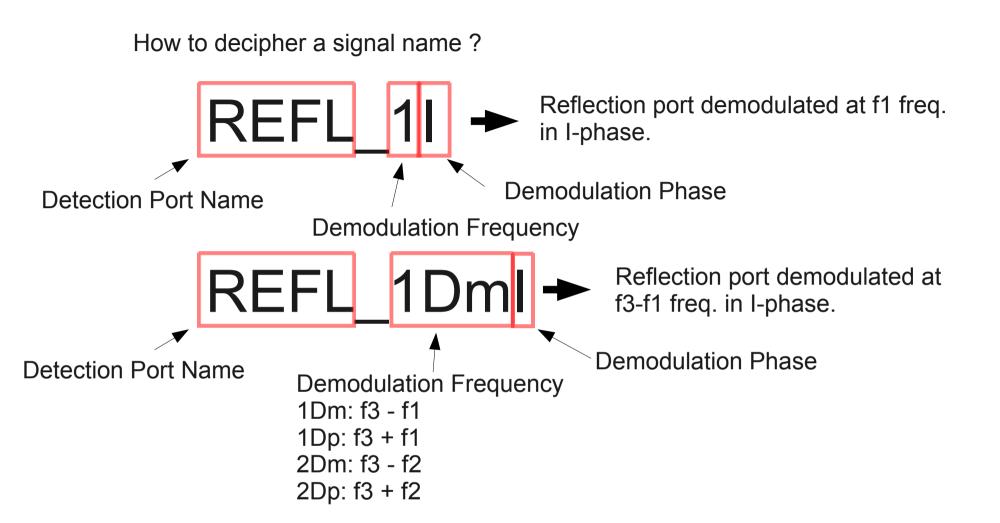
 $\pi/2$ 

 $\phi_0$ 



output power [1/input power]

#### Signal Ports and Naming Convention



#### **DC Power at PDs**

Attenuated to be less than 100mW on each PD

## Sensing Matrix

#### BRSE: 16.875MHz - 45MHz

	DARM	CARM	MICH	PRCL	SRCL
AS_DC	1	4.2e-5	1.0e-3	4.8e-6	4.7e-6
REFL_1I	5.4e-3	1	4.3e-5	6.5e-3	4.3e-3
REFL_1Q	5.0e-3	1.3e-2	1	1.02	0.67
POP_2I	2.3e-2	4.3	1.0e-2	1	2.5e-4
POP_1I	8.7e-2	16.23	3.1e-2	2.1	1

- Large Coupling from CARM to PRCL & SRCL
- Gain hierarchy to suppress CARM
- PRCL, SRCL mixed to MICH

# Sensing Matrix

#### Use of Non-Resonant Sideband (f3: 56.25MHz)

#### BRSE: 16.875MHz - 45MHz

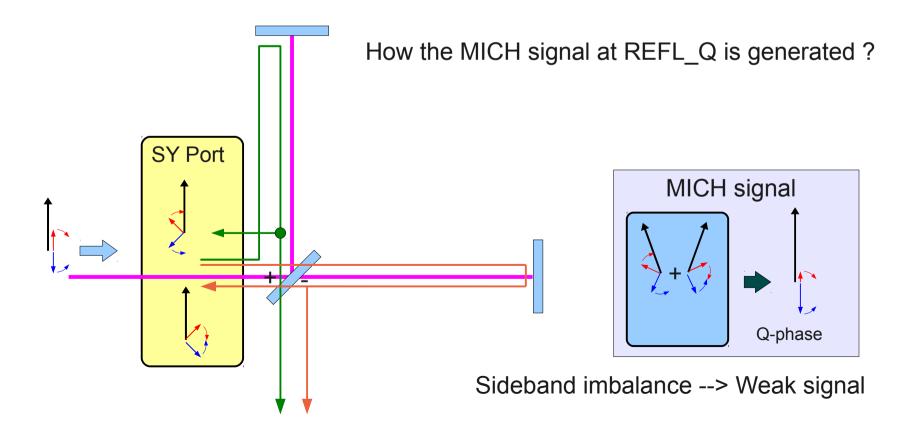
	DARM	CARM	MICH	PRCL	SRCL
AS_DC	1	4.1e-5	1.0e-3	4.8e-6	4.7e-6
REFL_1I	5.4e-3	1	3.9e-5	5.4e-3	4.5e-3
REFL_1DmQ	4.8e-3	2.5e-3	1	0.7	1.3
REFL_2Dml	2.3e-2	8.3e-2	0.18	1	0.32
REFL_1Dml	8.7e-2	1.5e-2	2.4e-2	1.7	1

- CARM coupling is now small
- Shot noise may not be so good.

# Loop Noise Coupling

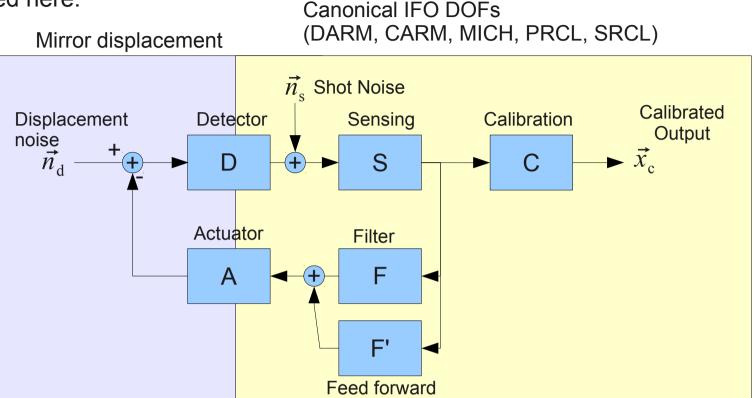
Just looking at sensing matrices is not enough

- Auxiliary DOFs in general have worse shot noise than DARM
- MICH is particularly problematic one.
  - MICH unavoidably couples to DARM (1/finesse)
  - MICH signal is weak
  - Driving MICH with this bad signal ---> Noise coupling to DARM



# Loop Noise Coupling

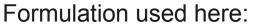
Formulation used here:

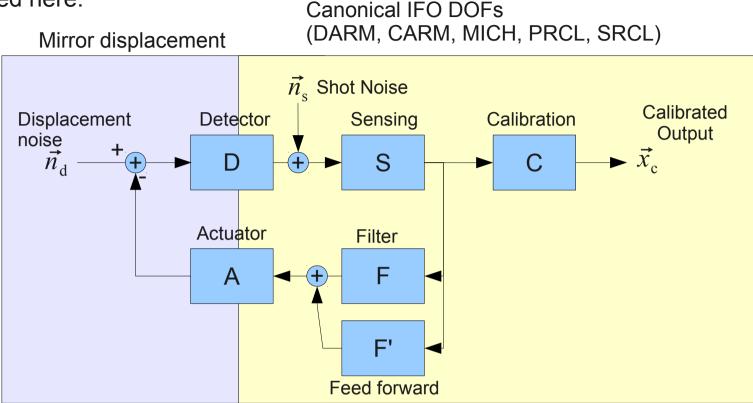


$$\vec{x}_{c} = (I+G)^{-1} \cdot S \cdot \vec{n}_{s} + (I+G)^{-1} \cdot SD \cdot \vec{n}_{d}$$
$$G \equiv S \cdot D \cdot A \cdot (F+F')$$

- D: Optical Gain Transfer Function calculated by Optickle
- A: Mechanical TFs of the mirror suspensions + optical spring stiffness
- F: Feedback filters
- F': Feed forward matrix
- S: Sensing matrix (here I just used identity matrix)

# Loop Noise Coupling





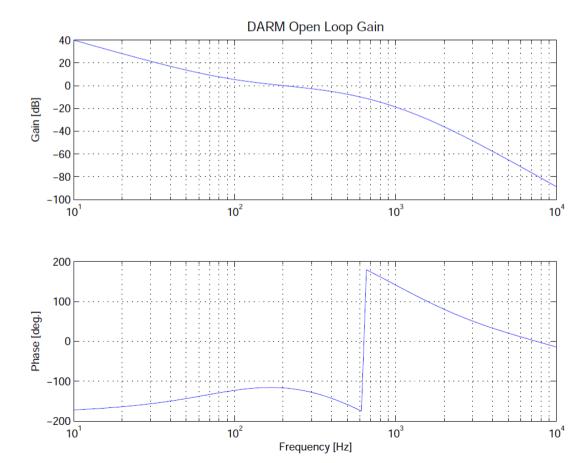
$$\vec{x}_{c} = (I+G)^{-1} \cdot S \cdot \vec{n}_{s} + (I+G)^{-1} \cdot SD \cdot \vec{n}_{d}$$
  
$$G \equiv S \cdot D \cdot A \cdot (F+F')$$

- Ideally, G is diagonal (D A is diagonal), but in practice it is not.
- Off diagonal elements of G introduce the shot noise of auxiliary DOFs to DARM
- F' is added to diagonalize G (Feed forward)

# **Control Loop Gains**

#### UGFs

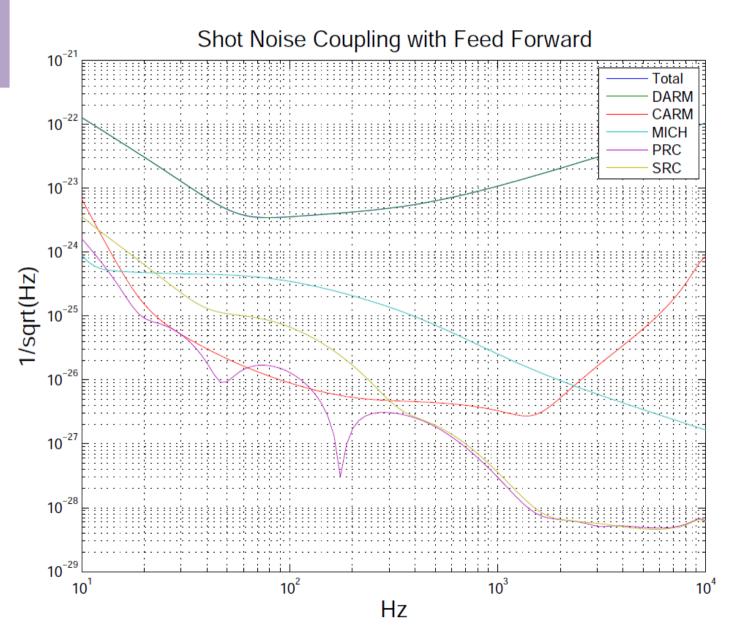
	BRSE	DRSE
DARM	200Hz	200Hz
CARM	10kHz	10kHz
MICH	50Hz	10Hz
PRCL	50Hz	50Hz
SRCL	50Hz	50Hz



#### 9MHz-45MHz

DARM: ASDC CARM: REFL 1I MICH: REFL 1Q PRCL: POP 2I SRCL: POP 1I

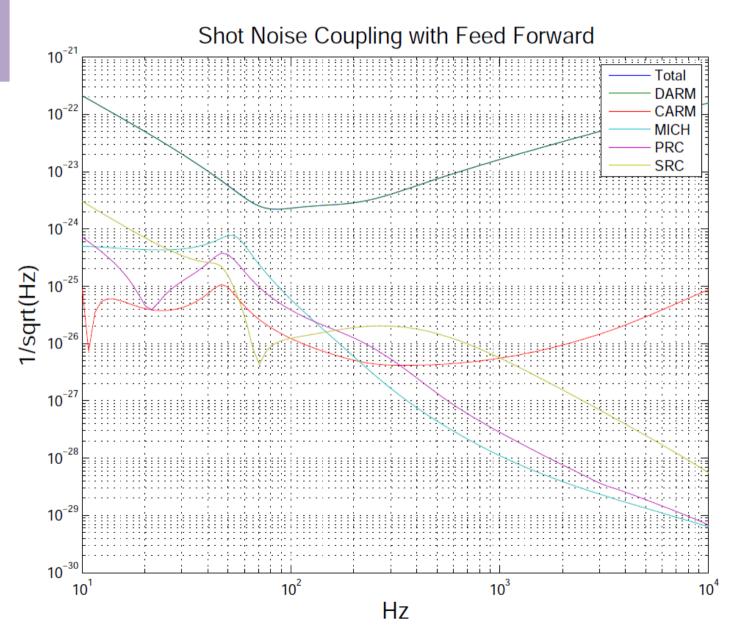
#### BRSE: f1=9MHz, Feed forward gain=100



## 9MHz-45MHz

DARM: ASDC CARM: REFL 1I MICH: REFL 1Q PRCL: POP 2I SRCL: POP 1I

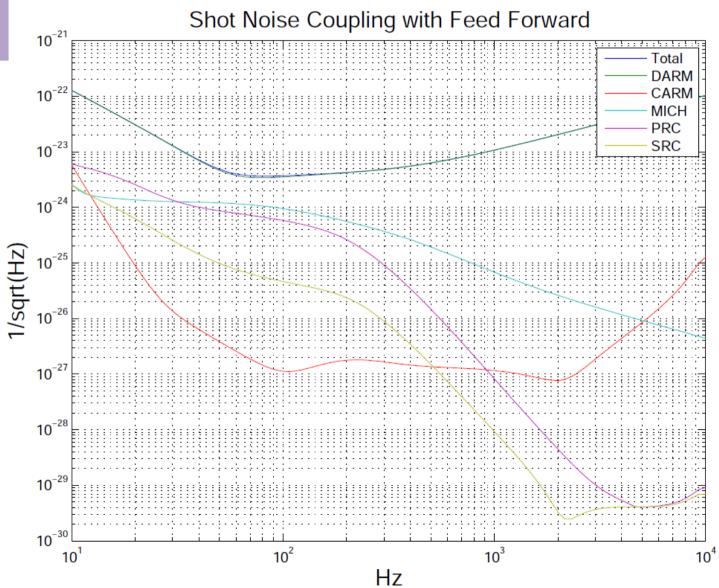
### DRSE: f1=9MHz, Feed forward gain=100



## 11.25MHz-45MHz

DARM: ASDC CARM: REFL 1I MICH: REFL 1Q PRCL: POP 2I SRCL: POP 1I

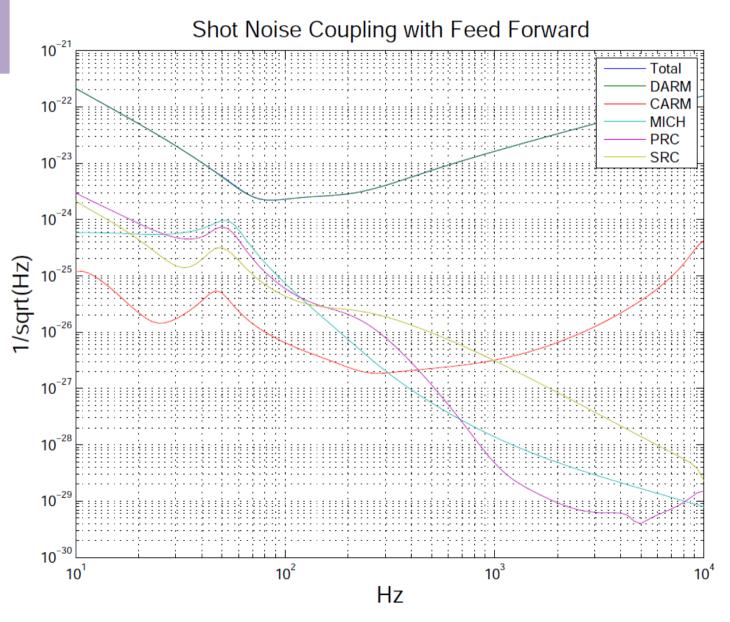
### BRSE: f1=11.25MHz, Feed forward gain=100



## 11.25MHz-45MHz

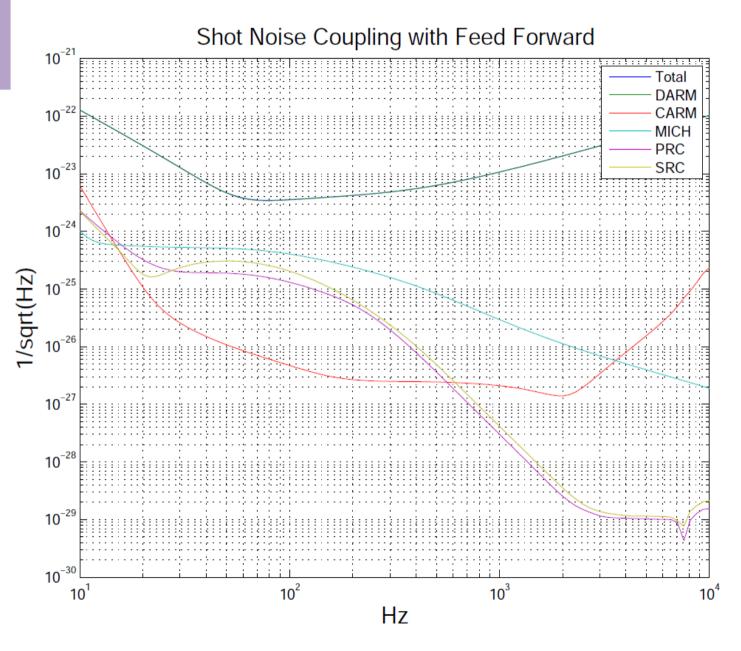
DARM: ASDC CARM: REFL 1I MICH: REFL 1Q PRCL: POP 2I SRCL: POP 1I

### DRSE: f1=11.25MHz, Feed forward gain=100



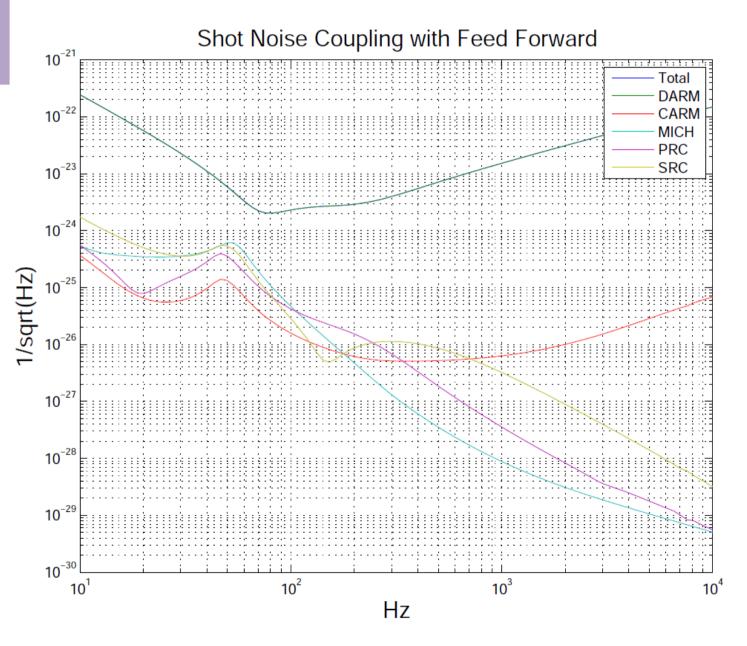
DARM: ASDC CARM: REFL 1I MICH: REFL 1Q PRCL: POP 2I SRCL: POP 1I

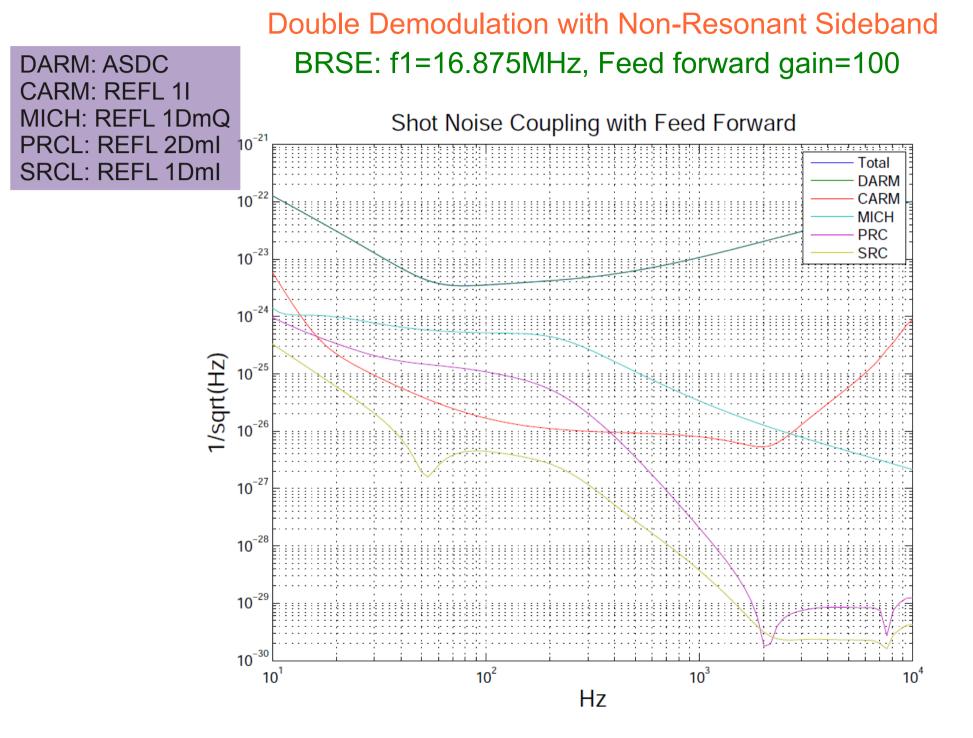
### BRSE: f1=16.875MHz, Feed forward gain=100

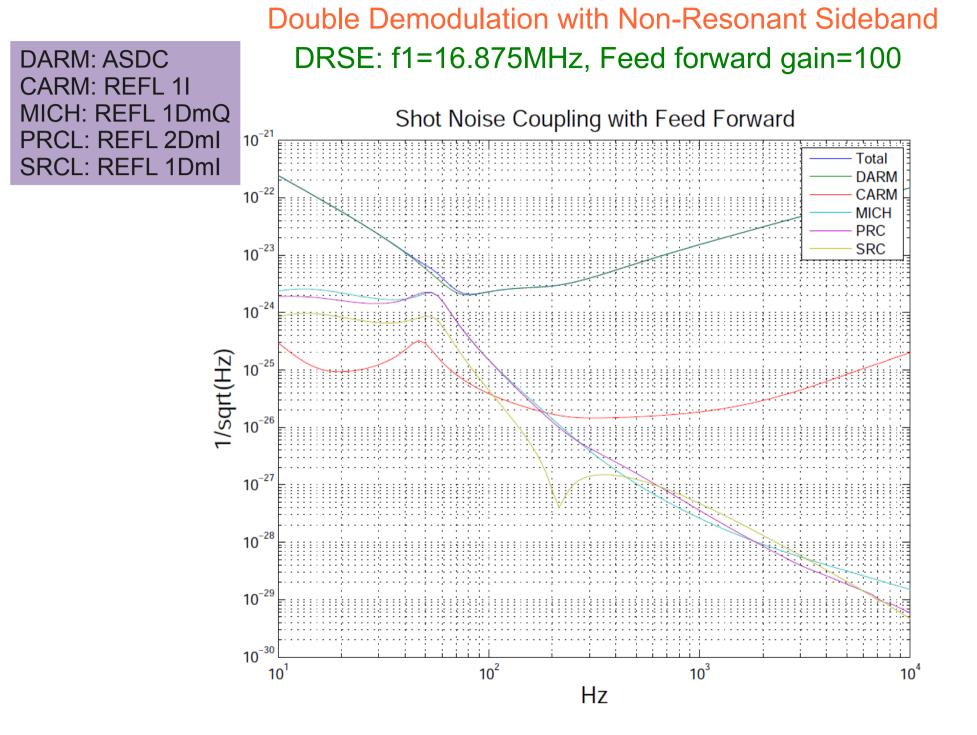


DARM: ASDC CARM: REFL 1I MICH: REFL 1Q PRCL: POP 2I SRCL: POP 1I

### DRSE: f1=16.875MHz, Feed forward gain=100







# **SRCL Non-Linearity**

- SRC detuning by offset => Error signal non-linearity
- Up conversion noise

## **Formalization**

$$y(t) = a x(t) + b x^{2}(t)$$

x: mirror displacement [m] y: error signal [W]

Calibration

$$x_{e}(t) = y(t)/a = x(t) + (b/a)x^{2}(t)$$

Non-linear part

x<sub>e</sub>: Displacement equivalent error signal [m] b/a: dimension is 1/m

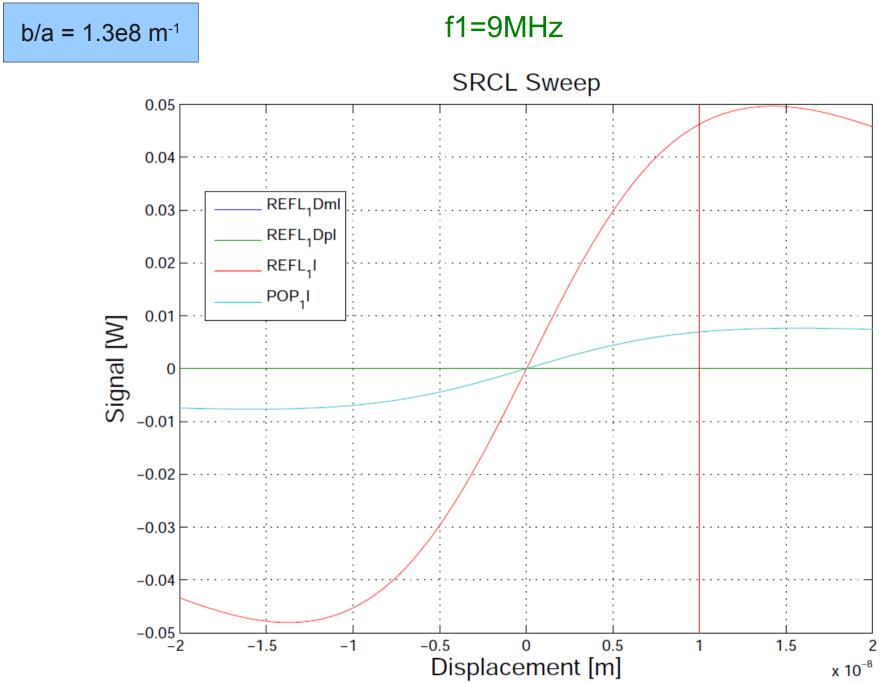
Total frequency conversion noise [ref. Applied Electronics, Koichi Shimoda]  $P_{\text{conv}}(f) = \left(\frac{b}{a}\right)^{2} \left[\int_{0}^{f} P(f - f') P(f') df' + 2\int_{0}^{\infty} P(f + f') P(f') df'\right]$ 

Up Conversion

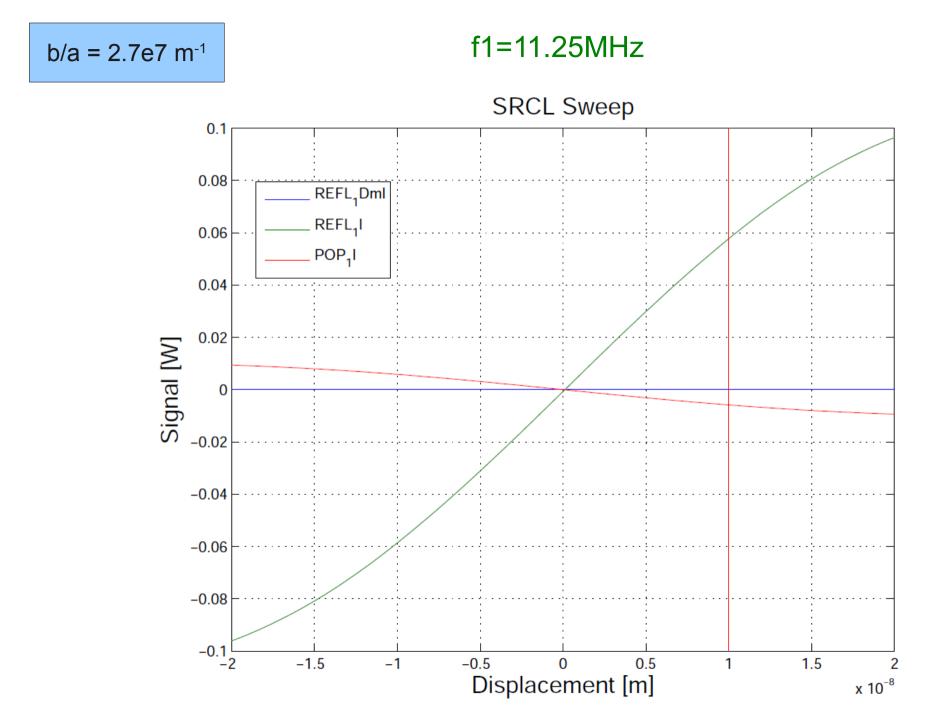
**Down Conversion** 

P(f): Displacement equivalent noise spectrum [m<sup>2</sup>/Hz], one sided.

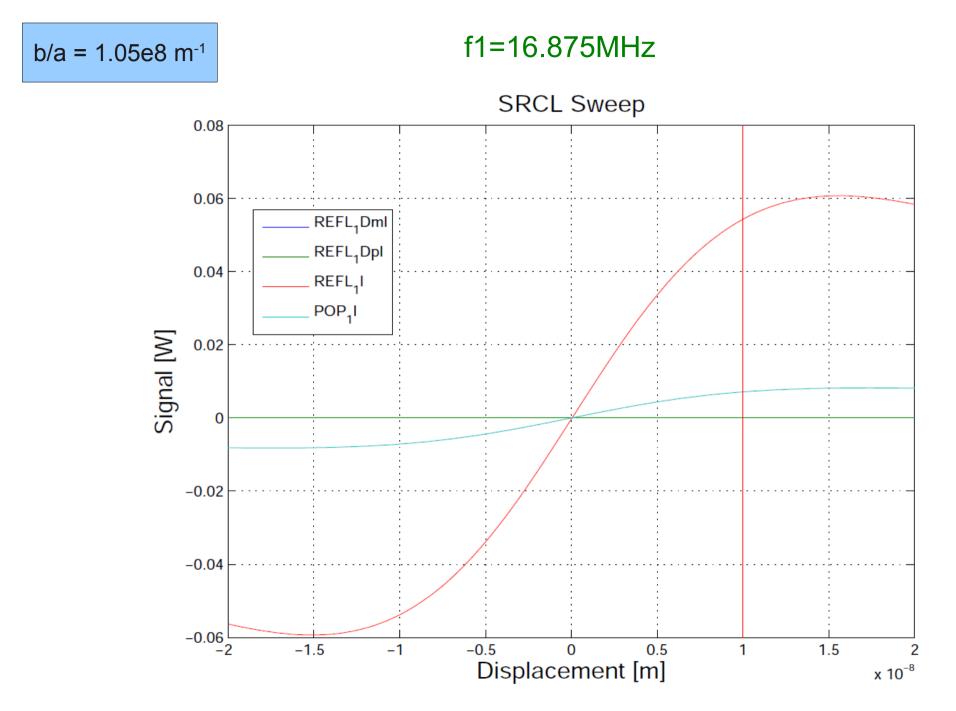
# SRCL error signal range, f1=9MHz



# SRCL error signal range, f1=11.25MHz

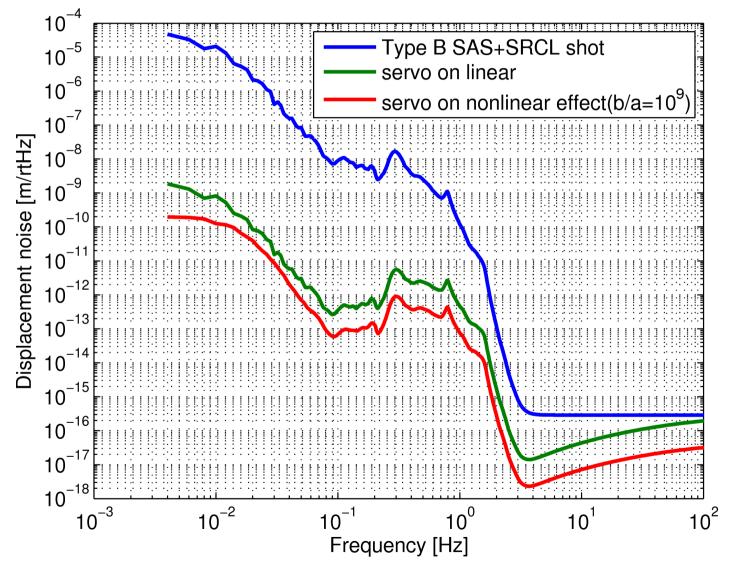


# SRCL error signal range, f1=16.875MHz



# **Up Conversion Noise**

- Blue Curve: SAS displacement noise + SRCL shot noise
- Green Curve: Above noise suppressed by the servo
- Red Curve: Non-linear up conversion noise (b/a=1e9)



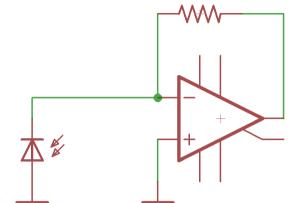
It does not seem to be a problem

# PD Dynamic Range

Offsets in MICH and CARM --> Dynamic Range of RFPD circuit

SRC detuned: f1 SB is not at the peak of the resonance

- f1 gets some phase rotation at REFL and POP
- → f1 is no longer pure PM for the carrier
- → Large offset at PDs for f1 SB



The buffer op-amp of the PD circuit has to handle this large RF signal

Max RF amplitude: ~ 0.1Vpp (?) Slew rate and linearity \_\_\_\_\_ Dynamic Range ~ 160dB Noise of the op-amp: >1nV/rtHz

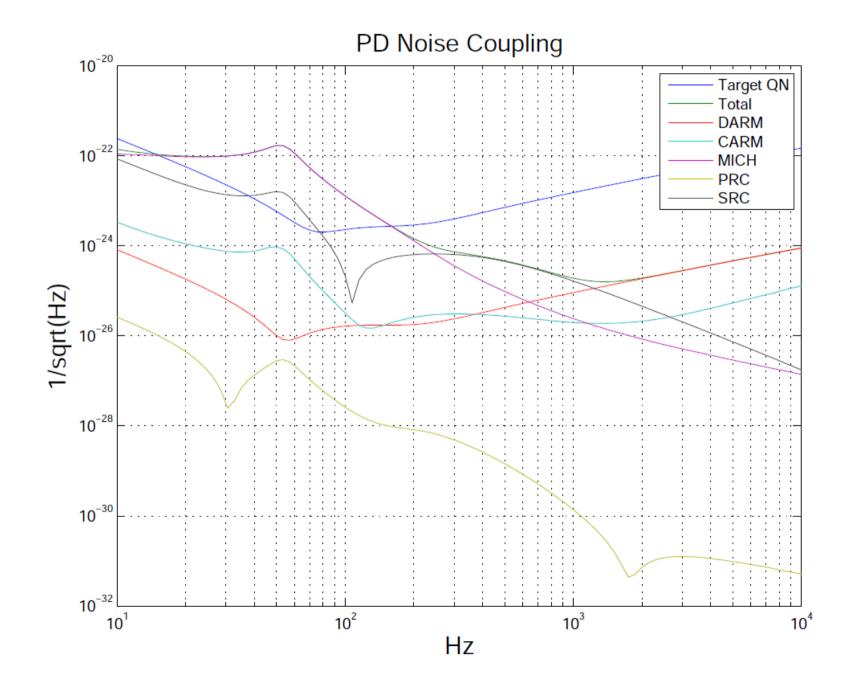
### **Actual Numbers**

REFL\_1 PD gets 55mW of offset RF signal@f1 frequency(16.875MHz) in DRSE Input power equivalent noise of op-amp is 55mW/1e8/rtHz = 5.5e-10W/rtHz Sensitivity is 1.64e9 W/m for CARM, 2.0e6 W/m for MICH Displacement equivalent op-amp noise is 3.4e-19m/rtHz for CARM, 2.7e-16m/rtHz for MICH

POP\_1 PD gets 7.2mW of offset RF signal@f1 frequency(16.875MHz) in DRSE Input power equivalent noise of op-amp is 7.2mW/1e8/rtHz = 7.2e-11W/rtHz Sensitivity is 3.3e5 W/m for SRCL Displacement equivalent op-amp noise is 2.2e-16m/rtHz for SRCL

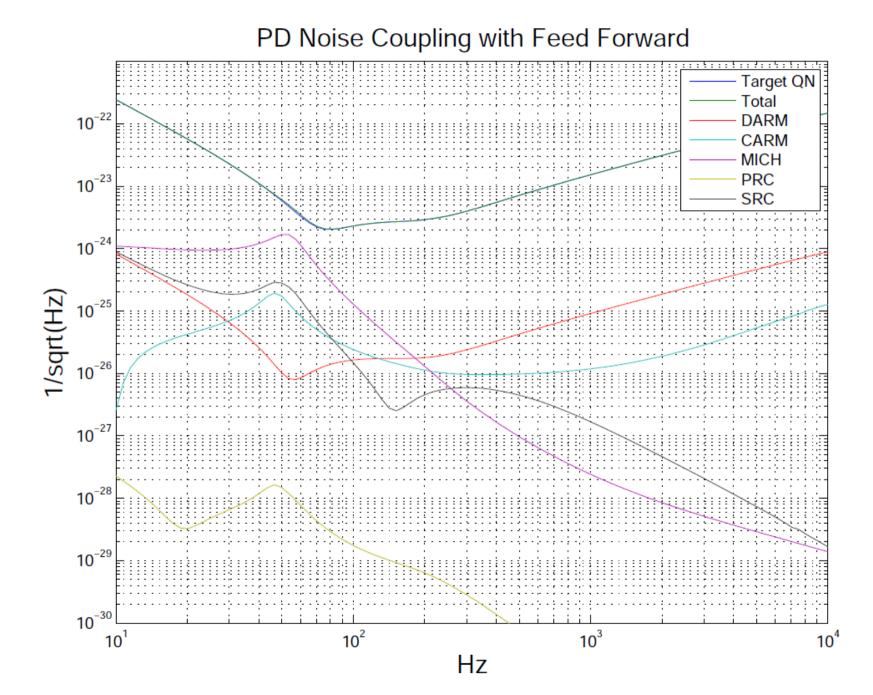
## **Risk: PD Noise Coupling**

DRSE: RFPD dynamic range = 160dB, DCPD dynamic range=194dB



## **Risk: PD Noise Coupling with Feed Forward**

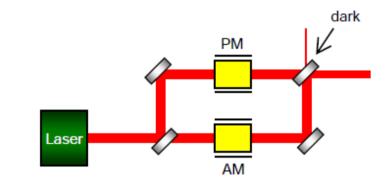
Feed Forward Gain = 100

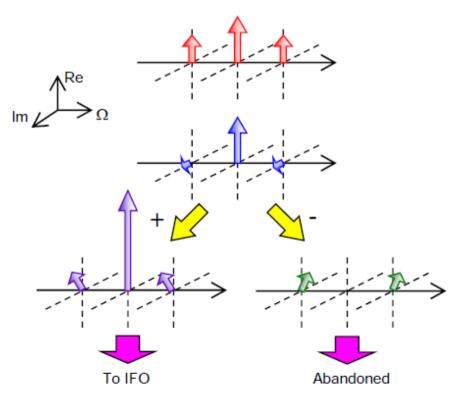


# Risk: SRCL detuning by Offset

How to deal with the PD dynamic range problem ?

- Find a good op-amp with larger dynamic range
- Increase the feed forward gain
- Current injection to PD to cancel the large RF signal (like AS\_I servo in iLIGO)
- Pre-rotate f1 sidebands



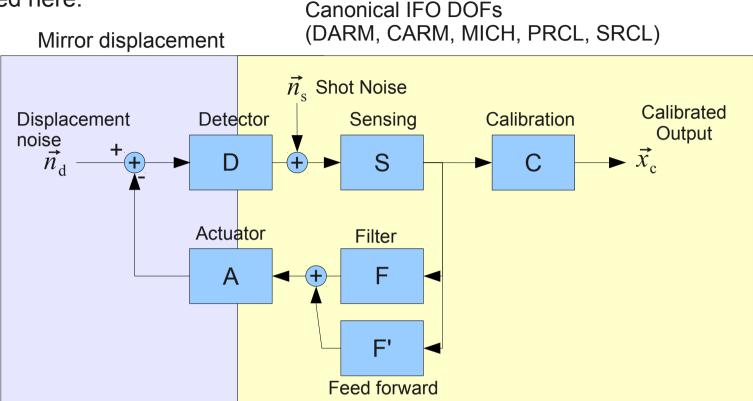


# Conclusion on the Modulation Frequencies

	9MHz	11.25MHz	16.875MHz
Loop Noise	Good	ОК	Good
SRCL Non-linearity	ОК	ОК	ОК
3 <sup>rd</sup> Harmonics Demodulation	ОК	No	ОК
Lprc,Lsrc	74.95m	73.28m	66.62m
Asymmetry	6.66m	3.33m	3.33m
Lmc	33.3m	26.65m	26.65m
f3	13.5MHz(f2*3/10)	61.9MHz(f2*11/8)	56.3MHz (f2*10/8)
DDM freq.	22.5MHz, 31.5MHz	16.9MHz, 50.6MHz	11.25MHz, 39.4MHz

# **Displacement Noise Requirements**

#### Formulation used here:



$$\vec{x}_{c} = (I+G)^{-1} \cdot S \cdot \vec{n}_{s} + (I+G)^{-1} \cdot SD \cdot \vec{n}_{d}$$
  
$$G \equiv S \cdot D \cdot A \cdot (F+F')$$

• (I+G)<sup>-1</sup>SD: transfer function from  $n_d$  to  $x_c$ 

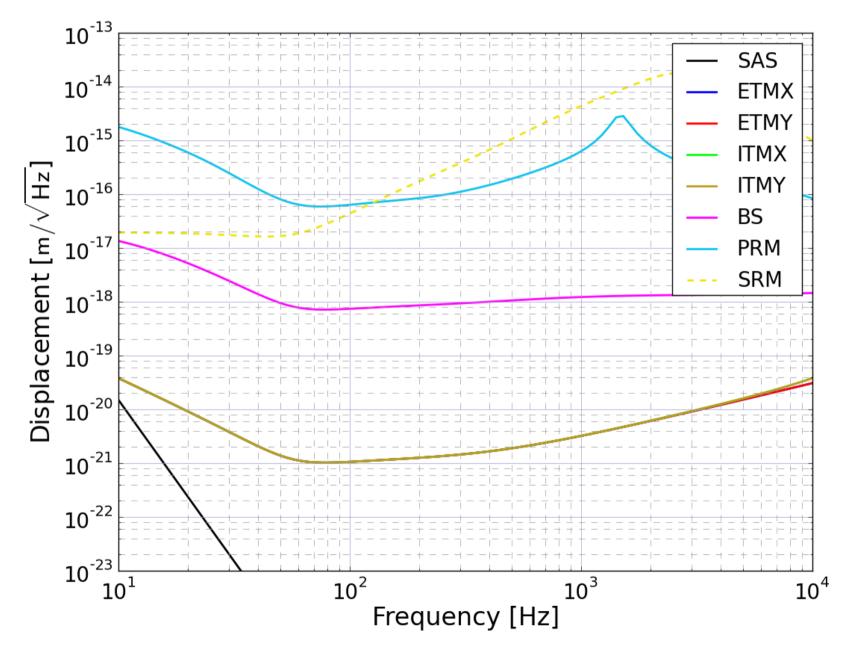
Safety factor

• Require  $n_d$ 's contribution to xc to be 1/10 of DARM shot noise

Requirement on each mirror's displacement noise (seismic, thermal, etc)

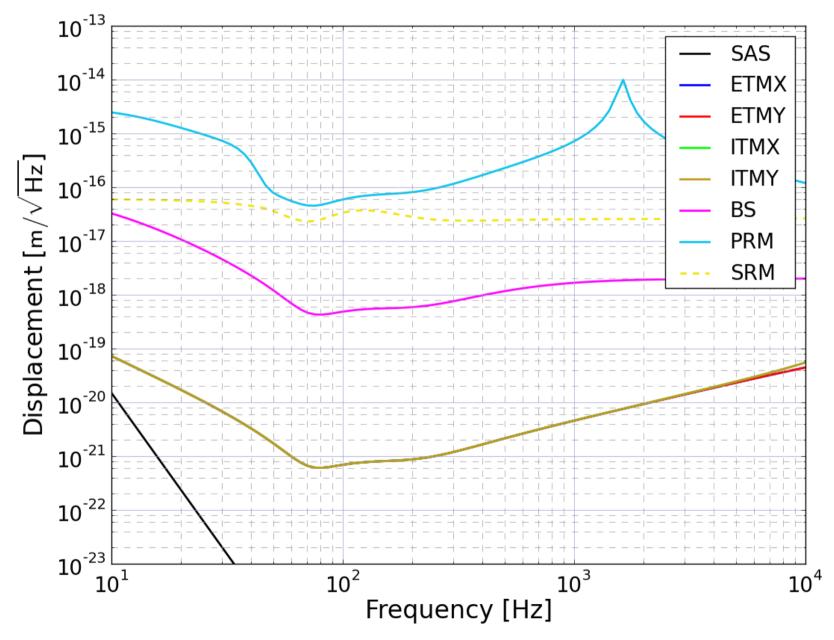
## **Displacement Noise Requirements**

BRSE



## **Displacement Noise Requirements**

DRSE



# Folding of Recycling Cavities

## Straight Recycling Cavity ==> Nearly Degenerated

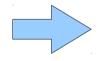
How badly degenerated ?

g-factor (g1\*g2) = 0.9998 One-way Gouy Phase Shift = 0.7deg. Transverse Mode Spacing = FSR/257 PRC Finesse = 57 (FWHM = FSR/57) (PRCL = 42.5m, occupying the same tunnel space)

• HG(m,n) modes resonate up to m+n = 2

 LG(p,q) modes resonate up to 2\*p+q = 2

The RFSB spatial modes are unstable (alignment fluctuation, thermal lensing)



Folding the PRC and focusing the beam inside ==> Stable PRC

### How about SRC ?

- f1 SB resonates in PRC-SRC
- If PRC is stable, HOMs cannot resonate in PRC-SRC.
- No need to fold SRC ? -> Not so simple
- GW sidebands may be scattered to HOMs by mode mismatch between the arm cavities and SRC.
- The loss of GW sidebands is higher for degenerated SRC

(Kip Thorne & Yi Pan)

# SRC Folding

Yi Pan's report (LIGO-T-060004): ITM ROC error of 0.25% ==> Up to 2% GW Signal Loss Loss  $\propto$  (ITM Error)<sup>2</sup> ==> 1% error -> 32% signal loss

The situation for LCGT should not be too different from aLIGO

But we should check it anyway



- HOM simulation using Finesse
- No definitive answer yet
- Large (1W) TEM00 leak at AS port if not folded
- Seems like non-folded SRC is bad

## For the moment, the default design is to fold SRC

- Cost increase (two more vacuum tanks, suspensions, mirrors)
- Additional control of SR2, SR3 alignment (we have to control PR2, PR3 anyway)
- Folded SRC provides a convenient port for green laser injection
- The beam size at AS is smaller and easy to handle (4mm)
- If necessary, the tunnel can accommodate straight SRC (Lsrc=40m)

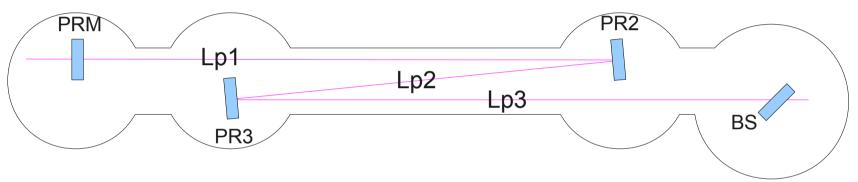
# Folding Design

#### How Stable ?

- HOM isolation ==> Stable is better
- Too stable ==> Arm alignment signal is suppressed
- Compromise between HOM and ASC ==> <u>One-way Gouy Phase Shift = 20deg.</u>

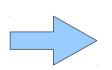
Not Optimized Yet

### How to fold the PRC/SRC ?



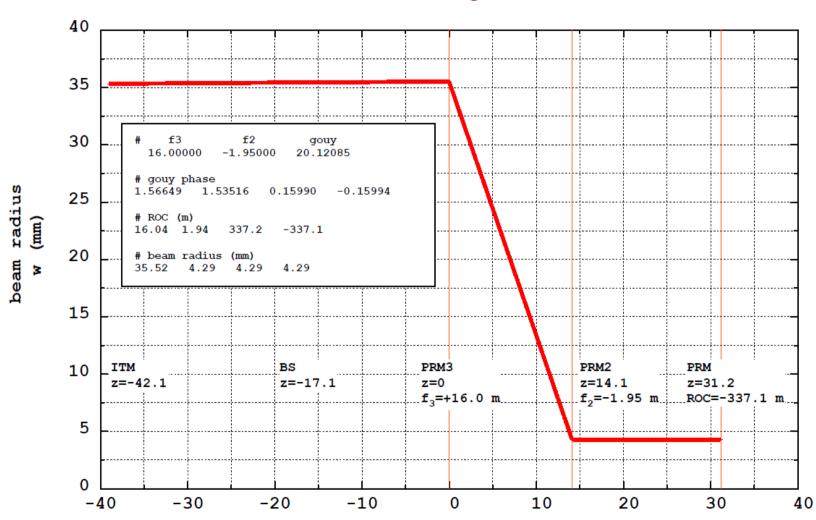
Constraints

- Minimum vacuum chamber spacing: 2.7m
- Astigmatism: Smaller folding angle is better ==> Longer Lp2



Mirror locations are almost uniquely determined Play with ROCs of PR2 and PR3

## Beam Propagation in PRC



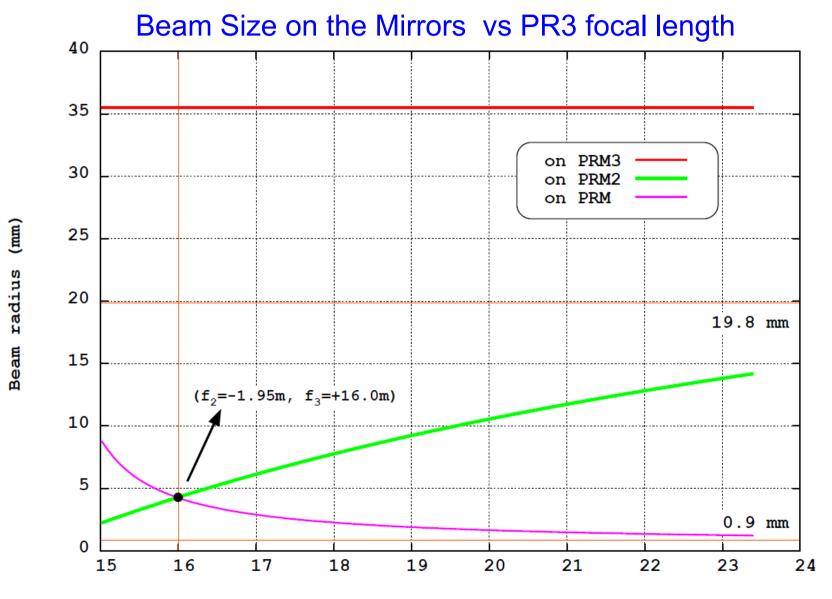
### Beam Width Change in PRC

z (m)

# **Folding Optimization**

Mirror distances: fixed One-way Gouy phase: 20deg

Small Beam Spot ==> Large Thermal Lensing

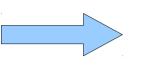


focal length of PRM3 (m)

# **Thermal Lens**

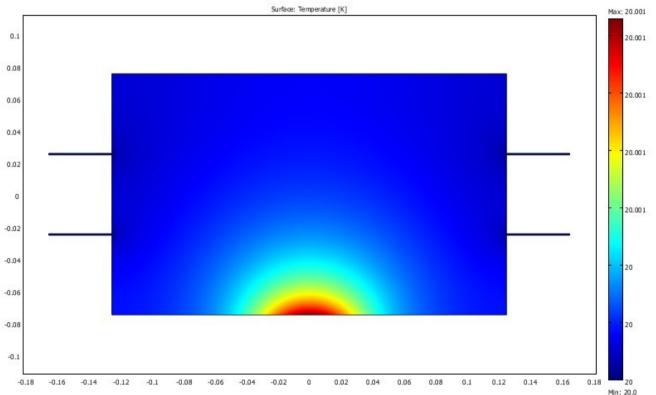
## **ITM Lensing**

1W heat deposit on the mirror



### ROC=11661km, No Problem Thanks to the high thermal conductivity of sapphire

## **1mK Temperature Raise**



Calculation by Muzammil A. Arain (UFL)

## Thermal Lens

### PRM, PR2

### Beam Spot Size: 4mm Power on HR: 800W

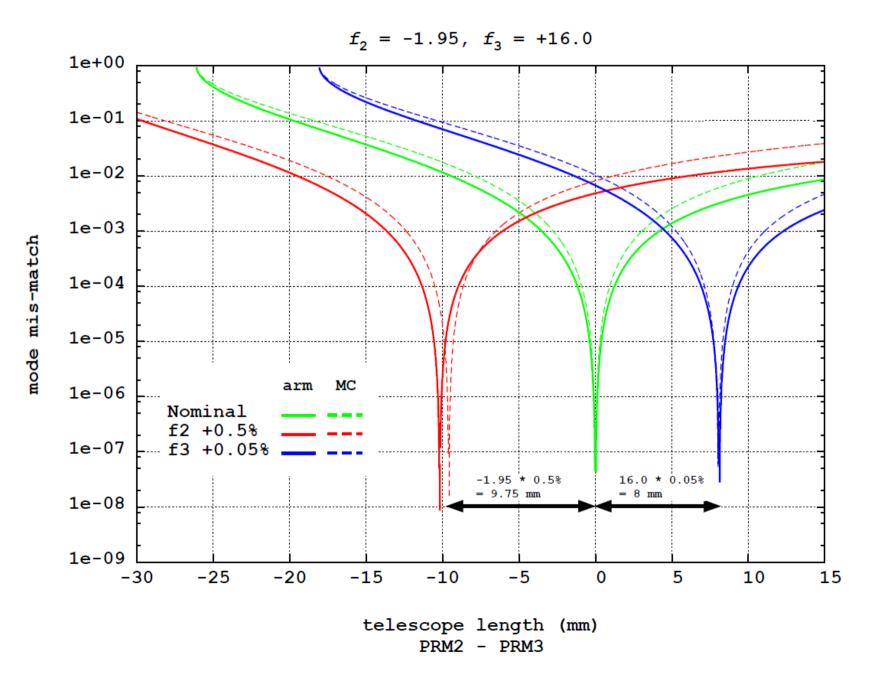
### PR3, BS

Beam Spot Size: 35mm Incident Power: 800W

	PRM	PR2	PR3	BS
10ppm absorption	18% ROC error	0.2% ROC error	0.3% ROC error	ROC 100km
1ppm absorption	2% ROC error	0.02% ROC error	0.03% ROC error	ROC 1000km

## ROC Error of PR2, PR3

#### Very Sensitive to PR3 ROC Error



# How to Handle PR3 ROC error ?

#### iLCGT

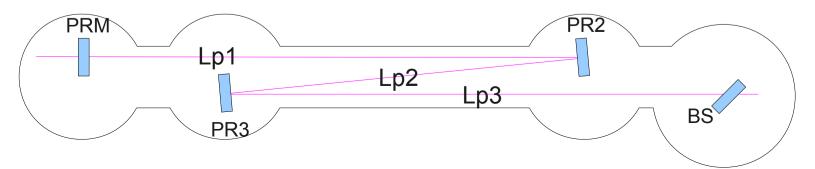
- No SAS. Suspensions can be easily moved by more than 10cm
- PR2 and PR3 for iLCGT will be used in bLCGT
- PRM is a blank with curvature

### bLCGT

- PR2 and PR3 position can be changed by more than 10cm at the installation time
- After installation, it takes time to move them

### Installation and Adjustment Plan

- 1. Make PR2 and PR3
- 2. Measure the ROCs of PR2 and PR3
- 3. Install them to iLCGT
- 4. Adjust the location of PR2 and PR3 to form the desired telescope
- 5. Remember the optimal location of PR2 and PR3
- 6. Measure the ROC of PRM, which match the actually formed PRC.
- 7. Order a PRM according to the measured ROC.
- 8. Install PR2 and PR3 at the remembered positions for bLCGT
- 9. Install the PRM



# Modulation frequency Fine adjustment

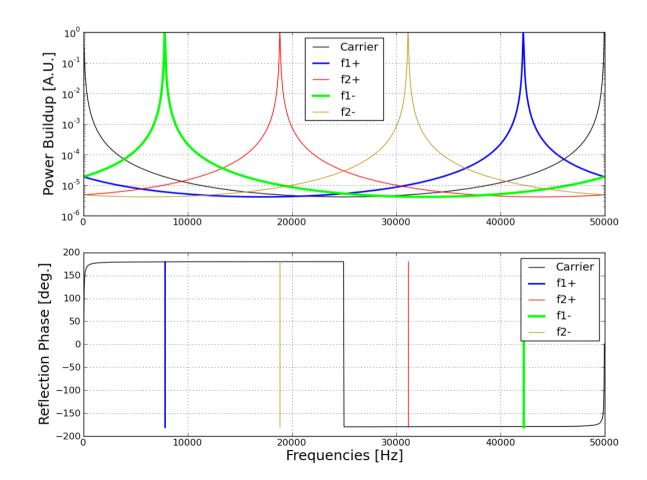
f1 and f2 SBs are not exactly anti-resonant to the arm cavities

- f1 and f2 get finite phase shifts from the arm cavities
  - In general, f1 and f2 cannot fully resonate in the PRC at the same time
- Fine adjust the MC length (thus f1, f2 frequencies) to achieve

 $\Phi_1:\Phi_2 = f_1:f_2$  ( $\Phi_1:$  phase shift of f1 by the arm,  $\Phi_2:$  phase shift of f2 by arm)

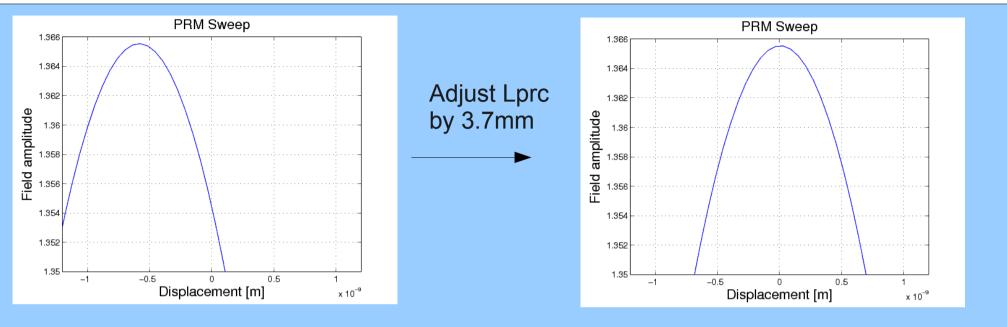
Locations of RF SBs in the FSR of AC

Lprc and Lsrc are adjusted accordingly

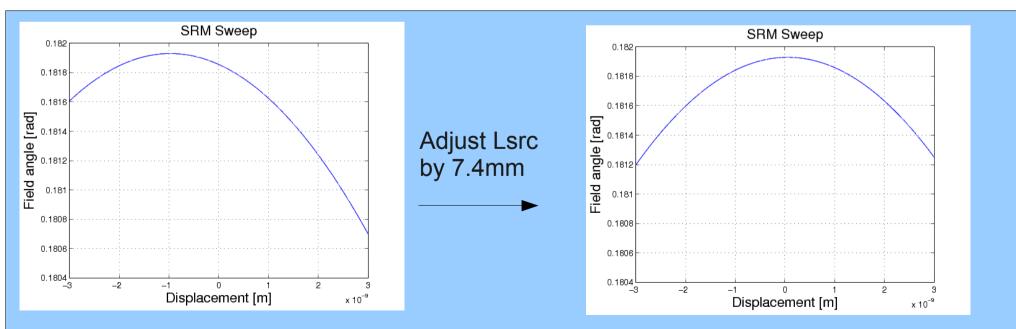


Lmc adjustment = -1.37cm

f2 resonance



#### f1 resonance



# **Alignment Sensing and Control**

#### **Basic Strategy**

Combination of Wave Front Sensing (WFS) and Optical Levers

#### Arm Cavity Misalignment Modes

Combinations of the ITM, ETM rotation to diagonalize the angular stiffness matrix

Hard - Soft basis

[Common Hard (CH), Common Soft (CS), Differential Hard (DH), Differential Soft (DS)]

#### Folding and ASC

- RCs are very stable --> TEM01 and TEM10 modes are suppressed
  - No ASC signal of TMs
- One-way Gouy phase shift in RCs --> about 20 deg.
- Needs optimization
- What to do with the alignment of folding mirrors ?
  - Not enough DOF from WFS
  - Control a linear combination of PRM, PR2, PR3 angles ?
  - Is it stable ?

Simulations with Optickle (Pickle), work in progress

# **bLCGT ASC Sensing Matrix**

					Angle (	venoing ivia trix t					
POY B Q2	-5.54	-4.5	-132	155	0.392	0.363	0.443	-0.00311	-0.00591	-0.0496	-372
POY B 12	- 1e+003	-1.17e+003	856	-1.22e+003	-84.6	-935	-7.9e+003	-0.0162	-0.0309	-0.259	-68.3
POY A Q2		98.2	-1.15e+003	1.23e+003	-5.64	-1.35	39.5	-0.0131	-0.025	-0.209	-3.05e+003
POÝ A I2		-23	1.06e+003	-1.15e+003	9.92	54.2	412	0.00955	0.0182	0.152	3e+003
POY BQ1	76.9	33	42.8	48.3	2.66	36.2	310	-0.143	-0.271	-2.27	67.1
POT BI1	58.1	61.4	54.9	-50.7	3.31	49.3	426	-1.59	-3.03	-25.4	283
POY A Q1	135	155	135	-155	11.6	127	1.07e+003	-0.00453	-0.00862	-0.0723	758
POŸ A I1	- 184	-20.2	-190	40.7	-7.69	-83.8	-705	7.85	14.9	125	-536
POXĒQ2	- 675	-851	-1.07e+003	1.37e+003	-57.9	-658	-5.58e+003	0.00518	0.00985	0.0825	-5.16e+003
POX B I2	591	761	810	-1.06e+003	50.8	583	4.94e+003	-0.00955	-0.0182	-0.152	4.2e+003
POXĀQ2		-57.8	87	-111	-4.48	-48.1	-406	-4.26e-005	-8.09e-005	-0.000678	115
POX A I2	- 459	-267	1.21e+003	-1.21e+003	-35.3	-313	-2.58e+003	0.0202	0.0384	0.322	2.21e+003
POXĒQ1	16.4	31.1	17.2	-52.7	0.0136	10.4	95.9	2.01	3.82	32	125
POX B I1	1.75	3.3	5.88	-11	1.09	2.02	8.96	1.93	3.66	30.7	24.2
POX_Ã Q1	- 223	-62.1	219	-57	-10.3	-116	-976	7.51	14.3	120	-3.85
– POX_A I1	102	156	-103	157	10.1	114	966	0.998	1.9	15.9	5.74
POP_ĒQ2	- 5.91	4.14	-0.136	0.165	-0.436	-0.812	-4.21	1.4e-006	2.65e-006	2.22e-005	-1.74
POP_B I2	1e+003	1.17e+003	-1.77	2.36	84.8	938	7.93e+003	-0.000147	-0.000279	-0.00234	2.8e+003
POP Ā Q2	18.9	-135	0.569	-0.589	-3.01	-65.6	-582	1.24e-005	2.36e-005	0.000197	-206
POP A I2	63.4	188	-0.585	0.451	-2.09	52.7	509	-1.01e-005	-1.92e-005	-0.000161	182
POP BQ1	43.4	4.25	7.14	-9.18	0.965	11.4	96.3	0.579	1.1	9.23	41.3
POP B I1	- 9.22	-1.14	34.8	-43.7	-0.208	-2.51	-21.3	-0.116	-0.22	-1.85	97.3
POP_A Q1	0.796	0.931	-155	195	0.055	0.594	5.01	0.000227	0.000432	0.00362	-452
POP_A I1	82.2	-64	-0.395	-0.193	0.423	4.12	33.7	-6.81	-12.9	-109	12.7
AS_ĒQ1	0.628	2.78	-922	-491	-0.0259	-4.5	-41.5	-0.000256	5.91	53.6	-166
AŠ_B I1	- 85.6	-125	6.65e+003	3.81e+003	-4.38	-45.2	-378	3.76	-36.5	-336	535
AS_Ā Q1	42.5	53.1	0.98	-34.7	3.75	41.8	354	-0.103	-0.19	-1.59	176
AŠ_A I1	- 51.6	-18	-1.95e+004	-1.5e+004	-2.56	-34.6	-296	-1.3	5.64	51.2	-2.02e+003
REFL_B_Q2	445	97.4	-1.51	2.35	5.28	236	1.9e+003	-4.01e-005	-7.62e-005	-0.000639	660
REFL_B I2	1.08e+004	-9.77e+003	8.28	14.8	-871	571	-570	0.000124	0.000235	0.00197	-490
REFL_Ā Q2	9.58e+003	-4.22e+003	-3.41	22.5	-356	2.27e+003	1.55e+004	-0.000239	-0.000455	-0.00381	5.27e+003
REFĒ_A I2	1.08e+004	-5.39e+003	-1	22.6	-448	2.3e+003	1.51e+004	-0.000219	-0.000416	-0.00349	5.1e+003
REFL_BQ1	26.4	-11	-943	1.19e+003	0.0786	4.98	39.8	-1.43	-2.71	-22.7	-2.75e+003
REFĒ_B I1	— -1.84e+003	-1.46e+003	21.1	-27.6	-110	158	685	-40.6	-77.2	-647	279
REFL_Ā Q1	1.23	10.9	-978	1.23e+003	1.57	3.41	36.1	-0.787	-1.5	-12.5	-2.85e+003
REFL_A I1	— -2.05 <b>e</b> +003	-1.47¢+003	7.82	-10.2	-99.4	194	955	-36.5	<b>-6</b> ₽.5	-5β2	294
	CS	СН	DS	DH	PRM	PR2	PR3	SRM	SR2	SR3	BS

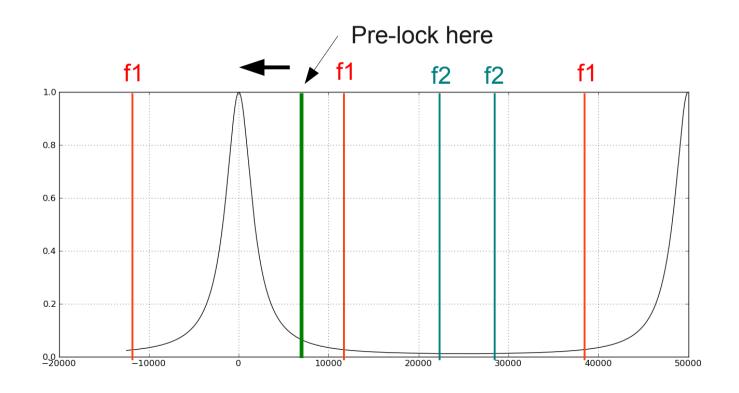
Angle Sensing Matrix [W/rad]

# Lock Acquisition

Principle: Lock acquisition has to be a deterministic process

Lock acquisition steps

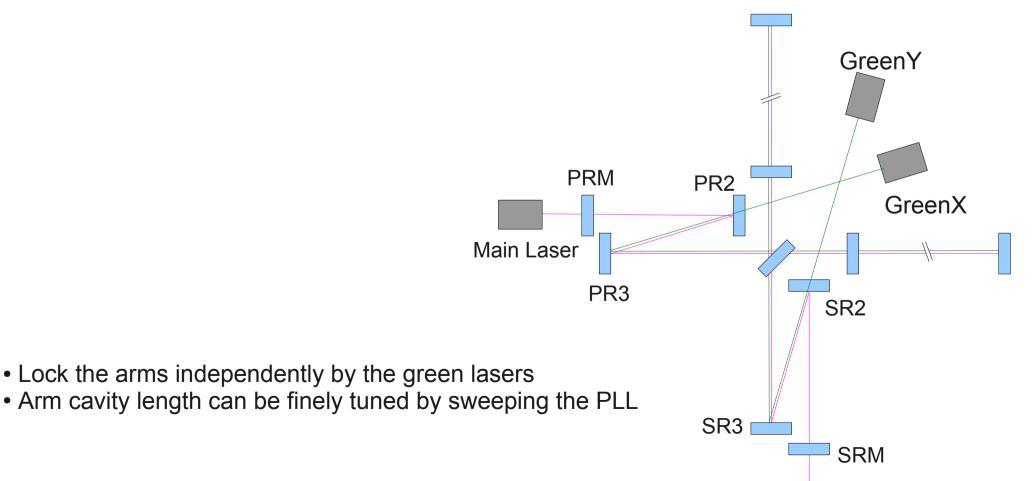
- 1. Pre-lock the arms at off-resonant positions (Green laser pre-lock)
- 2. Lock the central part using the third harmonics demodulation or non-resonant sideband
- 3. Reduce the arm offset to the full resonance
- 4. The error signals to low noise ones



# **Green Laser Pre-Lock**

### Basic ideas for green laser lock

- Two green lasers (Frequency doubled from 1064nm)
- Green lasers are phase locked to the main laser by PLL
- Green Lasers are injected from PR2 for X-arm, and SR2 for Y-arm
- PR3 and SR3: High reflectivity for green (>90%)
- BS is transparent to green
- Arm finesse for green is low (~10)
- Two green lasers are frequency shifted by ~ 100MHz

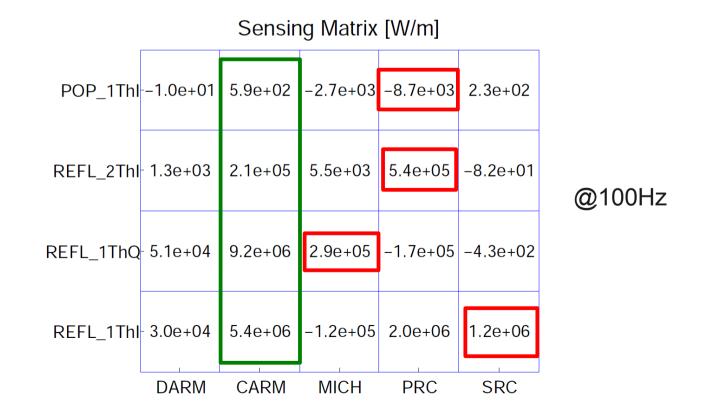


# Third Harmonics Demodulation

- Beat between 2\*f1 and f1 (Insensitive to the arms)
- Useful for lock acquisition.
- Substitutes for NRS. No MZ, no AM necessary -> simple.

Unfortunately, all the f1 candidates cannot use this method in the usual sense, because 2\*f1 resonates in the PRC-SRC. (f1 frequencies tested: 9MHz, 11.25MHz, 13.5MHz, 16.875MHz, 19.3MHz)

Actually, 3<sup>rd</sup> harmonics demodulation produces some signal due to difference in the response of 2\*f1 and f1. However, strong interference from the carrier is present (carrier-3\*f1 beat).

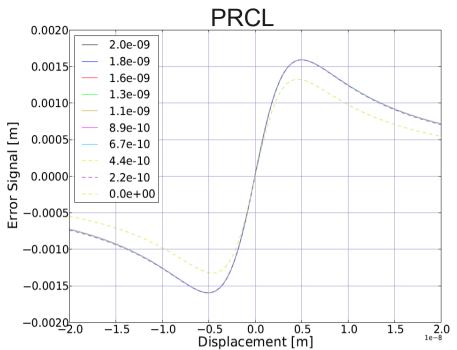


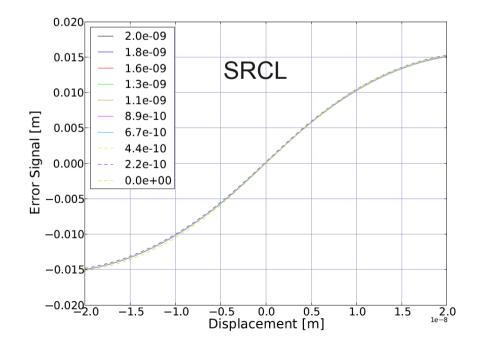
## **Third Harmonics Demodulation**

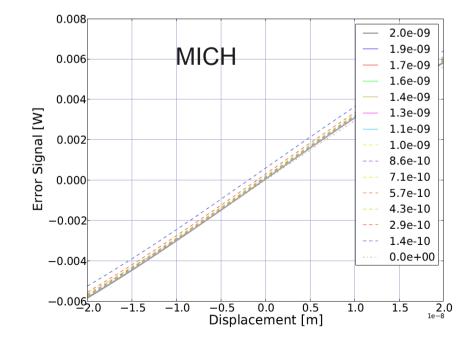
3<sup>rd</sup> Harmonics signal during lock acquisition

CARM offset: 2nm -> 0

MICH is affected by CARM





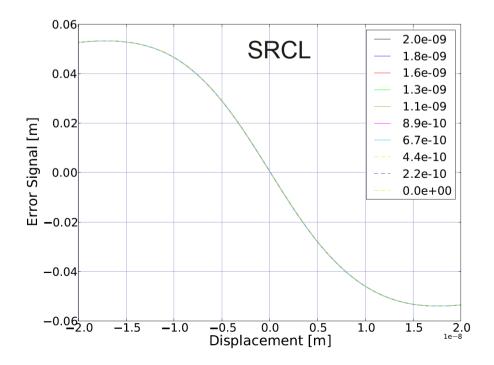


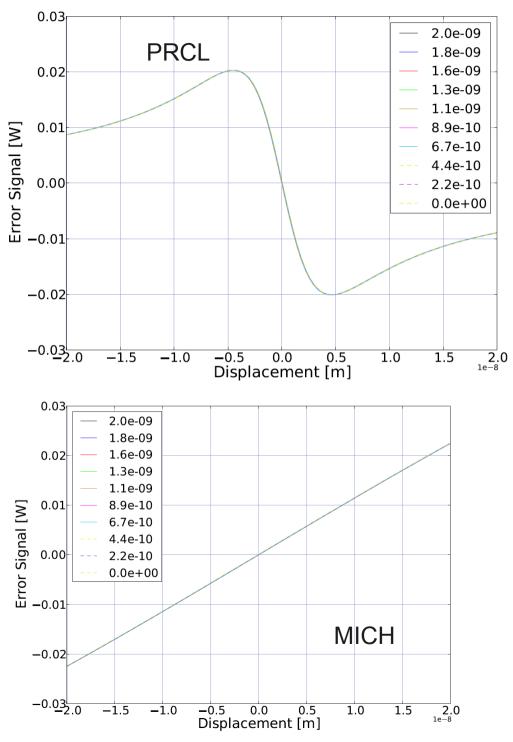
## Non-Resonant Sideband for Lock Acquisition

NRS serves as a local oscillator insensitive to the arms

NRS signals during the lock acquisition

CARM offset: 2nm -> 0





# **Detailed Optical Layout**

Detailed optical layout design is a non-trivial task !

We have to ...

- Take into account wedge deflection
- Make the two arms at the right angle
- Track the optical path length (for SB resonant conditions)
- Track the Gaussian mode evolution
- Track the Gouy phase evolution
- Take into account the dispersion effect for the green beams
- Trace secondary beams (AR reflected)
- Generate CAD files

A python package to do the above job was developed.

gtrace: A Gaussian ray tracing library (Validation of the library was done by Chen Dan)

# iLCGT

- iLCGT has to be on the way to bLCGT
- Minimum detour from the straight path to bLCGT
- Most parameters are the same as bLCGT

### Interferometer Configuration

- Fabry-Perot Michelson Interferometer (no recycling)
- Arm cavity finesse is the same as bLCGT

### Mirrors

- Test masses are fused silica
- All the other mirrors are to be used in bLCGT (BS and the folding mirrors)
- PRM is a blank with curvature (for mode matching)
- No SRM installed.

## LSC

• A simple frontal modulation scheme using f1 SB only

### ASC

• Wave front sensing at REFL and AS

# iLCGT Sensing Matrices

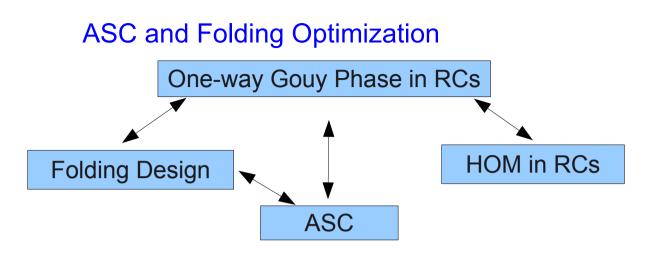
LSC

	DARM	CARM	MICH
AS_1I	1	$1.7  imes 10^{-3}$	$1.0  imes 10^{-3}$
REFL_1I	$8.8 \times 10^{-3}$	1	$1.3 \times 10^{-4}$
$REFL_1Q$	$4.5 \times 10^{-3}$	$5.5 \times 10^{-5}$	1

### ASC (Diagonalized)

	CSOFT	CHARD	DSOFT	DHARD
REFL_2IB	1	0	$-8.7 \times 10^{-5}$	$-1.8 \times 10^{-4}$
REFL_2IA	0	1	$1.3 \times 10^{-3}$	$8.7 \times 10^{-5}$
AS_1QB	$-2.5 \times 10^{-5}$	$3.4 \times 10^{-6}$	1	0
REFL_1QA	$1.3 \times 10^{-4}$	$-2.4 \times 10^{-5}$	0	1

# What to do next?

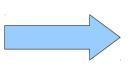


### **Technical Noise Couplings**

- Laser Noise (frequency, intensity)
- Modulator phase noise
- Actuator noise (hierarchical control)
- PD noise
- etc ....

## OMC Design (together with the IOO group)

- Requirements (HOM reduction ratio)
- Control Schemes
- Prototype test



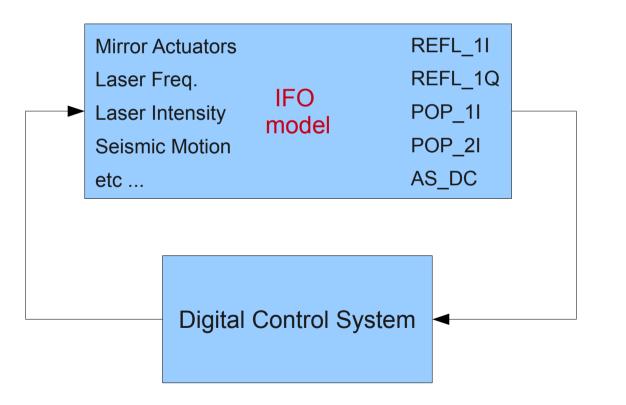
Requirements to other subsystems

# Simulated IFO plant

- Expedite the commissioning
- Make effective use of tunnel excavation & vacuum installation period (2 years)

### Develop a computer model of the IFO

- Connected to the digital control system
- Develop the LSC & ASC digital servo system before actual interferometer is available
- Once real interferometer is installed, use the pre-developed servo system



## Linear Model

Model Generation: Optickle Implementation: Digital System

### **Non-Linear Model**

Time-domain simulation: e2e Non-realtime Simulate lock acquisition etc..

## During the construction period

Tasks						FY2	011											FY2	012							FY2	013	
Tasks	4	5	6	7	8	9	10	11	12	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	4	5	6	7
Design																												
ASC																												
Folding Optimization																												
Simulated Plant Test																												
Linear Plant																												
Non-linear time domain plant																												
Digital Controller																												
Closed Loop Test																												
OMC																												
Requirement fix																												
LSC Design																												
ASC Design Prototype Fabrication																												
Prototype Fabrication																												
Prototype Test																												

# Schedule

# **Commissioning Period**

Tasks				FY2	2013									FY2	014					FY2015												
	8	9	10	11	12	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	4	5	9	7	8	9	10	11	12	1	2	3
FPMI																																
X-arm																																
Y-arm																																
MI																																
FPMI																																
Noise hunting																																
Observation																																
RSE1																																
RSE1 Preparation																																
DRMI																																
PRFPMI																																
RSE																																
Observation																																
RSE2																																
VIS Upgrade																																
RSE																																
Observation																																

Taska						FY2	016						FY2017												
Tasks	4	5	6	7	8	9	10	11	12	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CRSE																									
Installation of Cryogenic System																									
Single Arm Tests																									
FPMI																									
RSE																									
Noise hunting																									
Observation																									
Noise Hunting																									

# Risks

- Arm loss may be higher --> PRC becomes under coupled
  - Prepare several PRMs with slightly different reflecvitities
- Arm loss may be smaller
  - Shot noise increase of the DDM signals
- HD phase depends on the amount of reflectivity mismatch between the arms
  - DARM offset may have to be very large
  - HD phase may be almost 90 deg.
- SRC detuning by offset
- PR3 ROC error
  - Leave room for moving PRM, PR2, PR3, SRM, SR2 and SR3
- ASC design
  - How to control the folded PRC/SRC?
- OMC design
  - Control Schemes

# Summary

### Interferometer Design (bLCGT)

- RSE interferometer
- Variable BRSE/DRSE
- 66m folded recycling cavities

#### Length Control Scheme

- 16.875MHz-45MHz PM, Single demodulation
- Optional Non-Resonant Sideband

### Alignment Sensing Scheme

- WFS & Optical Lever
- Needs more study

#### Lock Acquisition

- Green laser pre-lock
- Third harmonics demodulation or NRS

### <u>TO DO</u>

- Alignment Sensing Schemes
- Folding design optimization
- OMC design
- Technical noise couplings
- Simulated IFO plant

## Interferometer Design (iLCGT)

- Fabry-Perot Michelson
- No Recycling